

# $I^2C^{\otimes}$ CMOS 8 × 10 Unbuffered Analog Switch Array with Dual/Single Supplies

## ADG2108

#### FEATURES

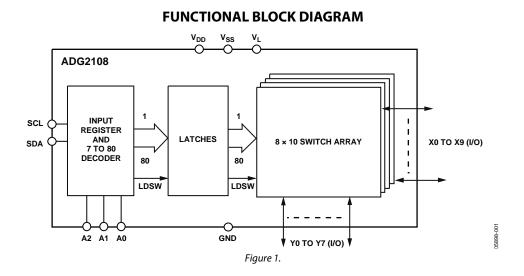
I<sup>2</sup>C-compatible interface 3.4 MHz high speed I<sup>2</sup>C option 32-lead LFCSP\_VQ (5 mm × 5 mm) Double-buffered input logic Simultaneous update of multiple switches Up to 300 MHz bandwidth Fully specified at dual ±5 V/single +12 V operation On resistance 35 Ω maximum Low quiescent current < 20 μA

#### **APPLICATIONS**

AV switching in TV Automotive infotainment AV receivers CCTV Ultrasound applications KVM switching Telecom applications Test equipment/instrumentation PBX systems

#### **GENERAL DESCRIPTION**

The ADG2108 is an analog cross point switch with an array size of  $8 \times 10$ . The switch array is arranged so that there are eight columns by 10 rows, for a total of 80 switch channels. The array is bidirectional, and the rows and columns can be configured as either inputs or outputs. Each of the 80 switches can be addressed and configured through the I<sup>2</sup>C-compatible interface. Standard, full speed, and high speed (3.4 MHz) I<sup>2</sup>C interfaces are supported. Any simultaneous switch combination is allowed. An additional feature of the ADG2108 is that switches can be updated simultaneously, using the LDSW command. In addition, a RESET option allows all of the switch channels to be reset/off. At power on, all switches are in the off condition. The device is packaged in a 32-lead, 5 mm  $\times$  5 mm LFCSP\_VQ.



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#### **REVISION HISTORY**

4/06—Revision 0: Initial Version

### **SPECIFICATIONS**

 $V_{\rm DD}$  = 12 V  $\pm$  10%,  $V_{SS}$  = 0 V,  $V_{\rm L}$  = 5 V, GND = 0 V, all specifications  $T_{\rm MIN}$  to  $T_{\rm MAX}$  unless otherwise noted.  $^1$ 

Table 1.

	BV	ersion	YV	/ersion		
_		–40°C to		–40°C to		
Parameter	+25°C	+85°C	+25°C	+125°C	Unit	Conditions
ANALOG SWITCH						
Analog Signal Range		$V_{\text{DD}} - 2 V$		$V_{DD} - 2 V$	V max	
On Resistance, Ron	30		30		Ωtyp	$V_{DD} = 10.8 \text{ V}, V_{IN} = 0 \text{ V}, I_S = -10 \text{ mA}$
	35	40	35	42	Ωmax	
	32		32		Ωtyp	$V_{DD} = 10.8 V$ , $V_{IN} = 1.4 V$ , $I_{S} = -10 mA$
	37	42	37	47	$\Omega$ max	
	45		45		Ωtyp	$V_{DD} = 10.8 V$ , $V_{IN} = 5.4 V$ , $I_s = -10 mA$
	50	57	50	62	Ωmax	
On Resistance Matching	4.5		4.5		Ωtyp	$V_{DD} = 10.8 V$ , $V_{IN} = 0 V$ , $I_S = -10 mA$
Between Channels, ΔR <sub>ON</sub>	8	9	8	10	$\Omega$ max	
On Resistance Flatness, R <sub>FLAT(ON)</sub>	2.3		2.3		Ωtyp	$V_{DD} = 10.8 V$ , $V_{IN} = 0 V$ to 1.4 V, $I_S = -10 mA$
	3.5	4	3.5	5	Ωmax	
	14.5		14.5		Ωtyp	$V_{DD} = 10.8 V$ , $V_{IN} = 0 V$ to 5.4 V, $I_S = -10 mA$
	18	20	18	22	Ωmax	
LEAKAGE CURRENTS						$V_{DD} = 13.2 V$
Channel Off Leakage, IOFF	±0.03		±0.03		μA typ	$V_x = 7 V/1 V$ , $V_y = 1 V/7 V$
Channel On Leakage, Ion	±0.03		±0.03		μA typ	$V_{x} = V_{y} = 1 V \text{ or } 7 V$
DYNAMIC CHARACTERISTICS <sup>2</sup>					F	
Coff	11		11		pF typ	
	18.5		18.5		_pE typ _	
ton	170		170		ns typ	$R_L = 300 \Omega$ , $C_L = 35 pF$
CON	185	190	185	195	ns max	Π <sub>L</sub> = 500 Ω <sub>2</sub> , C <sub>L</sub> = 55 pi
toff	210	150	210	175	ns typ	$R_L = 300 \Omega, C_L = 35 pF$
COFF	250	255	250	260	ns max	$M_{\rm L} = 500  \Omega_2,  C_{\rm L} = 55  {\rm pr}$
THD + N	0.04	233	0.04	200	% typ	$R_L = 10 \text{ k}\Omega$ , $f = 20 \text{ Hz to } 20 \text{ kHz}$ , $V_S = 1 \text{ V p-p}$
PSRR			90		dB typ	f = 20 kHz; without decoupling; see Figure 24
–3 dB Bandwidth	210		210		MHz typ	Individual inputs to outputs
-	16.5		16.5		MHz typ	8 inputs to 1 output
Off Isolation	-69		-69		dB typ	$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$
Channel-to-Channel Crosstalk						$R_L = 75 \Omega, C_L = 5 pF, f = 5 MHz$
Adjacent Channels	-63		-63		dB typ	
Nonadjacent Channels	-76		-76		dB typ	
Differential Gain	0.4		0.4		% typ	$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$
Differential Phase	0.4		0.4		° typ	$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$
Charge Injection	-3.5		-3.5		pC typ	$V_s = 4 V, R_s = 0 \Omega, C_L = 1 nF$
LOGIC INPUTS (Ax, RESET) <sup>2</sup>	5.5		5.5		P- 9P	
Input High Voltage, VINH		2.0		2.0	V min	
Input High Voltage, VINH		2.0 0.8		2.0 0.8	V min V max	
	0.005	0.0	0.005	0.0		
Input Leakage Current, I <sub>IN</sub>	0.005	. 1	0.005	. 1	µA typ	
	_	±1	_	±1	µA max	
Input Capacitance, C <sub>IN</sub>	7		7		pF typ	

	BV	<b>ersion</b>	Y١	/ersion		
	-40°C to		–40°C to			
Parameter	+25°C +85°C		+25°C +125°C		Unit	Conditions
LOGIC INPUTS (SCL, SDA) <sup>2</sup>						
Input High Voltage, V <sub>INH</sub>		0.7 VL		0.7 V∟	V min	
		$V_L + 0.3$		$V_L + 0.3$	V max	
Input Low Voltage, VINL		-0.3		-0.3	V min	
		$0.3 V_{L}$		0.3 VL	V max	
Input Leakage Current, I <sub>IN</sub>	0.005		0.005		μA typ	$V_{IN} = 0 V \text{ to } V_L$
		±1		±1	μA max	
Input Hysteresis		0.05 V∟		0.05 V∟	V min	
Input Capacitance, C <sub>IN</sub>	7		7		pF typ	
LOGIC OUTPUT (SDA) <sup>2</sup>						
Output Low Voltage, V <sub>OL</sub>		0.4		0.4	V max	I <sub>SINK</sub> = 3 mA
		0.6		0.6	V max	$I_{SINK} = 6 \text{ mA}$
Floating State Leakage Current		±1		±1	μA max	
POWER REQUIREMENTS						
lod	0.05		0.05		μA typ	Digital inputs = $0 V \text{ or } V_L$
		1		1	µA max	
lss	0.05		0.05		μA typ	Digital inputs = $0 V \text{ or } V_L$
		1		1	μA max	
l.						Digital inputs = $0 V \text{ or } V_L$
Interface Inactive	0.3		0.3		μA typ	
		2		2	μA max	
Interface Active: 400 kHz f <sub>SCL</sub>	0.1		0.1		mA typ	
		0.2		0.2	mA max	
Interface Active: 3.4 MHz f <sub>SCL</sub>	0.4		0.4		mA typ	-HS model only
-		1.2		1.7	mA max	

 $^1$  Temperature range is as follows: B version: –40°C to +85°C; Y version: –40°C to +125°C.  $^2$  Guaranteed by design, not subject to production test.

 $V_{DD}$  = +5 V ± 10%,  $V_{SS}$  = -5 V ± 10%,  $V_L$  = 5 V, GND = 0 V, all specifications  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted.<sup>1</sup>

Table 2.

	B Version		YV	ersion			
Parameter	-40°C to +25°C +125°C		+25°C	–40°C to +125°C	Unit	Conditions	
ANALOG SWITCH					•		
Analog Signal Range				$V_{DD} - 2 V$	V max		
On Resistance, R <sub>ON</sub>	34		34		Ωtyp	$V_{DD} = +4.5 V$ , $V_{SS} = -4.5 V$ , $V_{IN} = V_{SS}$ , $I_S = -10 \text{ mA}$	
	40	45	40	50	Ωmax		
	50	10	50		Ωtyp	$V_{DD} = +4.5 V$ , $V_{SS} = -4.5 V$ , $V_{IN} = 0 V$ , $I_S = -10 mA$	
	55	65	55	70	$\Omega \max$		
	66		66		Ωtyp	$V_{DD} = +4.5 V, V_{SS} = -4.5 V, V_{IN} = 1.4 V, I_{S} = -10 mA$	
	75	85	75	95	$\Omega \max$		
On Resistance Matching	4.5		4.5		Ωtyp	$V_{DD} = +4.5 \text{ V}$ , $V_{SS} = -4.5 \text{ V}$ , $V_{IN} = V_{SS}$ , $I_S = -10 \text{ mA}$	
Between Channels, $\Delta R_{ON}$	8	9	8	10	$\Omega \max$		
On Resistance Flatness, R <sub>FLAT(ON)</sub>	17		17	10	Ωtyp	$V_{DD} = +4.5 V$ , $V_{SS} = -4.5 V$ , $V_{IN} = V_{SS}$ to 0 V, $I_S = -10 mA$	
	20	23	20	25	$\Omega \max$		
	34	25	34	25	Ωtyp	$V_{DD} = +4.5 V$ , $V_{SS} = -4.5 V$ , $V_{IN} = V_{SS}$ to $1.4 V$ , $I_S = -10 \text{ mA}$	
	42	45	42	48	Ω max		
LEAKAGE CURRENTS	74	Ъ	72	то	2211107	$V_{DD} = 5.5 V, V_{SS} = 5.5 V$	
Channel Off Leakage, IOFF	±0.03		±0.03		μA typ	$V_{DD} = 5.5 V, V_{SS} = 5.5 V$ $V_X = +4.5 V/-2 V, V_Y = -2 V/+4.5 V$	
Channel On Leakage, Ion	±0.03		±0.03		μA typ	$V_x = +4.5 V = -2 V \text{ or } +4.5 V$ $V_x = V_y = -2 V \text{ or } +4.5 V$	
DYNAMIC CHARACTERISTICS <sup>2</sup>	±0.03		±0.05		ил тур	$v_{\rm X} - v_{\rm Y} = -2 v  01 + 4.3 v$	
	e		6		n E turn		
	6		-		pF typ		
Con	9.5		9.5		pF typ		
ton	170	215	170	220	ns typ	$R_L = 300 \Omega, C_L = 35 pF$	
		-215	200 -	220 -	ns max		
toff	210	255	210	260	ns typ	$R_L = 300 \Omega$ , $C_L = 35 pF$	
	250	255	250	260	ns max		
THD + N	0.04		0.04		% typ	$R_L = 10 \text{ k}\Omega$ , $f = 20 \text{ Hz}$ to $20 \text{ kHz}$ , $V_S = 1 \text{ V} \text{ p-p}$	
PSRR	200		90		dB typ	f = 20 kHz; without decoupling; see Figure 24	
–3 dB Bandwidth	300		300		MHz typ	Individual inputs to outputs	
	18		18		MHz typ	8 inputs to 1 output	
Off Isolation	-66		-64		dB typ	$R_L = 75 \Omega, C_L = 5 \text{ pF}, f = 5 \text{ MHz}$	
Channel-to-Channel Crosstalk						$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$	
Adjacent Channels	-62		-62		dB typ		
Nonadjacent Channels	-79		-79		dB typ		
Differential Gain	1.5		1.5		% typ	$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$	
Differential Phase	1.8		1.8		° typ	$R_L = 75 \Omega$ , $C_L = 5 pF$ , $f = 5 MHz$	
Charge Injection	-3		-3		pC typ	$V_{S} = 0 V, R_{S} = 0 \Omega, C_{L} = 1 nF$	
LOGIC INPUTS (Ax, RESET) <sup>2</sup>							
Input High Voltage, V <sub>INH</sub>		2.0		2.0	V min		
Input Low Voltage, V <sub>INL</sub>		0.8		0.8	V max		
Input Leakage Current, I <sub>IN</sub>	0.005		0.005		μA typ		
		±1		±1	μA max		
Input Capacitance, C <sub>IN</sub>	7		7		pF typ		
LOGIC INPUTS (SCL, SDA) <sup>2</sup>							
Input High Voltage, VINH		0.7 VL		0.7 V∟	V min		
		$V_L + 0.3$		$V_L + 0.3$	V max		
Input Low Voltage, V <sub>INL</sub>		-0.3		-0.3	V min		
		0.3 VL		$0.3 V_{L}$	V max		

	ΒV	ersion	YV	ersion		
		–40°C to		–40°C to		
Parameter	+25°C	+125°C	+25°C	+125°C	Unit	Conditions
Input Leakage Current, I <sub>IN</sub>	0.005		0.005		μA typ	$V_{IN} = 0 V \text{ to } V_L$
		±1		±1	μA max	
Input Hysteresis		0.05 V∟		0.05 V∟	V min	
Input Capacitance, C <sub>IN</sub>	7		7		pF typ	
LOGIC OUTPUT (SDA) <sup>2</sup>						
Output Low Voltage, Vol		0.4		0.4	V max	I <sub>SINK</sub> = 3 mA
		0.6		0.6	V max	$I_{SINK} = 6 \text{ mA}$
Floating State Leakage Current		±1		±1	μA max	
POWER REQUIREMENTS						
ldd	0.05		0.005		μA typ	Digital inputs = $0 V \text{ or } V_L$
		1		1	μA max	
lss	0.05		0.005		μA typ	Digital inputs = $0 V \text{ or } V_L$
		1		1	μA max	
lL						Digital inputs = $0 V \text{ or } V_L$
Interface Inactive	0.3		0.3		μA typ	
		2		2	μA max	
Interface Active: 400 kHz $f_{SCL}$	0.1		0.1		mA typ	
		0.1		0.1	mA max	
Interface Active: 3.4 MHz f <sub>SCL</sub>	0.4		0.4		mA typ	-HS model only
		0.3		0.3	mA max	

 $^1$  Temperature range is as follows: B version: –40°C to +85°C; Y version: –40°C to +125°C.  $^2$  Guaranteed by design, not subject to production test.

#### I<sup>2</sup>C TIMING SPECIFICATIONS

 $V_{DD}$  = 5 V to 12 V;  $V_{SS}$  = -5 V to 0 V;  $V_L$  = 5 V; GND = 0 V;  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted (see Figure 2).

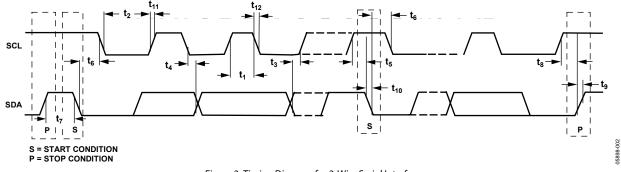
Table 3. ADG2108 Limit at T<sub>MIN</sub>, T<sub>MAX</sub> Parameter<sup>1</sup> Conditions Min Max Unit Description Serial clock frequency **f**scl Standard mode 100 kHz 400 Fast mode kHz High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 3.4 MHz  $C_B = 400 \text{ pF} \text{ maximum}$ 1.7 MHz Standard mode 4 thigh, SCL high time t1 μs Fast mode 0.6 μs High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 60 ns  $C_B = 400 \text{ pF} \text{ maximum}$ 120 ns  $t_2$ Standard mode 4.7 t<sub>LOW</sub>, SCL low time μs Fast mode 1.3 μs High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 160 ns  $C_B = 400 \text{ pF} \text{ maximum}$ 320 ns Standard mode 250 t3 t<sub>su;DAT</sub>, data setup time ns Fast mode 100 ns High speed mode<sup>2</sup> 10 ns t4<sup>3</sup> Standard mode 0 3.45 tHD;DAT, data hold time μs Fast mode 0 0.9 μs High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 0 70 ns  $C_B = 400 \text{ pF} \text{ maximum}$ 0 150 ns 4.7 t5 Standard mode t<sub>SU;STA</sub>, setup time for a repeated start condition μs Fast mode 0.6 μs High speed mode<sup>2</sup> 160 ns Standard mode 4 μs t<sub>HD:STA</sub>, hold time for a repeated start condition t<sub>6</sub> Fast mode 0.6 μs High speed mode<sup>2</sup> 160 ns t7 Standard mode 4.7  $t_{\text{BUF}}$ , bus free time between a stop and a start condition μs Fast mode 1.3 μs Standard mode 4 tsu;sto, setup time for a stop condition  $t_8$ μs Fast mode 0.6 μs High speed mode<sup>2</sup> 160 ns Standard mode 1000 t<sub>RDA</sub>, rise time of SDA signal t9 ns Fast mode  $20 + 0.1 C_B$ 300 ns High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 10 80 ns  $C_B = 400 \text{ pF} \text{ maximum}$ 20 160 ns Standard mode 300 t<sub>FDA</sub>, fall time of SDA signal **t**<sub>10</sub> ns Fast mode  $20 + 0.1 C_B$ 300 ns High speed mode<sup>2</sup>  $C_B = 100 \text{ pF} \text{ maximum}$ 10 80 ns  $C_B = 400 \text{ pF} \text{ maximum}$ 20 160 ns

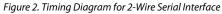
		ADG2108 Lim	nit at T <sub>MIN</sub> , T <sub>MAX</sub>		Description	
Parameter <sup>1</sup>	Conditions	Min	Max	Unit		
t <sub>11</sub>	Standard mode		1000	ns	t <sub>RCL</sub> , rise time of SCL signal	
	Fast mode	20 + 0.1 C <sub>B</sub>	300	ns		
	High speed mode <sup>2</sup>					
	$C_B = 100 \text{ pF} \text{ maximum}$	10	40	ns		
	$C_B = 400 \text{ pF} \text{ maximum}$	20	80	ns		
t <sub>11A</sub>	Standard mode		1000	ns	t <sub>RCL1</sub> , rise time of SCL signal after a repeated start	
	Fast mode	20 + 0.1 C <sub>B</sub>	300	ns	condition and after an acknowledge bit	
	High speed mode <sup>2</sup>					
	$C_B = 100 \text{ pF} \text{ maximum}$	10	80	ns		
	$C_B = 400 \text{ pF} \text{ maximum}$	20	160	ns		
t <sub>12</sub>	Standard mode		300	ns	t <sub>FCL</sub> , fall time of SCL signal	
	Fast mode	20 + 0.1 C <sub>B</sub>	300	ns		
	High speed mode <sup>2</sup>					
	$C_B = 100 \text{ pF} \text{ maximum}$	10	40	ns		
	$C_B = 400 \text{ pF} \text{ maximum}$	20	80	ns		
t <sub>SP</sub>	Fast mode	0	50	ns	Pulse width of suppressed spike	
	High speed mode <sup>2</sup>	0	10	ns		

<sup>1</sup> Guaranteed by initial characterization. All values measured with input filtering enabled. C<sub>8</sub> refers to capacitive load on the bus line; t<sub>8</sub> and t<sub>F</sub> are measured between 0.3  $V_{DD}$  and 0.7  $V_{DD}$ .

<sup>2</sup> High speed I<sup>2</sup>C is available only in -HS models.
 <sup>3</sup> A device must provide a data hold time for SDA to bridge the undefined region of the SCL falling edge.

#### **TIMING DIAGRAM**





### **ABSOLUTE MAXIMUM RATINGS**

 $T_A = 25^{\circ}C$ , unless otherwise noted.

#### Table 4.

Parameter	Rating	may cause permanent
V <sub>DD</sub> to V <sub>SS</sub>	15 V	rating only; functiona
V <sub>DD</sub> to GND	–0.3 V to +15 V	other conditions abov
Vss to GND	+0.3 V to -7 V	section of this specific
V∟ to GND	–0.3 V to +7 V	maximum rating con
Analog Inputs	$V_{SS} - 0.3 V$ to $V_{DD} + 0.3 V$	device reliability.
Digital Inputs	−0.3 V to V <sub>L</sub> + 0.3 V or 30 mA, whichever occurs first	
Continuous Current		
10 V on Input; Single Input Connected to Single Output	65 mA	
1 V on Input; Single Input Connected to Single Output	90 mA	
10 V on Input; Eight Inputs Connected to Eight Outputs	25 mA	
Operating Temperature Range		
Industrial (B Version)	–40°C to +85°C	
Automotive (Y Version)	–40°C to +125°C	
Storage Temperature Range	–65°C to +150°C	
Junction Temperature	150°C	
32-Lead LFCSP_VQ		
$\theta_{JA}$ Thermal Impedance	108.2°C/W	
Reflow Soldering (Pb Free)		
Peak Temperature	260°C (+0/=5)	
Time at Peak Temperature	10 sec to 40 sec	

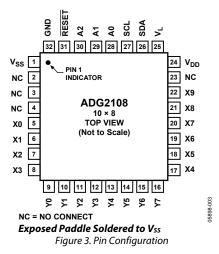
Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



## **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**



#### Table 5. Pin Function Descriptions<sup>1</sup>

Pin No.	Mnemonic	Description
1	V <sub>SS</sub>	Negative Power Supply in a Dual-Supply Application. For single-supply applications, this pin should be tied to GND.
2 to 4, 23	NC	No Connect.
5 to 8, 17 to 22	X0 to X9	Can be inputs or outputs.
9 to 16	Y0 to Y7	Can be inputs or outputs.
24	V <sub>DD</sub>	Positive Power Supply Input.
25	VL	Logic Power Supply Input.
26	SDA	Digital I/O. Bidirectional open drain data line. External pull-up resistor required.
27	SCL	Digital Input, Serial Clock Line. Open drain input that is used in conjunction with SDA to clock data into the device. External pull-up resistor required.
28	A0	Logic Input. Address pin that sets the least significant bit of the 7-bit slave address.
29	A1	Logic Input. Address pin that sets the second least significant bit of the 7-bit slave address.
30	A2	Logic Input. Address pin that sets the third least significant bit of the 7-bit slave address.
31	RESET	Active Low Logic Input. When this pin is low, all switches are open, and appropriate registers are cleared to 0.
32	GND	Ground. Reference point for all circuitry on the ADG2108.

 $^{\scriptscriptstyle 1}$  It is recommended that the exposed paddle be soldered to  $V_{\text{SS}}$  to improve heat dissipation and crosstalk.

### **TYPICAL PERFORMANCE CHARACTERISTICS**

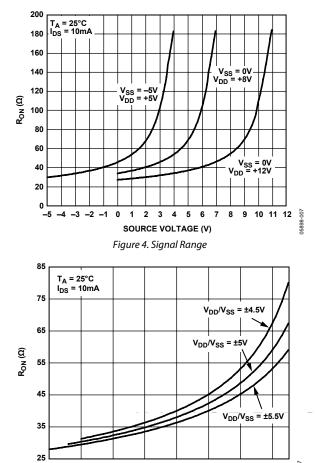


Figure 5.  $R_{ON}$  vs. Source Voltage, Dual  $\pm 5$  V Supplies

-2.5

-1.5

SOURCE VOLTAGE (V)

-0.5

0.5

1.5

05898-017

-5.5

-4.5

-3.5

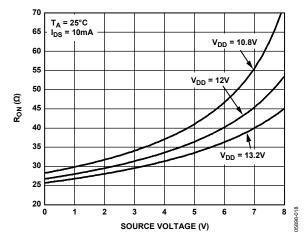


Figure 6. R<sub>ON</sub> vs. Supplies,  $V_{DD} = 12 V \pm 10\%$ 

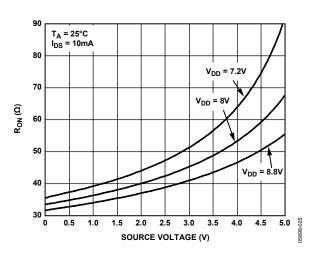
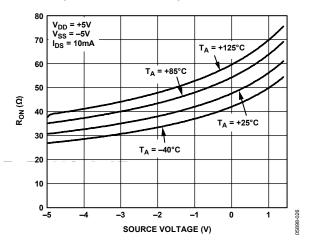


Figure 7. R<sub>ON</sub> vs. Source Voltage,  $V_{DD} = 8 V \pm 10\%$ 



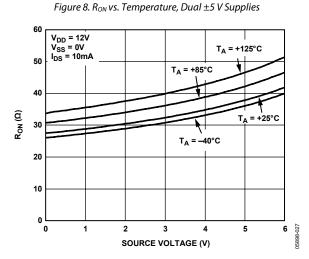


Figure 9.  $R_{ON}$  vs. Temperature,  $V_{DD} = 12 V$ 

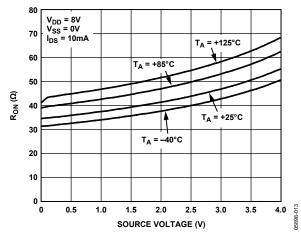


Figure 10.  $R_{ON}$  vs. Temperature,  $V_{DD} = 8 V$ 

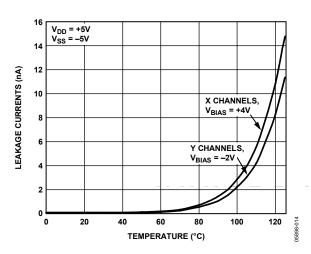


Figure 11. On Leakage vs. Temperature, Dual ±5 V Supplies

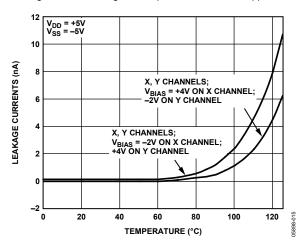


Figure 12. Off Leakage vs. Temperature, Dual ±5 V Supplies

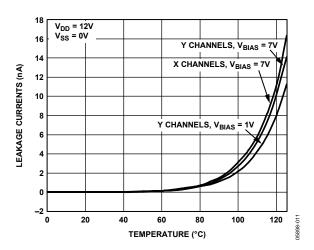
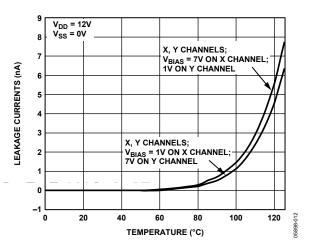


Figure 13. On Leakage vs. Temperature, 12 V Single Supply





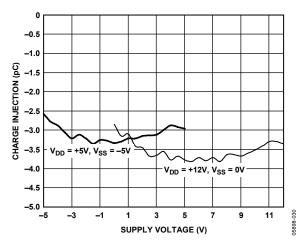
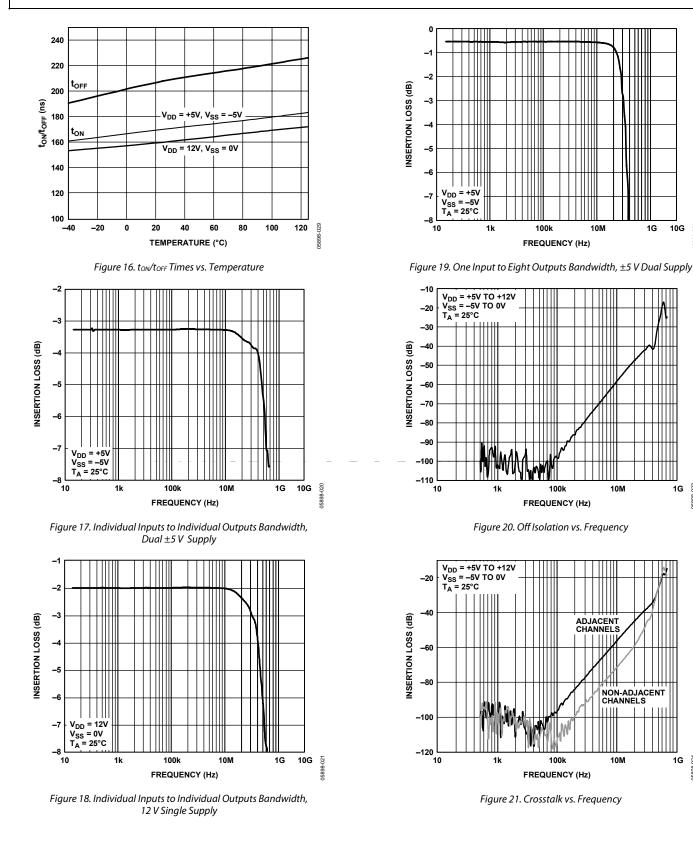


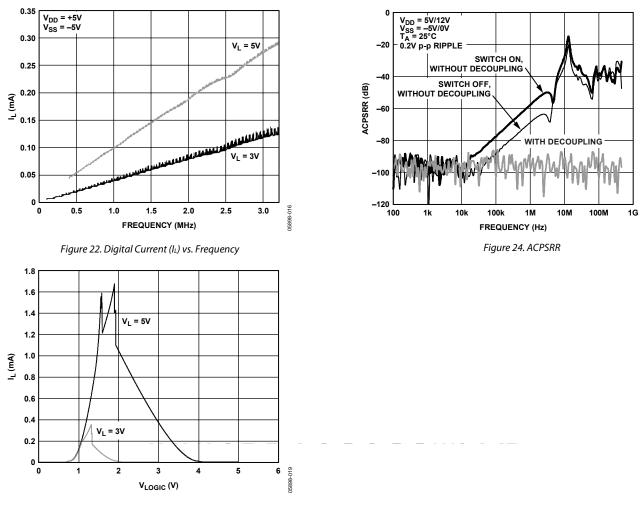
Figure 15. Charge Injection vs. Supply Voltage

022

05898-023

05898-024



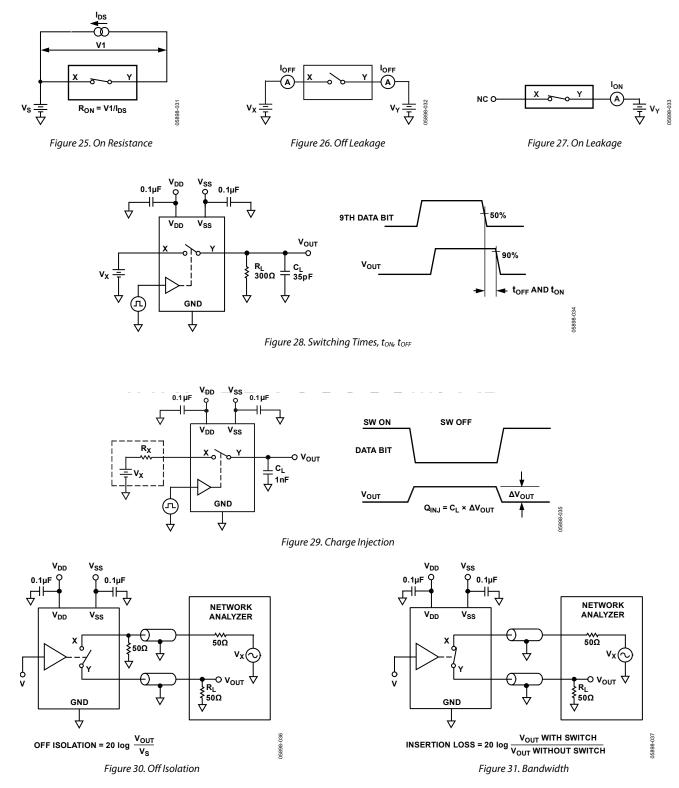


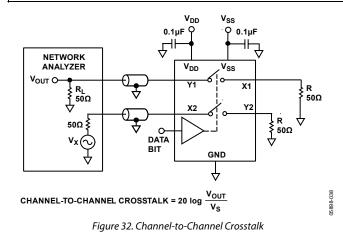
05898-028

Figure 23. Digital Current ( $I_L$ ) vs.  $V_{LOGIC}$  for Varying Digital Supply Voltage

### **TEST CIRCUITS**

The test circuits show measurements on one channel for clarity, but the circuit applies to any of the switches in the matrix.





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### TERMINOLOGY

On Resistance (Ron)

The series on-channel resistance measured between the X input/output and the Y input/output.

#### On Resistance Match ( $\Delta R_{ON}$ )

The channel-to-channel matching of on resistance when channels are operated under identical conditions.

#### On Resistance Flatness (R<sub>FLAT(ON)</sub>)

The variation of on resistance over the specified range produced by the specified analog input voltage change with a constant load current.

#### $Channel \ Off \ Leakage \ (I_{OFF})$

The sum of leakage currents into or out of an off channel input.

#### Channel On Leakage (IoN)

The current loss/gain through an on-channel resistance, creating a voltage offset across the device.

#### Input Leakage Current (IIN)

The current flowing into a digital input when a specified low level or high level voltage is applied to that input.

#### Input Off Capacitance (COFF)

The capacitance between an analog input and ground when the switch channel is off.

#### Input/Output On Capacitance (C<sub>ON</sub>)

The capacitance between the inputs or outputs and ground when the switch channel is on.

#### Digital Input Capacitance (C<sub>IN</sub>)

The capacitance between a digital input and ground.

#### Output On Switching Time (ton)

The time required for the switch channel to close. The time is measured from 50% of the logic input change to the time the output reaches 10% of the final value.

#### Output Off Switching Time (toff)

The time required for the switch to open. This time is measured from 50% of the logic input change to the time the output reaches 90% of the switch off condition.

#### Total Harmonic Distortion + Noise (THD + N)

The ratio of the harmonic amplitudes plus noise of a signal to the fundamental.

#### -3 dB Bandwidth

The frequency at which the output is attenuated by 3 dB.

#### **Off Isolation**

The measure of unwanted signal coupling through an off switch.

#### Crosstalk

The measure of unwanted signal that is coupled through from one channel to another as a result of parasitic capacitance.

#### **Differential Gain**

The measure of how much color saturation shift occurs when the luminance level changes. Both attenuation and amplification can occur; therefore, the largest amplitude change between any two levels is specified and is expressed as a percentage of the largest chrominance amplitude.

#### **Differential Phase**

The measure of how much hue shift occurs when the luminance level changes. It can be a negative or positive value and is expressed in degrees of subcarrier phase.

#### **Charge Injection**

The measure of the glitch impulse transferred from the digital input to the analog output during on/off switching.

**Input High Voltage (V**<sub>INH</sub>) The minimum input voltage for Logic 1.

**Input Low Voltage (V**<sub>INL</sub>) The maximum input voltage for Logic 0.

**Output Low Voltage (V**<sub>OL</sub>) The minimum input voltage for Logic 1.

**Input Low Voltage (V**<sub>INL</sub>) The maximum output voltage for Logic 0.

IDD Positive supply current.

Iss Negative supply current.

### THEORY OF OPERATION

The ADG2108 is an analog cross point switch with an array size of  $8 \times 10$ . The 10 rows are referred to as the X input/output lines, and the eight columns are referred to as the Y input/output lines. The device is fully flexible in that it connects any X line or number of X lines with any Y line when turned on. Similarly, it connects any X line with any number of Y lines when turned on.

Control of the ADG2108 is carried out via an I<sup>2</sup>C interface. The device can be operated from single supplies of up to 13.2 V or from dual  $\pm 5$  V supplies. The ADG2108 has many attractive features, such as the ability to reset all the switches, the ability to update many switches at the same time, and the option of reading back the status of any switch. All of these features are described in more detail here in the Theory of Operation section.

#### **RESET/POWER-ON RESET**

The ADG2108 offers the ability to reset all of the 80 switches to the off state. This is done through the RESET pin. When the RESET pin is low, all switches are open (off), and appropriate registers are cleared. Note that the ADG2108 also has a poweron reset block. This ensures that all switches are in the off condition at power-up of the device. In addition, all internal registers are filled with 0s and remain so until a valid write to the ADG2108 takes place.

#### LOAD SWITCH (LDSW)

LDSW is an active high command that allows a number of switches to be simultaneously updated. This is useful in applications where it is important to have synchronous transmission of signals. There are two LDSW modes: the transparent mode and the latched mode.

#### Transparent Mode

In this mode, the switch position changes after the new word is written into the input shift register. LDSW is set to 1.

#### Latched Mode

In this mode, the switch positions are not updated at the same time that the input registers are written to. This is achieved by setting LDSW to 0 for each word (apart from the last word) written to the device. Then, setting LDSW to 1 for the last word allows all of the switches in that sequence to be simultaneously updated.

#### READBACK

Readback of the switch array conditions is also offered when in standard mode and fast mode. Readback enables the user to check the status of the switches of the ADG2108. This is very useful when debugging a system.

### **SERIAL INTERFACE**

The ADG2108 is controlled via an I<sup>2</sup>C-compatible serial bus. The parts are connected to this bus as a slave device (no clock is generated by the switch).

#### HIGH SPEED I<sup>2</sup>C INTERFACE

In addition to standard and full speed I<sup>2</sup>C, the ADG2108 also supports the high speed (3.4 MHz) I<sup>2</sup>C interface. Only the -HS models provide this added performance. See the Ordering Guide for details.

#### SERIAL BUS ADDRESS

The ADG2108 has a 7-bit slave address. The four MSBs are hard coded to 1110, and the three LSBs are determined by the state of Pin A0, Pin A1, and Pin A2. By offering the facility to hardware configure Pin A0, Pin A1, and Pin A2, up to eight of these devices can be connected to a single serial bus.

The 2-wire serial bus protocol operates as follows:

1. The master initiates data transfer by establishing a start condition, defined as when a high-to-low transition on the SDA line occurs while SCL is high. This indicates that an address/data stream follows. All slave peripherals connected to the serial bus respond to the start condition and shift in the next eight bits, consisting of a 7-bit address (MSB first) plus an R/W bit that determines the direction of the data transfer, that is, whether data is written to or read from the slave device.

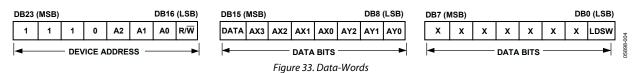
- 2. The peripheral whose address corresponds to the transmitted address responds by pulling the SDA line low during the ninth clock pulse, known as the acknowledge bit. At this stage, all other devices on the bus remain idle while the selected device waits for data to be written to or read from its serial register. If the  $R/\overline{W}$  bit is 1 (high), the master reads from the slave device. If the  $R/\overline{W}$  bit is 0 (low), the master writes to the slave device.
- 3. Data is transmitted over the serial bus in sequences of nine clock pulses: eight data bits followed by an acknowledge bit from the receiver of the data. Transitions on the SDA line must occur during the low period of the clock signal, SCL, and remain stable during the high period of SCL because a low-to-high transition when the clock is high can be interpreted as a stop signal.
- 4. When all data bits have been read or written, a stop condition is established by the master. A stop condition is defined as a low-to-high transition on the SDA line while SCL is high. In write mode, the master pulls the SDA line high during the 10th clock pulse to establish a stop condition. In read mode, the master issues a no acknowledge for the ninth clock pulse (that is, the SDA line remains high). The master then brings the SDA line low before the 10th clock pulse and then high during the 10th clock pulse to establish a stop condition.

Refer to Figure 33 and Figure 34 for a graphical explanation of the serial data transfer protocol.

### WRITING TO THE ADG2108

#### **INPUT SHIFT REGISTER**

The input shift register is 24 bits wide. A 3-byte write is necessary when writing to this register and is done under the control of the serial clock input, SCL. The contents of the three bytes of the input shift register are shown in Figure 33 and described in Table 6.



#### Table 6. Input Shift Register Bit Function Descriptions

Bit	Mnemonic	Descriptions
DB23 to DB17	1110xxx	The MSBs of the ADG2108 are set to 1110. The LSBs of the address byte are set by the state of the three address pins, Pin A0, Pin A1, and Pin A2.
DB16	R/W	Controls whether the ADG2108 slave device is read from or written to.
		If $R/W = 1$ , the ADG2108 is being read from.
		If $R/\overline{W} = 0$ , the ADG2108 is being written to.
DB15	Data	Controls whether the switch is to be opened (off) or closed (on). If Data = 0, the switch is opened/off.
		If Data = 1, the switch is closed/on.
DB14 to DB11	AX3 to AX0	Controls I/Os X0 to X9. See Table 7 for the decode truth table.
DB10 to DB8	AY2 to AY0	Controls I/Os Y0 to Y7. See Table 7 for the decode truth table.
DB7 to DB1	Х	Don't care.
DB0	LDSW	This bit is useful when a number of switches need to be updated simultaneously. If LDSW = 1, the switch position changes after the new word is read. If LDSW = 0, the input data is latched, but the switch position is not changed.

As shown in Table 6, Bit DB14 to Bit DB11 control the X input/output lines, while Bit DB10 to Bit DB8 control the Y input/output lines. Table 7 shows the truth table for these bits. Note that the full coding sequence is written out for Channel Y0, and Channel Y1 to Channel Y7 follow a similar pattern. Note also that the RESET pin must be high when writing to the device.

DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	
DATA	AX3	AX2	AX1	AX0	AY2	AY1	AY0	Switch Configuration
Х	0	0	0	0	0	0	0	Reserved
Х	0	0	0	1	0	0	0	Reserved
1	0	0	1	0	0	0	0	X0 to Y0 (on)
0	0	0	1	0	0	0	0	X0 to Y0 (off)
1	0	0	1	1	0	0	0	X1 to Y0 (on)
0	0	0	1	1	0	0	0	X1 to Y0 (off)
1	0	1	0	0	0	0	0	X2 to Y0 (on)
0	0	1	0	0	0	0	0	X2 to Y0 (off)
1	0	1	0	1	0	0	0	X3 to Y0 (on)
0	0	1	0	1	0	0	0	X3 to Y0 (off)
Х	0	1	1	0	0	0	0	Reserved
Х	0	1	1	1	0	0	0	Reserved
1	1	0	0	0	0	0	0	X4 to Y0 (on)
0	1	0	0	0	0	0	0	X4 to Y0 (off)
1	1	0	0	1	0	0	0	X5 to Y0 (on)
0	1	0	0	1	0	0	0	X5 to Y0 (off)
1	1	0	1	0	0	0	0	X6 to Y0 (on)
0	1	0	1	0	0	0	0	X6 to Y0 (off)
1	1	0	1	1	0	0	0	X7 to Y0 (on)
0	1	0	1	1	0	0	0	X7 to Y0 (off)

#### Table 7. Address Decode Truth Table

DB15 DATA	DB14 AX3	DB13 AX2	DB12 AX1	DB11 AX0	DB10 AY2	DB9 AY1	DB8 AY0	Switch Configuration
1	1	1	0	0	0	0	0	X8 to Y0 (on)
0	1	1	0	0	0	0	0	X8 to Y0 (off)
1	1	1	0	1	0	0	0	X9 to Y0 (on)
0	1	1	0	1	0	0	0	X9 to Y0 (off)
Х	1	1	1	0	0	0	0	Reserved
Х	1	1	1	1	0	0	0	Reserved
Х	0	0	0	0	0	0	1	Reserved
Х	0	0	0	1	0	0	1	Reserved
1	0	0	1	0	0	0	1	X0 to Y1 (on)
0	0	0	1	0	0	0	1	X0 to Y1 (off)
0	1	1	0	1	0	0	1	X9 to Y1 (off)
Х	0	0	0	0	0	1	0	Reserved
Х	0	0	0	1	1	1	0	Reserved
1	0	0	1	0	0	1	0	X0 to Y2 (on)
0	0	0	1	0	0	1	0	X0 to Y2 (off)
0	1	1	0	1	0	1	0	X9 to Y2 (off)
Х	0	0	0	0	0	1	1	Reserved
Х	0	0	0	1	0	1	1	Reserved
1	0	0	1	0	0	1	1	X0 to Y3 (on)
0	0	0	1	0	0	1	1	X0 to Y3 (off)
0	1	1	0	1	0	1	1	X9 to Y3 (off)
Х	0	0	0	0	1	0	0	Reserved
Х	0	0	0	1	1	0	0	Reserved
1	0	0	1	0	1	0	0	X0 to Y4 (on)
0	0	0	1	0	1	0	0	X0 to Y4 (off)
				••				
0	1	1	0	1	1	0	0	X9 to Y4 (off)
Х	0	0	0	0	1	0	1	Reserved
Х	0	0	0	1	1	0	1	Reserved
1	0	0	1	0	1	0	1	X0 to Y5 (on)
0	0	0	1	0	1	0	1	X0 to Y5 (off)
0	1	1	0	1	1	0	1	X9 to Y5 (off)
Х	0	0	0	0	1	1	0	Reserved
Х	0	0	0	1	1	1	0	Reserved
1	0	0	1	0	1	1	0	X0 to Y6 (on)
0	0	0	1	0	1	1	0	X0 to Y6 (off)
0	1	1	0	1	1	1	0	X9 to Y6 (off)
Х	0	0	0	0	1	1	1	Reserved
X	0	0	0	1	1	1	1	Reserved
1	0	0	1	0	1	1	1	X0 to Y7 (on)
0	0	0	1	0	1	1	1	X0 to Y7 (off)
								Vote V7 (eff)
0	1	1	0	1	1	1	1	X9 to Y7 (off)

#### WRITE OPERATION

When writing to the ADG2108, the user must begin with an address byte and  $R/\overline{W}$  bit, after which the switch acknowledges that it is prepared to receive data by pulling SDA low. This address byte is followed by the two 8-bit words. The write operations for the switch array are shown in Figure 34. Note that it is only the condition of the switch corresponding to the bits in the data bytes that changes state. All other switches retain their previous condition.

#### **READ OPERATION**

Readback on the ADG2108 is designed to work as a tool for debug and can be used to output the status of any of the 80 switches of the device. The readback function is a two-step sequence that works as follows:

- 1. Select the relevant X line to be read back from. Note that there are eight switches connecting that X line to the eight Y lines. The next step involves writing to the ADG2108 to tell the part to reveal the status of those eight switches.
  - a. Enter the I<sup>2</sup>C address of the ADG2108, and set the  $R/\overline{W}$  to 0 to indicate a write to the device.

- b. Enter the readback address for the X line of interest, the addresses of which are shown in Table 8. Note that the ADG2108 is expecting a 2-byte write; therefore, be sure to enter another byte of don't cares (see Figure 35).
- c. The ADG2108 then places the status of those eight switches in a register than can be read back.
- 2. The second step involves reading back from the register that holds the status of the eight switches associated with the X line of choice.
  - a. As before, enter the  $I^2C$  address of the ADG2108. This time, set the  $R/\overline{W}$  to 1 to indicate a readback from the device.
  - b. As with a write to the device, the ADG2108 outputs a 2-byte sequence during readback. Therefore, the first eight bits of data out that are read back are all 0s. The next eight bits of data that come back are the status of the eight Y lines attached to that particular X line. If the bit is a 1, the switch is closed (on); similarly, if the bit is a 0, the switch is open (off).

The entire read sequence is shown in Figure 35.

## 

	-γ A2 χ		X AX1 X AX0 X AY2 X AY1 X AY0		<u> </u>	
START COND BY MASTER	ADDRESS BYTE	ACK BY SWITCH	DATA BYTE	ACK BY SWITCH	DATA BYTE	ACK STOP BY COND 6 SWITCH BY 6 MASTER 66
		Fig	gure 34. Write Operation			•

X Line	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0
X0	0	1	1	1	0	1	0	0
X1	0	1	1	1	1	1	0	0
X2	0	0	1	1	0	1	0	1
Х3	0	0	1	1	1	1	0	1
X4	0	1	1	1	0	1	0	1
X5	0	1	1	1	1	1	0	1
X6	0	0	1	1	0	1	1	0
X7	0	0	1	1	1	1	1	0
X8	0	1	1	1	0	1	1	0
Х9	0	1	1	1	0	1	1	0

#### Table 8. Readback Addresses for Each X Line

#### ADG2108 SCL A2 A1 A0 R/W RB7 RB6 RB5 RB4 RB3 RB2 RB1 RB1 RB0 SDA ×X х START COND BY MASTER NO ACK STOP BY COND SWITCH BY MASTER ACK BY SWITCH ACK BY SWITCH ADDRESS BYTE DATA BYTE DATA BYTE uuuu പ ſ Г *٦ ٢* v Y Y7 Y Y6 Y Y5 Y Y4 Y Y3 Y Y2 Y Y1 ~ ٧n

SDA 🔽	' ' \ <u>/ A2 </u>			<u> </u>		YO	7	
START COND BY MASTER	ADDRESS BYTE	ACK BY SWITCH	DUMMY READBACK BYTE	ACK BY MASTER	READBACK BYTE	NO ACK BY MASTER	STOP COND BY MASTER	05898-006

Figure 35. Read Operation

### **EVALUATION BOARD**

The ADG2108 evaluation board allows designers to evaluate the high performance ADG2108 8  $\times$  10 switch array with a minimum of effort.

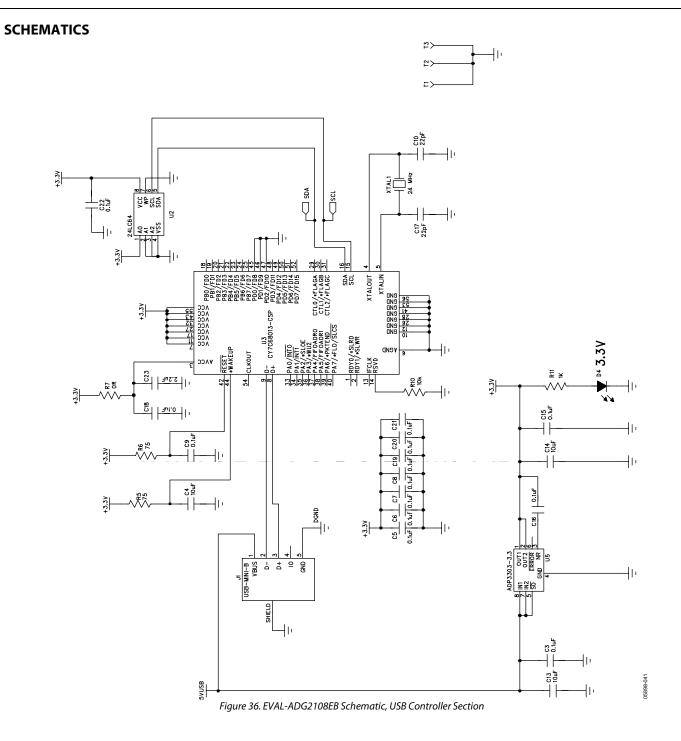
The evaluation kit includes a populated, tested ADG2108 printed circuit board. The evaluation board interfaces to the USB port of a PC, or it can be used as a standalone evaluation board. Software is available with the evaluation board that allows the user to easily program the ADG2108 through the USB port. Schematics of the evaluation board are shown in Figure 36 and Figure 37. The software runs on any PC that has Microsoft<sup>®</sup> Windows<sup>®</sup> 2000 or Windows XP installed.

#### **USING THE ADG2108 EVALUATION BOARD**

The ADG2108 evaluation kit is a test system designed to simplify the evaluation of the ADG2108. Each input/output of the part comes with a socket specifically chosen for easy audio/video evaluation. An application note is also available with the evaluation board that gives full information on operating the evaluation board.

#### **POWER SUPPLY**

The ADG2108 evaluation board can be operated with both single and dual supplies.  $V_{DD}$  and  $V_{SS}$  are supplied externally by the user. The  $V_L$  supply can be applied externally, or the USB port can be used to power the digital circuitry.



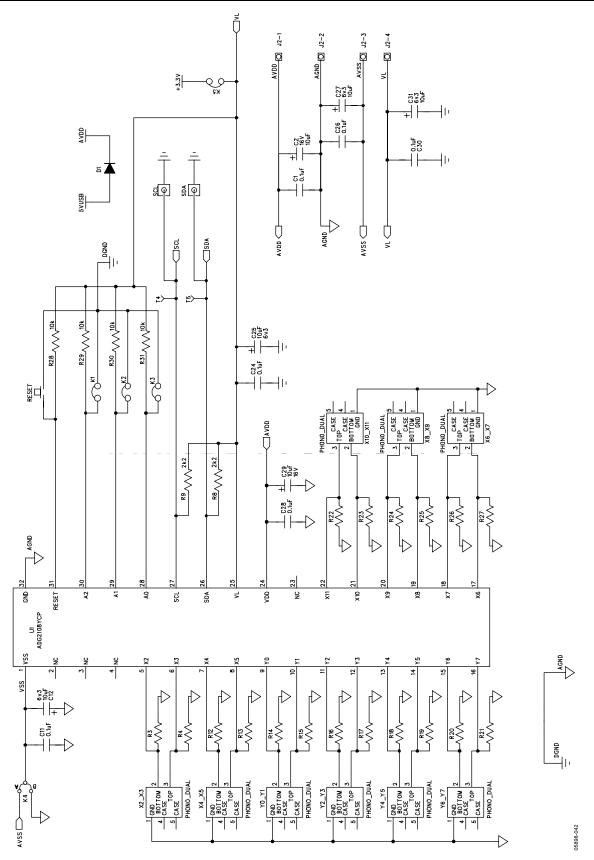
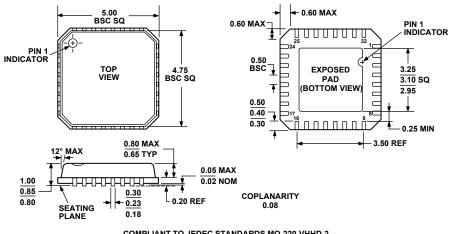


Figure 37. EVAL-ADG2108EB Schematic, Chip Section

### **OUTLINE DIMENSIONS**



COMPLIANT TO JEDEC STANDARDS MO-220-VHHD-2 Figure 38. 32-Lead Lead Frame Chip Scale Package [LFCSP\_VQ] 5 mm x 5 mm Body, Very Thin Quad (CP-32-2) Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model	Temperature Range	I²C Speed	Package Description	Package Option
ADG2108BCPZ-R21	-40°C to +85°C	100 kHz, 400 kHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADG2108BCPZ-REEL71	–40°C to +85°C	100 kHz, 400 kHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADG2108BCPZ-HS-RL71	–40°C to +85°C	100 kHz, 400 kHz, 3.4 MHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADG2108YCPZ-R21	–40°C to +125°C	100 kHz, 400 kHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADG2108YCPZ-REEL71	–40°C to +125°C	100 kHz, 400 kHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
ADG2108YCPZ-HS-RL71	–40°C to +125°C	100 kHz, 400 kHz, 3.4 MHz	32-Lead Lead Frame Chip Scale Package [LFCSP_VQ]	CP-32-2
EVAL-ADG2108EB			10 x 8 Evaluation Board	

 $^{1}$  Z = Pb-free part.

### NOTES

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