

Drive^{IT} Low Voltage General Purpose Motors

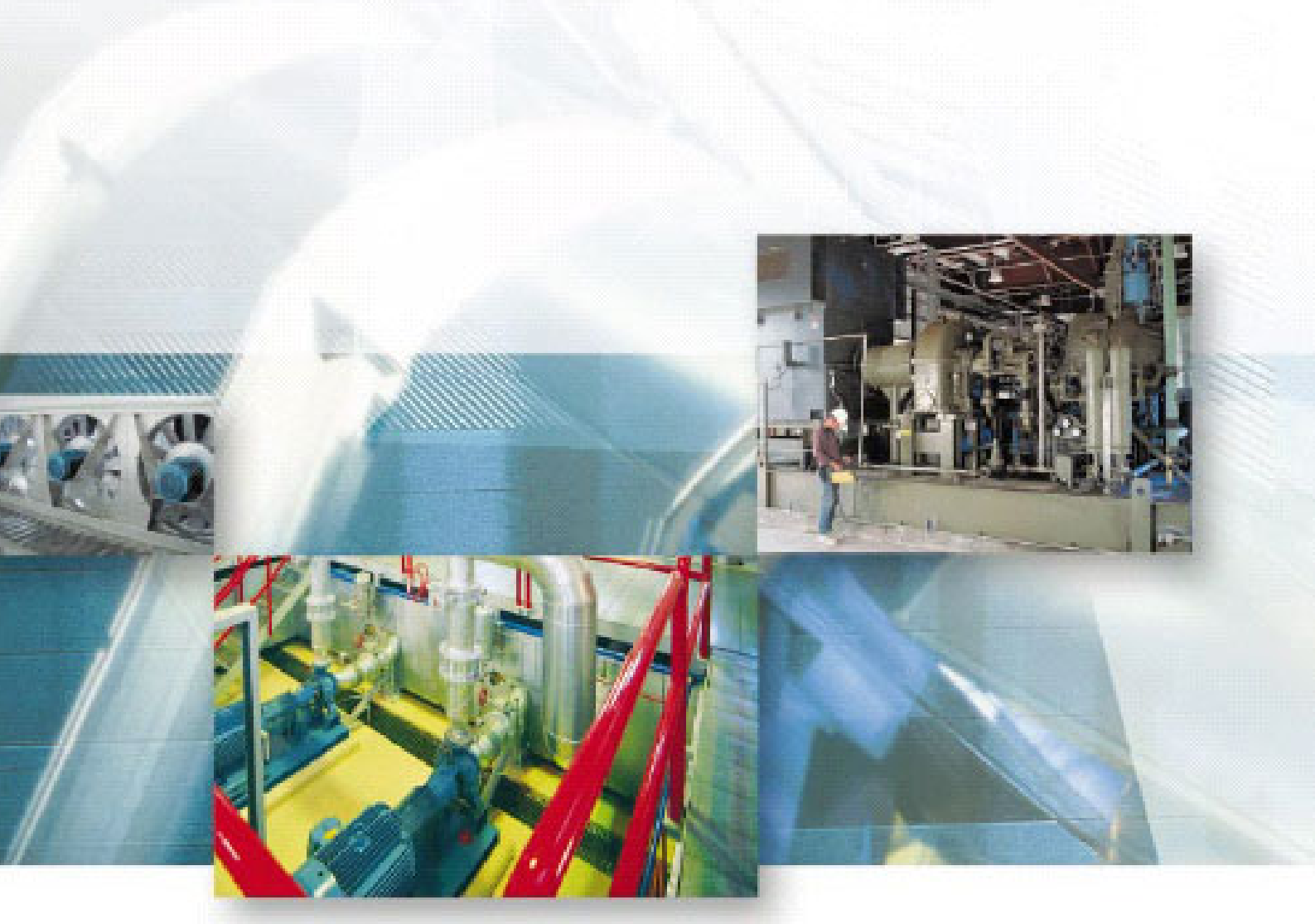


Industry^{IT}
enabled

ABB

Making you more competitive

ABB's General purpose motors are readily available from central stock locations and distributors throughout the world. While designed for standard and straightforward uses, the motors can be modified to meet most specifications. Built to the highest manufacturing standards, the General purpose motors use the best materials sourced from around the world. This brings a quality and reliability that can see motors operating for over 30 years. Competitively priced, the motors meet Eff2 energy efficient classification, with Eff1 as option.



Industrial^{IT}

As a key element of its business strategy, ABB has committed to a broad program of product development and positioning under the Industrial^{IT} umbrella. This initiative is geared towards increasing standardization of ABB products as the 'building blocks' of larger solutions, while incorporating functionality that will allow multiple products to interact seamlessly as components of real-time automation and information systems.

Motors and generators represent one of the fundamental building blocks in the Industrial^{IT} architecture.

ABB (www.abb.com) is a leader in power and automation technologies that enable utility and industry customers to improve performance while lowering environmental impacts. The ABB Group of companies operates in around 100 countries and employs around 133,000 people.

Drive^{IT} Low Voltage General Purpose Motors

Sizes 56 to 400, from 0.055 to 710 kW

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ABB reserves the right to change the design, technical specification and dimensions without prior notice.

General information

Standards

ABB motors are of the totally enclosed, three phase squirrel cage type, built to comply with international IEC and EN standards. Motors conforming to other national and international specifications are also available on request.

All production units are certified to ISO 9001 international quality standard as well ISO 14000 environmental standard and confirm to all applicable EU Directives.

IEC / EN

Electrical	Mechanical
IEC/EN 60034-1	IEC 60072
IEC/EN 60034-2	IEC/EN 60034-5
IEC 60034-8	IEC/EN 60034-6
IEC 60034-12	IEC/EN 60034-7
	IEC/EN 60034-9
	IEC 60034-14



Motors for EU motor efficiency levels

A Europe-wide agreement will ensure that the efficiency levels of electric motors manufactured in Europe are clearly displayed. In contrast to the American legislation on motor efficiency the European agreement does not establish mandatory efficiency levels.

It basically establishes three classes giving motor manufacturers an incentive to qualify for a higher class.

ABB is one of only a handful of leading motor manufacturers in Europe to have a motor range to meet or exceed the minimum efficiencies stated in the highest level of the EU agreement of LV motors.

These efficiency levels apply to 2- and 4-pole, three phase squirrel cage induction motors rated for 400V, 50 Hz with S1 duty class with the

output 1.1 to 90 kW, which account for the largest volume on the market.

The efficiency of motors from different manufacturers are collated in a database, EURODEEM, published by the European Commission. It is accessible over the Internet at <http://iamest.jrc.it/projects/eem/eurodeem.htm>.

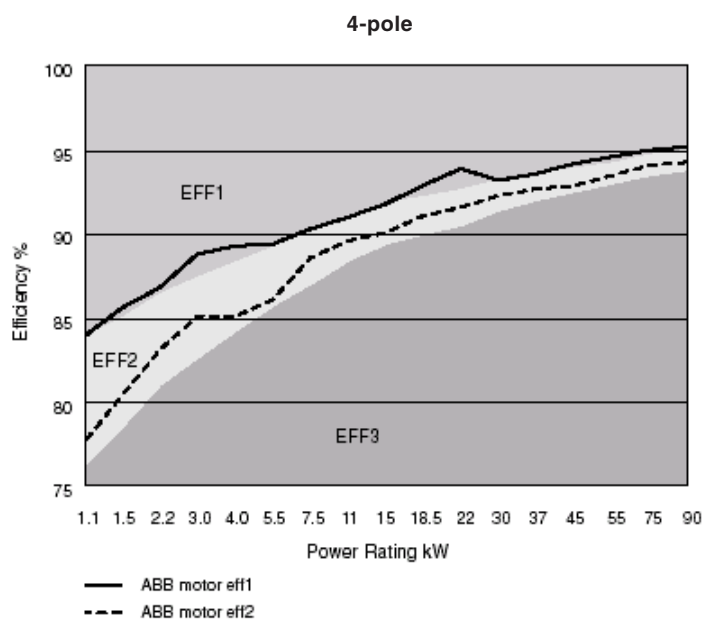
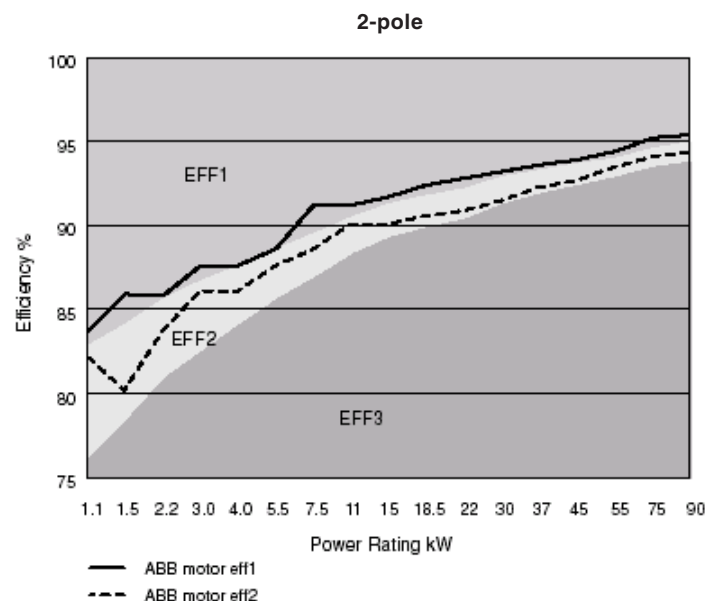
EU efficiency classes for 2-pole motors

Output kW	2-pole Boarderline	
	EFF2/EFF3	EFF1/EFF2
1.1	76.2	82.8
1.5	78.5	84.1
2.2	81.0	85.6
3	82.6	86.7
4	84.2	87.6
5.5	85.7	88.6
7.5	87.0	89.5
11	88.4	90.5
15	89.4	91.3
18.5	90.0	91.8
22	90.5	92.2
30	91.4	92.9
37	92.0	93.3
45	92.5	93.7
55	93.0	94.0
75	93.6	94.6
90	93.9	95.0

EU efficiency classes for 4-pole motors

Output kW	4-pole Boarderline	
	EFF2/EFF3	EFF1/EFF2
1.1	76.2	83.8
1.5	78.5	85.0
2.2	81.0	86.4
3	82.6	87.4
4	84.2	88.3
5.5	85.7	89.2
7.5	87.0	90.1
11	88.4	91.0
15	89.4	91.8
18.5	90.0	92.2
22	90.5	92.6
30	91.4	93.2
37	92.0	93.6
45	92.5	93.9
55	93.0	94.2
75	93.6	94.7
90	93.9	95.0

ABB Three phase induction motors, 400 V 50 Hz - EU motor efficiency levels

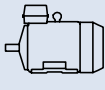
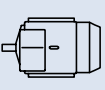
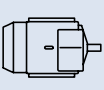
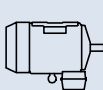
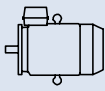
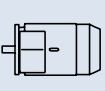
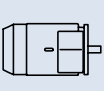
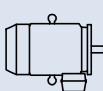
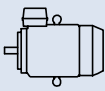
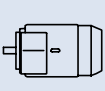
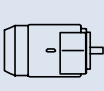
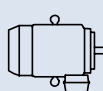
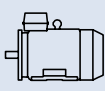
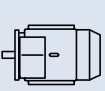
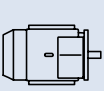
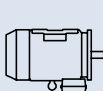
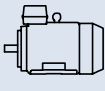
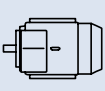
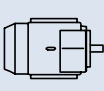
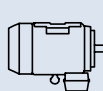
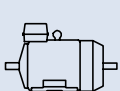
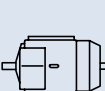
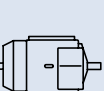
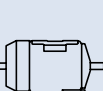


General technical specification

Mechanical and electrical design

Mounting arrangements

1

	Code/CodeII						Product code pos. 12
Foot-mounted motor.	IM B3 IM 1001	IM V5 IM 1011	IM V6 IM 1031	IM B6 IM 1051	IM B7 IM 1061	IM B8 IM 1071	A = foot-mounted, term.box top R = foot-mounted, term.box RHS L = foot-mounted, term.box LHS
							
Flange-mounted motor, large flange	IM B5 IM 3001	IM V1 IM 3011	IM V3 IM 3031	*) IM 3051	*) IM 3061	*) IM 3071	B = flange mounted, large flange
							
Flange-mounted motor, small flange	IM B14 IM 3601	IM V18 IM 3611	IM V19 IM 3631	*) IM 3651	*) IM 3661	*) IM 3671	C = flange mounted, small flange
							
Foot-and flange-mounted motor with feet, large flange	IM B35 IM 2001	IM V15 IM 2011	IM V36 IM 2031	*) IM 2051	*) IM 2061	*) IM 2071	H = foot/flange-mounted, term.box top S = foot/flange-mounted, term.box RHS T = foot/flange-mounted, term.box LHS
							
Foot-and flange-mounted motor with feet, small flange	IM B34 IM 2101	IM V17 IM 2111	IM 2131	IM 2151	IM 2161	IM 2171	J = foot/flange-mounted, small flange
							
Foot-mounted motor, shaft with free extensions	IM 1002	IM 1012	IM 1032	IM 1052	IM 1062	IM 1072	
							
*) Not stated in IEC 60034-7.							

Insulation

ABB uses class F insulation systems, which, with temperature rise B, is the most common requirement among industry today.

The use of Class F insulation with Class B temperature rise gives ABB products a 25° C safety margin. This can be used to increase the loading by up to 12 per cent for limited periods, to operate at higher ambient temperatures or altitudes, or with greater voltage and frequency tolerances. It can also be used to extend insulation life. For instance, a 10 K temperature reduction will extend the insulation life.

Class F insulation system

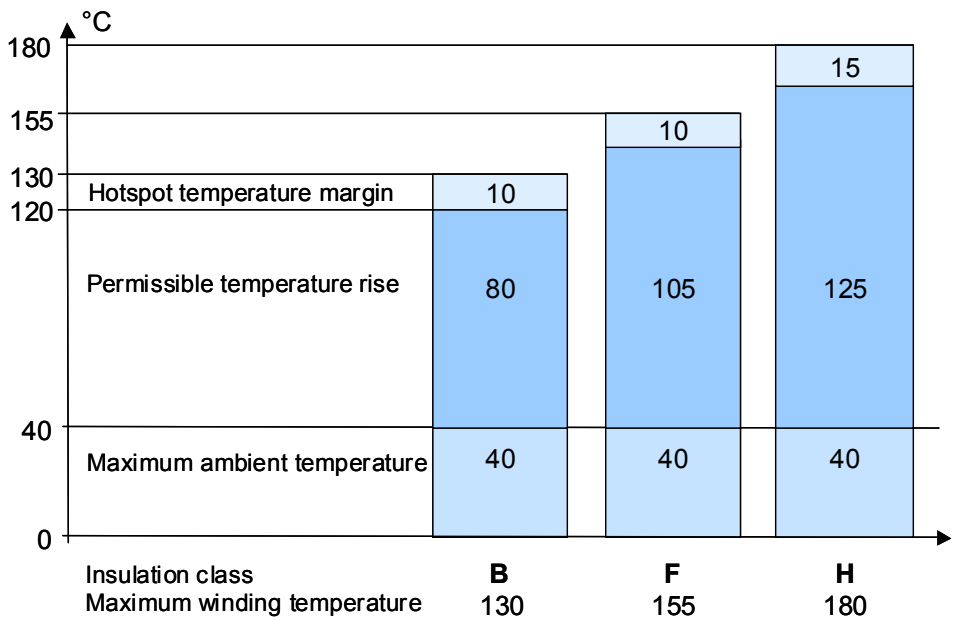
- Max ambient temperature 40° C
- Max permissible temperature rise 105 K
- Hotspot temperature margin + 10 K

Class B rise

- Max ambient temperature 40° C
- Max permissible temperature rise 80 K
- Hotspot temperature margin + 10 K

Insulation system temperature class

- Class F 155° C
- Class B 130° C
- Class H 180° C



Safety margins per insulation class

Frequency converter drives

Squirrel cage induction motors offer excellent availability, reliability and efficiency. With a frequency converter – a variable speed drive (VSD) – the motor will deliver even better value. A variable speed drive motor can be started softly with low starting current, and the speed can be controlled and adjusted to suit the application demand without steps over a wide range. Also the use of a frequency converter together with a squirrel cage motor usually leads to remarkable energy and environmental savings.

However, all motors are not suitable for variable speed drive. There are several points that have to be taken into account in the design and selection of the motor, if it is intended for variable speed operation.

Within the General purpose motor range ABB offers motors designed for both Direct On Line (DOL) and variable speed applications.

For demanding applications the use of ABB Process performance motors is recommended.

The following points must be taken into account, when selecting a motor to a variable speed drive:

1. Dimensioning

The voltage (or current) fed by the frequency converter is not purely sinusoidal. This may increase the losses, vibration, and noise of the motor. Furthermore, a change in the distribution of the losses may affect the motor temperature balance and lead to an increase in the temperature of the bearings. In each case, the motor must be correctly sized according to the instructions supplied with the selected frequency converter.

When using ABB converters, please use ABB's DriveSize dimensioning programme or the loadability curves of the corresponding converter type for sizing the motors. The loadability curve for applicable General purpose motors used with ABB's ACS 600- and ACS 800- frequency converters can be found in figure 3.

2. Speed range

In a frequency converter drive, the actual operating speed of the motor may deviate considerably from its nominal speed (i.e. the speed stamped on the rating plate).

For higher speeds, ensure that the highest permissible rotational speed of the motor or the critical speed of the entire equipment is not exceeded. When high speed operation exceeds the nominal speed of the motor, the following points should be checked:

- Maximum torque of the motor
- Bearing construction
- Lubrication
- Balancing
- Critical speeds
- Shaft seals

- Ventilation
- Fan noise

Guideline values of maximum speeds for M3AA motors within the General purpose motor range are described in figure 1 below. Exact values are available on request.

Figure 1. Guideline values of maximum speeds for General purpose motor in aluminium frame:

Motor size	Speed r/min	
	2-pole	4-pole
M3AA 90-100	6000	6000
M3AA 112-200	4500	4500
M3AA 225-280	3600	3600

At low speed operation the motor's ventilation fan loses its cooling capacity, which causes a higher temperature rise in the motor and in the bearings. A separate constant speed fan can be used to increase cooling capacity and loadability at low speed. It is also important to check the performance of the grease at low speeds.

3. Lubrication

Variable speed operation affects on the bearing temperature, which must be taken into account when selecting the lubrication method and grease type. For example the life time of sealed bearings can be remarkably shorter than in direct on line operation. More information can be found from product specific sections of this catalogue and from ABB's Low Voltage Motors Manual.

4. Insulation protection

Frequency converter supply causes higher voltage stresses at the windings of the motor than the sinusoidal supply. Thus, the insulation system and possible filters must be selected according to the used voltage, cable length and converter type.

When using ABB's low voltage frequency converters, selection criterias mentioned in figure 2 must be followed.

5. Bearing currents

Bearing voltages and currents must be avoided in all motors. Assuming the use of a standard ABB Single drive, with IGBT components and a 6-pulse diode supply unit, insulated bearings and/or properly dimensioned filters at the converter output must be used according to the instructions in figure 2. (For other alternatives and converter types, please contact ABB.) When ordering, clearly state which alternative will be used.

For more information about bearing currents and voltages, please contact ABB.

6. Cabling, grounding and EMC

The use of a frequency converter puts higher demands on the cabling and grounding of the drive system. The motor must be cabled by using shielded symmetrical cables and cable glands providing 360° bonding (also called EMC-glands). For motors up to 30 kW unsymmetrical cables can be used, but shielded cables are always recommended.

More information about grounding and cabling of a variable speed drive can be found from the manual

“Grounding and cabling of the drive system” (Code: 3AFY 61201998 R0125 REV A) and the ABB’s Low Voltage Motors Manual.

For fulfilling the EMC requirements, special EMC cable(s) must be used in addition to the correct cable gland mounting, with special, extra earthing pieces. Please refer to the manuals of the frequency converter.

Validity

Measures mentioned in Figure 2 apply to the applicable motors within the General motors range (not high-output versions) with a ABB's single drives, based on IGBT components and using 6-pulse diode supply unit. For other alternatives and converter types, please contact ABB.

Figure 2. Selection rules for insulation and filtering in variable speed drives

	Motor nominal power P_N or frame size		
	$P_N < 100\text{ kW}$	$P_N \geq 100\text{ kW or } \geq \text{IEC 315}$	$P_N \geq 350\text{ kW } \geq \text{IEC 400}$
$U_N \leq 500\text{ V}$	Standard motor	Standard motor + Insulated N-bearing	Standard motor + Insulated N-bearing + Common mode filter
$U_N \leq 600\text{ V}$	Standard motor + dU/dt-filter OR Reinforced insulation	Standard motor + dU/dt-filter (reactor) + Insulated N-bearing OR Reinforced insulation + Insulated N-bearing	Standard motor + Insulated N-bearing + dU/dt-filter + Light Common mode filter OR Reinforced insulation + Insulated N-bearing + Common mode filter
$U_N \leq 690\text{ V}$	Reinforced insulation + dU/dt-filter	Reinforced insulation + dU/dt-filter (reactor) + Insulated N-bearing	Reinforced insulation + Insulated N-bearing + dU/dt-filter + Light common mode filter

dU/dt filter (reactor)

Series reactor. DU/dt -filter decreases the changing rate of the phase and main voltages and thus reduces voltage stresses in the windings. DU/dt -filters also decrease so-called common mode currents and the risk of bearing currents. DU/dt -filters are designed so that dU/dt -rate of main voltages at motor terminals is less than 1 kV/s. See ABB manual, ACS 600 dU/dt -filter selection guide.

Common mode and light common mode filters

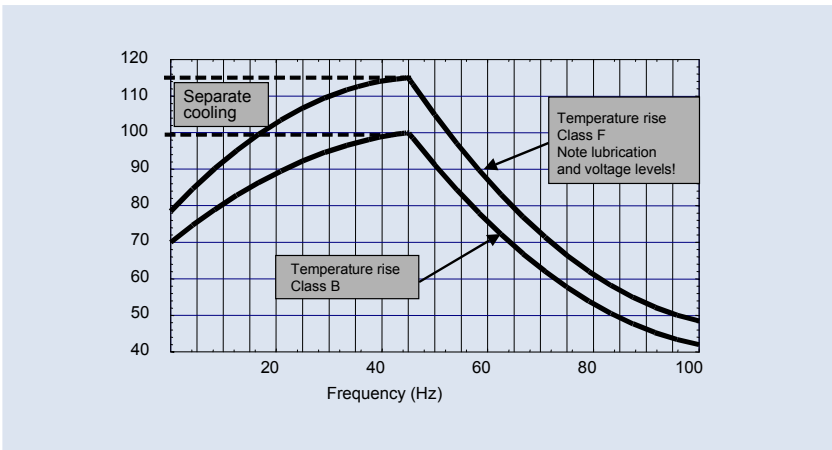
Common mode filters are made of toroidal cores installed around motor cables. These filters reduce so-called common mode

currents in VSD applications and thus decrease the risk of bearing currents. Common mode filters do not significantly affect the phase or main voltages on the motor terminals.

Insulated Bearings

Bearings with insulated inner or outer races are used as the standard solution. So-called hybrid bearings, i.e. bearings with non-conductive ceramic balls, can also be used in special applications. More information for spare part selection is available on request.

Figure 3. Motor loadability with ACS 600 and ACS 800, Field weakening point 50 Hz.





Drive^{IT} Integral Motors

Totally enclosed squirrel cage three phase low voltage motors,
Sizes 71 - 100, 0.37 to 2.2 kW



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Features

Drive^{IT} Integral Motor - the choice for a demanding environment

Demanding environments place a requirement for high protection class motors with good vibration endurance. This is why the integral motor is IP 55 protected. In addition to the wide selection of digital and analogue user interfaces, the integral motor offers higher integration into the modern control system with its fieldbuses, to meet the demands for distributed control.

Products according to your needs

Integral motor models are available as 2, 4 or 6 pole versions. The integral motor is delivered as an integrated, ready-to-use unit equipped with a brake, separate ventilation, or any other selected variants. The pre-set parameters offer configuration required by most of the simple applications and make commissioning and use as easy as possible. For more demanding applications, an optional control panel or PC software tool can be used to select from a range of more advanced application macros.

Fulfil EMC limits at every level

Electro Magnetic Compatibility is an important issue in AC automation. The integral motor complies with European distribution limits with the help of built-in EMC filters, so that no external filtering is needed. Standard models of the integral motor fulfil EMC requirements in industrial environments and models with RFI filter in the domestic environments.

Excellent features for OEM's

The integral motor provides a low cost way to enhance an application's performance: it is not limited to "soft starting" applications in which integrated motor-drive combinations have traditionally been used.

Features include up to 180 % overload capacity during start-up, PTC interface, built-in mechanical brake control and electrical braking produce an unbeatable combination for material handling applications. The robust design withstands supply voltage fluctuations and the wide selection of fieldbus options makes integration into automation systems easy.

One of the most interesting features is the Positioning Macro, which together with an optional encoder makes it possible to eliminate expensive PLCs in simple positioning applications. This feature is useful for example in controlling conveyor lines or opening doors.

Intelligent control for pumps and fans

The built-in PID controller's two parameter sets make the integral motor ideally suited for pump and fan applications. The integral motor can be configured to indicate directly parameters such as the flow rate of a pumped fluid, for instance. With the integral motor it is possible to make a connection to building automation via a LonWorks fieldbus adapter.

Typically no overload capacity is needed in pump or fan applications. This allows the integral motor to be optimised for squared torque use.

The integral motor offers

- Mounting to demanding environment
- Ready-to-use configuration with pre-set parameters
- Full configurable functionality when using an IP65 control panel
- Easy adaptation to automation systems with wide range of fieldbuses
- Built-in EMC filter and brake chopper
- Simple positioning tasks with Positioning application macro
- Optimised selection integral motor models and integrated variants



Connections

To achieve maximum compatibility the integral motor provides all necessary connections and options. Options are IP 65 protected which means that they can withstand extremely hostile environments like places with high moisture. Options are placed straight on the side of the drive and no extra installing space is required.

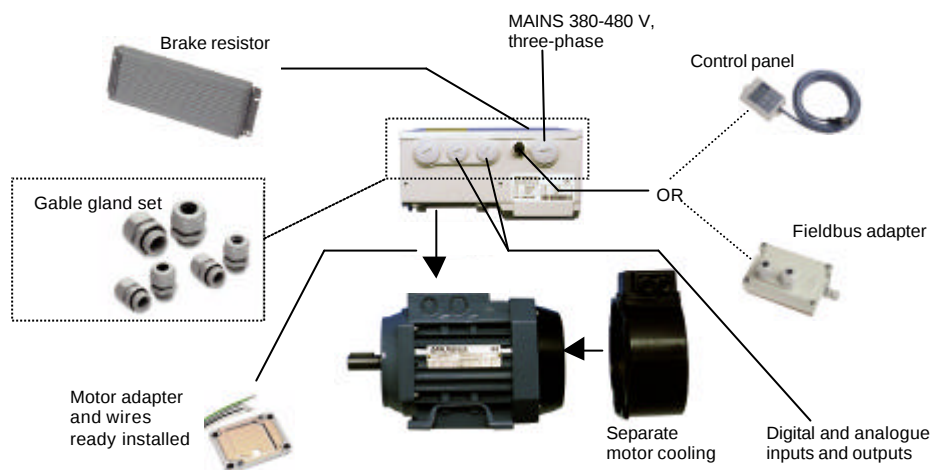
The various options are shown below. After the integral motor has been specified, it will be delivered as a ready assembled and parametrized unit.

With analogue inputs you can set the output frequency or control positioning speed or direction. As there are two analogue inputs, intelligent PID control is possible.

Analogue output can indicate chosen operating data values like output current or DC bus voltage.

With digital inputs the integral motor can be e.g. started, stopped or the rotation direction changed. Digital inputs are also used in positioning function.

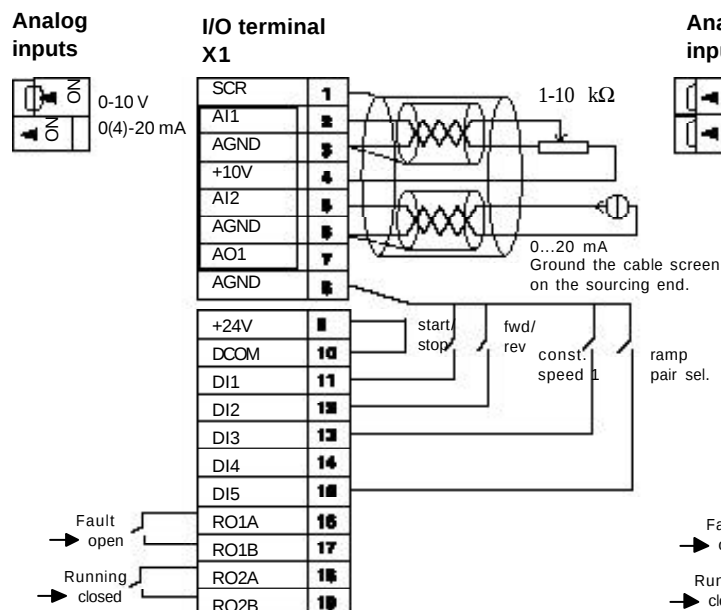
Two relay outputs pass fault and alarm signals or indicate when selected parameter values are exceeded.



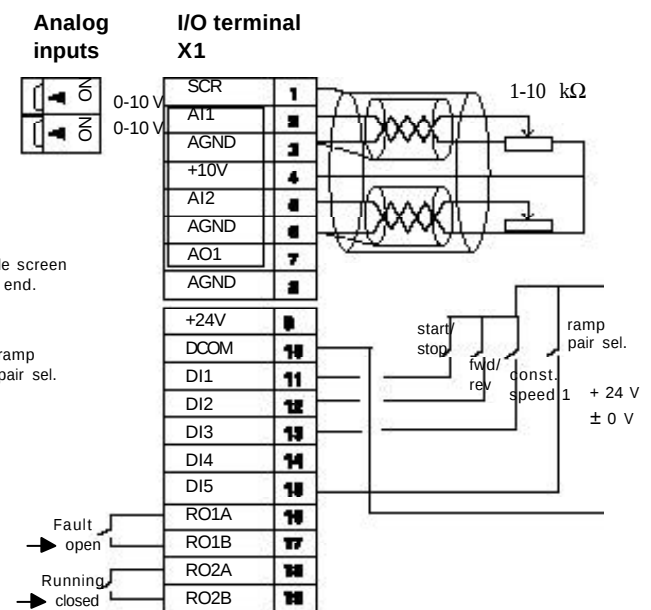
I/O Connection Examples

These connections are shown as examples only. More detailed information can be found from the frequency converter part's User's Manual.

Drive NPN connected



Drive PNP connected with external power supply



Ordering information

Sample order

1. Standard design

When ordering an integral motor, please state the following minimum data in the order, as in the example.

2. Special designs

In addition to the minimum data all special features desired shall be stated expressly in the text of the order.

3. Note

- If the order is based on a quotation please state the number
- If the same motors were supplied before (replacement motors) please state their serial number (see motor rating plate).

Motor type	M3VK 80C
Pole number	4
Mounting arrangement (IM-code)	IM B3 (IM 1001)
Rated output	0.75 kW
Product code	3GVK082662-ASC
Variant codes if needed	
Type of drive	Standard drive

A	B	C	D	E	F	G	
M3VK	80C	3GVK 082 662 - A S C, 450 etc.					
		1-4	5-6	7	8-10	11	12
						13	14

A Motor type
B Motor size
C Product code
D Mounting arrangement code
E Voltage and frequency code
F Generation code
G Variant codes

Explanation of the product code:

Positions 1 to 4

3GVK = Business area LV Motors
Totally enclosed fan cooled squirrel cage
integral motor with aluminium frame

Positions 5 and 6

IEC-frame

- 07 = 71
- 08 = 80
- 09 = 90
- 10 = 100

Position 7

Speed (Pole pairs)

- 1 = 2 poles
- 2 = 4 poles
- 3 = 6 poles

Position 8

- 6 = Standard Drive
- 7 = Drive with RFI filter

Position 9-10 - Running number series

Position 11

- (Dash)

Position 12

Mounting arrangement

- A** = Foot-mounted motor.
- B** = Flange-mounted motor. Large flange with clearance holes.
- C** = Foot-mounted motor. Small flange with tapped holes.
- F** = Foot- and flange-mounted motor. Special flange.
- H** = Foot- and flange-mounted motor. Large flange with clearance holes.
- J** = Foot- and flange-mounted motor. Small flange with tapped holes.
- V** = Flange-mounted motor. Special flange.

Position 13

Voltage and frequency code

Single-speed

- D** = 380-420 VD 50 Hz
440-480 VD 60 Hz
- S** = 220-240 VD 50 Hz
380-420 VY 50 Hz
440-480 VY 60 Hz
- X** = Other voltage/frequency

Position 14

Generation code = A, B, C...

The product code must be, if needed, followed by variant codes.

General purpose integral motors

For constant torque applications



TEFC squirrel cage three-phase integral motors M3VK

IP55, IC 411; Insulation class F, temperature rise class B

Output kW	Type designation	Product code	Input current I_{1N} A	Cont. output current $I_{2N}^{1),2)}$ A	Max. current 150 % $I_{max}^{3)}$ A	Max.starting current 180 % ⁴⁾ A	Over current limit (peak) A	Line fuse ⁵⁾ A	Power losses Power circuit W	Control circuit W	Total weight kg
3000 r/min = 2 poles			380-480 V 50 Hz			Standard Drive					
0.37	M3VK 71A	3GVK 071 661-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	10
0.55	M3VK 71B	3GVK 071 662-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	11
0.75	M3VK 80A	3GVK 081 661-••C	2.2	2.4	3.6	4.3	9.5	4	23	17	14
1.1	M3VK 80B	3GVK 081 662-••C	3.2	3.4	5.1	6.1	13	6	33	18	16
1.5	M3VK 80C	3GVK 081 663-••C	4.1	4.1	6.2	7.4	16	10	45	19	16
1.5	M3VK 90S	3GVK 091 661-••C	4.1	4.1	6.2	7.4	16	10	45	19	18
2.2	M3VK 90L	3GVK 091 662-••C	6.0	5.4	8.1	9.7	21	10	66	20	21
1500 r/min = 4 poles			380-480 V 50 Hz			Standard Drive					
0.37	M3VK 71B	3GVK 072 662-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	11
0.55	M3VK 80A	3GVK 082 661-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	14
0.75	M3VK 80B	3GVK 082 662-••C	2.2	2.4	3.6	4.3	9.5	4	23	17	15
0.95	M3VK 80C	3GVK 082 663-••C	3.2	3.4	5.1	6.1	13	6	33	18	16
1.1	M3VK 90S	3GVK 092 661-••C	3.2	3.4	5.1	6.1	13	6	33	18	18
1.5	M3VK 90L	3GVK 092 662-••C	4.1	4.1	6.2	7.4	16	10	45	19	21
2.2	M3VK 100LA	3GVK 102 661-••C	6.0	5.4	8.1	9.7	21	10	66	20	26
1000 r/min = 6 poles			380-480 V 50 Hz			Standard Drive					
0.37	M3VK 71A	3GVK 083 661-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	14
0.55	M3VK 80B	3GVK 083 662-••C	1.6	1.8	2.7	3.2	7.1	4	17	16	15
0.75	M3VK 90S	3GVK 093 661-••C	2.2	2.4	3.6	4.3	9.5	4	23	17	18
1.1	M3VK 90L	3GVK 093 662-••C	3.2	3.4	5.1	6.1	13	6	33	18	21
1.5	M3VK 100L	3GVK 103 661-••C	4.1	4.1	6.2	7.4	16	10	45	19	28
3000 r/min = 2 poles			380-480 V 50 Hz			Drive with RFI filter					
0.37	M3VK 71A	3GVK 071 761-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	12
0.55	M3VK 71B	3GVK 071 762-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	13
0.75	M3VK 80A	3GVK 081 761-••C	2.2	2.4	3.6	4.3	9.5	4	23	19	15
1.1	M3VK 80B	3GVK 081 762-••C	3.2	3.4	5.1	6.1	13	6	33	20	17
1.5	M3VK 80C	3GVK 081 763-••C	4.1	4.1	6.2	7.4	16	10	45	21	18
1.5	M3VK 90S	3GVK 091 761-••C	4.1	4.1	6.2	7.4	16	10	45	21	19
2.2	M3VK 90L	3GVK 091 762-••C	6.0	5.4	8.1	9.7	21	10	66	22	23
1500 r/min = 4 poles			380-480 V 50 Hz			Drive with RFI filter					
0.37	M3VK 71A	3GVK 072 762-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	13
0.55	M3VK 80A	3GVK 082 761-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	15
0.75	M3VK 80B	3GVK 082 762-••C	2.2	2.4	3.6	4.3	9.5	4	23	19	16
0.95	M3VK 80C	3GVK 082 763-••C	3.2	3.4	5.1	6.1	13	6	33	20	17
1.1	M3VK 90S	3GVK 092 761-••C	3.2	3.4	5.1	6.1	13	6	33	20	19
1.5	M3VK 90L	3GVK 092 762-••C	4.1	4.1	6.2	7.4	16	10	45	21	22
2.2	M3VK 100LA	3GVK 102 761-••C	6.0	5.4	8.1	9.7	21	10	66	22	28
1000 r/min = 6 poles			380-480 V 50 Hz			Drive with RFI filter					
0.37	M3VK 71A	3GVK 083 761-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	15
0.55	M3VK 80B	3GVK 083 762-••C	1.6	1.8	2.7	3.2	7.1	4	17	18	16
0.75	M3VK 90S	3GVK 093 761-••C	2.2	2.4	3.6	4.3	9.5	4	23	19	19
1.1	M3VK 90L	3GVK 093 762-••C	3.2	3.4	5.1	6.1	13	6	33	20	22
1.5	M3VK 100L	3GVK 103 761-••C	4.1	4.1	6.2	7.4	16	10	45	21	29

The two bullets in the product code indicate choice of mounting arrangement, voltage and nominal frequency.

1) Power stages are designed for the continuous I_{2N} current.

These values apply at altitudes less than 1000 m ASL.

2) With 8 kHz switching frequency derate I_{2N} to 70% in -10°C...40°C or to 60% in 40°C...50°C.

3) 150 % of nominal current I_{2N} allowed for one minute every 10 minutes.

4) 180 % of nominal current I_{2N} allowed for two seconds.

5) Fuse type: UL class CC or T. For non-UL installations IEC269gG.

Use 60°C rated power cable (75°C if T_{amb} above 45°C).

Follow local rules for cable cross-sections.

Shielded motor cable is recommended.

Max. wire sizes/Power terminals (mm²):

single core: 4 (AWG 12), stranded: 2.5 (AWG 14)/torque 0.8 Nm

Max. wire sizes/Control terminals (mm²):

0.5-1.5 (AWG 22...AWG 16)/torque 0.4 Nm.

General purpose integral motors

For constant torque applications



TEFC squirrel cage three-phase integral motors M3VK

IP55, IC 411; Insulation class F, temperature rise class B

			Input current I_{1N}	Cont. output current $I_{2N}^{1)}$	Max. current 150 % $I_{max}^{2)}$	Max.starting current 180 % ³⁾	Over current limit (peak)	Line fuse ⁴⁾	Power losses Power circuit	Control circuit	Total weight
Output Type kW	designation	Product code	A	A	A	A	A	A	W	W	kg
3000 r/min = 2 poles			380-480 V 50 Hz			Standard Drive					
1.1	M3VK 80C	3GVK 081 673-••C	3.2	3.4	5.1	6.1	13	6	33	18	16
1.5	M3VK 90L	3GVK 091 672-••C	4.1	4.1	6.2	7.4	16	10	45	19	21
2.2	M3VK 90LB	3GVK 091 673-••C	6.0	5.4	8.1	9.7	21	10	66	20	23
1500 r/min = 4 poles			380-480 V 50 Hz			Standard Drive					
1.1	M3VK 90L	3GVK 092 672-••C	3.2	3.4	5.1	6.1	13	6	33	18	21
1.5	M3VK 100LA	3GVK 102 671-••C	4.1	4.1	6.2	7.4	16	10	45	19	26
2.2	M3VK 100LC	3GVK 102 673-••C	6.0	5.4	8.1	9.7	21	10	66	20	30
3000 r/min = 2 poles			380-480 V 50 Hz			Drive with RFI filter					
1.1	M3VK 80C	3GVK 081 773-••C	3.2	3.4	5.1	6.1	13	6	33	20	17
1.5	M3VK 90L	3GVK 091 772-••C	4.1	4.1	6.2	7.4	16	10	45	21	22
2.2	M3VK 90LB	3GVK 091 773-••C	6.0	5.4	8.1	9.7	21	10	66	22	25
1500 r/min = 4 poles			380-480 V 50 Hz			Drive with RFI filter					
1.1	M3VK 90L	3GVK 092 772-••C	3.2	3.4	5.1	6.1	13	6	33	20	22
1.5	M3VK 100LA	3GVK 102 771-••C	4.1	4.1	6.2	7.4	16	10	45	21	27
2.2	M3VK 100LC	3GVK 102 773-••C	6.0	5.4	8.1	9.7	21	10	66	22	32

The two bullets in the product code indicate choice of mounting arrangement, voltage and nominal frequency.

1) Power stages are designed for the continuous I_{2N} current.

These values apply at altitudes less than 1000 m ASL.

2) With 8 kHz switching frequency derate I_{2N} to 70% in -10°C...40°C or to 60% in 40°C...50°C.

3) 150 % of nominal current I_{2N} allowed for one minute every 10 minutes.

4) 180 % of nominal current I_{2N} allowed for two seconds.

5) Fuse type: UL class CC or T. For non-UL installations IEC269gG.

Use 60°C rated power cable (75°C if T_{amb} above 45°C).

Follow local rules for cable cross-sections.

Shielded motor cable is recommended.

Max. wire sizes/Power terminals (mm²):

single core: 4 (AWG 12), stranded: 2.5 (AWG 14)/torque 0.8 Nm

Max. wire sizes/Control terminals (mm²):

0.5-1.5 (AWG 22...AWG 16)/torque 0.4 Nm.

General purpose integral motors

For pump and fan use, squared torque applications



TEFC squirrel cage three-phase integral motors M3VK
IP55, IC 411; Insulation class F, temperature rise class B

				Input current I_{IN} A	Cont. output current $I_{2NSQ}^{1),2),3)}$ A	Over current limit (peak) A	Line fuse ⁴⁾ A	Power losses Power circuit Control circuit W W		Total weight kg
Output kW	Type designation	Product code								
3000 r/min = 2 poles				380-480 V 50 Hz		Standard Drive				
0.75	M3VK 80A	3GVK 081	861-••C	1.6	2.2	7.1	4	17	16	14
1.1	M3VK 80B	3GVK 081	862-••C	2.2	2.8	9.5	4	23	17	16
1.5	M3VK 80C	3GVK 081	863-••C	3.2	3.8	13	6	33	18	16
1.5	M3VK 90S	3GVK 091	861-••C	3.2	3.8	13	6	33	18	18
2.2	M3VK 90L	3GVK 091	862-••C	4.1	5.0	16	10	45	19	21
3.0	M3VK 100L	3GVK 101	861-••C	6.0	6.6	21	10	66	20	27
1500 r/min = 4 poles				380-480 V 50 Hz		Standard Drive				
0.75	M3VK 80B	3GVK 082	862-••C	1.6	2.2	7.1	4	17	16	15
1.1	M3VK 90S	3GVK 092	861-••C	2.2	2.8	9.5	4	23	17	18
1.5	M3VK 90L	3GVK 092	862-••C	3.2	3.8	13	6	33	18	21
2.2	M3VK 100LA	3GVK 102	861-••C	4.1	5.0	16	10	45	19	26
3.0	M3VK 100LB	3GVK 102	862-••C	6.0	6.6	21	10	66	20	30
3000 r/min = 2 poles				380-480 V 50 Hz		Drive with RFI filter				
0.75	M3VK 80A	3GVK 081	961-••C	1.6	2.2	7.1	4	17	18	15
1.1	M3VK 80B	3GVK 081	962-••C	2.2	2.8	9.5	4	23	19	17
1.5	M3VK 80C	3GVK 081	963-••C	3.2	3.8	13	6	33	20	18
1.5	M3VK 90S	3GVK 091	961-••C	3.2	3.8	13	6	33	20	19
2.2	M3VK 90L	3GVK 091	962-••C	4.1	5.0	16	10	45	21	22
3.0	M3VK 100L	3GVK 102	961-••C	6.0	6.6	21	10	66	22	28
1500 r/min = 4 poles				380-480 V 50 Hz		Drive with RFI filter				
0.75	M3VK 80B	3GVK 082	962-••C	1.6	2.2	7.1	4	17	18	16
1.1	M3VK 90S	3GVK 092	961-••C	2.2	2.8	9.5	4	23	19	19
1.5	M3VK 90L	3GVK 092	962-••C	3.2	3.8	13	6	33	20	22
2.2	M3VK 100LA	3GVK 102	961-••C	4.1	5.0	16	10	45	21	27
3.0	M3VK 100LB	3GVK 102	962-••C	6.0	6.6	21	10	66	22	31

The two bullets in the product code indicate choice of mounting arrangement, voltage and nominal frequency.

1) Power stages are designed for the continuous I_{2NSQ} current.

These values apply at altitudes less than 1000 m ASL.

2) With 8 kHz switching frequency derate I_{2NSQ} to 70% in -10°C...40°C or to 60% in 40°C...50°C.

3) No overloadability

4) Fuse type: UL class CC or T. For non-UL installations IEC269gG.

Use 60°C rated power cable (75°C if T_{amb} above 45°C).

Follow local rules for cable cross-sections.

Shielded motor cable is recommended.

Max. wire sizes/Power terminals (mm²):

single core: 4 (AWG 12), stranded: 2.5 (AWG 14)/torque 0.8 Nm.

Max. wire sizes/Control terminals (mm²):

0.5-1.5 (AWG 22...AWG 16)/torque 0.4 Nm.

For 6 poles integral motors in Pump&Fan application select a product from General purpose codes.

General purpose integral motors

For pump and fan use, squared torque applications



TEFC squirrel cage three-phase integral motors M3VK

IP55, IC 411; Insulation class F, temperature rise class B

Output kW	Type designation	Product code	Input current I_{IN} A	Cont. output current $I_{2NSQ}^{1),2),3)}$ A	Over current limit (peak) A	Line fuse ⁴⁾ A	Power losses		Total weight kg
							Power circuit W	Control circuit W	
3000 r/min = 2 poles			380-480 V 50 Hz		Standard Drive				
1.1	M3VK 80C	3GVK 081 873-••C	2.2	2.8	9.5	4	23	17	16
1.5	M3VK 90L	3GVK 091 872-••C	3.2	3.8	13	6	33	18	21
2.2	M3VK 90LB	3GVK 091 873-••C	4.1	5.0	16	10	45	19	23
3.0	M3VK 100LB	3GVK 101 873-••C	6.0	6.6	21	10	66	20	31
1500 r/min = 4 poles			380-480 V 50 Hz		Standard Drive				
1.1	M3VK 90L	3GVK 092 872-••C	2.2	2.8	9.5	4	23	17	21
1.5	M3VK 100LA	3GVK 102 871-••C	3.2	3.8	13	6	33	18	26
2.2	M3VK 100LC	3GVK 102 873-••C	4.1	5.0	16	10	45	19	30
3000 r/min = 2 poles			380-480 V 50 Hz		Drive with RFI filter				
1.1	M3VK 80C	3GVK 081 973-••C	2.2	2.8	9.5	4	23	19	17
1.5	M3VK 90L	3GVK 091 972-••C	3.2	3.8	13	6	33	20	22
2.2	M3VK 90LB	3GVK 091 973-••C	4.1	5.0	16	10	45	21	24
3.0	M3VK 100LB	3GVK 101 973-••C	6.0	6.6	21	10	66	22	31
1500 r/min = 4 poles			380-480 V 50 Hz		Drive with RFI filter				
1.1	M3VK 90L	3GVK 092 972-••C	2.2	2.8	9.5	4	23	19	22
1.5	M3VK 100LA	3GVK 102 971-••C	3.2	3.8	13	6	33	20	27
2.2	M3VK 100LC	3GVK 102 973-••C	4.1	5.0	16	10	45	21	31

The two bullets in the product code indicate choice of mounting arrangement, voltage and nominal frequency.

1) Power stages are designed for the continuous I_{2NSQ} current.

These values apply at altitudes less than 1000 m ASL.

2) With 8 kHz switching frequency derate I_{2NSQ} to 70% in -10°C...40°C or to 60% in 40°C...50°C.

3) No overloadability

4) Fuse type: UL class CC or T. For non-UL installations IEC269gG.

Use 60°C rated power cable (75°C if T_{amb} above 45°C).

Follow local rules for cable cross-sections.

Shielded motor cable is recommended.

Max. wire sizes/Power terminals (mm²):

single core: 4 (AWG 12), stranded: 2.5 (AWG 14)/torque 0.8 Nm.

Max. wire sizes/Control terminals (mm²):

0.5-1.5 (AWG 22...AWG 16)/torque 0.4 Nm.

For 6 poles integral motors in Pump&Fan application select a product from General purpose codes.

Technical Specification for Frequency Converter

Mains connection

Power range: 0.55 - 3.0 kW

Voltage: 3-phase, 380 to 480 V $\pm$ 10 %

Frequency: 48 to 63 Hz

Power factor: 0.98

Motor connection

Voltage: 3-phase, from 0 to U_{supply}

Frequency: 0 to 250 Hz

Constant torque applications

Continuous loading capability:

- Rated output current I_{2N}

Overload capacity (max. ambient temperature of 40°C):

- At constant torque: $1.5 \cdot I_{2N}$ for one minute every 10 minutes
- Starting torque: $1.8 \cdot I_{2N}$ for two seconds
- Characteristic data for short time, intermittent and periodic load cycles are available on request.

Switching frequency:

- Standard 4 kHz
- Low noise 8 kHz *)

Squared torque applications

Continuous loading capability:

- Rated output current I_{2NSQ}

No overload capacity

Switching frequency:

- Standard 4 kHz
- Low noise 8 kHz *), with derating

Programmable control connections

Two analogue inputs:

- Voltage signal: 0 (2) to 10 V, 200 k Ω single ended
- Current signal: 0 (4) to 20 mA, 500 Ω single ended
- Potentiometer reference: 10 V $\pm$ 2 % max. 10 mA, 1 k Ω $\leq R \leq$ 10 k Ω
- Response time: < 64 ms
- Resolution: 0.1 %
- Accuracy: $\pm$ 1 %

One analogue output: 0 (4) to 20 mA, load < 500 Ω

Auxiliary voltage: 24 V DC, max 180 mA

Five digital inputs: 12-24 V DC with internal or external supply, PNP and NPN logic

- Input impedance: 1.5 k Ω
- Response time: < 5 ms

Two relay outputs:

- Switching voltage: 12 to 250V AC or max. 30 V DC/0.5 A
- Max. continuous current: 10 mA to 2 A

Built-in brake chopper

Pulse encoder: Connected to digital inputs DI4 and DI5, max. 25 V DC / 100 mA, max. pulse frequency 200 kHz

Serial communication for external control:

- Modbus protocol as standard, other fieldbus options available: PROFIBUS-DP, InterBus-S, DeviceNet, CANOpen, LONWORKS®

Programmable features *)

Nine application macros for easy configuration:

- Factory, ABB Standard, 3-Wire, Alternate, Motor Potentiometer, Hand-Auto, PID-Control, Pre-magnetize, Positioning

Acceleration time: 0.1 to 1800 s

Deceleration time: 0.1 to 1800 s

Skip frequencies: Two bands

Start and stop: Flying start, Torque boosting, Premagnetising function, DC hold function, DC injection braking

Functions:

- Output current and frequency limit, Programmable volts/herz ratio, IR compensation, Slip compensation, PID-control with sleep function, Seven preset speeds, Automatic fault reset, Two acceleration and two deceleration ramps, Control for electromechanical brake

Protection

Limits

- Over current trip limit: $3.5 \cdot I_2$
- DC current regulation limit: $0.5 \dots 1.5 \cdot I_2$
- DC over voltage trip limit: 875 V
- DC under voltage trip limit: 333 V
- Power-loss ride-through: 500 ms
- Over temperature limit: 105°C inside power module

Inverter protection:

- Output short circuit, Input phase loss, Inverter overload, Output earth-fault, Serial communication error, Loss of AI signal, I/O terminal short circuit, Auxiliary voltage short circuit, Brake resistor overload

Motor protection:

- Stall protection, Over temperature protection by R_t estimation or PTC thermistors.

Environmental limits

Ambient operating temperature:

- Output current = I_{2N} and $f_{\text{switch}} = 4$ kHz: -10 to 40°C
- Output current = $0.7 \cdot I_{2N}$ and $f_{\text{switch}} = 8$ kHz: -10 to 40°C
- Output current = $0.6 \cdot I_{2N}$ and $f_{\text{switch}} = 8$ kHz: 40 to 50°C
- Output current = I_{2NSQ} and $f_{\text{switch}} = 4$ kHz: -10 to 40°C
- Output current = $0.7 \cdot I_{2NSQ}$ and $f_{\text{switch}} = 8$ kHz: -10 to 40°C
- Output current = $0.6 \cdot I_{2NSQ}$ and $f_{\text{switch}} = 8$ kHz: 40 to 50°C
- Refer to page 16 for more derating information

Installation altitude:

- Output current = I_2 : 0 to 1000 m
- Output current reduced by 1% for every 100 m above 1000 m. Max altitude 2000 m.

Protection class: IP 65

Colour: NCS 1502-Y, RAL 9002, PMS 420 C

Contamination levels: According to IEC-721-3-3

Electromagnetic Compatibility (EMC):

- Standard Drive: Fulfils EN 61800-3 2nd Environment distribution limits
- Drive with RFI filter: Fulfils EN 61800-3 1st and 2nd Environment distribution limits

Harmonic emissions:

- Units with < 1 kW input power fulfil EN 61000-3-2
- Units with > 1 kW input power are to be used only in professional applications

Product compliance

- Low Voltage Directive 73/23/EEC with amendments
- EMC Directive 89/336/EEC with amendments
- Quality Assurance systems ISO 9001 and ISO 14001
- CE, UL, cUL and C-Tick approvals

*) Adjustable only with control panel.

Frequency Converter Options

IP 65 Control Panel Kit

Variant code: 611

Full configurable functionality is available when using the optional control panel. With the control panel, parameters can be exchanged between two drives using the parameter upload/download procedure.



Fieldbus Gateways and RS485/232 Adapter

Variant code: see the table below

The integral motor can be connected to all major automation systems with the help of the large variety of fieldbuses. The fieldbus gateways are available in robust IP 65 boxes, which can be conveniently fitted on one side of the drive. The Modbus protocol is standard in all integral motor units and can be used by means of an RS485/232 adapter (CFB-RS).



Fieldbus technical data

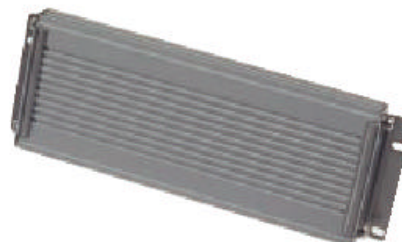
Fieldbus	Type code	Variant code	Protocol mode	Device profile	Baudrate (min.-max.)
PROFIBUS	CFB-PDP	612	DP	Profidrive V.2	9.6 kbits/s - 12 Mbits/s
InterBus-S	CFB-IBS	613	PCP	Drivecom (Profile 21)	500 kbits/s
DeviceNet	CFB-DEV	616	N.A.	AC Drive	125 - 500 kbits/s
CANOpen	CFB-CAN	614	N.A.	Drives and Motion control (DS402 V.1.1)	10 - 1000 kbits/s
LonWorks®	CFB-LON	615	LONtALK®	Variable Speed Motor Drive 6010	78 kbits
Modbus	CFB-RS	617	RTU	Vendor Specific	300 - 19200 bit/s

N.A. = Not applicable

Integral Brake Resistors

Variant code: see the table below

The integral motor brake resistor offers an optimal solution for braking, as braking choppers are a standard feature of the drives. The IP 65 brake resistors can be fitted on one side of the integral motor.



Brake resistor technical data

Integral motor output kW (general purpose ratings)	Brake resistor Type code	Variant code	Resistance Ohm W	Max. average resistor power W	Max. instantaneous resistor power
0.37...0.55 kW	CA-BRK-R1-1	618	390	39	700
0.75 kW	CA-BRK-R1-1	618	390	39	950
1.1 kW	CA-BRK-R1-2	619	125	39	1500
1.5 kW	CA-BRK-R1-2	619	125	39	2100
2.2 kW	CA-BRK-R2	620	125	45	3080

Cable gland set

Variant code: 230

A selection of cable glands for integral motor. The glands are for the following cable diameters: 5-9 mm (2 pcs), 6-12 mm (2 pcs) and 9-16 mm (2 pcs).



More options for frequency converter available separately

- AnyBus Communicator fieldbus gateways (Profibus-DP and DeviceNet)
- DriveWindow Light 2 start-up and maintenance PC tool.

General purpose integral motors

Variant codes, motor part

S = Included as standard.
 NA = Not applicable.
 R = On request.
 P = New manufacture only.

Code	Variant	Frame size			
		71	80	90	100
Balancing					
052	Balancing to grade R (IEC 60034-14).	P	P	P	P
423	Balanced without key.	P	P	P	P
424	Full key balancing.	P	P	P	P
Bearings and lubrication					
040	Heat resistant grease. (-25 - +150°C)	P	P	P	P
042	Locked drive-end.	P	P	S	S
057	2RS bearings at both ends.	P	P	P	P
Branch standard designs					
178	Stainless steel/acid proof bolts.	P	P	P	P
425	Corrosion protected stator and rotor core.	P	P	P	P
Cooling system					
068	Metal fan.	P	P	P	P
183	Separate motor cooling (fan axial, N-end).	P	P	P	P
Drain holes					
065	Plugged drain holes.	P	P	NA	NA
066	Modified drain hole position.	P	P	P	P
076	Draining holes with plugs.	S	S	S	S
Earthing bolt					
067	External earthing bolt.	P	P	P	P
Heating elements					
450	Heating element, 100-120 V.	P	P	P	P
451	Heating element, 200-240 V.	P	P	P	P
Mounting arrangements					
007	IM 3001 flange mounted, IEC flange, from IM 1001 (B5 from B3).	P	P	P	P
008	IM 2101 foot/flange mounted, from IM 1001 (B34 from B3).	P	P	P	P
009	IM 2001 foot/flange mounted, from IM 1001 (B35 from B3).	P	P	P	P
047	IM 3601 flange mounted, IEC flange, from IM 3001 (B14 from B5).	P	P	P	P
048	IM 3001 flange mounted, IEC flange, from IM 3601 (B14 from B5).	P	P	P	P
Painting					
114	Special paint colour, standard grade. RAL-colour no. must be specified.	P	P	P	P

General purpose integral motors

Variant codes, motor part

S = Included as standard.
 NA = Not applicable.
 R = On request.
 P = New manufacture only.

Code	Variant	Frame size			
		71	80	90	100
Protection					
005	Protective roof, vertical motor, shaft down.	P	P	P	P
073	Sealed against oil at D-end.	P	P	P	P
158	Degree of protection IP 65.	P	P	P	P
Rating & instruction plates					
003	Individual serial number.	P	P	P	P
013	Restamping to output for class F temperature rise.	P	P	P	P
098	Stainless rating plate.	P	P	P	P
138	Mounting of additional identification plate, aluminium.	P	P	P	P
Shaft & Rotor					
069	Two shaft extensions as per basic catalogue	P	P	P	P
165	Shaft extension with open key way	R	R	R	R
410	Stainless / acid proof steel shaft (standard or non-standard design)	P	P	P	P
Standards and regulations					
029	Fulfilling Underwriters Laboratory (UL) requirements	R	R	R	R
Stator winding temperature sensors					
436	PTC-thermistors (3 in series), 150°C	P	P	P	P
Testing					
140	Test confirmation	R	R	R	R
Variable speed drives					
470	Prepared for hollow shaft pulse tacho (L&L equivalent)	P	P	P	R
473	2048 pulse tacho (L&L equivalent)	P	P	P	R
477	Separate motor cooling (fan axial, N-end) and 2048 pulse tacho (L&L equivalent)	P	P	P	R

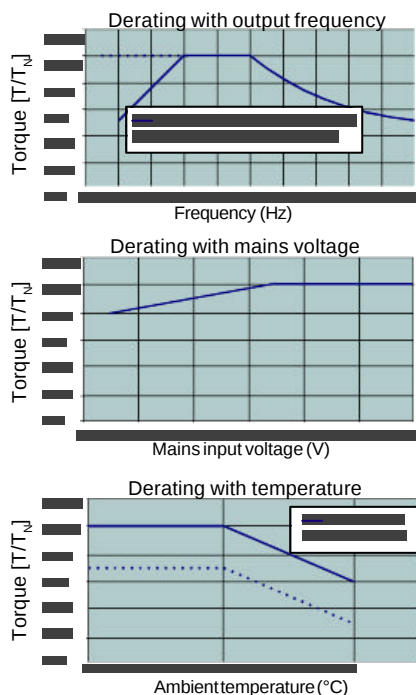
General purpose integral motors

Variant codes, frequency converter part

S = Included as standard.
NA = Not applicable.
R = On request.
P = New manufacture only.

Code	Variant	Frame size			
		71	80	90	100
Unit body					
230	Standard cable gland set	P	P	P	P
Brake resistor					
618	Inverter brake resistor for 0.37 kW, 0.55 kW & 0.75 kW unit (general purpose ratings)	P	P	P	NA
619	Inverter brake resistor for 1.1 kW & 1.5 kW unit (general purpose ratings)	NA	P	P	P
620	Inverter brake resistor for 2.2 kW unit (general purpose ratings)	NA	NA	P	P
Panel kit					
611	Inverter control panel kit	P	P	P	P
Fieldbus type					
612	CFB-PDP	P	P	P	P
613	CFB-IBS	P	P	P	P
614	CFB-CAN	P	P	P	P
615	CFB-LON	P	P	P	P
616	CFB-DEV	P	P	P	P
617	CFB-RS	P	P	P	P

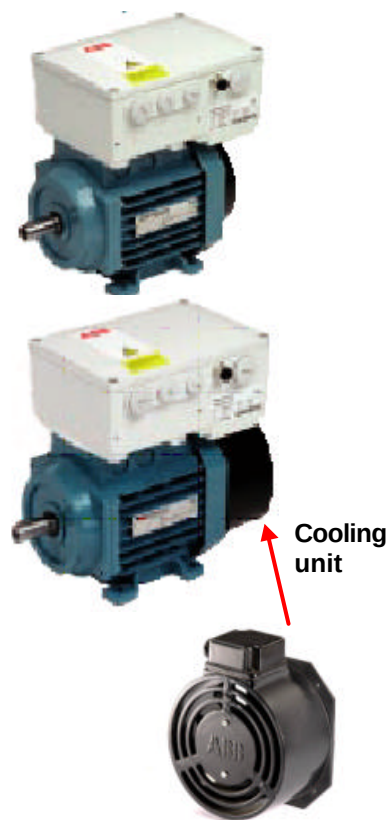
Derating Information



If the integral motor is used at low frequencies, separate cooling is recommended, particularly if the motor load is high and the speed is low.

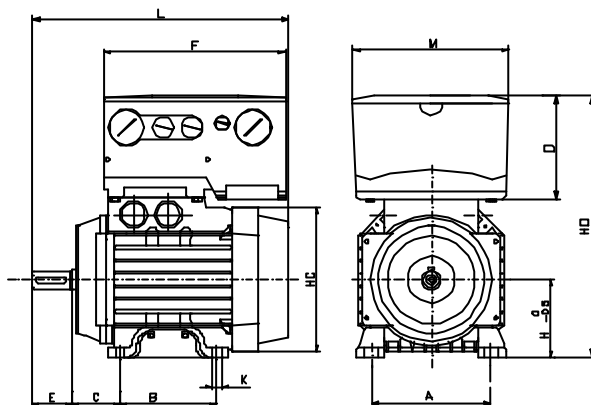
M3VK

M3VK
with separate
cooling unit

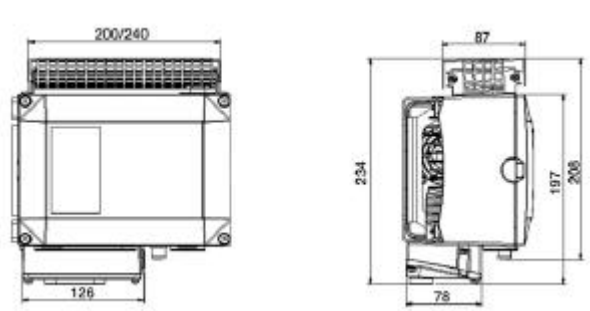


General purpose integral motors

Dimensions



Dimensions with integrated options added



Integral Motor Standard Drive	Product Code Drive with RFI filter	Dimensions													
		A	B	C	E	H	HC	K	L	D std*	D w RFI*	HD std*	HD w RFI*	F	M
3GVK 071 661-...C	3GVK 071 761-...C	112	90	45	30	71	130	7	283	110	146	261	297	221	171
3GVK 071 662-...C	3GVK 071 762-...C	112	90	45	30	71	130	7	283	110	146	261	297	221	171
3GVK 081 661-...C	3GVK 081 761-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 081 662-...C	3GVK 081 762-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 081 663-...C	3GVK 081 763-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 091 661-...C	3GVK 091 761-...C	140	100	56	50	90	170	10	282	110	146	300	336	221	171
3GVK 091 662-...C	3GVK 091 762-...C	140	125	56	50	90	170	10	307	110	146	300	336	261	171
3GVK 072 662-...C	3GVK 072 762-...C	112	90	45	30	71	130	7	283	110	146	261	297	221	171
3GVK 082 661-...C	3GVK 082 761-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 082 662-...C	3GVK 082 762-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 082 663-...C	3GVK 082 763-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 092 661-...C	3GVK 092 761-...C	140	100	56	50	90	170	10	282	110	146	300	336	221	171
3GVK 092 662-...C	3GVK 092 762-...C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 102 661-...C	3GVK 102 761-...C	160	140	63	60	100	190	12	349	110	146	310	346	261	171
3GVK 083 661-...C	3GVK 083 761-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 083 662-...C	3GVK 083 762-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 093 661-...C	3GVK 093 761-...C	140	100	56	50	90	170	10	282	110	146	300	336	221	171
3GVK 093 662-...C	3GVK 093 762-...C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 103 661-...C	3GVK 103 761-...C	160	140	63	60	100	190	12	349	110	146	310	346	221	171

* std = Standard Drive, w RFI = Drive with RFI filter



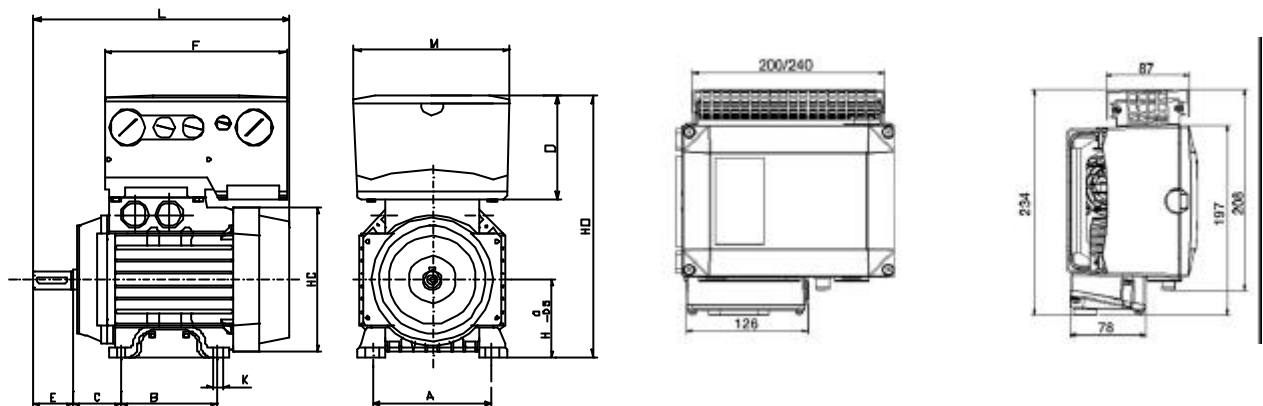
Integral Motor Standard Drive	Product Code Drive with RFI filter	Dimensions													
		A	B	C	E	H	HC	K	L	D std*	D w RFI*	HD std*	HD w RFI*	F	M
3GVK 081 673-...C	3GVK 081 773-...C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 091 672-...C	3GVK 091 772-...C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 091 673-...C	3GVK 091 773-...C	140	125	56	50	90	170	10	307	110	146	300	336	261	171
3GVK 092 672-...C	3GVK 092 772-...C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 102 671-...C	3GVK 102 771-...C	160	140	63	60	100	190	12	349	110	146	310	346	221	171
3GVK 102 673-...C	3GVK 102 773-...C	160	140	63	60	100	190	12	349	110	146	310	346	261	171

* std = Standard Drive, w RFI = Drive with RFI filter

General purpose integral motors

Dimensions in pump and fan use

Dimensions with integrated options added



Integral Motor Standard Drive	Product Code Drive with RFI filter	Dimensions													
		A	B	C	E	H	HC	K	L	D std*	D w RFI*	HD std*	HD w RFI*	F	M
3GVK 081 861-••C	3GVK 081 961-••C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 081 862-••C	3GVK 081 962-••C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 081 863-••C	3GVK 081 963-••C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 091 861-••C	3GVK 091 961-••C	140	100	56	50	90	170	10	282	110	146	300	336	221	171
3GVK 091 862-••C	3GVK 091 962-••C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 101 861-••C	3GVK 101 961-••C	160	140	63	60	100	190	12	349	110	146	310	346	261	171
3GVK 082 862-••C	3GVK 082 962-••C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 092 861-••C	3GVK 092 961-••C	140	100	56	50	90	170	10	282	110	146	300	336	221	171
3GVK 092 862-••C	3GVK 092 962-••C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 102 861-••C	3GVK 102 961-••C	160	140	63	60	100	190	12	349	110	146	310	346	221	171
3GVK 102 862-••C	3GVK 102 961-••C	160	140	63	60	100	190	12	349	110	146	310	346	261	171

* std = Standard Drive, w RFI = Drive with RFI filter

Integral Motor Standard Drive	Product Code Drive with RFI filter	Dimensions													
		A	B	C	E	H	HC	K	L	D std*	D w RFI*	HD std	HD w RFI*	F	M
3GVK 081 873-••C	3GVK 081 973-••C	125	100	50	40	80	150	10	275	110	146	280	316	221	171
3GVK 091 872-••C	3GVK 091 972-••C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 091 873-••C	3GVK 091 973-••C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 101 873-••C	3GVK 101 973-••C	160	140	63	60	100	190	12	349	110	146	310	346	261	171
3GVK 092 872-••C	3GVK 092 972-••C	140	125	56	50	90	170	10	307	110	146	300	336	221	171
3GVK 102 871-••C	3GVK 102 971-••C	160	140	63	60	100	190	12	349	110	146	310	346	221	171
3GVK 102 873-••C	3GVK 102 973-••C	160	140	63	60	100	190	12	349	110	146	310	346	221	171

* std = Standard Drive, w RFI = Drive with RFI filter

Notes:

Notes:

[illegible]

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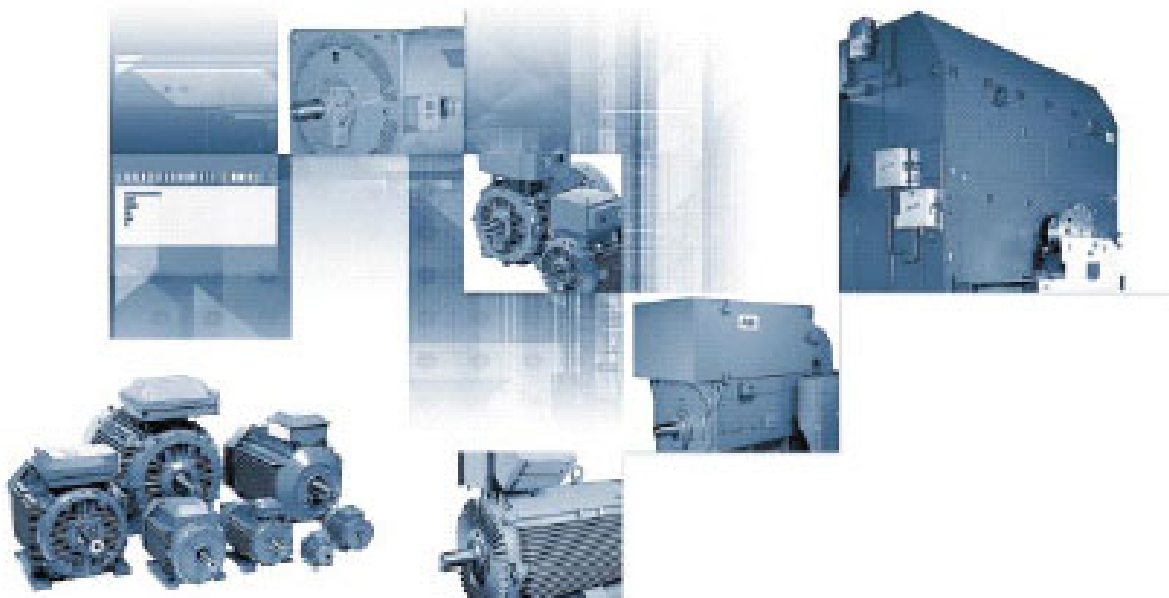
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- Permanent magnet motors
- High speed motors
- Wind turbine generators
- NEMA motors
- Water cooled motors
- Motors for roller table drives
- Slip ring motors
- Wood dryer motors
- Fan application motors

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Drive^{IT} Low Voltage Motors

Manufacturing sites (*) and some of the larger sales companies.

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