图形点阵液晶显示模块使用手册

CM12864-26SLYB

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图形点阵液晶显示模块使用手册

CM12864-26SLYB

一． 概述

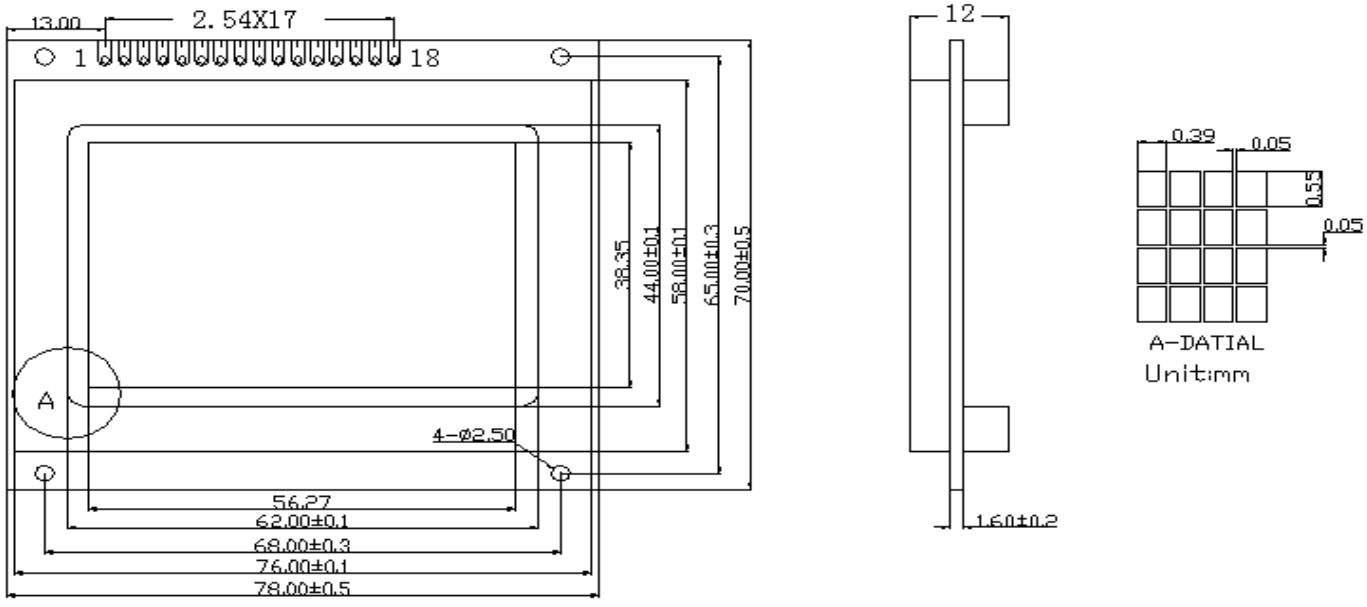
CM12864-26 是一种图形点阵液晶显示器,它主要由行驱动器/列驱动器及格 128×64 全点阵液晶显示器组成。可完成图形显示，也可以显示 8×4 个(16×16 点阵)汉字。

主要技术参数和性能：模块内自带-10 负压，用于 LCD 的驱动电压

1.电源：VDD：+5V；
2.显示内容：128(列)×64(行)点
3.全屏幕点阵
4.七种指令
5.与 CPU 接口采用 8 位数据总线并行输入输出和 8 条控制线
6.占空比 1/64
7.工作温度：-10℃∽+55℃，存储温度：-20℃∽+70℃
8.显示模式：黄绿膜、灰膜、蓝膜、黑白膜
9.背光特性：LED 背光（黄绿色、蓝色、白色、红色）
10.模块封装方式：COB
11.视角方向：6:00
12.功耗：模块自带负压

二． 外形尺寸图

1．外形尺寸图

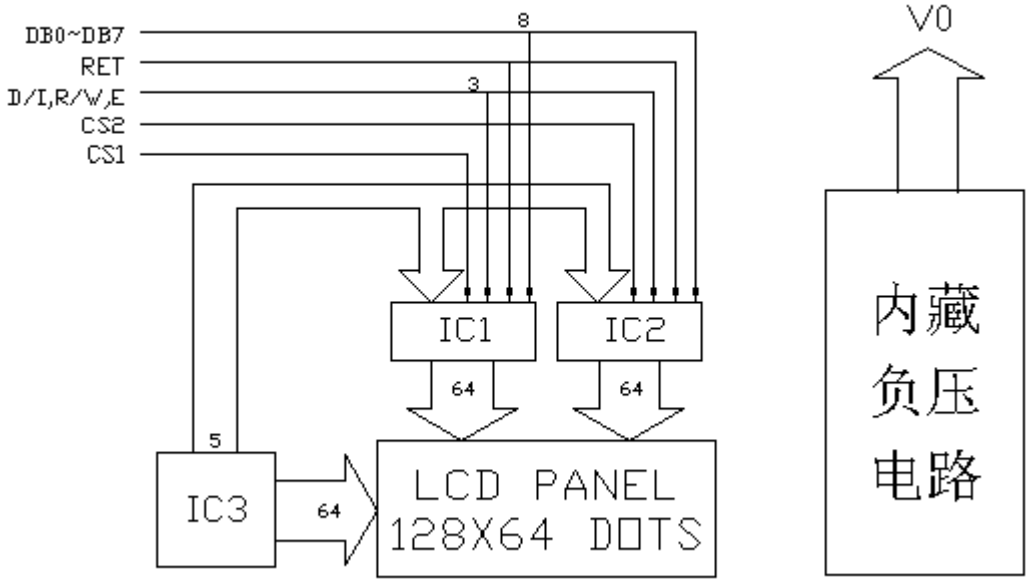


2． 外形尺寸

表 1

ITEM	NOMINAL DIMEN	UNIT
模块体积	78.0×70.0×12.0	mm
视域	62.0×44.0	mm
行列点阵数	128×64	dots
点距离	0.05×0.05	mm
点大小	0.39×0.55	mm

三．模块主要硬件构成说明 （结构框图）



IC3 为行驱动器。IC1，IC2 为列驱动器。IC1，IC2，IC3 含有以下主要功能器件。了解如下器件有利于对 LCD 模块之编程。

1.指令寄存器(IR)

IR 是用来寄存指令码,与数据寄存器寄存数据相对应.当 D/I=1 时,在 E 信号下降沿的作用下,指令码写入 IR.

2.数据寄存器(DR)

DR 是用来寄存数据的,与指令寄存器寄存指令相对应.当 D/I=1 时,在 E 信号的下降沿作用下,图形显示数据写入 DR,或在 E 信号高电平作用下由 DR 读到 DB7~DB0 数据总线.DR 和 DDRAM 之间的数据传输是模块内部自动执行的.

3.忙标志:BF

BF 标志提供内部工作情况.BF=1 表示模块在进行内部操作,此时模块不接受外部指令和数据.BF=0 时,模块为准备状态,随时可接受外部指令和数据.

利用 STATUS READ 指令,可以将 BF 读到 DB7 总线,从而检验模块之工作状态.

4.显示控制触发器 DFF

此触发器是用于模块屏幕显示开和关的控制。DFF=1 为开显示（DISPLAY ON),DDRAM 的内容就显示在屏幕上，DDF=0 为关显示（DISPLAY OFF)。

DDF 的状态是指令 DISPLAY ON/OFF 和 RST 信号控制的。

5.XY 地址计数器

XY 地址计数器是一个 9 位计数器。高三位是 X 地址计数器，低 6 位为 Y 地址计数器,XY 地址计数器实际上是作为 DDRAM 的地址指针,X 地址计数器为 DDRAM 的页指针，Y 地址计数器为 DDRAM 的 Y 地址指针。

X 地址计数器是没有记数功能的，只能用指令设置。

Y 地址计数器具有循环记数功能，各显示数据写入后，Y 地址自动加 1，Y 地址指针从 0 到 63。

6.显示数据 RAM(DDRAM)

DDRAM 是存贮图形显示数据的。数据为 1 表示显示选择，数据为 0 表示显示非选择。DDRAM 与地址和显示位置的关系见 DDRAM 地址表（见第 6 页)。

7.Z 地址计数器

Z 地址计数器是一个 6 位计数器，此计数器具备循环记数功能，它是用于显示行扫描同步。当一行扫描完成，此地址计数器自动加 1，指向下一行扫描数据，RST 复位后 Z 地址计数器为 0。

Z 地址计数器可以用指令 DISPLAY START LINE 预置。因此，显示屏幕的起始行就由此指令控制，即 DDRAM 的数据从哪一行开始显示在屏幕的第一行。此模块的 DDRAM 共 64 行，屏幕可以循环滚动显示 64 行。

四．模块的外部接口

外部接口信号如下表 2 所示：

表 2

管脚号	管脚名称	LEVER	管脚功能描述
1	/CS1	H/L	L:选择芯片(左半屏)信号
2	/CS2	H/L	L:选择芯片(右半屏)信号
3	GND	0	电源地
4	VDD	5.0V	电源电压
5	V0	6.0V∽-10V	液晶显示器驱动电压
6	D/I	H/L	D/I=“H”，表示 DB7∽DB0 为显示数据 D/I=“L”，表示 DB7∽DB0 为显示指令数据
7	R/W	H/L	R/W=“H”，E=“H”数据被读到 DB7∽DB0 R/W=“L”，E=“H→L”数据被写到 IR 或 DR
8	E	H/L	R/W=“L”，E 信号下降沿锁存 DB7∽DB0 R/W=“H”，E=“H”DDRAM 数据读到 DB7∽DB0
9	DB0	H/L	
10	DB1	H/L	
11	DB2	H/L	数据线
12	DB3	H/L	
13	DB4	H/L	
14	DB5	H/L	
15	DB6	H/L	
16	DB7	H/L	

17	LED+	5V	LED(+5V)或 EL 背光源
18	LED-	-	LED(0V)或 EL 背光源

五．指令说明

指令表

指令	指令码										功能
	R/W	D/I	D7	D6	D5	D4	D3	D2	D1	D0	
显示 ON/OFF	0	0	0	0	1	1	1	1	1	1/0	控制显示器的开关，不影响 DDRAM 中数据和内部状态
显示起始行	0	0	1	1	显示起始行（0 ···· 63）						指定显示屏从 DDRAM 中哪一行开始显示数据
设置 X 地址	0	0	1	0	1	1	1	X：0 ··· 7			设置 DDRAM 中的页地址(X 地址)
设置 Y 地址	0	0	0	1	Y 地址（0 ··· 63）						设置地址(Y 地址)
读状态	1	0	BUSY	0	ON/OFF	RST	0	0	0	0	读取状态 RST 1:复位 0:正常 ON/OFF 1:显示开 0:显示关 BUSY 0:READY 1:IN OPERATION
写显示数据	0	1	显示数据								将数据线上的数据 DB7∽DB0 写入 DDRAM
读显示数据	1	1	显示数据								将 DDRAM 上的数据读入数据线 DB7∽DB0

1.显示开关控制(DISPLAY ON/OFF)

代码	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
形式	0	0	0	0	1	1	1	1	1	D

D=1:开显示(DISPLAY ON) 意即显示器可以进行各种显示操作

D=0:关显示(DISPLAY OFF) 意即不能对显示器进行各种显示操作

2.设置显示起始行(DISPLAY START LINE)

代码	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
形式	0	0	1	1	A5	A4	A3	A2	A1	A0

前面在 Z 地址计数器一节已经描述了显示起始行是由 Z 地址计数器控制的。A5~A0 6 位地址自动送入 Z 地址计数器,起始行的地址可以是 0~63 的任意一行。

例如:

选择 A5~A0 是 62,则起始行与 DDRAM 行的对应关系如下：

DDRAM 行：62 63 0 1 2 3 ·····28 29

屏幕显示行： 1 2 3 4 5 6 ····· 31 32

3.设置页地址（SET PAGE “X ADDRESS”)

代码形式	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
	0	0	1	0	1	1	1	A2	A1	A0

所谓页地址就是 DDRAM 的行地址，8 行为一页,模块共 64 行即 8 页,A2~A0 表示 0~7 页。读写数据对地址没有影响,页地址由本指令或 RST 信号改变复位后页地址为 0。页地址与 DDRAM 的对应关系见 DDRAM 地址表。

4.设置 Y 地址(SET Y ADDRESS)

代码形式	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
	0	0	0	1	A5	A4	A3	A2	A1	A0

此指令的作用是将 A5~A0 送入 Y 地址计数器，作为 DDRAM 的 Y 地址指针。在对 DDRA M 进行读写操作后，Y 地址指针自动加 1,指向下一个 DDRAM 单元。

DDRAM 地址表：

表 4

	CS2=1					CS1=1					
Y=	0	1	……	62	63	0	1	……	62	63	行号
X=	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	0 ↓ 7
0 ↓	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	8 ↓ 55
X=7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	DB0 ↓ DB7	56 ↓ 63

5.读状态(STATUS READ)

代码形式	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
	0	1	BUSY	0	ON/OFF	RET	0	0	0	0

当 R/W=1 D/I=0 时,在 E 信号为“ H ”的作用下，状态分别输出到数据总线(DB7~DB0)的相应位。

BF: 前面已叙述过(见 BF 标志位一节)。

ON/OFF: 表示 DFF 触发器的状态（见 DFF 触发器一节)。

RST: RST=1 表示内部正在初始化，此时组件不接受任何指令和数据。

6.写显示数据(WRITE DISPLAY DATE)

代码形式	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
	0	1	D7	D6	D5	D4	D3	D2	D1	D0

D7~D0 为显示数据,此指令把 D7~D0 写入相应的 DDRAM 单元,Y 地址指针自动加 1。

7.读显示数据(READ DISPLAY DATE)

代码形式	R/W	D/I	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
	1	1	D7	D6	D5	D4	D3	D2	D1	D0

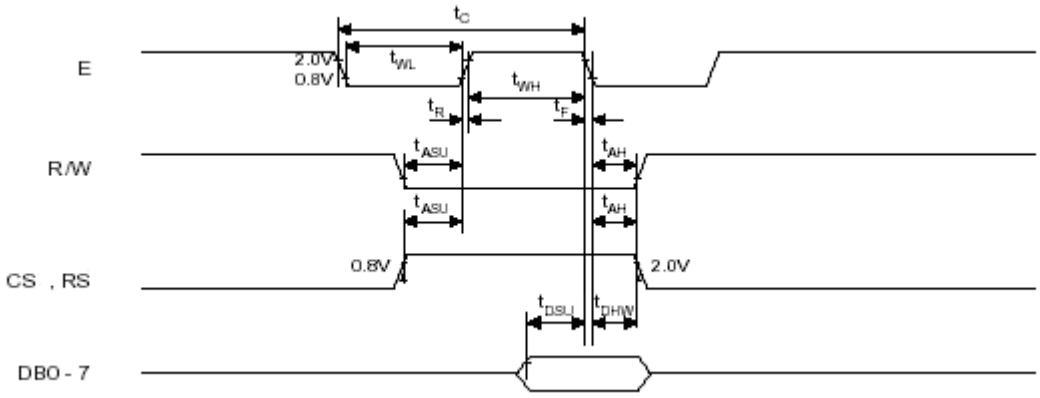
此指令把 DDRAM 的内容 D7~D0 读到数据总线 DB7~DB0，Y 地址指针自动加 1。

Return

六、读写操作时序

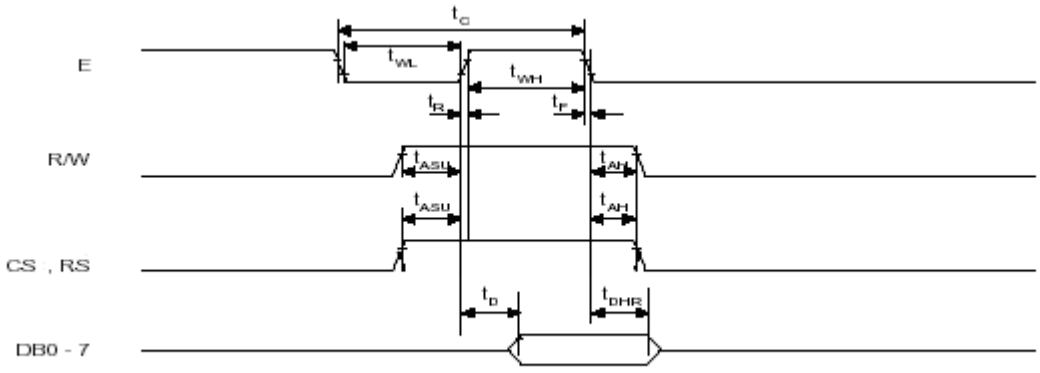
1.写操作时序

图　3



2.读操作时序

图　4



3.读写时序参数表

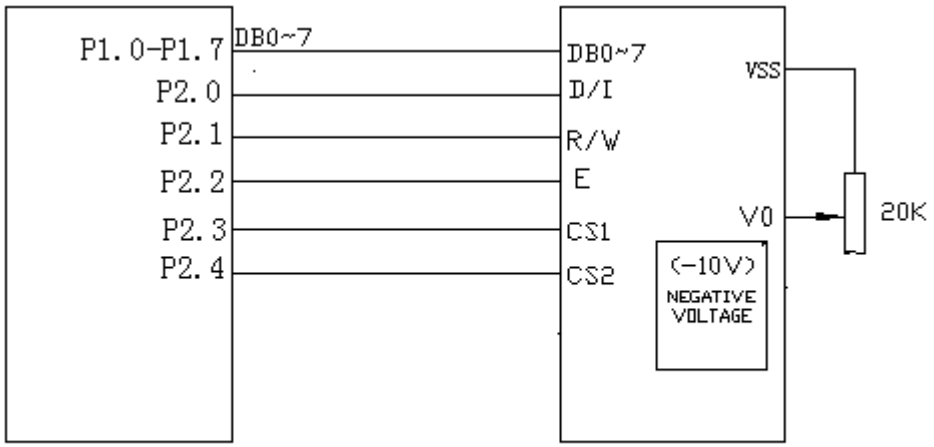
Characteristic	Symbol	Min	Typ	Max	Unit
E cycle	t_C	1000	-	-	ns
E high level width	t_{WH}	450	-	-	ns
E low level width	t_{WL}	450	-	-	ns
E rise time	t_R	-	-	25	ns
E fall time	t_F	-	-	25	ns
Address set-up time	t_{ASU}	140	-	-	ns
Address hold time	t_{AH}	10	-	-	ns
Data set-up time	t_{DSU}	200	-	-	ns
Data delay time	t_D	-	-	320	ns
Data hold time (write)	t_{DHW}	10	-	-	ns
Data hold time (read)	t_{DHR}	20	-	-	ns

Return

七．应用举例

CM12864-26 与单片机 8031 的一种接口如图 5.所示：
注:V0 为液晶驱动电压。此图为模块内自带负压的示例，若外接负压，则接到 V0。

图 5




```
        ORG     0000H
        LJMP    MAIN
        ORG     0003H
        LJMP    ZHONGDUAN
        ORG     0035H
ZHONGDUAN:
        LCALL   DELAY
        CLR     EA
```

```
                JB      P3.2,$
                SETB    EA
                LCALL   DELAY
                RETI

    CS1         EQU     P2.3
    CS2         EQU     P2.4
    DI          EQU     P2.0
    RW          EQU     P2.1
    E           EQU     P2.2
    DATA1       EQU     50H
    DATA2       EQU     51H
    DATA3       EQU     52H
 ;***********写左半屏命令*******************
WRITE_COMMAND_L:
    CLR     CS1
    CLR     RW
    CLR     DI
    MOV     P1,DATA1
    SETB    E
    CLR     E
    SETB    CS1
    RET

 ;***********写左半屏数据*******************
WRITE_DATA_L:
    CLR     CS1
    CLR     RW
    SETB    DI
    MOV     P1,DATA2
    SETB    E
    CLR     E
    SETB    CS1
    RET
 ;***********写右半屏命令*******************
WRITE_COMMAND_R:
    CLR     CS2
    CLR     RW
    CLR     DI
    MOV     P1,DATA1
    SETB    E
    CLR     E
```

```
    SETB    CS2
    RET

;***********写右半屏数据*******************
WRITE_DATA_R:
    CLR     CS2
    CLR     RW
    SETB    DI
    MOV     P1,DATA2
    SETB    E
    CLR     E
    SETB    CS2
    RET
;**********延时程序******************
    MS40:     MOV     R7,#0E8H
    MS2:      MOV     R6,#0FFH
    MS1:      DJNZ    R6,MS1
              DJNZ    R7,MS2
              RET
    DELAY:    MOV     R5,#07H
    DELAY1:   LCALL   MS40
              DJNZ    R5,DELAY1
              RET
;************************************



MAIN:
          MOV       P2,#0FFH
          MOV       SP,#60H
          SETB    EA
          SETB    EX0
          SETB    IT0

          MOV       DATA1,#3EH
          LCALL     WRITE_COMMAND_L
          LCALL     WRITE_COMMAND_R
          MOV       DATA1,#3FH
          LCALL     WRITE_COMMAND_L
          LCALL     WRITE_COMMAND_R
          MOV       DATA1,#0C0H
          LCALL     WRITE_COMMAND_L
```

```
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#0B8H     ;PAGE ADDRESS
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H      ;Y  ADDRESS
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M21:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#64
L21:    MOV     DATA2,#0AAH
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L21
        INC     DATA3
        DJNZ    R1,M21
        LCALL   DELAY

        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M22:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#64
L22:    MOV     DATA2,#55H
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L22
        INC     DATA3
        DJNZ    R1,M22
        LCALL   DELAY
```

```
        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M23:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#32
L23:    MOV     DATA2,#0FFH
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        MOV     DATA2,#00H
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L23
        INC     DATA3
        DJNZ    R1,M23
        LCALL   DELAY

        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M24:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#32
L24:    MOV     DATA2,#00H
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        MOV     DATA2,#0FFH
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L24
        INC     DATA3
        DJNZ    R1,M24
        LCALL   DELAY
```

```
        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M25:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#32
L25:    MOV     DATA2,#0AAH
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        MOV     DATA2,#55H
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L25
        INC     DATA3
        DJNZ    R1,M25
        LCALL   DELAY

        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M26:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        LCALL   WRITE_COMMAND_R
        MOV     R2,#32
L26:    MOV     DATA2,#55H
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        MOV     DATA2,#0AAH
        LCALL   WRITE_DATA_L
        LCALL   WRITE_DATA_R
        DJNZ    R2,L26
        INC     DATA3
        DJNZ    R1,M26
        LCALL   DELAY
```

```
        MOV     DPTR,#CHINESE1
        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M27:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_L
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_L
        MOV     R2,#64
L27:
        CLR     A
        MOVC    A,@A+DPTR
        MOV     DATA2,A
        LCALL   WRITE_DATA_L
        INC     DPTR
        DJNZ    R2,L27
        INC     DATA3
        DJNZ    R1,M27

        MOV     DPTR,#CHINESE2
        MOV     R1,#8
        MOV     DATA3,#0B8H
        MOV     DATA1,DATA3
M28:    MOV     DATA1,DATA3
        LCALL   WRITE_COMMAND_R
        MOV     DATA1,#40H
        LCALL   WRITE_COMMAND_R
        MOV     R2,#64
L28:
        CLR     A
        MOVC    A,@A+DPTR
        MOV     DATA2,A
        LCALL   WRITE_DATA_R
        INC     DPTR
        DJNZ    R2,L28
        INC     DATA3
        DJNZ    R1,M28
        LCALL   DELAY
        LJMP    MAIN

CHINESE1:
```

DB
0FFH,0FFH,003H,023H,0A3H,023H,063H,0B3H,013H,013H,0D3H,083H,003H,003H,083H,063H
DB
043H,003H,003H,003H,003H,003H,0E3H,0A3H,0A3H,0A3H,0A3H,0A3H,0A3H,0E3H,003H,003H
DB
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076H,024H,000H,0F0H,050H,050H,057H,052H,0F2H,002H,002H,0F2H,052H,057H,050H,050H
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000H,000H,000H,007H,002H,002H,002H,002H,007H,000H,000H,007H,002H,002H,002H,002H
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DB
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,0C3H

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