

# **USER'S MANUAL**



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## Part 1 Product introduction

#### Overview

#### Power button:

- Press and hold :
  - 1. Power on/off.
- Temporarily press :
  - Normal mode : To cycle through the various information of Easy Showily.
  - Setting mode : To confirm the option of setting items and then back to normal mode.

#### Function button:

- Press and hold :
  - 1. Normal mode : To enter the setting mode.
- > Temporarily press :
  - Normal mode : To reset the accumulation of Kilometer and Counter.
  - Setting mode : To set and switch among each setting items.



#### LCD:

- 1. Normal mode : Display information.
- Setting mode : Display setting items.

#### **GPS Antenna Location**

#### Track button:

- Press and hold :
- 1. Normal mode : To set up a new track.
- > Temporarily press :
- Normal mode : To mark a point in the current track.
- Setting mode : To switch options of selected items.

# Part 2 Features

Easy Showily is a Auto-show Track Logger with internal antenna. u-blox ATR0625 used in its core is high-tech component and included function of auto-log record of journey. USB interface ensures easy linking with computer to read the log data or programming it any where without install any driver or software. The GPS acquisition status, the last record of time and position could all be stored in non-volatile memory. The Easy Showily not only has 16 GPS channels but also powered by 2\*AAA alkaline battery, no need to charge. Furthermore, it is with very low power-consumption, you could use it by full power operation (record 1 point per second) for 15 hours continually. If shake mode is available, then the battery life will be longer.

- Easy Showily built-in u-blox GPS IC ATR0625.
- Maximum 16 channels can be acquisitioned quickly.
- Highest tracking sensitivity: -158 dBm
- Internal decode"SBAS" is used excluding the need for external hardware in receiving SBAS signal.
- Data-logging acts like the in-flight black box and can record of position, date and time as long as power source is maintained.
- For down-load of log-data and programming of Easy Showily, the provided software tool "Win\_Tool" can simplify the usage.
- USB interface, not need to install any driver or software.
- System requirement: Windows XP® or Vista®.
- Advance Web Browser: Internet Explorer.

### Part 3 Safety notes

- GPS (Global Positioning System) is provided by the United States government. Its accuracy may varies depending on special conditions (area at war or if it is blocked). Any control by USA will affect this system and its accuracy.
- If installed on the transportation device, driver must not operate this while driving.
- GPS performance is affected when satellite coverage is degraded as near a high-rise building, in the tunnel or under a cover.
- Personal replacement of components and re-structuring of this is prohibited and may result in loss of legal usage.
- Operation of this device is strictly prohibited in highly explosive environment such mining, in-flight or other unauthorized area against use of this.
- Avoid exposing this at places of high temperature and humidity.
- Return to original dealer immediately if it emits strange smell or fume.
- Set the Easy Showily on the place where can receive GPS signal easily for 10 to 15 minutes if it is the first time to be used. This procedure enables the device to gather some Almanac Data and ensures the quicker position fixed and better GPS performance.

# Part 4 User's guide

- Package:
  - Easy Showily (Auto-show Track Logger)
  - AAA alkaline battery \*2
  - USB extensive cable (15cm) \*1
  - User's manual.
- Easy Showily Operation:
  - Press and hold "Power" button to power on it. The LCD will show up the main screen to confirm it is in the normal mode and GPS start acquisitioning.

- After power on, press and hold "Power" button to turn the power off.
- "FIX" show up in the upper right of main screen indicates GPS acquisition is done. If not, the GPS acquisition fails.

 In the normal mode, temporarily press "Track" button ("PUSH" will show up in the upper right of main screen) to mark a point in the current track.



 In the normal mode, press and hold the "Track" button ("NEW" will show up in the upper right of main screen) to re-start a new track.

H:150	'NE₩
<u>S: 100</u>	)km∕h

 If the battery icon shows up in the button right of main screen, the power is too low to work normally. Please replace batteries for avoiding worse GPS performance, un-working device and incorrect data recorded.



- In the normal mode, temporarily press "Power" button to change the information showed on LCD.
  - A . Heading and speed information (after positioning) :



Temporarily press "Function" button to change the

monuation	10111 0	pood	o unnuuo.
	ετν ί		° CTV
<b>U</b> • 120	L TVI 1	1.120	L T U
A · 1E00		A - 1	15000+
H• TOOO		<b>n</b>	12001.0

B . Kilometer accumulated at present :

DISTANCE FIX	DISTANCE FIX
120.5 km	120.5 mi

C . Counter accumulated at present :

Temporarily press "Function" button to switch the following 3 accumulative value of counter.



Total value of counter.

Value of motion counter.

Value of non-motion counter.

D . Average speed at present :



E · latitude and longitude at present (after positioning) or last positioning (before positioning) :



(When the first time use or after cold start)

F . Local time at present: (Based on the zone set by user)



(When the first time use or after cold start)

 In the normal mode, press and hold "Function" button will enter the setting mode and then the LCD will show up setting information.



- In the setting mode, temporarily press the "Power" button or no operation more than 15 second, it will back to normal mode.
- In the setting mode, temporarily press the "Function" button to switch the following 3 setting categories. And the information showed on the second line is present and selected status.



 In the setting mode, temporarily press the "Track" button to switch setting value showed on the second line of the screen. The setting value would be confirmed when you skip to the other setting category or back to normal mode. 1. LOG Mode Setting:

Walk mode, Bicycle mode, Car mode, User define mode.



2.Shake mode (power saving) function :

2. SHAKE	MODE	2. SHAKE	MODE
On		Off	

3. Show the usage capacity of the record:



 If you want to reset the accumulative value of Kilometer and counter, please enter the information B (kilometer accumulated) under normal mode, and temporarily press the "Function" button, then the "RESET?" will be showed up. At this moment, you just press the "Function" button again, the kilometer accumulated and counter accumulated will reset simultaneously, otherwise, you just temporarily press the "Power" button to switch to other information mode, or ignore it for 5 seconds, and then the "RESET" will be canceled.



 When shake mode is enable and stationary more than 5 minutes, its power will be turned off (that interval can be set by yourself), until the device with movement again.
 The Easy Showily will not auto power on/off while shake mode is disable. And if you turn it off manually while shake mode is enable, then the shake mode will be disabled simultaneously.

- When the USB is used as interface:
  - Turn the Easy Showily power off.
  - Connect Easy Showily to USB port of computer.
  - The built-in access tool (Win\_Tool) will execute automatically, and then read the log data and transfer its format to Google Maps automatically.
  - User can transfer the log data to other format to suit other software or programming Easy Showily via Win\_Tool.
- Battery Replacement:
  - Turn off the Easy Showily.
  - Take off the USB cover.
  - Take out the battery cover.
  - Replace new batteries. (AAA 1.5v battery \*2; Alkaline batteries are recommended.)
  - Be sure not to drop the battery.
  - Put the battery cover back.
  - Put on the USB cover.

Cautions: Remove the batteries when you do not use the Easy Showily for a long time. Otherwise, it may result in leakage of the batteries.

# Part 5 Operation notes

- Easy Showily will do self-check once it is powered. GPS start to work when LCD shows up the main screen. GPS automatically starts acquisition and auto-logs. If sky is clear overhead, it requires only 34 sec for acquisition. (If the data in its memory is still valid, it needs only 4~33 sec). After acquisition, Easy Showily starts record the track.
- For the first time if it is placed at the area well exposed to the satellite signal, this device requires approx 13 min (theoretically 12.5 min) to receive or update Almanac. Refer to trouble shooting guide when signal is not received well.
- If Easy Showily formatting the internal data is not correct, or if satellite data has been deleted, it takes longer time to position. But under the following conditions, it can take even longer time to get cold start.
  - If it is not in use for over 3 months (the almanac is olddated).
  - If the last recorded position data is over 500 km.
- After positioning, Easy Showily begins to auto-log the following way.
  - Maximum data up to 94000 Points.
  - Recording in a circular way.
  - Auto-logging goes on without the need of any device.
  - Log-data can be read out by way of the "Win\_Tool" included.
  - Data includes latitude, longitude, and altitude, time in year-month-date-hour-min-sec (UTC) and special point mark status.
  - After successful positioning, it wills auto-log GPS data into its internal memory chip. It recorded in a rotational order.

The earliest (oldest) data will replaced by the latest (newest) one when memory space is full (when data excesses 94000 maximum).

- The operating time may differ depending on the situation, environment condition or the type of battery.
- In the operation, please keeps the GPS antenna facing the open sky for good performance.
- For the high sensitivity of shake sensor, please keep the device in the level state when you enable the shake mode.
- Pleas be aware that you have to replace both two batteries simultaneously; otherwise the life of battery will be slashed.
- The Shake mode will be disabled automatically when the low battery icon shows up; this procedure can ensure the normal working of device. Please re-enable the shake mode after replacing batteries if the function is still needed.

# Part 6 Access Tool

 Plug in the Easy Showily to computer via USB connector, and the access tool will execute automatically. Otherwise, please find the device named "Win\_Tool" in the "My Computer", and click its icon to execute it.





Key in the password and click "Log in". If you don't enable the password protect, this step will be omitted.



 Win\_Tool will read log data from device, and present it on Google Maps via browser automatically.



At the same time, Win\_Tool will be miniaturized and hidden in the system tray. Click the icon, and Win\_Tool will show up.







🛬 Win_Tool Ver:1.0.5.5 F/W Ver:3.8	
Language Photo_Tool Help	
LOG Data Device Setting LOG Mode GPS Setting	
⊂[LOG Data Access] ┌[LOG data source] ☞ Easy Showly ◯ Other:	
Transfer the LOG data format to: 1. Google Maps (*.html)	Transfer
Panoramio User number Difference China Map	
<u>GM 20071229081641.html</u>	
Total LOG points: 2571	Clear LOG

4. Win\_Tool Instruction:

#### 4.0 Auto-backup the track file (\*.tes):

The track file stored in the Easy Showily will be auto-backup to the default path when the Win\_Tool is executed. The format of back up file is (\*.tes).

4.0.1 The path of the backup file (\*.tes): Partition of system:\Documents and Settings \Username\My Documents\ EASY\_SHOWILY\_LOG\_DATA\[Device ID of Easy Showily] (if the Device ID is not set, and the default is Easy\_Showily)\

4.0.2 The file name of the backup file (\*.tes): Back\_Up\_[The UTC time at the first point of the track].tes

#### 4.1 Menu:

Language Photo\_Tool Help

4.1.1 Language:

The language selection of Win\_Tool includes English, Traditional Chinese, Simplified Chinese, German and Japanese are supported.



4.1.2 Photo\_Tool:

Select the "Geotagging/Report" item to enter the detail page, please refer to part 4.6.

Language Photo_Tool Help
Geotagging / Report

#### 4.1.3 Help:



4.1.3.1: Win\_Tool User Manual:

Enter the webpage for Win\_Tool instruction.

4.1.3.2: Download TimeMachineX:

Enter TimeMachineX webpage for downloading.

4.1.3.3: MSCHART Register:

Please select this item to complete the MSCHART Register when the report function is not working. Note:

1. The computer which is login should be Administrator or the one has the same authorities.

2.For Windows Vista, please turn off UAC (User Account Control) and reboot your computer before register.

4.1.3.4 : Download latest Win\_Tool:

Press this item to download the latest version of Win\_Tool.



#### 4.2 LOG Data Tab:

LOG data source] Easy Showily C Other:	
Transfer the LOG data forma Panoramio User number M 20071229081641.html	at to: 1. Google Maps (".html)  Transfer

#### 4.2.1 Clear LOG:

Press the "Clear LOG" button to delete all LOG data in the device.



Note:

After pressing the "Clear LOG" button, the following message will show on the LCD when you power on the device. And it will take around 30 sec. to complete the clear log process.



4.2.2 LOG File Convert:

- I . Select the LOG Data source:
  - I .1 From Easy Showily: (default)

[LOG data source] © Easy Showily C Other:

I .2 From other backup files:

[LOG data source	÷]		
C Easy Showily	· Other:	Up_2007_12_29_00_16_41.tes	Select LOG File

Press the "Select LOG File" button to choose the track file. Note:

 The value of the "Total LOG points" shows the recorded points of the selected track.



Ⅱ. Choose the LOG Data format:

Easy Showily C Other:		Here
Transfer the LOG data forma	t to 1. Google Maps (*.html)	Transfer
Panoramio User number	1. Google Maps (*.html) 2. Google Faith (*.kmz)	4 (m)
M 20071229081641.html	3. Virtual Earth (*.htm)	
	5. OziExplorer (*.plt)	
	<ol> <li>PaPaGo (".txt)</li> <li>Single GPX (".gpx)</li> </ol>	-
	8. Multi GPX (*.gpx)	
Total LOG points: 2571	10. Excel (*.csv)	Clear LOG

Please select a format that you want to transfer to, and press the "Transfer" button to start the operation. Also you can copy or delete the transferred file by right click function.

Righ	t Click	
GE 2007122908764 GE 2007122908371 GE 2007122912064 GE 2007123119450	Copy to Copy to Copy all to	<u>3324 kmz</u> <u>217 kmz</u>
	Delete Delete all	

Following transfer formats are supported:

II.1 Google Maps: Double click the file and it will be opened via browser, IE browser is suggested. All recorded tracks will be transferred into only ONE file i.e. a html file includes several tracks and the time of every point will be shown according to time zone of device.

Transfer the LOG data forma	t to: 1. Google Maps (*.html) 🗨 Transfer
Panoramio User number	China Map
GM 20071229081641.html	

Note:

- 1. You can tick the "Panoramio" item to show the Panoramio photo map. The details please refer to the Part 4.7
- Please tick the item of "China Map" if the recorded track is located in Mainland China.
- The Google Maps will auto-divide a single track into two if it includes more than 10,000 way points.

This procedure can ensure that the browser will show the

complete track normally.

- 4. Share your track data with your friend.
  - 4.1 Copy the file and e-mail it to your friend via your mail client such as outlook.
  - 4.2 You also can e-mail your track data by right click function, and select the item of "Mail to friend".

	er	🗂 China M	1ар	
Cop	y to(zip) y to(html)			
Dele Dele	te te all			
Mail	to friend			
Easy Showily traj : 檔案(P) 编辑(E)	ectory 那件(桃文字) 被親(Y) 描入(D) 格式	to IRD M	17(4) 取明图	×
· · · · · · · · · · · · · · · · · · ·	)•  🖬    X 🗈 🙇 [	0   <u>1</u> 3   <del>1</del>	-) 3891(D   🥹	
	asa@gmail.com			
副本(広): 主旨の:	Easy Showily trajectory.			
附件	BOM 20071229081641 a	np (52 KB)	制件递项(M)	
	Y	Google M	aps format	

II.2 Google Earth: Please be aware that the software of Google Earth must be installed first (you can download it from <u>http://earth.google.com</u>). Every track will be transferred to different files, i.e. one file for one track, and the time of every point will be shown according to time zone of device.

Transfer the LOG	â data format to: 2. Google Earth (*.kmz)	
		🗂 3D Track
0071229081641.kmz	GE 20071231203324.kmz	
0071229083711.kmz	GE 20071231232217.kmz	
0071229120642.kmz		
0071231194505.kmz		

#### Note:

- 1. Tick the item of "3D Track", and you can see the track including altitude on Google Earth.
- I .3 Virtual Earth: Double click the file and it will be opened via browser, IE browser is suggested. All recorded tracks will be transferred into only ONE file i.e. a htm file includes several tracks and the time information of every point will be shown according to time zone of device.



Note:

- The Virtual Earth will auto-divide a single track into two if it includes more than 10,000 way points. This procedure can ensure that the browser will show the complete track normally.
- II.4 TimeMachineX: Please be aware that the software of TimeMachineX must be installed first (free download), and all recorded tracks will be transferred into only ONE file, i.e. a tk1 file includes several tracks. All detailed instruction of TimeMachineX please refers to Part 7

	Transfer the LDG data format to: 4. TimeMachineX (*.tk1)	•	Transfer
K1 200	171229001641. <u>lk1</u>		

II.5 OziExplorer: The software of OziExplorer must be installed first (buy by yourself). Every track will be transferred to different files i.e. one file for one track and the time information of every point will be UTC.

Transfer the LO	G data format to: 5. OziExplorer (*.plt)	•	Transfer
1 20071229001641.plt	OZI 20071231123324.pt		
20071229003711.plt	OZI 20071231152217.ptt		
20071229040642.plt			
20071231114505.plt			

II.6 PaPaGO: The software of PaPaGO must be installed first (buy by yourself). You also can double click the file to open it by notepad. All recorded tracks will be transferred to only ONE file and the time information of every way point will be shown according to the time zone of device.



II.7 Signal GPX: All recorded tracks will be transferred to only ONE file, and the file can be uploaded to some websites supporting GPX format to share your track or applied to other software. The time information of every point will be UTC.



II.8 Multi GPX: Every recorded track will be transferred to different files i.e. one file for one track. And these files can be uploaded to some websites supporting GPX format to share your track or applied to other software. The time information of every point will be UTC.

Transfer the LOG data format to:	8. Multi GPX (*.gpx) 🛛 👻
----------------------------------	--------------------------

mGPX	20071229001641.qpx	mGPX_20071231123324.qpx
mGPX	20071229003711.qpx	mGPX_20071231152217.qpx
mGPX	20071229040642.qpx	
mGPX	20071231114505.gpx	

II.9 NMEA: Every recorded track will be transferred to different files i.e. one file for one track. Transfer to NMEA format according to recorded track data (including GPRMC and GPGGA only).

Transfer the LOG dat	a format to: 9. NMEA (*.nmea)	•	Transfer
NMEA 20071229001641.nmea NMEA 20071229003711.nmea NMEA 20071229040642.nmea NMEA 20071231114505.nmea	NMEA 20071231123324.nmea NMEA 20071231152217.nmea		

II.10 Excel: Every recorded track will be transferred to different files i.e. one file for one track. And the time information of every point will be shown according to time zone of device.

Transfer the LOG	data format to: 10. Excel (*.csv)	Transfer
CSV 20071229081641.csv	CSV 20071231203324.csv	
CSV 20071229083711.csv	CSV 20071231232217.csv	
CSV 20071229120642.csv		
CSV 20071231194505.csv		

II.11 Universal Transverse Mercator(UTM): Double click the file to open it by notepad. Every track will be transferred to different files i.e. one file for one track. And the time information of every point will be shown according to the time zone of device.

Transfer the LOC	6 data format to:	11. UTM (*.txt)	<b>•</b>	Transfer
20071229081641.txt	UTM 2007123	1203324.txt		
20071229083711.txt	UTM 2007123	1232217.bd		
20071229120642.txt				
20071231194505.bd				

 II.12 TWD67TM2: Double click the file to open it by notepad. Every track will be transferred to different files i.e. one file for one track.

Transfer the LOG data f	ormat to: 12.	TWD67TM2 (*.txt)	•	Transfer
D67TM2 20071229081641.txt	TWD67TM2	20071231203324.bd	ş	
D67TM2 20071229083711.bd	TWD67TM2	20071231232217.txt		
D67TM2 20071229120642.txt				
D67TM2 20071231194505.bd				

4.2.3 Win\_Tool Update:

The button of "Download latest Win\_Tool" will be shown up automatically when the Win\_Tool version in your device is not the newest one.

Transfer the LOG data format to:	1. Google Maps (*.html) 💌	Transfer
Panoramio User number	China Map	
M 20071229081641 html		
2001122000101114		
<u>10011220010113888</u>		

Note :

- All log data would be deleted and all parameters would be return to the original setting after Win\_Tool updating. (The password would be canceled too if you have set.)
- About the detail of update, please refer to the downloaded file.

- I. Update Instruction:
  - I .1 Extract the downloaded file.
  - I .2 Plug in the Easy Showily to computer, but not execute the Win\_Tool.
  - I .3 Double click the "Easy\_Showily\_UPDATE.exe" in the downloaded file.



I.4 The following dialogue will pop out. Please press the "Update" button.

😫 Eary_Showily_UPDATE	
Warring! All data will delete and back to factory setting. Password protect will be disable	e.
	00%
Update	

 5 Warning message: All log data will be deleted, parameters will be return to the original setting and the password protect will be disabled after updating. If you accept, please press "OK" to continue the process, otherwise please press "Cancel" to stop the



I .6 The update is in progress.

📽 Easy_Showily_UPDATE			X
Warring!! All data will dele	le and back to factory setting. Passwo	rd protect will be disable.	
			14%
	Update		

#### I .7 Press "OK" to complete the update procedure.



- I .8 Plug out the Easy Showily.
- I .9 Please power on the Easy Showily, the message of "Clear LOG data now.." should be shown on the LCD, and eliminated about 30 seconds later. If the "Clear LOG data now.." didn't show up, please do the "Clear LOG" process by Win\_Tool manually, otherwise it would work abnormally.

#### 4.3 Device Setting Tab:

LOG Data Device Setting   LOG Mode   GPS Setting	
(Device Cettine)	
[Device Setting]	
1. Metric System 💌 +8 💌	
[Enable Password]	
New: This is Demo	
Confirm: Enable Password Change	
[LCD Setting]	
Contrast 205	
Back Light (sec) 5 SET	
[Shake Mode for Power Saving]	
OFF; Always log.     SET	
C ON; No motion after 5 Mins. auto power off.	

#### 4.3.1 System Unit:

Set the system unit at the device; one for Metric unit, the other for Imperial unit.

[Sys	tem Unit]	
	1. Metric System	-

#### 4.3.2 Device Zone:

The time zone of device can be adjusted according to your requirement.

Please be aware that the time zone of device will affect the showing time on the Easy showily and some track files, such as Google Maps, Google Earth, Virtual Earth, PaPaGo, Excel and UTM formats. Besides, the time zone of device will also be the reference time for Geotagging.



4.3.3 Enable password protection or change password: User could enable password protection here, and the maximum of password is 10 characters or digits. If you want to disable password protection, just keep blank in both "New" and "Confirm", and then click "Change Password".

No Password Protect:

[Enable Password]	
New:	Enable Password
Confirm:	

Password Protect:

[Change Password]-	
New:	Change Bassword
Confirm:	Change Password

4.3.4 Change device ID:

Please key in the Device ID you prefer, and then press the "Change" button.



- 4.3.5 LCD Contrast and backlight:
  - I . LCD Contrast Setting: The LCD Contrast depends on the temperature. The higher temperature is, the darker for contrast, in another word, the lower temperature is, the lighter for contrast. The reference Value: 200 at 25°C (77°F)
  - II. LCD Backlight Setting: Turn off backlight if the device is not used for the time you set. The default is 15 sec.



4.3.6 Shake mode (power saving) setting:

To enable the Shake mode, the device will be power off when there is no movement after 5 minutes (default); and it will be power on automatically when it moves again. To disable Shake mode, device will be never power off automatically.

If you turn it off manually while shake mode enables, then the shake mode will be disabled simultaneously.

-[Shake Mo	de for Power Saving	1		
OFF;	Always log.			SET
O ON;	No motion after	5	Mins. auto power	off.

#### 4.4 LOG Mode Tab:

The LOG mode of Easy Showily can be set here.

OG Mode:	4. User Define	•	Set Log Mode	
[User Define	LOG Mode ]			
1. By Time	Interval 5 s	econd/point		
C 2. By Dista	nce Interval			
3. By Head	ling Change			
4. By Spee	d Change Hir	nheet		Lowest
Valid Spe	ed for Record (km/hr) 1	00		1

There are four modes as following:

I . Walk mode:

A track point is logged per each 10 sec. or 20 m while its speed is above 1 km/hr.

LOG Mode:	1. Walk	▼ S	iet Log Mode	
- [ User Define I	.OG Mode ]			
C 1. By Time	Interval 10	second/point		
C 2. By Dista	nce Interval 20	meter/point		
3. By Head	ing Change			
C 4. By Spee	d Change	Highwart		Laurat
Valid Spe	ed for Record (km/	hr) 2000		1
6 5 Mix Mod	e (Time + Bange)			Eactory Setting

Ⅱ. Bicycle mode:

A track point is logged per each 20 sec. or 100 m while its speed is above 3 km/hr.

LOG Mode:	2. Bicycle	✓ Set Log I	Mode
- [ User Define I	LOG Mode ]		
C 1. By Time	Interval 20	second/point	
C 2. By Distant	nce Interval 100	meter/point	
C 3. By Head	ling Change		
C 4. By Spee	d Change	Highest	owert
Valid Spe	ed for Record (km/ł	r) 2000	3
6 5. Mix Mod	e (Time + Range)		Factory Setting

#### III. Car mode:

A track point is logged if each heading change is bigger 10 degrees while its speed is above 5 km/hr.

LOG Mode:	3. Car 💌	Set Log Mode
- [ User Define L	DG Mode ]	
C 1. By Time	nterval	
C 2. By Distar	ce Interval	
3. By Head	ng Change 10 Deg/point	
C 4. By Speed	Change	L server an
Valid Spe	d for Record (km/hr) 2000	5
C 5. Mix Mode	(Time + Range)	Factory Setting

IV. User define mode:

There are 5 kinds of setting for selection, including Time Interval, Distance Interval, Heading Change, Speed Change and Mix both time and distance.

LOG Mode:	4. User Define 🗾	Set Log Mode
[User Define l	OG Mode ]	
1. By Time	nterval 5 second/point	
2. By Distar	ce Interval	
3. By Head	ng Change	
4. By Spee	I Change History	Louiset
Valid Spe	ed for Record (km/hr) 100	1
C 5 Mix Mod	(Time + Banne)	Eactory Setting

#### IV.1 By Time Interval:

Auto-track logging is done by time-programming while moving at an effective speed.

[User Define LOG Mode ]     [	
C 2. By Distance Interval	
G 3. By Heading Change	
C 4. By Speed Change	Laurat
Valid Speed for Record (km/hr) 100	1
C 5. Mix Mode (Time + Range)	Factory Setting
IV.2 By Distance Interval: Auto-track logging is done by distance-programming while moving at an effective speed. [User Define LOG Mode] C 1. By Time Interval C 2. By Distance Interval C 3. By Heading Change Valid Speed Change Valid Speed for Record (km/hr) 100 C 5. Mix Mode [Time + Bance] Eactory Setting

#### IV.3 By Heading Change:

Auto-track logging is done by programming of course change while moving at an effective speed

[User Define LOG Mode ]	
C 1. By Time Interval	
C 2. By Distance Interval	
3. By Heading Change 10 Deg/point	
C 4. By Speed Change Highest	Lowest
Valid Speed for Record (km/hr)	1
5. Mix Mode [Time + Hange]	Factory Setting

IV.4 By Speed Change:

4 modes of multi-speed auto-logging: While moving at 4 different speeds, track logging can be done independently by separately programming by time and distance at each speed range.

[User Define LOG Mode ]			
C 1. By Time Interval			
C 2. By Distance Interval			
C 3. By Heading Change			
4. By Speed Change Highest	High M	iddle Low	Lowest
Valid Speed for Record (km/hr) 100	70 40	10	1
Log Time Interval (second) Not LOG.	0 8	5 2	Not LOG.
C 5. Mix Mode (Time + Range)			Factory Setting

#### IV.5 Mix (Time & Range) mode:

Auto-track logging is done by either time or distance programming whenever any of these conditions is met.

- [User Define LOG Mode ]	
C 1. By Time Interval 5 second/point	
C 2. By Distance Interval 100 meter/point	
C 3. By Heading Change	
C 4. By Speed Change Hinhest	Lowest
Valid Speed for Record (km/hr) 100	1
5. Mix Mode (Time + Range)	Factory Setting

Note:

- The way point will NOT be recorded if the velocity exceeds the range of "Valid Speed for Record".
- All Log parameters will be return to the original setting when pressing the "Factory Setting" button.
- All log modes would start to record when getting position fixed (the character of "FIX" should be shown on LCD display).

# 4.5 GPS Setting Tab:

GPS Mode 3. Factory setting	-	Cold Start
[GPS Parameters ]	Auto 20./20	_[SBAS]
nx Mode /~ /	500.00	C ON C OFF
Initial Min. SVs[3~6]	4	0.57
nitial Signal Min. Strength[dBHz]	20	5E1
Vavigation Signal Min. Strength[dBHz]	15	
<sup>o</sup> Accuracy Mask[m]	100	
Accuracy Mask[m]	300	
PDOP Mask	23.0	
TDOP Mask	23.0	

 GPS Cold Start : There are two ways for cold start. Firstly, Click "Cold Start" button in Win\_Tool. Secondly, you can just press and hold the function and track buttons simultaneously, and then power on it (cold stat manually).

Both two ways can re-start GPS by cold start mode. Please be aware the cold start manually function will not work when the battery is low.

Ⅱ.GPS Mode setting:

There are 6 modes as following.

II.1 High Accuracy:

Under High Accuracy mode, you can get acquisition with most accurate, but need most time to get it successfully.

GPS Mode 1. High Accuracy	-	Cold Start
[GPS Parameters] Fix Mode 3.3	3D only 💌	[SBAS]
2D Fix Altitude[m]	500.00	Le old te old
nitial Min. SVs[3~6]	4	CET
nitial Signal Min. Strength[dBHz]	25	551
avigation Signal Min. Strength[dBHz]	20	
P Accuracy Mask[m]	50	
[Accuracy Mask[m]	50	
PDOP Mask	10.0	
TDOP Mask	10.0	

II.2 Middle Accuracy:

Under Middle Accuracy mode, you can get acquisition with more accurate, but need more time to get it successfully.

GPS Mode 2. Middle Accuracy	-	Cold Start
[GPS Parameters ] Fix Mode	3D only 💌	[SBAS]
2D Fix Altitude[m]	500.00	NE UN NE UPP
Initial Min. SVs[3~6]	4	CET
Initial Signal Min. Strength[dBHz]	25	OE I
Navigation Signal Min. Strength[dBHz]	18	
P Accuracy Mask[m]	75	
T Accuracy Mask[m]	150	
PDOP Mask	15.0	
TDOP Mask	15.0	

#### II.3 Factory Setting:

Under Factory Setting mode, you can get acquisition with average accurate by taking regular time.

GPS Mode 3. Factory setting		Cold Start
[GPS Parameters]		-1 2042 1
Fix Mode 2.4	Auto 2D/3D 💌	C ON C OFF
2D Fix Altitude[m]	500.00	32 011 32 011
Initial Min. SVs[3~6]	4	OFT
Initial Signal Min. Strength[dBHz]	20	001
Navigation Signal Min. Strength[dBHz]	15	
P Accuracy Mask[m]	100	
T Accuracy Mask[m]	300	
PDOP Mask	23.0	
TDOP Mask	23.0	

#### II .4 Middle Acquisition time:

Under Middle Acquisition time mode, you can get quicker acquisition but with worse accuracy.

[GPS Setting] GPS Mode	4. Middle Acquisit	tion time 💌	Cold Start
[GPS Parameters ]-		1 4-4- 20 /20	
Fix Mode	4	2. Auto 20730	🖲 ON 🔎 OFF
2D Fix Altitude[m]		00.00	
Initial Min. 5Vs[3"6]		3	SET
Initial Signal Min. Stre	ngtn[dBH2] Strength[dBH2]	14	
P Accuracy Mask[m]	. Suengul(db1/2)	150	
T Accuracy Mask[m]		200	
PDOP Mask		25.0	
TDOP Mask		25.0	

#### II.5 Fast Acquisition time:

Under Fast Acquisition time mode, you can get quickest acquisition, but with worst accuracy.

GPS Mode 5. Fast Acquisition t	ime 💌	Cold Start
[ GPS Parameters ] Fix Mode 2.1	Auto 2D/3D 💌	SBAS ]
2D Fix Altitude[m] Initial Min. SVs[3~6]	500.00 3	CET.
Initial Signal Min. Strength[dBHz] Navigation Signal Min. Strength[dBHz]	15 14	JEI
P Accuracy Mask[m]	200	
PDOP Mask	300 28.0	
TDOP Mask	28.0	

#### Ⅱ.6 User define:

You can adjust the setting according to the environment and your demand by yourself.

GPS Mode 6. User define	-	Cold Start
[GPS Parameters]	2. Auto 2D/3D 👻	[SBAS]
2D Fix Altitude[m]	500.00	• ON C OFF
nitial Min. SVs[3~6]	3	CET.
nitial Signal Min. Strength[dBHz]	15	5E1
lavigation Signal Min. Strength[dBHz]	14	
Accuracy Mask[m]	200	
Accuracy Mask[m]	300	
200P Mask	28.0	
FDOP Mask	28.0	

III. GPS parameters instruction:

- III.1 Fix Mode: There are three criteria for acquisition:
  - III.1.1 2D only: get acquisition faster but less accuracy. The altitude will be used by default.
  - III.1.2 Auto 2D/3D: Auto-switch 2D or 3D fix according to the current GPS signal.(suggest selecting)
  - III.1.3 3D only: get acquisition slower but greater accuracy.
- III.2 2D Fix Altitude: When the GPS positioning is under 2D situation (without altitude), the data of altitude on the track will be shown as the value you set.
- III.3 Initial Min. SVs: Set how many GPS satellites used for the initial positioning.("4" is suggested i.e. 3D fix)
- III.4 Initial Signal Min Strength: Set the GPS satellite's strength used for the initial acquisition. The bigger value is, the greater accuracy provided, but you have to spend more time for acquisition. (The value between 20 and 40 is suggested. Under 20 is worse accuracy, and over 40, sometimes you can NOT receive the signal with strength at 40 dBHz under cloudy or rainy day)
- III.5 Navigation Signal Min Strength: Set the GPS satellite's strength used after positioning. The bigger value is, the greater accuracy provided, but you have to spend more time for acquisition. (The value between 15 and 40 is suggested. Under 15 is worse accuracy, and over 40, sometimes you can NOT receive the signal with strength at 40 dBHz under cloudy or rainy day)

- III.6 PDOP Mask: When the value is bigger, the inaccuracy is greater, still you can position the GPS in the worse environment. The smaller value brings the better accuracy, but you may not be able to fix position in the worse environment. (The value between 5 and 30 is suggested.)
- III.7 TDOP Mask: When the value is bigger, the inaccuracy is greater, still you can position the GPS in the worse environment. The smaller value brings the better accuracy, but you may not be able to fix position in the worse environment. (The value between 5 and 30 is suggested.)
- III.8 P Accuracy Mask: When the value is bigger, the inaccuracy is greater; still you can position the GPS in the worse environment. The smaller value brings the better accuracy, but you may not be able to fix position in the worse environment. (The value between 50 and 300 is suggested.)
- III.9 T Accuracy Mask: When the value is bigger, the inaccuracy is greater; still you can position the GPS in the worse environment. The smaller value brings the better accuracy, but you may not be able to fix position in the worse environment. (The value between 50 and 300 is suggested.)
- III.10 SBAS: Enable/Disable SBAS function.

# 4.6 Geotagging and report functions :

- 4.6.1 Select a Log data source in the LOG Data tab.
- 4.6.2 Choose the "Photo\_Tool" in the menu bar and click the item of "Geotagging/Report" to enter the page for advanced operation.

🐞 Win_Tool ¥er:1.0.5.5 F/₩ ¥er:3.8	
Lar Photo_Tool Help	
LOcata Geotac (Report e GPS Setting	
-I LOG Data Access 1	
⊂[LOG data source]	
Transfer the LOG data format to: 1. Google Maps (*.html)	▼ Transfer
T Panoramio User number China Map	
<u>GM_20071229081641.html</u>	
Total LOG points: 2571	Clear LOG



#### I. Geotagging for JPEG photos:

- I .1 Please be aware that the time zone of device and digital camera should be the same as each other, otherwise you will not have the correct Geotagging. We suggest that you can modify the device time zone to meet the camera's one if you have taken the photos and those two time zone were different. This procedure will ensure you a correct Geotagging.
- I .1.1 Press "Load JPEG Photos" button to select photos that you want to Geotag into [JPEG Photos] area, and the Geotagging will be done according to the chosen track and device time zone (The amount of way point for the chosen track should be more than 0).
- I.2 The minimized pictures will be shown in the [Selected JPEG Photos] area if you tick the item of "Show Thumbnail". Please be aware this item would slow down the photo selecting process.

- I.1.3 The select photo which is Geotagged before will not be Geotagged again if you tick the item of "Ignore already Geotagging photo".
- I.4 If you want to auto-backup the original photos after Geotagging, please tick the item of "Generate Original back-up photo after Geotagging", and the name of the file will be "BACK\_(original file name)".

Tin Tool -Geotageis	(P)						E101
Photo URL   Selected LOG Se	chan 20071129_081641 ker	•	Record points	108	-	Map [Condinates] [Protu/URL Pointon]	1444 R945 2.5
(JPEI) Im)	Photo Talian Time	after Georgaging	Langitude	Albuda	Datum A		2
Pre_cont	9 200712-2911-2719	24.7057110.10	121.1623648	26.4	W\$5.04	-	Ser.
PK_CONLI	°G 2007122911-3054	24 7053352 N	121.1625057.6	269 m	WGS-84	REB D	and Que
C [Make Report/Google Ear	er(FAC2)/Google Mappin/146.)	with Photos (			2	ELE CODE PARAMET, AND	Earge ferroliges
Mas Photo Show Size [320 • [0 Make Report	Map Type roogkE arti(KM2) • Photo Map Photo-Tuack Map			11 8 6 8	nack Line Opech ed J	ion] Colus Opacity	viah (5

- I .2 Remove the photo in the [JPEG Photos] area:
  - I .2.1 In the [JPEG Photos] area, choose one or more photos you want to remove, and use right click function to cancel it. You also can erase it by pressing "Delete" key on the keyboard.
  - I .2.2 Right click the mouse in the [JPEG Photos] area and select "Cancel All Photos" to remove all select photos.

[JPEG Photos]

File name	_	Photo Taken Time	Latitude	Longitude	Altitude	Datum 📩
Right	Click					
PIC	Cancel	Selected Photo	4.7057110 N	121.1823664 E	246 m	WGS-84
	Cancel	All Photos				
ALLE	Pre-vie	w/Check Photo Position				
PIC_	Add/C	hange Photo Description	4.7053262 N	121.1825057 E	249 m	WGS-84
	Manua	l Geotaging (Photos)				~
<						>

- 3 Manual Geotagging: The photo can be Geotagged manually when there is no track or you want to modify the geographic coordinates.
  - I .3.1 Manual Geotagging:
    - I .3.1.1 In the Map tab, please drag the red mark on map to the correct position or switch to the coordinate tab and key in the exact Latitude (format: dd.ddddddd degree), Longitude (format: ddd.dddddd degree) and Altitude in their blank



I .3.1.2 Select a photo you want to Geotag from the [JPEG Photos] area, and use the right click function to choose "Manual Geotagging (Photos)". Now, the process is complete.

[JPEG Photos]

File name Right	Photo Taken Time	Latitude	Longitude	Altitude	Datum 🔥
PIC_(	Cancel Selected Photo Cancel All Photos	7057110 N	121.1823664 E	246 m	WGS-84
A	Pre-view/Check Photo Positi	on			
PIC_0	G Add/Change Photo Descripti	on 7053262 N	121.1825057 E	249 m	WGS-84
a the	Manual Geotaging (Photos)				
<					>

- I .3.2 Modify the geographic data of Geotagged photos:
  - I .3.2.1 Select a photo you want to modify the geographic data. Use right click function to choose "Preview/Check Photo Position in GM" item to show the present position on Google Maps, and directly drag the mark to the proper position or key in the exact Latitude (format: dd.dddddd degree), Longitude (format: dd.dddddd degree) and Altitude in their blank in Coordinates tab.



48

 3.2.2 Select a photo which can fit in with the position you modify as last step, and use the right click function to choose "Manual Geotagging (Photos)". Now, the modification is complete.

#### I. Generate a Google Earth file (\*.kmz) including photos:

- II.1 Select JPEG photos and complete the Geotagging.
- II.2 If you want to add or modify the description to photos, please select a photo in the [JPEG Photos] area, use right click function to choose "Add/Change Photo Description" item, key in the detail and press the "Complete" button.



🛬 Photo / URL Description		X
(Baba) DI Dassription:		
This is a olum biossom		
Concrete	Cancel	
0		

[JPEG Photos]

	Photo Taken Time	Latitude	Longitude	Altitude	Datum	Description	W^
'nG	2007:12:29 11:27:19	24.7057110 N	121.1823664 E	246 m	WGS-84	This is a plum	32
۶G	2007:12:29 11:30:54	24.7053262 N	121.1825057 E	249 m	WGS-84		32
<							>

- ${\rm I\hspace{-.1em}I}$  .3 Add the web picture (JEPG) or video link to the track map.
  - II .3.1 Switch to URL tab, and key in (paste) the link of web picture or video to the blank of "URL Link".
  - II.3.2 Select a correct URL type (JPEG Photo or Video).
  - II.3.3 Press the "Add URL" button.

II.3.4 The URL item will be added to the [URL Link] area.



## II.3.5 Geotag the URL item:

II .3.5.1 In the Map tab, please directly drag the red mark on map to the correct position or switch to the coordinate tab and key in the exact Latitude (format: dd.ddddddd degree), Longitude (format: ddd.ddddddd degree) and Altitude in their blank.

Map Coordinates	Map Coordinates
[Photo/URL Poistion ] Initial	[Photo/URL Poiston ] Initial
	Lahudo[Deg.] 25.048807 Norh  Corgbude(Deg.) 121.5130/5 Ext  Abhude(m) 53

II .3.5.2 Select a photo you want to Geotag from the [URL Link] area, and use the right click function to choose "Manual Geotagging (URL)". Now, the process is complete.



II.3.6 Modify the geographic data of Geotagged RUL item:

II.3.6.1 Select a URL item you want to modify the geographic data. Use right click function to choose "Preview/Check URL Position in GM" item to show the present position on Google Maps, and directly drag the mark to the proper position or key in the exact Latitude (format: dd.dddddd degree), Longitude (format: ddd.dddddd degree) and Altitude in their blank in Coordinates tab



- II.3.6.2 Select a URL item which can fit in with the position you modify as last step, and use the right click function to choose "Manual Geotagging (Photos)". Now, the modification is complete.
- II.3.7 If you want to add or modify the description to URL item, please select one in the [URL Link] area, use right click function to choose "Add/Change URL Description" item, key in the detail and press the "Complete" button.



n Photo / URL Description	
Photo/URL Description:	
This is URL item	
Complete	Cancel
1	

#### [URL Link ]

File name	Latitude	Longitude	Description	Altitude	GeoTag
http://images.google.com.tw/im	24.7057110 N	121.1823664 E	This is URL item	P	Y

II.3.8 Remove the URL item in the [URL Link] area:

- II.3.8.1 In the [URL Link] area, choose one or more items you want to remove, and use the right click function to cancel it. You also can erase it by pressing "Delete" key on the keyboard.
- II .3.8.2 Right click the mouse in the [URL link] area and select "Cancel All URL Item" to remove all items.

File name	Right Chek	Latitude	Longitude	Description	Altitude	GeoTag
ktp://mages.google	Pre Adv	acel Selected U acel All URL I -view/Check I d/Change URI nual Geotagin	RL 18em terms IRL Position . Description g (URL)	This is URL item	P	Ŷ

- II.4 Generate a Google Earth Map file including photos and URL items:
  - II.4.1 Select the Map Type as "Google Earth (KMZ)".
  - II.4.2 Select the Max. Size of photo you want to show on map.
  - II.4.3 Press the "Photo Map" button.
  - II .4.4 The Google Earth Map File (PGE\*\*\*.kmz) including photos and URL items will be shown up.

[Make Report Google Earth(FMC)/Google Maps(HTML) with Phonos ]	
Nain Report	[Tack Lize Operion]           Red.

- II.5 Generate a Google Earth Map File including photos, URL items and a track. Please be aware that the recorded point of select track (\*.tes) should be more than 0.
  - II.5.1 Select a LOG section (\*.tef).
  - II.5.2 Select the Map Type as "Google Earth (KMZ)".
  - II.5.3 Select the Max. Size of photo you want to show on map.
  - II .5.4 Select the color, transparency and width of the track line, also tick the item of "3D Track" if you want to show the track on Google Earth with height.
  - II.5.5 Press the "Photo-Track Map" button.
  - II.5.6 The Google Earth Map file (PTGE<sup>\*\*\*</sup>.kmz) including photos, URL items and a track will be shown up.
  - Note: If the time of select photos doesn't match the chosen LOG section, those photos will not be integrated into the map.

Photo URL		-			_	Mag: Coordinates	
1 Selected LOG Section	20071229_003711 14	-	Record points	101	*	[Photo/URL Pointon]	UPL_LHAD
Load JPES Photos	Thumbnal already Geotagging Photo ele Original Sackup photo	after Geotiagging					88 8408
PEG Photos [							61 <b>2</b> 6
lie name	Photo Taken Time	Latitude	Lingkide	Although	Dates m		() and
PC_0385.PG	2007 12 29 11 27 19	24.7057110 N	121.1823664 E	246 m	W\$5.84	ET A	Prins .
PC_00KJPS	20071229112054	24.70532N2 N	121.1425057 E	249 m	WOS AN	NER.	
		-				BODDE Coogle - Mil	E#14 02000 Hardway - 270-522
Make Report/Google Earth(0	C)/Google Mapu(HTHL)	with Photos ]		•			
Har Photo Show See	Map Type 1	Intel Topota Topota	Tillion (A)	-ř	rack Line Opecta	on ]	
320 · Goog	6.44(042)			P.e	d	-	
Make Report	Photo Map			9		-1 caa	war b 🔳
P	oto Junk Map (5)			24	a 3	- Opacity	-] [ 30 Tuck

II.6 Copy and Delete the Map file:

Select a file in the list and use the right click function to complete the copy or deletion process.



\* Following is a Google Earth Map including photos, URL items and a recorded track.



## I. Generate a Google Maps file (\*.html) including photos:

- III.1 Select JPEG photos and complete the Geotagging.
- III.2 If you want to add or modify the description to photos, please refer to page 49 at part II.2.
- III.3 Add the web picture (JEPG) or video link to the track map, please refer to page 50 at part II.3.
- III.4 Generate a Google Maps Map File including photos (and URL items):
  - III.4.1 Select the Map Type as "Google Maps (HTML)".
  - III.4.2 Select the Max. Size of photo you want shown on map.
  - III.4.3 Please key your exclusive "Google Maps API Key" in its blank if you want to share the map with your Blog.
  - III.4.4 Press the "Photo Map" button.
  - III.4.5 The Google Maps Map File (PGM\*\*\*.html) including photos will be shown up.

[Make Report/Google Earth(EMC)/Google Maps(HTHE] with Photos ]		
Google Maps API Key 🔕		
Mar Pedid Non-See 100 2 + Prove American State S Mala Pepol Page March 11 - Prove American State S	[Track Line Operation]  Fied []  Gramming Color Color  Bite []  Fied []  Field Map	van 18 💽

- III.5 Generate a Google Maps Map File including photos, URL items and a track. Please be aware that the recorded point of select track (\*.tes) should be more than 0.
  - III.5.1 Select a LOG Section (\*.tef).
  - III.5.2 Select the Map Type as "Google Maps (HTML)".
  - III.5.3 Select the Max. Size of photo you want to show on map.
  - III.5.4 Please key your exclusive "Google MAPS API Key" in its blank if you want to share the map with your Blog.
  - III.5.5 Select the color and width of track line, also tick the item of "Hybrid Map" if you want to use the map with both

road and satellite image.

- III.5.6 Press the "Photo-Track Map" button.
- III.5.7 The Google Maps Map File (PTGM\*\*\*.html) including photos, URL items and a track will be shown up.
- Note: If the time of select photos doesn't match the chosen LOG section, those photos will not be integrated into the map.

Noto UFL		_				Map Coordinates	
Selected LOG Section	20071225_003711.5d	-	Plecord points	120	1	[Photo-URL Pointon]	URLLINO
Load JPES Photos	Thumbnali stready Geotagging Photo are Driginal backup photo	after Geotagging					al lavel
IPEG Photos ]							NER
Ne natie	Photo Taken Time	Lathida	Longitude	Althude	Datum 🔿		ASS N
PC_036.JPG	2007 12 25 11 27 15	24.7057110 N	121 1829644	26 n	VSSA	LUN B	9- (
PC_036.PS	20171225113054	247053323	121.1825087E	245 m	WS5-84	NER.	
Maile Report Groute Fastur	M715 and MandHTML1	with Physics 1				Raton Couge - 1985	ERI GOCCO Harge-ay - IF IF IS D
Soogle Maps API Key							
Max Photo Show Size 300 J • Goog	Map Type (2)	OM 20071229083	(11.10H (V)	1	each Line Opecho	-10)	
Make Report	Photo Map			6	-	-J Color	vian 15 💌
	1			-			

III.6 Copy and Delete the Map File:

Select a file in the list and use the right click function to complete the copy or deletion process.



\* Following is a Google Maps Map including photos, URL items and a track.



- IV. Generate an analytic report for select track: Please be aware that the record points of select track (\*.tes) should be more than "0".
  - IV.1 Select a LOG Section for the generation of report (\*.tef). If the select one is Google Maps Map File (PTGM\*\*\*.html) including photos and track, it will replaced the original track map in report, and then the step IV.2 can be ignored.
  - IV.2 Select the color and width of track line, also tick the item of "Hybrid Map" if you want to use the map with both road and satellite image.
  - IV.3 Press the "Make Report" button to generate all diagrams and open <Report> page.

Photo UFL						Map Coordinates	
Selected LOG Section	20071225_003711.52		<b>Record points</b>	129	*	[Photo/URL Pointon]	URL_LHKO
Load JPCS Photos	Numbrial skeady Geologging Photo in Driginal backup photo	after Geotragging					al Inell
[JPEG Photos ]							ALK M
Filenate	Photo Taken Time	Laitude	Longitude	Athude	Datum 🗥		1000
PC_035JPG	2007/12/25/11/27/15	24.7057110 N	121.1829664 E	26 n	W\$5-84		-
PC.036.85	2007/12/25/11 30:54	24.7053352 N	121.1825087 E	245 m	WESH	ARR.	~ / '
¢		_				ROOM Coope - 108	Real access single-ay - IF IF IF IF
Maia Report Google Earli(1)	Cl/Google Maps(HTML)	with Photos ]					
Google Maps API Key:				-			
Mars Report	Map Type Map (HTML) • Photo Map	CM 2007122908	1711.0000	-[1 R	nd J	on] (2)	van js 💌
0	ottp-Track Mag					F Hybrid Map	



IV.4 In the <Report > page, please reconfirm if every chart is completed, tick some you want to add to report and key the note in the description column.

Speed	Altitude	Heading	Distance	Speed_J	Altitude_J	Heading_J	Distance_J	Track Map
🔽 Spe	ed Chart(J	loin to the	Report)					
Descript	ion							

IV.4.1 Speed Chart:



IV.4.2 Altitude Chart:



#### IV.4.3 Heading Chart:



IV.4.4 Distance Chart:



IV4.5 Chart for Speed vs. Journey:



IV.4.6 Chart for Altitude vs. Journey:



IV.4.7 Chart for Heading vs. Journey:



IV.4.8 Chart for Distance vs. Journey:



IV.4.9 Track Map:



IV.5 Press the "Create Report" button to generate the report with html format, and open the report by browser automatically.

Speed Altitude	Heading   Distance   Speed_)   Altitude_)   Heading_)   Die	istance_1 Track.Map
Track Map(Join	to the Report)	Crealer Peport
Description		<u>_</u>

The content of report includes not only above charts and map, but also the track information (please refer to the following).

Truck Information		
12 A.S.		
Device Name	(This is Demo	
Track Points		
Distance	2 21 Km(1 38 MHz)	
Total Time	B Hour 19 Manute 37 Second ( 2007-12-29T08-16:41 - 2007-12-29T08-36:18 )	
Meve Time	0 Hour 19 Mante 37 Second	
Step Time	D Hour 0 Minute 0 Second	
Avg. Speed(Total)	# 77 Emh (4.21 Mitch)	
Avg. Speed(Mave)	6 77 Kmh (4 21 M2-h)	
Max. Speed	[94, 15 Emds (58.50 Mileds)	
Max. Altitude	(0) Meters (196 85 Freits)	
Min. Altitude	53 Maters (173 SE Fests)	
Zane	40	

IV.6 Press the "Save Report" button to indicate the path for saving.

Speed Abtude Heading Distance Speed Abtude Heading D	istance_1 Track.Map
Track Map(Join to the Report)	Create Report
Description	Save Secont
	<u></u>

#### 4.7 Google Maps with Panoramio:

- I. View all nearby public photos on the Panoramio of the selected track points.
  - I .1 Tick the item of "Panoramio User number" and do not key in anything.
  - I .2 Click "Transfer" button to convert LOG data to Google Maps format and execute it via browser automatically.
  - I .3 Just click any track point icon on the Google Maps.
  - I .4 All nearby photos on the Panoramio of the selected track point will show up.

1 Transfer the LOG data forma	at to: 1. Google Maps (*.html) 🗨 Trouser
Panoramio User number	🗌 🗆 China Map 🛛 🕐
<u>GM 20071229081641.html</u>	Keep Blank



- II. View all nearby photos held by yourself on the Panoramio of the selected track points.
  - I After Geotagging your photos (Please refer to 4.6 part I), press the "Upload photo to Panoramio" button to link to Panoramio website and upload your photos.
     Please be aware that you have to register and login Panoramio before you upload photos.



 I.2 Back to Win\_Tool, tick the item of "Panoramio User number" and key in your Panoramio user number in the blank (you can find the number in the URL of your Panoramio personal page. Ex: http://www.penoramio.com/user/776596).

Transfer the LOG da	ata format to: 1. Google Maps (*.htr	ni) 💌 Transfer
🔽 Panoramio User number 🚺	776586 🗌 🗌 China Map	2 (7)
GM 20071229081641.html		

- II .3 Click "Google Maps" button to convert LOG data into Google Maps format with your Panoramio user number and execute it via browser automatically.
- II.4 Just click any track point icon on the Google Maps.
- II.5 All nearby your own photos on the Panoramio of the selected track point will show up.



# Part 7 Application of TimeMachineX

1. Download and install TimeMachineX :

Please download the TimeMachineX from Wintec website (www.wintec.com.tw) Support/GPS Application/WPL-1000, and then install it.

- 2. Instruction:
  - 2.1 Plug in the Easy Showily to PC, and execute Win\_Tool.
  - 2.2 Convert the log data to TimeMachineX format (\*.tk1)

Win_Tool Ver:1.0.5.5 F/W Ver:3.8	
Language Photo_Tool Help	
LOG Data Device Setting LOG Mode GPS Setting	
CLOG Data Access ] CLOG data source ] ⓒ Easy Showly ○ Other: Transfer the LOG data format to: 4 TimeMachineX (*.1k1) TK1 20071229001641.1k1	
, Total LOG points: 2571	Clear LOG

2.3 Execute TimeMachineX and switch to "Track Convert" page. The tk1 file should be shown up in the TK1 list.

Connection Device Set	ing 🔁 Track Convert	Tustida Con	oto Teol Configuration	
182 183 8HC Gee	ge Hass   Voud Eath   GP	CIV PLT DO M	NEA]	
TKI	Total Tracks	Total Points	Device Name	Device Isla
TK1_20071229001641	. 6	2571	Entry Showity	

NOTE: If that tk1 file doesn't show up in the TK1 list, please close TimeMachineX and repeat step 2.2 or manually copy the tk1 file to the TK1 folder under the TimeMachineX installation path (ex: C:\Program Files\Time Machine X\TK1\)

Transfer	the LOG data format to	; 4. TimeMachineX (*.tk1)	•	Transfer
Right 0	Click			
<u>TK1 20071229001</u>	Copy to Copy all to			
	Delete Delete all			

## 3. TK1 trajectory file convert

3.1 Select a tk1 file and use the right key function to convert to TK2 format. (TK2 will separates all tracks, one track one file.)

112 113 1142 Googe Hapi Voue Eath GPX COV   PLT   1x1   1MEA								
	Total Tracks	Total Points	Device Name	Device Info				
1997 30 34 34 54 54 54 54 54 54 54 54 54 5		.84	Enty Showly					

Connection Device Set	m 12	Track Carve	Tuck Editor Photo Too	200	réquisie				
1 112   113   10C   Geo	gie Hages	Voud Eath (	PK COV PLT THE INEA						
TK2	De	Zone	Time of First Point	Pei	Time	Dis	Numb	Devic.	Devic
20071229_001641.02		-08.00	2007-12-25708 16-412+08 8	105	1177	2213	1	Easy_	
20071229_003711.052		-08.88	2007-12-29700 37 112-00 0	939	123.	917	1	Easy_	
20071229_128642.02		-08.08	2007-12-29112-05-422-08-0	929	243_	917_	5	Easy_	
20071231_194505.62		-02.00	2007-12-31719-45-052-00-00	85	1013	1804	1	Easy_	
20871231_203324.62		-02.50	2007-12-31720 33 242+08 0	179	546	2845		Easy_	
20071231 232217.82		-08.00	2007-12-31723 22-172-00 0	343	6822	158	1	Easy_	
## 4. Track Editor

- 4.1 Convert the tk1 file to tk2 format first.
- 4.2 Change to "Track Editor" page, enter "Edit Track" tab and select a TK2 file you want to edit.

Cornector Device Lato	ng 🔁 Trank Co		tuck Editor 😨	Photo Taol	Configuration				
Track Report		-				e			
[1]	22								
TK2 (Switch TK3)	Description	Zone	Time of	Points	Time	Distance	Number	Device	Device
20071229_001641.92		+ 08:00	2007-12	105	1177	2213	1	Easy Sh	
20071221 083711 92		- 08.00	2007-12	939	12378	91737	1	Easy Sh.	
2007122 2000	Double Cli	ck P	2907-12	929	24396	91787	5	Easy Sh.	
20071231_194505.82		-	2907-12	85	1003	1864	1	Easy Sh.	
20071231_203324.92		+ 08.00	2007-12	178	545	2845		Easy Sh_	
20071231_232217.02		- 08.00	2007-12	343	6822	15886	1	Enty Sh.	







- 5. Report Function
  - \* Please refer to the Q&A of TimeMachineX regarding the detailed instruction
  - 5.1 Please covert the track to TK2 format first
  - 5.2 Switch to "Track Editor" page, enter "Report" subpage, choose "Track Files" tab and select a TK2 file you want to edit.
  - 5.3 Preview the report:

In each chart tab, please tick if you want to add Introduction, Chart or Comment to the report.



## 5.3.1 Track Information

Track Flat: Point: Track Map: Track | Spd +H +T | Spd +Heading-Point | Heading-Dist +Journey | All +Spd +Journey | Speed | Vector Track | Halas Report |

Naie Exp Shoreby	
Neders of Point 20	
Delavia [21.3124:-57.11146	
All Time (3 Monde 1956	wwg200743287083731 - 260742281726330
Direction Division Di	and .
The Tax	
In the Internet of Second	
Average Torestival Teresti (31.724 Dam(10.100 M	H.
Average Speed Move Taxe) 36 806 COP(22.97) M	4
Max Speed	
Max Altrada (201 Meres (271 4/8) Fe	4
Min Albude 41 Materia 134 514 Fe	N.
Tas - R.B.	
10 bantos bana banak lanak banaki bana	All transfer in the second sec
Part 0 1 200122470817155-0830 250498 32151330 54 0 0	0.0
Pare 1 0 200122010037122-0030 200002 12550300 53 1 4	14 82
Part 2 0 20012201082018-0020 2534064 121313254 51 7 7	3 28
Part 0 20011220108.07252-0620 2539655 121312255 51 2 4	2 2/2
Part 20011221082222-0830 20062 12131214 58 6 20	5 23
Page 5 0 2007 12 20100 37 252 -00.00 21.040403 121.57.0000 50 1 2	2 222
Part 0 2007 12 20100 37 372 400.00 25 040430 127 57 3050 40 5 5	2 25
Poet 7 0 2007 12 2017 01 27 392-00:00 25 04/515 121 51 0000 40 2 4	1 15
Port 8 0 2001 12 2010 27 402 -00:00 25 54/522 321 512114 48 1 2	11 73
Part 0 2001 12 20100 21 52 -00 20 21 04000 121 51 51 200 47 13 12	1 12
Part 10 0 20012231083825680 2534884 12315285 46 25 1	1 22
Feett 0 2007/12/2010/38/3/2-08/00 25/04088 12/15/2014 46 3 5	1 20
Part 10 2001 12 20100 36 427-00.00 25 3967/1 121 31288 45 12 24	1 26
Pairt1 1 2001122870139.047-00.00 25.040708 127.512422 40 41 50	4 34

## 5.3.2 Track Map:



## 5.3.3 Track:



5.3.4 The chart for Speed, Altitude and Time:



5.3.5 The chart for Speed, Heading and Points



5.3.6 The chart for Heading, Distance and Journey:



## 5.3.7 The chart for Altitude, Speed and Journey:



### 5.3.8 The pie chart for Speed:



#### 5.3.9 The vectorial picture of Track:



5.3.10 Create and save a report: you can create a report including photo link URL and save it. (Please refer to the Q&A of TimeMachineX regarding detailed instruction)



You can save the report by pressing "Report Save As" button.

Deck Malter	Add Mailor	Added Photo	Title Latitude Longs. Desin.	Physic	Hale HTML Papert
Latha	de of Photo				Fiepor Save As
24.875340					dh.
121.296102	ide of Photo				<b>A</b>
Photo Text Description	HTML				Save
	LINL	-1			report
Photo	Lister UPL	_			Wei Tee
B	cito Tille				G MAP C Satellie
		6	and the second se	3	C Hybed

- 6. Geotagging for JPEG photos:
  - Please refer to the Q&A of TimeMachineX regarding detailed instruction.
  - 6.1 Please convert the track to TK2 format first.
  - 6.2 Switch to "Photo Tool" page, enter "Photo" tab and select the folder (photos) for Geotagging.

Time Machine	K - (Plants Tavil)										. 0
Connection	Device Setting	ck Care	ver 10 Task	Edu Prot	Taal 🕸 C	intipast	-				
Photo Lund	Gunda Earth Lory	_	100		-		-				
ARCH PARTY AND	Las is Plat Provid	-	Party Library Lib	NEW LAST STUDY TO AD	In Leading Ph	10.00	A POLO	INFECTION IN	(where i		
	# _ AVRSP_skil_Populor	A	PhotoNater		Phote Pa	*	_		Photo Sc		
	# AVRUTATIOE_Programmer		PIC_0372.PG		C \Decu		Seting	Aunayh DiD	HA. 357 MB		
	III CEMO		PIC_0373.PG		C /Decu	ments and	(Setting)	(workDD	HA. 359 MB		
	Blacker of		PC_0076_PG		C'Deou	ments an	l Selegi Conten	Accept D/D	44. 155 MB		
Selec	t the folder of		PC_0376_PG		ins area	SDO	ns p	ROIOS I	ou nie a	older	
	photostate		PC_0000.PG		C-996	lecte	d 100	your p	review.		
	HIM. EP		PC 0362.PG		C Deck	-	Selling	(umph.DD)	44. 370 MB		
	MANUAL PHOTO		PC_0303.PG		C:/Decu	nets m	1 Setting	(youngh EHD)	HA. 371 MB		
	Hereiter (200)		PC.084.95		C.Vorse	events, sea	( setter)	(weekEDD)	HA		1 107
	a - waaroon		100	0.00		-	_				
Selected Photos D	water Club or House spin club haven	ont				_					
Photo Name	Picture Laken time		Lattate	Longitude	Allade	Speed	200	Datum	Image Width	truge Height	New SPS Into
PE_0372.PG	2007 12 25 08 57 57 37 3907 13 3907 13 39 30 42 42								244	124	
PIC_0374.JPG	2007 12 29 10 59 05								2440	3364	
PIC_0375.JPG	2007 12:29 10:59 40								2254	2440	
PIC_0076JPG	2007.12.29.10.59.50		-						3264	2443	
PRC_00003Pfs	20071229110857		The	s area show	rs photos	sele	cted		2445	3254	
PIC 0382./PG	2007 12 29 11 22 32			for Ger	DTagging	L			2441	3254	
PIC_0080.PG	20071229112316								3354	2448	
PIC,0304.JPG	2007 12 25 11 26 23								2264	2448	
PIC_0305.PG	2007 12 29 11 27 19								1264	2448	
Pictose Pa	20411223113054				_		_	_	104	2946	
Track Date	And the second second						_				2004 C
5.0	OuteTime	Late	ube Li	righter A	Nude	[interval]	H	Distance (n)	Speed	Pleasing	
Tusk.Data SP	2007 12 29 11 30 54	(in	ute Ita	ngkale (4	liude	[interval]	4	Datasia (d	1054	Heading	

## 6.3 Switch to "Photo Tool" page, enter "Track" tab and select a TK2 track for Geotagging.

hele Track Google Ea	th Locr									
Debis Bactup Proto eller Au	in Great aggreg	AND DECEMPT								
TK2 (Dwitch TK3)	Time of	First Point	Points	Time	Distance	Device	Devic	et.		
20071229_081641.92	2007-12-	2970816412-0800	105	1177	2213	EasyS	h.,.			
1 X.	2007.13.	39718 17 117.46.00	928	12379	\$1737	Easy S	÷			
20071229 12842 9	Select	t a track file	929	24396	91707	Easy S				
20071231_194505.84	Land do	uble click it.	85	1003	1804	Easy 5	6. C			
ected Physics Disaste Club at	Maure INPI CASH Rawl	and a								
60 Name 0072.956 0073.956 0075.956 0076.955 0076.955 0081.955 0081.955 0081.955 0081.955	Potent Taken time 2007 12:23:00:57:07 2007 12:23:00:57:07 2007 12:23:10:51:40 2007 12:23:10:51:40 2007 12:23:10:41 2007 12:23:11:08:57 2007 12:23:11:08:57 2007 12:23:11:08:57 2007 12:25:11:21:52	Lathabe	Longhula		Allade Spee	d Dun	Datun	Image Width 3254 2448 2448 2544 2544 2544 2448 2448 2	Image Height 2448 2554 2564 2440 2440 2564 2554 2554 2554 2564	New SPS In
0004.PG 2005.PG 2006.PG	2007 12 25 11 25 20 2007 12 25 11 27 19 2007 12 25 11 30 54							1264 1264 1264	2448 2448 2449	

## 6.4 After selecting a track file (TK2), TimeMachineX will start to Geptag according to time automatically.

Corrector	Deven Se	try 🔁 Tax	a Comment	Track.Editor	Photo Tool	Configu	ator				
Photo Trace Track Area Do Dona Bach	Georgie Katth) i die Och TK lie to P	Lever    the Salacta Association	us Certaged								
VAL THE	(Dwritch TK2)	Time of F	rst Point	Po	nto Time	Distance	Device	Device	rt.		
200712	29_081641.9.2	2007-12-2	970816-412-0	EQ0 101	1177	2213	Easy Sh.				
200717	29,083711 92	2007-12-2	9798:37112-0	100 939	12379	\$1737	Easy Sh				
200712	29_120642.92	2007-12-2	9T12 06 422+0	100 929	24396	91707	Easy Sh.				
200712	01_194505.sz	2007-12-3	1719-45-052-0	80 85	1003	1904	Easy Sh	d:			
Fruits Name	Doubh Cick at Hour Pictur	e right clich lunctio e Taken time	Laitude	1	inglish	Allale Speed	Die.	Datum	Image Width	Image Height	New GPS Into
PIC_0072_PIG PIC_0073_PIG PIC_0075_PIG PIC_0075_PIG PIC_0076_PIG	2007 2207 2007 2007 2007	12 29:00:57:07 12 29:00:57:57 12 29:10:59:05 12 29:10:59:05 12 29:10:59:40 12 29:10:59:50	25.0409 25.0409 24.73115 24.7257 24.7257 24.7257		12 Plates Hotbag	and		v05-84 v05-84 v05-84 v05-84 v05-84	3254 2448 2440 2354 2354	2448 3254 3254 240 240	
PIC_0381.JPG PIC_0382.JPG PIC_0380.JPG PIC_0384.JPG	2007 2007 2007 2007 2007	12 23 11 21 41 12 23 11 22 32 12 25 11 23 16 12 25 11 25 30	24.70543 24.70549 24.70599 24.70599		21.142573	240		455-84 455-84 455-84 455-84	2648 2648 3254 3254	3254 3254 3448 2448	
PIC_0085.PG	2907	1225112719	24 70571 24 70532	1	21.162366 21.162566	246 249		v55.84 v55.94	2254	2448 2449	
Track Date	(C										
Dard D	OdeTine	1011112-0010	Laikute	Longhalt	Altude	Interv	*H 19	fance [n]	Speed	Heating	_
Part 1	2007-12-297	08 37 1 22-08 00	25.040477	121 51 32	11 52	1	4		14	17	
Net 2 0	206712-297	08 37 192-08 00	25.040454	121 51 32	54	7	7		3	295	
Point 3 0	2007-12-297	08.37 212-08.00	25.048456	121 51 32	16 51	2	4		7	272	
Poet 4 0	2007-12/297	00 37 272-00 00	25.048467	121.5131	14 50	6	(10		.8	276	
Point 0	2007-12-297	08 27 292 400 00	25.040469	121.5330	8 50	1	3		3	279	
Page 6 0	2007-12-290	08.37.372+08.00	25.045498	121 51 30	50 45				12	306	
Point 7 0	2007-12-297	38 37 38 408 00	25/04/01/5	121.5130	10 40	2	4			85	

- 6.5 Convert the track including Geotagged photos to Google Earth format.
  - 6.5.1 Press the "Photo KMZ" button to create a KMZ file including photos only.
  - 6.5.2 Press the "Photo-Track KMZ" button to create a KMZ file including photos and a track.
  - 6.5.3 Press the "Track KMZ" button to create a KMZ file including a track only.

30 Track	Circles 20	Devation angle							
	Make the KMZ	  :Nie.	Multi Daw Sa	1000	1962 Anna (HC, 0372 Anna ( 3807 225 ( 0 2807 225 ( 0	1 2	Com	pleted KI	AZ file
Internet Phatest Data	in Chill ar Moure eight chill functio	el.							
Proto Name	Picture Taken time	Laltude	Longhube	Altab	Speed	Die. Dalum	Image Width	Image Height	Nava GPS Into
KC_0372.JPG	2007 12 29:00:57:07	25.040963	121.512200	4		W05-84	3264	2448	
K_0373.JPG	29071229-065757	25.048883	121.512194			W25-04	2448	3264	
C_0374.(PG	2907 12 29 10 59 05	24,731197	121 100122	135		W35-04	2440	3354	
10,0075.PG	200712291015940	24.725/18	121.100205	153		W55-04	2,54	2440	
5_0076.PG	2007 12 29 10 19 50	28.725082	121.100963	1/2		9955-04	3.54	200	
5 0001 JPG	20071225112641	24.775400	121 102624	242		WCC.M	2641	1254	
1C 0382.4PG	20071225112222	24 705490	121 10260	242		WCC.64	2441	2354	
1000.PG	20071225112215	24.705556	121 162571	263		W05.64	225.4	2442	
C.0004.PG	2007 12 25 11 26 23	24.705742	121.182353	346		WS5-64	3264	2448	
NC,0085.PG	2007 12:29 11:27 19	24,705711	121.102366	246		WS5.64	3254	2448	
PIC_0386.IPG	2007 12 29 11 30 54	24.705327	121.182508	26	_	W\$5.94	2264	2449	_
tab.0ata	liter fine	Latheb	Louiste	Land and the	Internet hit	Deteriolal	Keent	Heaters	100
#10	20071322670637112-00.00	121040475	121 11200	54			0		
and the second	10012-15-265-06-12-1-77-06-00	26.040427	274 40 3340				14	100	
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	and the second of the world.	an output	141.01.00	-	1		-		
21 J	2007 12 251 08 37 212 408 00	25.049496	121 51 3218	55	-8			272	
#f 4 0	2007-12-291-08-37 272-08-00	25.049467	121.512114	50		10		275	
0 294	2007-12/20198/27/282-00:00	25 (4046)	1,21 57 3088	50	1			479	
100 E	2007-12-297-08-37-372-08-00	25.045498	121.513050	49				306	
tee 7 0	2007-12/297/08 37 392-08:00	25/040515	121 513000	40	:/2	4	18	45	

### 7. Notes

7.1 The detailed instruction of TimeMachineX please refer to the Q&A of TimeMachineX.

Time Mathine X - (Track Conver	a					6	8 🛚
Correction Device Salt	rg 💽 Track Convert	Track Edge Photo Tool	234				
10 112 113 102 Geeg	in Maps   Visual Earth   GP	K COV PLT THE INNEA	1 0.				
Va TKI	Total Tracks	Total Points	14	desta		Device Info	
TK1_20071229001641		2571	- 10	iiy st	C Terms	CHEORIC IL.	

7.2 All functions of "Device Setting" page of TimeMachineX is NOT able to use by Easy Showily.



# Part 8 Trouble shooting

- If the vehicle enters the tunnel. The GPS signal transmits linearly down to earth and its signal is blocked out in this situation.
- GPS satellite coverage gets poor because of high-rise building or thick forest. Even though Easy Showily can receive reflected weak GPS signal, the data might be less accurate.
- The sun shade in the vehicle can partially block out GPS signal and effect good reception. The GPS satellite is under control of USA and the accuracy might vary depending on some special purpose (especially when manipulated by USA).
- After successful positioning of Easy Showily, if it is moved to another area of 500 km away it cannot be easily repositioned. This is because the firstly recorded data (position, time and number of satellites acquisitioned) is different from the new area. It will need longer time for re-positioning.
- When the low battery icon is showed, the battery is critically low and please replaces new batteries; otherwise the GPS will stop to work or lower the performance.
- Avoid placing 2 GPS devices too close during positioning.
- When the Auto-Run function is not working, please refer to MSDN-Enabling And Disabling AutoRun:

http://msdn2.microsoft.com/en-us/library/Aa969329.aspx



# 使用者說明書



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第一章 產品資訊

■ 外觀說明



# 第二章 產品特色

Easy Showily自動軌跡顯示記錄器(以下簡稱Easy Showily); 內建GPS衛星接收天線,GPS衛星接收核心採用最先進的歐洲知名ublox超高感度定位引擎ATR0625,Easy Showily具備猶如黑盒子般的 紀錄功能,用來記錄你所行走的軌跡,您可以隨時讀取所記錄下來 的資料(時間、地點)。藉由USB隨插即用介面與電腦設備連結,內 建非揮發記憶體儲存衛星資料,如衛星訊號狀態、上次使用的最後 的位置及時間。其可同時追蹤16顆定位衛星的訊號;Easy Showily 由2顆3A鹼性電池供電,不需充電且耗電量極低,您可以連續使用超 過15個小時(每秒記錄一點),若啟用Shake省電模式使用時間將可更 長。

- 使用最先進的GPS衛星定位核心(u-blox超高感度定位引擎 ATR0625)。
- 快速定位及追蹤16顆衛星的能力。
- 高追蹤衛星靈敏度:-158 dBm
- 內建SBAS解調器,不需額外硬體即可接收SBAS信號。
- 軌跡記錄功能,像一個黑盒子般記錄位置、日期與時間,只需 供給它電源即可。
- 內建軌跡讀取與設定Easy Showily的工具程式(Win\_Tool), 讓使用者能輕易的與Easy Showily溝通。
- USB隨插即用,不需安裝任何驅動程式或軟體。
- 系統需求:Windows XP® 或 Vista®。
- 建議搭配使用Internet Explorer 瀏覽器。

# 第三章 注意事項

- 全球衛星定位系統(Global Positioning System; GPS)由美 國政府所提供,有時因某種因素降低其精準度(如在戰時或刻 意封鎖某一區域時),在這種情況下,美國政府單位所做的任 何變動都可能影響GPS 設備的精準度與性能。
- 為了您的行車安全,我們強烈建議您不要於駕駛中同時操作本 裝置。
- 如果您位於建築物內,隧道或周邊有高大地形地物阻擋時,可 能會影響GPS 衛星訊號接收,此時並非表示本裝置故障。
- 不得任意更換或改裝機械結構及零件以免失去合法免執使用 權。
- 不得在飛機飛行中或炸礦遙控等敏感較高地區使用。
- 避免放置於高溫及高濕度地方太久。
- 如果發現本機異味或煙霧時請立刻關機並送服務站。
- 初次使用或久未使用時請先將Easy Showily開機後將其靜置於 收訊良好處約10~15分鐘,使其先行接收定位時所需之星曆資 料;如此於正式使用時可獲得較迅速且較佳的定位品質。

# 第四章 使用說明

- 標準包裝:
  - Easy Showily(自動軌跡顯示記錄器)
  - ▶ 鹼性AAA電池\*2
  - ➢ USB 延長線(15公分)\*1
  - ▶ 使用說明書
- Easy Showily的操作:
  - ➤ 當產品關機時,長按電源鍵即可開機,產品開機後,LCD 進入主畫面(主模式),表示GPS啟動並自動進入定位狀態。



- ▶ 在開機後若長按電源鍵,則表示將Easy Showily關機。
- 主畫面右上方出現FIX字樣表示GPS已經定位成功,若無 則表示未定位成功。



▶ 在主模式下,短按軌跡鍵(主畫面右上方出現PUSH字樣) 可立即記錄軌跡點,並標示於軌跡內。

H:150° PUSH S: 100 km/h

▶ 在主模式下,長按軌跡鍵(主畫面右上方出現NEW字樣)則 可開始另一條新的軌跡記錄。



➤ 當主畫面右下方出現空電池圖示表示電壓不足,請儘速 更換電池以免GPS降低定位效能、停止運作或影響記錄資 料之準確性。

H:150 100

在主模式下,短按電源鍵可切換不同資訊之主畫面: 1 顯示艏向與速度(GPS定位成功時):



6. 顯示目前之地區時間:(時區可由使用者自訂)



(初次使用或cold start後尚未定 位成功時)

在主模式下,長按功能鍵,則會進入設定模式;LCD將會 秀出設定畫面。



- 在設定模式下,短按電源鍵或未再進行任何操作15秒後,將回復至主模式(LCD秀主畫面)。
- 在設定模式下,短按功能鍵可切換不同之設定項。在設 定模式下,切換不同之設定項時,出現之值即為該設定 項當前之值。

1.LOG MODE 2. Shake Model B. Rec. Memory Car Λn 48.6×

在設定模式下,短按軌跡鍵可切換當前設定項之值。當 設定值變更後,離開設定模式或切換至其他設定項,即 表示選定該設定值。

1. 軌跡記錄模式設定:

步行模式、自行車模式、汽車模式、使用者自訂模 式。



2. Shake省電功能:

2. SHAKE	MODE	2. SHAKE	MODE
On		Off	

4. 顯示軌跡記錄容量:

						-	-
5	P	-	2	LAP.	-11/2	5	
	ĸ	ы				IK	YI.
P١		-					ч.
			10				
		- 4	Т	і.Г	1%		
	_	_				_	_

在主模式下,於主畫面二(顯示目前軌跡累積之里程 數)短按功能鍵會出現詢問是否將目前累積之里程數與時程歸零之選項,此時再次短按功能鍵則將目前累積之 里程數與時程同時歸零。若不欲將里程數與時程歸零則 短按電源鍵切換資訊主畫面或靜待5秒後,詢問選項將自 動取消。



- ➤ 倘若啟用Shake省電功能(Shake Mode),產品會在靜止 5分鐘(出廠預設值,時間亦可自行設定)後自動關機,直 到移動裝置時,裝置將自動開機並進行GPS定位與記錄軌 跡;倘若未啟用此則不會自動開關機。啟用Shake省電模 式時,若使用手動關機,此模式將同時關閉。
- 使用USB介面處理軌跡與設定:
  - ➢ 將Easy Showily關機。
  - ➢ 將Easy Showily連接到您的電腦之USB埠。
  - 內建的工具軟體(Win\_Tool)將自動執行;自動下載軌 跡並轉換成Google Maps格式。
  - 您亦可透過該將工具軟體軌跡轉換成其他格式以搭配其 他

軟體或設定Easy Showily功能。

更換電池:

- ➢ 將Easy Showily關機。
- ▶ 取下USB保護蓋。
- 取下電池蓋。
- ▶ 更換新電池(AAA 1.5v電池\*2;建議使用鹼性電池)。
- 確認電池安裝無誤。
- ▶ 裝回電池蓋。
- ➤ 蓋回USB保護蓋。

注意:長時間不使用Easy Showily時請移除電池,以免電池液

洩漏而導致機體損壞。

# 第五章 操作特性

- 供電後Easy Showily會自行啟動並自我測試完成後,Easy Showily之LCD會進入主畫面,表示GPS啟動,同時GPS進入自動 定位模式隨即開始接收衛星訊號,並自動進行定位追蹤。正常 在天空無遮蔽狀況下,定位約需34秒鐘。(如果內部記憶中的 位置推算資料仍有效,則只需3~33秒鐘。)定位後,將依據 使用者所選擇之記錄模式開始記錄軌跡。
- 當首次使用本產品時,將Easy Showily放置於衛星訊號良好的 環境中,大約13 分鐘內(理論值12.5分鐘)即可收到或更新 完整的星歷資料(ALMANAC)。若有任何收訊不良情形,請先 參考疑難排解,通常問題可以迎刃而解。
- Easy Showily利用內部儲存的初始資料,包含前次儲存的位置、日期/時間及衛星軌道資料,推算出目前天空所在的衛星 分佈並加以追蹤鎖定,以達到最佳的接收效果。如果內部儲存 的初始化資料不正確,或衛星軌道資料已被清除,則需要較長 的時間才能定位。但當下列狀況出現時,Easy Showily會採用 較長時間的冷開機模式:
  - 超過3個月未使用(星歷資料過舊)。
  - 與上次有效位置超過500公里。
  - Easy Showily定位後,若有啟動記錄功能,則會自動開始記錄,記錄的功能與資料如下:
    - 最多可紀錄94000筆資料。
    - ▶ 採循環式記錄。

- 單機無須其他裝置即可使用。
- 記錄資料可透過裝置內建的工具軟體(Win\_Tool)來讀 取轉換輸出格式。

記錄資料如下:

#### 1. 經度

#### 2. 緯度

94

3. 高度

4. 年、月、日、時、分、秒(UTC時間)

5. 特殊點標示

- 產品開機後,如果衛星定位成功,便開始自動記錄軌跡於產品內,您可以透過內建的工具軟體或於Easy Showily上進行記錄 模式之設定變更。本產品採圖盤式紀錄,當資料量超過94000 筆,即刪除一部份最舊的軌跡資料,使所記錄的軌跡持續維持 在最新的狀態。
- Easy Showily電池使用時間可能會依據使用情況,環境及電池 種類而有所不同。
- 使用時請盡量讓GPS天線正面朝向天空,以維持良好收訊品質。
- 使用Shake省電功能時請保持機身為水平放置,以維持震動感 測器之靈敏度。
- 更換電池時請注意需同時更換兩顆新電池以免降低效率及大幅 縮短使用時間。
- 低電量警示時,Shake功能將自動開閉以免影響震動感測器之 靈敏度而造成誤動作;若於更換新電池後仍須使用Shake功能 請重新啟用該功能。

# 第六章 存取工具軟體

 將裝置直接插入電腦端之USB埠,內建存取程式將自動執行, 接著請按下"確認"按鍵。若程式未自動執行,請至"我的電 腦"直接接點擊WIN\_TOOL圖示即可執行。

WIN_TOOL (F:)	X
這個磁碟或裝置包含數種類型的內容	
您希望 Windows 執行哪個動作?	
Win_Tool 正在使用 装置上提供的程式	^
新國片複製到我的電腦上的一個資料夾內 正在使用 Macrosoft 掃描器與數位相機精靈	
列印图片 正在使用 图片列印格靈	
₩ <b>被親影像的幻燈片秀</b> 正在使用 Windows 圖片及傳與檢視器	
View pictures 正在使用 ACDSee	
3 我的電腦 🔲	
檔案 [E] 編輯 [E] 檢視 [Y] 我的最愛 [A] 》	
③ 上一頁 · ○ · ♪ /2 搜尋 ▷ 資料夾	»
網址 🛛 🥊 我的電腦 🛛 🗸 Þ	移至
3.5 軟碟機 (A:)	^
3.5 軟磷機 (A.)	
3.5 軟碟機 (A.) ②③ SYSTEM (C.) ③③ WINGOL (G.)	
3.5 軟碟機 (A.) ② SYSTEM (C.) WINFOOL (G.)	~

2、 登錄裝置,若未設密碼保護則會直接執行步驟3。



3、 接下來程式將自動讀取軌跡並自動轉成Google Maps格式之軌 跡,並自動以瀏覽器開啟。



同時,Win\_Tool 會自動最小化並隱藏至畫面右下角。點擊Win\_Tool 圖示可回復正常操作畫面。





Win_Tool Ver:1.0.5.5 F/W Ver:3.8	
Language Photo_Tool Help	
軌跡資料   裝置設定   記錄模式   GPS 設定	
└[LGG 資料處理] └[軌跡槒來源] ☞ Easy Showily ○ 其他:	
將軌跡轉換格式爲: 1. Google Maps (*.html)	▼ 轉換
□ Panoramio User number □ 中國地圖	
GM 20071229081641 /tml	
總記錄 <b>點號</b> : 2571	諸除 LOG

- **4、** Win\_Tool操作說明:
- 4.0 軌跡檔 (\*. tes) 自動備份功能:

當Win\_Tool執行時,將會自動將目前Easy Showily內之軌跡記錄自動產生一備份檔(\*.tes)並儲存於預設路徑中。

- 4.0.1 備份檔(\*.tes)儲存路徑:系統槽:\Documents and Settings\使用者名稱\My Documents\ EASY\_SHOWILY\_LOG\_DATA\Easy Showily之裝置名稱(若未設 置裝置名稱,預設為:Easy Showily)\
- 4.0.2 備份檔(\*.tes)檔名: Back Up 軌跡記錄第一點時間(UTC).tes

#### 4.1 功能表項目:

Language Photo\_Tool Help

4.1.1 Language:

Win\_Tool操作語言介面選擇,提供英文、繁體中文、簡體 中文、德文及日文操作介面。

Language Photo_Tool	Help
1.English	
2.繁體中交	
3.簡體中交	
4.Deutsch	
5.日本語	

4.1.2 Photo\_Tool:

點選"Geotagging/Report"項目以開啟JPEG相片定位工具 與製作相片地圖及軌跡分析報告頁面;詳見4.6。

Language	Photo_Tool	Help
	Geotaggin	g / Report
	Centraggint	griveholl

4.1.3 Help:

Language	Photo_Tool	Help
		Win_Tool User Manual
		Download TimeMachineX
		MSCHART Register
		Download latest Win_Tool

- 4.1.3.1: Win\_Tool User Manual: 可開啟Win\_Tool線上使用說明網頁。
- 4.1.3.2: Download TimeMachineX: 可連結至TimeMachineX下載網頁。
- 4.1.3.3: MSCHART Register: 若製作報告功能無法正常使用時請點選此項目進行報告插件註冊後即可正常使用製作報告功能。 附註: 1.執行註冊時登錄電腦之身份需為Administrator,或
  - 1. 秋门 年前 时登球 电脑之牙伤 高两和山川川 511 4001, 或 擁有相同權限之身份。
  - 若為Vista作業系統請先關閉"使用者帳戶控制 (UAC)"後並重新開機方能執行註冊。
- 4.1.3.4: Download latest Win\_Tool: 點選該項目可下載最新版Win\_Tool。

撞 Win_Tool Ver:1.0.	6.0 F/W Yer:4.0	
Language Photo_Tool	Help	
軌跡資料 装置設定	Win_Tool User Manual	
[LOG 資料處理 ]	Download TimeMa Click Here	
[聖山明哨會米小球] (● Easu Showilu ()	MSCHART Register	
Losy Showing	Download latest Win_Tool	
Panoramio RegSv	32 3 🛛	轉換
<u>GM 20080917</u>	DllRegisterServer 在 MSCHR T20.0CX 成功。	
	確定	
總記錄點數	: 94205	- 諸除 LOG
Register MSCHART, plea	ise wait.	

# 4.2 軌跡資料分頁:

軌跡資料   裝置設定   記錄模式   GPS 設定	
- [LOG 資料處理]	
將動酵轉換格式為: 1. Google Maps (".html) □ Panoramio User number GM_20071229081641.html	▼
總記錄點數: 2571	諸除 LOG

4.2.1 清除Easy Showily裝置內所有軌跡記錄:

點擊"清除 LOG"可將裝置內記錄全部清除。



附註:

若設定清除所有紀錄時,當下一次裝置開機時需要30秒讓裝置 完全清除記錄;此時裝置上的LCD將秀出如下的訊息直到完成清 除軌跡記錄。



4.2.2 軌跡記錄轉檔:

I.指定軌跡檔來源:

I.1 從Easy Showily: (預設)

┌[軌跡檔來源]─	
Easy Showily	C 其他:

I.2 從其他備份之Easy Showily軌跡檔(\*.tes):

ー [ 軌跡檔列 C Easy Si	R源] howily (	其他:	Up_2007_12_29_00_16_41.tes	選擇軌跡檔
按下" 3	巽擇軌跔	东檔"	按鍵以選擇欲採用之軌跡	「檔。

附註:

 總記錄點數所顯示的為目前所指定之軌跡檔所記錄的總記錄 點數。

#### 總記錄點數: 2571

- [LOG 資料處理]		ere
將勧請轉換格式爲 Panoramio User number GM_20071229081641.html	Google Maps ["Hm] Google Earth ["Hm] Google Earth ["Hm] Google Earth ["Hm] TimeMachineX ["Ht] TimeMachineX ["Ht] Soluzioned ["Ht] FePaGo ["Ht] Soluzioned ["Ht]	· · · · · · · · · · · · · · · · · · ·
總記錄點數: 2571	10. Excel (".csv) 11. UTM (".txt) 12. TWD67TM2 (".txt)	<b></b> 諸除 LOG

透過下拉式選單選定欲轉檔的格式後,按下"轉換"按鍵開始 進行轉檔;在任一轉檔列表欄位中點擊滑鼠右鍵,可開啟複製 或刪除轉檔檔案之選單。

R	ight Click	
GE 2007122908	TE- VITZ GE 2007123120	13324.kmz
GE 2007122908	3711. Conv to	217.kmz
GE 2007122912 GE 2007123119	0642. 4505. Copy all to	
	Delete	
	Delete all	

Win\_Tool提供下列幾種轉檔格式:

II.1 Google Maps: 雙擊檔案即可使用瀏覽器開啟執行,建議 使用IE瀏覽器;執跡檔僅轉換成一個檔案且執跡點時間會 依據裝置時區做時間調整。

將軌跡	轉換格式爲:	1. Google Maps (*.html)	•	轉換
Panoramio User number		□ 中國地圖		
GM 20071229081641.html				

附註:

- 可勾選"Panoramio"選項以同時顯示Panoramio相片地圖; 詳見4.7。
- 若軌跡位於中國大陸可勾選"中國地圖"選項改用中國地圖。
- 3. 當單一筆軌跡超過10000點時,該筆軌跡將自動以上限10000 點分段以確保瀏覽器可完成軌跡之顯示。
- 4. 分享您的 Google Maps 格式軌跡給朋友。
  - 4.1 複製它並透過電郵軟體(例如:outlook)傳送給您的 朋友。
  - 4.2或點選該 Google Maps 執跡檔後按滑鼠右鍵開啟選單並 選擇"Mail to friend"項目寄送給您的朋友。

#	動跡轉換格式為:	1. Google Maps (*.html)	-	轉換
Panor Right Clic	< r	□ 中國地圖		
GM 20071223081	Copy to(zip) Copy to(html) Velete Velete all fail to friend			

🚰 Easy Showily tra	jectory 那什 (桃文字)
: 檔案(2) 編輯(2)	被現在 插入面 格式回 工具面 執行(法) 説明(出)
●傳送②  朝数0	D-  🛃   X 🗈 🙇   () 🚦 🌲 🔻 🖹 🦉 🖗 🕑 📑
這封郵件尚未送出	•
收件者	asa@gmail.com
副本心:	
主旨の:	Easy Showily trajectory.
附件	第日本 20071229081641.zip (52 KE)
Note: Advance browser In	Google Maps格式 軟路橋

II.2 Google Earth: 需先安裝Google Earth軟體(可於 Google Earth網站下載);會依執跡筆數自動轉換成多 個檔案且執跡點時間會依據裝置時區做時間調整。

將軌	跡轉換格式爲: 2. Google Earth (*.kmz)	▼ 轉換
		🗌 3D 軌跡
E 20071229081641.kmz	GE 20071231203324.kmz	
E 20071229083711.kmz	GE 20071231232217.kmz	
E 20071229120642.kmz		
E 20071231194505.kmz		

附註:

0000

 勾選" 3D執跡" 選項可在地圖中顯示包含高度之3D執 跡。 II.3 Virtual Earth: 變擊檔案即可開啟執行,建議使用IE瀏 覽器;僅轉換成一個檔案且軌跡點時間會依據裝置時區 做時間調整。

將動跡轉換格式為: 3. Virtual Earth (\*.htm) 🔻

轉換

VE 20071229081641.htm			

附註:

- 當單一筆軌跡超過10000點時,該筆軌跡將自動以上限 10000點分段以確保瀏覽器可完成軌跡之顯示。
- II.4 TimeMachineX: 需先安裝TimeMachineX軟體(免費下 載);僅轉換成一個檔案;詳見第七章說明。

將軌跡轉換格式為: 4. TimeMachineX(°.tk1) ▼

轉換

蘸拋

TK1 20071229001641.tk1

II.5 OziExplorer: 需先安裝OziExplorer軟體(另購);會 依軌跡筆數轉換成多個檔案,軌跡點時間為UTC時間。

將軌跡轉換格式為: 5. OziExplorer (".plt) 👤



II.6 PaPaGO: 需先安裝PaPaGO軟體(另購)或變擊檔案以記 事本開啟;僅轉換成一個檔案且軌跡點時間會依據裝置 時區做時間調整。

將軌跡轉換格式為:	6. PaPaGo (*.txt)	-	轉換

PPG	20071229081641.txt			

II.7 Signal GPX: 可上傳至支援GPX格式之GPS執跡分享網站 或應用於其他軟體;僅轉換成一個檔案,執跡點時間為 UTC時間。

	將軌跡轉換格式爲:	7. Single GPX (*.gpx)	•	轉換
PX 20071229001	<u>641.qpx</u>			

sG

II.8 Multi GPX: 可上傳至支援GPX格式之GPS軌跡分享網站或 應用於其他軟體;會依軌跡筆數轉換成多個檔案,軌跡 點時間為UTC時間。

將軌跡轉換格式爲: 8. Multi GPX (\*.gpx) 釀換 -


Ⅱ.9 NMEA: 會依軌跡筆數自動轉換成多個檔案並根據軌跡記錄資訊轉換成NMEA格式(僅含GPRMC,GPGGA)。

將軌跡轉	換格式爲: 9. NMEA (*.nmea)	▼ 轉換
NMEA 20071229001641.nmea NMEA 20071229003711.nmea NMEA 20071229040642.nmea NMEA 20071231114505.nmea	NMEA 20071231123324.nmea NMEA 20071231152217.nmea	

II.10 Excel: 會依執跡筆數自動轉換成多個檔案,且執跡點時間會依據裝置時區做時間調整。

	將動詞	轉換格式爲: 10. Excel (*.csv)	•	(  轉換
<u>csv</u>	20071229081641.csv	CSV 20071231203324.csv		
<u>csv</u>	20071229083711.csv	CSV 20071231232217.csv		
CSV	20071229120642.csv			
<u>csv</u>	20071231194505.csv			

II.11 世界橫參卡脫投影座標(UTM): 雙擊檔案可以記事本開 啟,會依執跡筆數自動轉換成多個檔案且執跡點時間會 依據裝置時區做時間調整。

將軌跡轉換格式爲:	11. UTM (*.txt)	-	轉換
-----------	-----------------	---	----

Ⅱ.12 TWD67TM2: 變擊檔案可以記事本開啟, 會依軌跡筆數自 動轉換成多個檔案。

將軌跡轉換格式為: 12. TWD67TM2 (\*.txt) 🔻

轉換

M2 20071231232217.txt

4.2.3 Win\_Tool版本更新:

當Win\_Tool偵測到Easy showily上之Win\_Tool不是最新版 本時,會出現"下載最新版Win\_Tool"之按鍵,可直接按 下該按鍵下載最新版Win\_Tool。

- [LOG 資料處理]	
● Easy Showily ○ 其他:	
將軌跡轉換格式爲: 1. Google Ma	ps (*.html) ▼ 轉換
□ Panoramio User number □ 中	國地圖
GM 20071229081641.html	
總記錄點數: 2571	<b></b> 諸除 LOG
	下載最新版Win_Tool

附註:

- 更新後所有的軌跡資料將被清除且所有參數設定都將回 復至原廠設定值(包含取消密碼保護)。
- 2. 更新內容詳見下載之檔案。

- I. 更新方式:
  - I.1 將下載後之更新檔解壓縮。
  - I.2 將Easy Showily插入電腦之USB埠,但不需執行 Win\_Tool。
  - I.3 直接執行更新檔資料夾內之更新工具

" Easy\_Showily\_UPDATE.exe" 。



# I.4 按下"Update"按鍵。

K Fary_Showily_UPDATE	
Warring! All data will delete and back to factory setting. Password protect will be disable	ι,
	00%
Update	
<u>*</u>	

I.5 提醒訊息:更新後所有的軌跡資料將被清除且所有 參數設定都將回復至原廠設定值(包含取消密碼保 護);若要繼續更新則按下 "OK" 鍵繼續執行, 否則請按下 "Cancel" 終止更新。



#### I.6 更新進行中

Sary_Showily_UPDATE		×
Warring! All data will dele	le and back to factory setting. Password	d protect will be disable.
		14%
	Update	

# I.7 更新結束請按下"OK"以結束更新工具程式

Warring! All data will dele	te and back to factory setting. Passwon	d protect will be disable.
	Upgade Dotal Heas ping out the device.	100 %

I.8 從電腦移除 Easy Showily。

I.9 請將 Easy Showily 開機,此時 LCD 將顯示

"Clear LOG data now.."以完成所有的更新程序,約30秒後將進入至主畫面;若LCD 未顯示 "Clear LOG data now.."請透過 Win\_Tool 進行" Clear LOG"動作;若更新後未完成" Clear LOG"動作,將會造成 Easy Showily 所記錄的軌跡 錯誤或動作異常。

## 4.3 裝置設定分頁:

動跡溶料	装置設定	記錄模式	GPS 設定	
and the second second				

_ ( 排界設定 )	
[表施單位]	[裝置時區]
1. 公制單位 📃	+8
[設置密碼]	[ 裝置名稱 ]
新密碼:	這是Demo
確認:	
[LCD 設定]	
對比	200
背光(秒)	設定
[Shake省電模式]	
◎ 開閉 Shake 省電模式;持續記錄.	設定
○ 開啓 Shake 省電模式; 靜止 5 分鐘	後自動關機.

4.3.1 系統單位:

設定裝置所使用的單位;分為公制與英制單位。

[系統單位]	
1. 公制單位	•

4.3.2 裝置時區:

使用者可依據您的需求調整裝置時區。

注意:裝置時區值將影響Easy Showily所顯示之地區時間; 及轉換軌跡檔為Google Maps, Google Earth, Virtual Earth, PaPaGO, Excel, UTM 格式時之軌跡點時及作JPEG 相片定位(Geotagging)時之參考時間。



4.3.3 設置或變更密碼:

使用者可設定裝置密碼保護;密碼長度最多為10個英文字 母或數字。當要取消密碼保護時,只要將"新密碼"及

"確認"欄位清空後再點擊"更改密碼"即可。 未設置密碼時:

- [設置密碼 ]	
新密碼:	
	設置密碼
馆記名:	

已設置密碼時:

[更改密碼]	
新密碼:	
確認	更改密碼
ALDO.	

4.3.4 設定裝置名稱:

使用者可自行設定裝置名稱。

-[裝置名稱]
這是Demo
更改

4.3.5 設定LCD 對比與背光點亮時間:

I. 設定LCD對比: LCD 對比與溫度相關, 溫度越高對比越深,

温度越低對比越淺。參考值: 200 於 25℃ (77°F)。 Ⅱ 設定[C])背光時間:設定[C])背光點亮時間。預設值15秒。



4.3.6 Shake省電模式設定:

啟用Shake省電模式,裝置會在超過5分鐘(預設值)未動 作時自動關機,直到裝置被移動才自動開機;以達省電之 功能;若關閉此模式,裝置將不會自動開關機。啟用Shake 省電模式時,若使用手動關機,此模式將同時關閉。

┌[Shake省電模式]	
◎ 關閉 Shake 省電模式; 持續記錄.	設定
○ 開啓 Shake 省電模式;靜止 5 分鐘後自動國	翻機.

## 4.4 記錄模式分頁:

可在此分頁設定Easy Showily 之軌跡記錄模式。

軌跡資料   裝置設定 記錄模式   GPS 設定	
_ [ LOG 模式 ]	
LOG 模式: 4. 使用者定義 ▼ 設定 LOG 模式	
┌[使用者定義 LOG 模式 ]	
<ul> <li>① 1.時間間隔</li> <li>5</li> <li>秒/記錄一點</li> </ul>	
C 2.移動範圍	
○ 3. 艏向變動	
C 4.速度變動	<b>马</b> /瓜清
取 <u>高速</u> 有效的記錄速度範圍(公里·小時) 100	1
C 5.混合模式(時間+範圍)	原廠設定

共分為下列四種主要模式:

I.步行模式:

當移動速度介於1~2000 km/h 時,每隔10秒或每移動20公尺 就紀錄一點。

_[LOG 模式 ]	
LOG 模式: 1. 步行 🗾 設定 LOG 模式	
○【使用者定義LOG模式】 ○【使用者定義LOG模式】 ○1.時間間隔 ○2.移動範圍 ○2.移動範圍 ○3.艏向變動 ○4.速度變動 ●4.速度變動 ●4.速度變動	最低速
有效的記錄速度範圍 (公里/小時) 2000 ● 5. 混合模式 時間+範圍)	1 原廠設定

Ⅱ. 自行車模式:

當移動速度介於 3-2000 km/h 時,每隔 20 秒或每移動 100 公尺就紀錄一點。 [LOG模式]

LOG 模式: 2. 自行車 🗾 設定 LOG 模式	
- [使用者定義 LOG 模式 ]	
<ul> <li>○ 1. km (a) a (b) (c) (c) (c) (c) (c) (c) (c) (c) (c) (c</li></ul>	
<ul> <li>3. 艏向變動</li> <li>4. 速度變動</li> </ul>	
最高速 有效的記錄速度範圍 (公里小时) [2000	最低速 3
◎ 5 退会増守 味問(新岡)	百两段定

#### Ⅲ.汽車模式:

當移動速度介於5~2000 km/h 時,當艏向變化超過10度就紀錄一點。

-[LOG 模式]			
LOG 模式:	3.汽車 👤 _	設定 LOG 模式	
<ul> <li>【使用者定義 LOI</li> <li>● 1.時間間隔</li> <li>● 2.移動範圍</li> <li>● 3.艏向奨動</li> <li>● 4.速度装動</li> <li>有效的記錄速度</li> </ul>	G 模式 ] 10 度記錄一點 最高速 範圍 (公里小時) 2000		最低速 5
● 5. 混合模式 @	時間+範圍)		原廠設定

#### IV.使用者自訂模式:

使用者自訂記錄模式包含時間間隔、距離間隔、艏向變 化、速度變化及混合時間距離間隔等五種。

- [LOG 模式 ]	
LUG 模式: 4. 使用者定義	
┌[使用者定義 LOG 模式 ]	
<ul> <li>① 1.時間間隔</li> <li>5</li> <li>秒/記錄一點</li> </ul>	
C 2.移動範圍	
C 3. 艏向變動	
C 4. 速度變動	具作演
有效的記錄速度範圍 (公里/小時) 100	1
C 5 混合模式 (時間+範圍)	原廢設定
	10110120102

IV.1 時間間隔:

當移動速度介於有效的紀錄速度範圍內,會依據設定的 時間間隔做紀錄。

[使用者定義 LOG 模式]	
C 2.移動範圍	
○ 3.艏向變動	
○ 4.速度變動 品高速	品低速
有效的記錄速度範圍(公里/小時) 100	1
C 5. 混合模式 (時間+範圍)	原廠設定

IV.2 距離間隔:

當移動速度介於有效的紀錄速度範圍內,且移動範圍超 過設定的距離間隔時就紀錄一點。

- [使用考定義   OG 模式 ]	
[ KC/17-BAC4X COOL (X-24 ]	
○ 1.時間間隔	
<ul> <li>② 2.移動範圍</li> <li>100</li> <li>公尺/記錄一點</li> </ul>	
C 3. 艏向變動	
○ 4.速度變動	
最高速	最低速
有效的記錄速度範圍(公里/小時) 100	1
○ 5. 混合模式 (時間+範圍)	原廠設定

IV.3 艏向變化:

當移動速度介於有效的紀錄速度範圍內,且艏向變化超 過設定的角度時就紀錄一點。

[视用·省ル我 LUG 快鸿]	
C 1.時間間隔	
C 2.移動範圍	
<ul> <li>③ 艏向變動</li> <li>10 度記錄一點</li> </ul>	
○ 4.速度變動	最低速
有效的記錄速度範圍(公里/小時) 100	1
C 5. 混合模式 (時間+範圍)	原廠設定

Ⅳ.4 速度變化:

速度變化模式分為四個速度區間,當移動速度介於有效 的紀錄速度範圍內,且移動速度落在而每個區間中,則 會依據相對應的時間間隔作為記錄條件。

┌ [ 使用者定義 LOG 模式 ]	
C 1.時間間隔	
C 2.移動範圍	
C 3. 艏向變動	
<ul> <li>● 4.速度變動</li> <li>母高速 高速 一般 低速 品低</li> </ul>	ŧ
有效的記錄速度範圍(公里/小時) 100 70 40 10 1	10
時間間隔(秒) 不紀錄. 10 8 5 2 不	紀錄
○ 5. 混合模式 (時間+範圍) 原M	版設定

IV.5 混合時間距離間隔:

亦即混合時間間隔與距離間隔的設定條件, 若滿足任一

個條件就紀錄一點。

ⓒ 5.混合模式 時間+≇	ē圍)	原廠設定
有效的記錄速度範圍(	公里/小時) 100	1
○ 4.速度變動	最高速	最低速
〇 3.艏向變動		
〇 2.移動範圍	100 公尺/記錄一點	
○ 1.時間間隔	5 秒/記錄一點	
┌[使用者定義 LOG 模式	1	

附註:

- "有效的紀錄速度範圍"表示當速度超過此範圍則不做任何 記錄。
- 2. "原廠設定"可將所有記錄模式參數回復成原廠設定值。
- 所有模式皆需在定位成功時才會紀錄(Easy Showily LCD顯 示"FIX")。

## 4.5 GPS設定分頁:

- 軌跡資料   裝置設定   記錄模式 G	PS 設定	
[GPS 設定] GPS 模式 3. 原廠設定	•	冷開機
[GPS 參數]	2. Auto 2D/3D 💌	[SBAS]
2D 定位時高度項[公尺] 初次定位最少衛星數[3~6]	500.00	
初次定位衛星訊號最小強度[dBHz]	20	設定
位置精度過濾值[公尺]	100	
時間精度過濾値[公尺]  PDOP過濾値	300	
TDOP過濾值	23.0	

I.GPS冷開機:可在Win\_Tool上點擊"冷開機"或直接在開機的狀態下,同時按住功能鍵與軌跡鍵後再長按電源鍵開機(低電源時將不提供硬體"冷開機"功能),即可對GPS做冷開機動作。

Ⅱ.GPS 模式設定:

共分為以下六種:

Ⅱ.1 高準確度模式:

較為嚴格的GPS定位要求,此模式下所得之定位點準確度最高;但相對的此模式下之定位時間與定位率會較低。

軌跡資料 装置設定 記錄模式 GPS 設定

[GPS 設定]	•	冷開機
GP5 快式 [] ●準備度 [GP5 參数] 定位模式 20 定位時高度項(公尺] 初次定位最少衛星數(3~6] 初次定位衛星訊就最小強度(dBH2] 定位時衛星訊就最小強度(dBH2] 位置精度過濾值(公尺] 時間構度過濾值(公尺] PDOP/微慮值	3. 3D only Y 500.00 4 25 20 50 50 10.0	冷開機 「SBAS] ののFF 設定
TDOP過濾值	10.0	

Ⅱ.2 中等準確度模式:

中等的GPS定位要求,此模式下所得之定位點準確度略遜於 高準確度模式;但相對的此模式下之定位時間與定位率會高 於高準確度模式。

- [ GPS 設定 ] GPS 模式 2. 中等準確度	•	冷闌機
[GPS 參數] 定位模式 2D 定位時高度項(公尺)	3. 3D only	SBAS ]
初次定位最少衛星數[3~6] 初次定位衛星訊號最小強度[dBHz]	4	設定
定位時衛星訊號最小速度[dbH2] 位置精度過濾値[公尺] 時間精度過濾値[公尺]	75 150	
PDOP過濾値 TDOP過濾値	15.0 15.0	

Ⅱ.3 原廠設定模式:

普通的GPS定位要求,此模式下所得之定位點準確度略遜於 中等準確度模式;但相對的此模式下之定位時間與定位率會 高於中等準確度模式。

-[GPS設定] GPS模式 3.原廠設定	•	冷開機
[GPS 参數]	2. Auto 2D/3D 💌	[SBAS]
2D 定位時高度項[公尺] 初次定位最少衛星數[3~6] 初次定位海見到難長小強度(404-1)	500.00 4 20	設定
它在時衛星訊號最小強度[dBHz] 位置精度過濾值[公尺]	15	
時間諸度過濾値[公尺] PDOP過濾値	300	
TDOF過濾值	23.0	

Ⅱ.4 中等定位速度模式:

中等的定位速度與定位率要求,此模式下之定位時間與定位 率會高於原廠設定模式;但相對的此模式下所得之定位點準 確度會略遜於原廠設定模式。

GPS 模式 4. 中等定位通	度 👤	冷開機
- [ GPS 参數 ]	2. Auto 2D/3D 💌	
2D 定位時高度項[公尺] 初次定位最少衛星數[3~6]	500.00 3	
初次定位衛星訊號最小強度[dBHz] 定位時衛星訊號最小強度[dBHz]	18	EXXE
位置精度過濾値[公尺] 時間構度過濾値[公尺]	150	
PDOP過濾值	25.0	
TDOP過濾值	25.0	

Ⅱ.5 快速定位速度模式:

要求較快的定位速度與較佳的定位率,此模式下之定位時間 與定位率會最高;但相對的此模式下所得之定位點準確度將 再避於中等定位速度模式。

[ GPS 設定 ] GPS 模式 5. 快速定位线	度 🗸	冷開機
- [ GPS 參數 ] 定位模式	2. Auto 2D/3D 💌	
2D 定位時高度項[公尺] 初次定位最少衛星數[3~6]	500.00 3	設定
初次定位衛星訊號最小強度[dBHz] 定位時衛星訊號最小強度[dBHz]	15	
回道有度過濾値[公尺] 時間猪度過濾値[公尺] PDDPS廠庫値	300	
TDOP過濾值	28.0	

Ⅱ.6 使用者定義模式:

使用者可依自己的需求與使用環境調整最合適的GPS參數。 [GPS Bpr]

[ more ]		
GPS 模式 6. 使用者定義	•	冷開機
[GPS 參數]		
定位模式	2. Auto 2D/3D 💌	
2D 定位時高度項[公尺]	500.00	
初次定位最少衛星數[3~6]	3	=1.0
初次定位衛星訊號最小強度[dBHz]	15	II.
定位時衛星訊號最小強度[dBHz]	14	
位置精度過濾値[公尺]	200	
時間精度過濾値[公尺]	300	
PDOP過濾值	28.0	
TDOPS局a值值	28.0	
	120.0	

Ⅲ. GPS 參數說明:

- Ⅲ.1 定位模式:選擇輸出的GPS定位模式;區分為以下三種:
  - Ⅲ.1.1 2D定位:較寬鬆的定位要求,只要GPS衛星訊號達到2D定 位之水準即輸出定位成功;定位速度快但準確度較差, 定位之高度項將為預設值。
  - Ⅲ.1.2 2D/3D自動切換: 會依據使用時的GPS衛星訊號自動切換 為2D或3D定位。(建議使用)
  - III.1.3 強制3D定位:較嚴謹的定位要求,GPS衛星訊號需達到3D 定位之水準才會輸出定位成功;定位速度慢但準確度較 高,定位之高度項對準確。
- III.2 2D定位時高度項: 若輸出定位為2D時,以此設定值作為固定 的計算高度。
- III.3 初次定位最少衛星數:開機後,使用於初次定位所需的最少 GPS衛星數;建議值為4顆,亦即3D定位。
- Ⅲ.4 初次定位衛星訊號最小強度:開機後,使用於初次定位時 GPS衛星所需的最低信號強度,此值越高定位準確度較高, 但亦較難定位成功;建議值20~40。
- III.5 定位時衛星訊號最小強度:定位完成後,使用於定位解算的 衛星所需之最低訊號強度,此值越高定位準確度較高,但 亦較難定位成功;建議值15~40。
- III.6 PDOP(位置幾何稀釋精度)過濾值:此值設越大,在環境較差 的情況下雖可以定位,但誤差亦會變大,相對的,此值設定 越小則積確度越高,但有效定位亦會變少;建議值5~30。
- III.7 TDOP(時間幾何稀釋精度)過濾值:此值設越大,在環境較差 的情況下雖可以定位,但誤差亦會變大,相對的,此值設定 越小則精確度越高,但有效定位亦會變少;建議值5~30。
- III.8 位置精度過濾值:設定位置精度門檻值,此值設越大,在環 境較差的情況下雖可以定位,但誤差亦會變大,相對的,此 值設定越小則精確度越高,但有效定位亦會變少;建議值50 ~300。

- III.9 時間精度過濾值:設定時間精度門檻值,此值設越大,在環境較差的情況下雖可以定位,但誤差亦會變大,相對的,此 值設定越小則精確度越高,但有效定位亦會變少;建議值50 ~300。
- Ⅲ.10 SBAS (星基輔助系統): 啟用/關閉SBAS功能。

#### 4.6 JPEG相片定位功能與製作報告功能:

4.6.1 於Win\_Tool主頁面之軌跡資料頁面選擇軌跡檔(\*.tes)。
 4.6.2 於Win\_Tool主頁面功能表點選"Photo\_Tool" \

"Geotagging/Report"項目以開啟JPEG相片定位工具與製作相 片地圖及軌跡分析報告頁面。

输 Win_Tool Yer:1.0.5.5 F/W Yer:3.8	
Lar Photo_Tool Help	
動。一科 Geotagying/Report PS 設定	
-[LOG 資料處理]	
- [軌跡檔來源 ]	
● Easy Showily ○ 其他: ①	
將軌跡轉換格式爲: 1. Google Maps (*.html)	▼ 轉換
□ Panoramio User number □ 中國地圖	
GM_20071229081641.html	
總記錄點數: 2571	諸除 LOG



- I.JPEG相片定位功能:
- I.1 按下"選入JPEG相片"按鍵以選擇欲定位之JPEG 相片定位至 [JPEG相片區]並自動依據指定之軌跡檔(\*.tes)(當軌跡點數 不為0時)與裝置時區做為參考依據對選入之JPEG 相片作定位 (Geotagging)。
  - 注意:裝置時區若與相機設定之時區不同步將無法自動完成 相片定位或定位錯誤;此時請先將裝置時區調整成與 相機設定之時區相同,以確保能對相片作正確定位。
  - I.1.1 若勾選"顯示縮圖"則會在[JPEG相片區]顯示選入相片之 縮圖;注意,此選項會使相片選入速度變慢。
  - I.1.2 若勾選"忽略已定位之相片",若選入之相片已作過定位 則略過該相片,不對其再次作定位。
  - I.2.3 若勾選"定位完成後備份原始相片",當選入之相片完成 定位時會自動於相片原始儲存路徑下自動備份原始相片; 備份相片檔名為"BACK 原始檔名"。

Tin Tool -One	HEELINE?						80
RENT URL	auteriae (2007) 229_087641 v		10844	108	-	地震 度度    相关AJFL 地理位置	hatal
all pecoline	<ul> <li>第三項第</li> <li>第二項目</li>     &lt;</ul>						
86	5.042	4.2	相求	単度			T an allow
and the second	385.JPG 200712291127	19 24.7057110N	121.1823648	26.0	W55.04		Part 2
No.	306JPG 2007122511-30	54 24.7053262 N	121.1825097.6	249 m	WESTER	REB (D	and O and
12/160/1026	H2 Goode Earth/OK2#6.Goo	de MapsHTML #				ELE CODE N'NGWAY, AND, E	terms fectrologies - 1 1000
******	HERE			1	0.000		
320 _	GoogleE wth(NAZ)			6	. <u> </u>	. #5	88 5 -
2010	ALC ADDREED						C 20 84

- I.2 移除[JPEG相片區]內之相片:
- I.2.1 在[JPEG相片區]內選擇(可多選)欲移除之相片後,按滑 鼠右鍵並選擇"Cancel Selected Photo"或直接按下鍵 盤之"Delete"鍵以移除所選擇之相片。
- I.2.2 在[JPEG相片區]內按滑鼠右鍵並選擇"Cancel All Photos"可移除[JPEG相片區]內所有的相片。

[JPEG相片區]

檔名	照相時間	緯度	經度	高度	<b>座標系約</b>
Right Cl	ick	057110 N	121.1823664 E	246 m	WGS-84
	Cancel All Photos	_			
PIC_03	Add/Change Photo Description	053262 N	121.1825057 E	249 m	WGS-84
	Manual Geotaging (Photos)				~

- I.3 手動定位相片:當軌跡點數為0(沒有軌跡檔時)或欲手動定 位相片或修改相片地理位置時可使用此功能。
  - I.3.1 手動定位相片:
    - I.3.1.1 直接將地圖分頁中地圖內之位置標示拖曳至欲定位之 位置或切換至座標分頁直接將欲寫入相片之緯度(輸入 格式:dd.dddddd 度)、經度(輸入格式: ddd ddddddd 度)及高度填入至對應欄位。

地图 座標	地園 庄標
[租片/URL地理位置] Initial	[相片/URL地理位置] Initial
	韓皮(Prog) [75:045832 [2010] [21:513205 [東(丘)] [東(丘)]

I.3.1.2 於[JPEG相片區]點選(單選)欲定位之相片後,按滑 鼠右鍵並選擇" Manual Geotagging (Photos)",完 成定位。

[JPEG相片區]

檔名	照相時間	緯度	經度	高度	座標系約
Right C	lick				
PIC_03	Cancel Selected Photo	2057110 N	121.1823664 E	246 m	WGS-84
	Cancel All Photos	_			
A	Pre-view/Check Photo Position	_			
PIC_03	Add/Change Photo Description	1053262 N	121.1825057 E	249 m	WGS-84
	Manual Geotaging (Photos)				~
<					>

I.3.2 修改已定位之相片地理位置:

I.3.2.1 點選欲修改位置之相片後按滑鼠右鍵並選擇"Preview/Check Photo Position in GM"選項將目前位置 顯示於Google Maps地圖中,再直接將地圖內之位置標 示直接拖曳至欲定位之位置或切換至座標分頁直接將 欲寫入相片之緯度(輸入格式:dd.dddddd 度)、經度 (輸入格式:ddd.dddddd 度)及高度填入至對應欄 位。

MER UPL						地圖 探護
	20071225_001641.M		1058814	105	-	相片ARL物理过量 ( PC_0363PG
all'uncontre						
(JPEG相时语)						HAR NAR
44	Statt	47	407	8.2	日間末1 へ	H BALCADAS
	Cauri Selected Photo Cauri Al Photo	4.7057115 N	121.1823664 E	245.m	WG5-84	BTTA BTTB
X	Add/Chenge Photo Desciption Manual Geotoging (Photo)	4.7053262 N	121,1625087 E	249 m	WS5-84	NER. 2
c		-			- 2	

I.3.2.2 於[JPEG相片區]點選(單選)欲修改位置之相片後, 按滑鼠右鍵並選擇" Manual Geotagging (Photos)",完成修改定位。

## Ⅱ.製作包含已定位相片之GoogleEarth檔(\*.kmz):

- Ⅱ.1 選入JPEG相片並完成定位。
- II.2 若欲對相片加入描述,於[JPEG相片區]點選(單選)欲加 入描述之相片後按滑鼠右鍵並選擇"Add/Change Photo Description"以開啟"相片/URL描述"對話框,於填入對 相片之描述後,再按下"完成",將描述加入所選擇之相片 欄位。若欲修改相片之描述,操作方式亦同。

[JPEG相片画]

檔名 Right	Click 照相時間	緯度	經度	高度	座標系約
Right	CHICK				
PIC	Cancel Selected Photo	24.7057110 N	121.1823664 E	246 m	WGS-84
	Cancel All Photos				
N	Pre-view/Check Photo Position				
PIC	Add/Change Photo Description	24.7053262 N	121.1825057 E	249 m	WGS-84
a t	Manual Geotaging (Photos)				
					$\sim$
<					>

🖢 Photo / URL Description		X
Hitta ou 1920.		
10/00/08/20		
ALC: THE FORMER		
1		
31.5	Pr:m	
	25/0	

[JPEG相片區]

	照相時間	緯度	經度	高度	座標系統	描述	^
385.JPG	2007:12:29 11:27:19	24.7057110 N	121.1823664 E	246 m	WGS-84	這是梅花	
386.JPG	2007:12:29 11:30:54	24.7053262 N	121.1825057 E	249 m	WGS-84		
<						>	1

- Ⅱ.3 在軌跡地圖中添加網路上的JPGE相片或影片連結。
  - Ⅱ.3.1 切換至URL分頁並將網路相片/影片所提供之完整連結填

入(貼入)"添加URL鏈結"之欄位。

- Ⅱ.3.2 選擇正確的URL類型(URL-JPEG相片或URL-影片)
- Ⅱ.3.3 按下"添加URL項"按鍵。
- Ⅱ.3.4 URL項目增加至URL列表中。

	相片	URL								
		3	選擇軌跡 2	20071229_0	81641.tef	•	記錄	點數 105	~	
	法		2 URL 💈	「 陸載	PEG 相片	URL	-			
	1047	m_		連結 <sup>h</sup>	ttp://imag	es.google.com.	tw/imgres?imgurl=h	ttp://p6.p.pixnet.	net/albums/use	rpi
	[URL)	(mi 🗄 )								
	檔名			緯度	緸	度	描述	高度	Geo標記	Τ
1	http://i	mages.go	oale.com.tw/im					P	N	

Ⅱ.3.5 定位URL項:

Ⅱ.3.5.1 直接將地圖分頁中地圖內之位置標示拖曳至欲定位之 位置或切換至座標分頁直接將欲寫入相片之緯度(輸入 格式:dd.dddddd 度)、經度(輸入格式: ddd.ddddddd 度)、經度(輸入格式:

地圖 座標	地圖 庄標
[相片/URL地理位置] Initial	[相片/URL地理位置] Initial
	健康(Prg) (5046857 (元N) ▼ 経費(Prg) (72.553075 東 副産(公尺) 53

II.3.5.2 於[URL鏈結區]點選(單選)欲定位之相片後,按滑 鼠右鍵並選擇" Manual Geotagging (URL)",完成 定位。

[URL 鏈結區]

檔名	Right Click	緯度	經度	描述	高度	Geo標記
http://images.goog	le.com.v/m	25 0468370 N	121.5130750 E		Ρ	Y
	√d Ca	ncel All URL Item:	item :			
	Pre-view/Check URL Position					
	Add/Change URL Description					
	Ma	nual Geotaging (U	RL)			

Ⅱ.3.6 修改已定位URL項之地理位置:

II.3.6.1 點選欲修改位置之URL項後按滑鼠右鍵並選擇"Preview/Check URL Position in GM" 選項將目前位置顯 示於Google Maps地圖中,再直接將地圖內之位置標示 直接拖曳至欲定位之位置或切換至座標分頁直接將欲 寫入URL項之緯度(輸入格式:dd.dddddd 度)、經度 (輸入格式:ddd.dddddd 度)及高度填入至對應欄 位。

HEH URL			2018 日本
	38/98538 20071229_081641.ml ·	1218 Blidt 103 -	相HAURL地理位置」 URL_LMO
atta URL 18	UPLINE PEGRAPUPL UPLINE	2	
Inur Margi	and Chick		日 白 相思報
86.	Garcel Scientel (TEL Dan Carrol 2019), Dan Carrol 2019), Dan Provinse Clinik (TEL Dan Add/Change (TEL Darington Macroal Oweniging (TEL)	第四日   第四日   第四日   9-1552   9-152   9-152   9-152   9-1552   9-	

- II.3.6.2 再次於[URL鏈結區]點選(單選)欲修改位置之URL項 後,按滑鼠右鏈並選擇" Manual Geotagging (URL)",完成修改定位。
- II.3.7 若欲對URL項目加入描述,於[URL鏈結區]點選(單選) 欲加入描述之URL項目後按滑鼠右鏈並選擇"Add/Change URL Description"以開啟"相片/URL描述"對話框,於 填入對URL項目之描述後,再按下"確定",將描述加入 所選擇之URL項目欄位。若欲修改URL項目之描述,操作方 式亦同。

[URL 鏈結區]	Click				
檔名	緯度	(程度)	描述	高度	Geo標記
http://images.google.com	Cancel Selected UF Cancel All URL Ite Pre-view/Check UF Add/Change URL Manual Geotaging	L Item 50 ms L Position Description (URL)	E	P	Y

🛬 Photo / URL Description		
相對加加措施。		
這是URL項目		
	取消	
60		

[URL 鏈結區]

檔名	緯度	經度	描述	高度	Geo標記
http://images.google.com.tw/im	25.0468370 N	121.5130750 E	這是URL項目	P	Y

Ⅱ.3.8 移除[URL鏈結區]之URL項:

- Ⅱ.3.8.1 在[URL鏈結區]中選擇(可多選)欲移除之URL項後, 按滑鼠右鍵並選擇" Cancel Selected URL Item" 或 直接按下鍵盤之" Delete" 鍵以移除所選擇之URL項。
- II.3.8.2 在[URL鏈結區]內按滑鼠右鍵並選擇" Cancel All URL Items" 可移除[URL鏈結區]所有的URL項。

[URL 鏈結區]	Clink				
檔名	Click <sub>腹</sub>	經度	描述	高度	Geo標記
Totip //mages google.com.tw/	Cancel Selected UI Cancel All URL 1s Pre-view/Check UI Add/Change URL Manual Geotaging	RL Item ems RL Position Description ; (URL)	這是URL項目	P	Y

 II.4 製作僅含已定位相片(及已定位URL項)之Google Earth地 圖檔:

Ⅱ.4.1 選擇地圖類型為"GoogleEarth (KMZ)"。

Ⅱ.4.2 選擇相片於地圖內之最大顯示尺寸。

Ⅱ.4.3 按下"相片地圖"按鍵。

Ⅱ.4.4 產生僅含相片之Google Earth地圖檔(PGE\*\*\*.kmz)。

(製作報告/告告相片之 Google Earth(OKT瘤/Google MapdHTML瘤)		
EPREAMENT ISOURCE AND IN THE AND INTERNAL AND	(1036339) E j MA.	RX 5 .

 II.5 製作包含已定位相片(及已定位URL項)與執跡之Google Earth地圖檔:當選定之執跡檔(\*.tes)記錄點數不為0時。
 II.5.1 選擇欲顯示之執跡段(\*.tef)。

- Ⅱ.5.2 選擇地圖類型為"GoogleEarth (KMZ)"。
- Ⅱ.5.3 選擇相片於地圖內之最大顯示尺寸。
- II.5.4 選擇軌跡線條顏色、透明度與寬度及是否使用3D軌跡顯示。
- Ⅱ.5.5 按下"相片軌跡地圖"按鍵。
- II.5.6 產生包含已定位相片(及已定位URL項)與執跡之Google Earth地圖檔(PTGE\*\*\*, kmz)。
- NOTE:若選入之相片時間並未包含於選擇之軌跡段記錄時間內, 該相片將不會嵌入至地圖中。

ar los		_				地圖 長標	
	第二20071225_0027111日 12日 1日月位之相片 王氏注意合辞自相片		DISE	100	1		ULLAS
IPEGREM TAK )	-		1.2.2		1		NER .
86	14942	14.7	142	82	日間おくへ		Case C
PC_DOLP	20071229112719	24.7057110 N	121.1123644	26 m	W\$5-64	1	<b>9</b>
PC DIM PC	20071225113054	34.785382N	121.1625057.6	249 m	WS544	NER.	
						Roton Guage - MERC	EFE GOOD Hardway - UTIN 12
(製作新売/約会相比2.6)	order Fastball (MC) and Konsteiler b	1 March 1 M. 10 1-					
(第11年春/他会相片26)	ogle Earth(OC)@/Google 1	Report HILLING		(4)			

Ⅱ.6 複製及刪除地圖檔:

在地圖檔列表中點選欲複製或刪除之檔案後,點擊滑鼠右鍵,可 開啟<sup>1</sup> Right Click



<包含已定位相片(及已定位URL項)與軌跡之Google Earth地圖>



#### Ⅲ. 製作包含已定位相片之Google Maps檔(\*.html):

- Ⅲ.1 選入JPEG相片並完成定位。
- Ⅲ.2 若欲對相片加入描述,操作方式如同Ⅱ.2。
- Ⅲ.3 在軌跡地圖中添加網路上的JPGE相片或影片連結,操作方式 如同Ⅱ.3。
- III.4 製作僅含已定位相片(及已定位URL項)之Google Maps地圖 檔:
  - Ⅲ.4.1 選擇地圖類型為"GoogleMaps(HTML)"。
  - Ⅲ.4.2 選擇相片於地圖內之最大顯示尺寸。
  - Ⅲ.4.3 若欲將地圖分享於您個人之部落格請填入您專屬的 Google Maps API Key。
  - Ⅲ.4.4 按下"相片地圖"按鍵。

Ⅲ.4.5 產生僅含相片之Google Earth地圖檔(PGM\*\*\*.html)。

- [製作報告/告告相片之 Google Earth(NC/瘤/Google Mape)+THL瘤 }		
Google Maps API Key		
相片最大量引尽了 地面積型 (1) [ICM Product 2 New (4)]	(#1848.84)	
120 (2) • GoogleMapo(HTML) •	5 <u> </u>	0.020022
	4	RR 10 -
MITTER HILL BARD	E	
	50 J 1 10 1 10 10	

- Ⅲ.5 製作包含已定位相片(及已定位URL項)與軌跡之Google Maps地圖檔:當選定之軌跡檔(\*.tes)記錄點數不為0時。
   Ⅲ.5.1 選擇欲顯示之軌跡段(\*.tef)。
  - Ⅲ.5.2 選擇地圖類型為"GoogleEarth (KMZ)"。
  - Ⅲ.5.3 選擇相片於地圖內之最大顯示尺寸。
  - III.5.4 若欲將地圖分享於您個人之部落格請填入您專屬的 Google Maps API Key。
  - III.5.5 選擇軌跡線條顏色、寬度及是否使用衛星/道路混合 地圖。
  - Ⅲ.5.6 按下"相片軌跡地圖"按鍵。
  - III.5.7 產生包含已定位相片(及已定位URL項)與執跡之Google Maps地圖檔(PTGM\*\*\*.html)。

NOTE:若選入之相片的時間並未包含於選擇之軌跡段記錄時間 內,該相片將不會嵌入至地圖中。

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Ⅲ.6 複製及刪除地圖檔:

在地圖檔列表中點選欲複製或刪除之檔案後,點擊滑鼠右鍵,可 開啟複製或刪除檔案之選單。



<包含已定位相片(及已定位URL項)與軌跡之Google Maps地圖>



Ⅳ. 製作軌跡分析報告:當選定之軌跡檔記錄(\*. tes)點數不為0時。

- IV.1 選擇欲製作報告之軌跡段(\*.tef);若所選擇之軌跡段已製 作包含相片與軌跡之Google Maps地圖(PTGM\*\*\*.html)則將 自動使用該相片-軌跡地圖取代報告之軌跡地圖;並可略過步 驟IV.2。
- IV.2 選擇報告內執跡地圖的執跡線條顏色、寬度及是否使用衛星/ 道路混合地圖。
- IV.3 按下"製作報告"按鍵以開啟報告圖表頁面並製作報告所需 之圖表。
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|------------|--------------------|--------------|---------------|-------|--------|------------|--------------------|
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| PC.000     | JPG 30071225113054 | 24.7053282.N | 121.1825067 E | 249 m | WISH   | NER.       |                    |
|            |                    |              |               |       |        | V Barriera |                    |



IV.4 於報告圖表頁面依序確認所有圖表皆完成繪製,並選擇是 否將該項圖表顯示於報告中(於各圖表分頁勾選加入報告 選項)及是否對該項圖表加入描述(直接將描述填入各圖 表分頁之描述欄位即可)。

速度	高度	方向	距離	速度 里程	高度 里程	方向 単程	距離 単程	動跡地圖
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☑ 速度分佈圖(加	入至報告中)
描述	

Ⅳ.4.1 速度分佈圖:



IV.4.2 高度分佈圖:



IV.4.3 方向分佈圖:



Ⅳ.4.4 距離分佈圖:



IV4.5 速度-里程分佈圖:



IV.4.6 高度-里程分佈圖:



IV.4.7 方向-里程分佈圖:



IV.4.8 距離-里程分佈圖:



#### IV.4.9 軌跡地圖:



IV.5 按下"製作報告"按鍵以產生軌跡報告(html格式),並 自動以瀏覽器開啟該軌跡報告。

速度   直度   方向   距離   速度_星程   直度_星程   方向_星程   距離_星程   動跡地面	
☑ 軟飾均圖(加入至報告中)	産会報告
操造	0

報告內容除上述分佈圖與地圖外,尚包含軌跡資訊列表。

No. 1000000000000000000000000000000000000	机器资源	
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和正本的設計	039	
總別程	91.74 Em/37.00 Mile)	
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移動時間	3 Hour 26 Manute 19 Second	
靜止時間	O Hour O Maure O Second	
平均速度(總時間)	[16.60 Em/h (16.50 Mile/h)	
平约速度(移動)	26.63 Kmh (16.58 Mieh)	
最高速度	(104.60 Kmh (64.99 Mich)	
最大高度	290 Meters (977.69 Frets)	
最小高度	-41 Meters (-134 51 Feets)	
#\$100		

IV.6 按下"儲存報告"按鍵以選擇報告儲存路徑並儲存軌跡報告。

速度   直度   方向   距離   速度_星程   直度_星程   方向_星程   話	離_星程 動跡地圖
▶ 軟篩地圖(加入至報告中)	產生報告
描述	体包括金

#### 4.7 Google Maps 結合 Panoramio 應用:

- I.檢視在您的軌跡點附近,所有登錄在Panoramio上的公開照片。
   I.1 勾選 "Panoramio User number" 且輸入欄位留空。
  - I.2 按下"轉換"按鍵以將您的軌跡轉換成Google Maps 格 式,並自動以瀏覽器開啟。
  - 1.3 點選任一在地圖上之軌跡點。
  - I.4 Panoramio會秀出所有位於您點選的軌跡點附近的公開照 片。

<ol> <li>約</li> <li>10</li> <li>10</li></ol>	. Google Maps (*.html) 📃 💌	塑换
Panoramio User number	□ 中國地圖	2
<u>GM 20071229081641.html</u>	留空	



- II. 檢視在您點選的軌跡點附近,所有在Panoramio上,屬於您個人的 照片。
  - II.1 將您的相片作定位(詳見4.6之I)後,按下Panoramio欄位 內之"Upload photo to Panoramio"按鍵以連結至Panoramio 網站,並上傳您的相片。附註:您必須先註冊並登入Panoramio 後方能上傳相片。



II.2 回到Win\_Tool,勾選 "Panoramio User number" 並在輸入欄 位填入您的Panoramio 使用者編號(您可以從Panoramio上個 人頁面的網址列中找到使用者編號;例如:

http://www.panoramio.com/user/776586)。



- II.3 再次按下"轉換"按鍵以將您的軌跡轉換成 Google Maps 格式(含有您的 Panoramio 使用者編號),並自動以瀏覽器開啟。
- Ⅱ.4 點選任一在地圖上之軌跡點。
- II.5 Panoramio即會秀出所有位於您點選的執跡點附近,您個人上 傳的照片。



# 第七章 TimeMachineX應用簡介

- 下載並安裝TimeMachineX:
  - 請至本公司網頁(www.wintec.com.tw)下載專區\GPS產品\ WPL-1000下載並安裝最新版之TimeMachineX。
- 2. 操作步驟:
  - 2.1 將EASY SHOWILY插入電腦並執行Win\_Tool.
  - 2.2 使用Win\_Tool將EASY SHOWILY之軌跡轉換為TimeMachineX之 格式(\*.tkl)

🎕 Win_Tool Ver:1.0.5.5 F/W Ver:3.8	
Language Photo_Tool Help	
軌跡資料   装置設定   記錄模式   GPS 設定	
- [LOG 資料處理] - [軌跡檔本源] ⓒ Easy Showily ○ 其他: 培動跡轉換格式爲: <mark>4 TimeMachineX [".状1]</mark> <u>TK1_20071228001641 tk1</u>	
總記錄點數: 2571	诸除 LOG

2.3 執行TimeMachineX並切換至"執跡轉換頁面",此時該tkl檔 案已出現在TKI欄位中。

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NOTE:若該檔案未出現於TK1欄位中,請關閉TimeMachineX並重複步 驟2.2或使用手動複製方式,將該tk1檔案複製到PC上TimeMachineX 之安裝路徑下之TK1資料夾內(TimeMachineX預設安裝路徑 C:\Program Files\Time Machine X\TK1\)



- 3. TK1軌跡檔轉換
- 3.1 選擇該tk1檔案後按滑鼠右鍵選擇將軌跡轉換成TK2格式;亦即 將軌跡分段。

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20071229_120642.82		-08.66	2007-12-29712-05-422-00-00	829	241	917_	5	Easy_		
20071231_194505.02		-05.66	2007-12-31719-45-052-08.00	85	1083	1804	1	Easy_		
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4. 軌跡編輯

- 4.1 需先將軌跡轉換為TK2格式。
- 4.2 將TimeMachineX切換至軌跡編輯頁面/修正軌跡項目,並選擇 欲編輯之TK2軌跡段。

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#### 4.3 開始軌跡編輯並於完成編輯後存檔

\*詳細使用說明讀詳見TimeMachineX之Q&A

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📓 : 另存為新的TK2軌跡檔。

5. 製作報告

\*詳細使用說明請詳見TimeMachineX之Q&A

5.1 需先將軌跡轉換為TK2格式。

5.2 將TimeMachineX切換至軌跡編輯頁面/製作報告/軌跡檔項目, 並選擇欲編輯之TK2軌跡段

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·	2	- 00.00	2007-12-	343	6872	15886	1	Enty Sh	

5.3 報告項目預覽:

各分析圖及軌跡地圖分頁皆可選擇是否將圖形及所填入之前言 與評論加入至報告內。



### 5.3.1 位置點:軌跡資訊總覽。

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#### 5.3.2 軌跡地圖:



#### 5.3.3 軌跡圖:



5.3.4 速度-高度-時間圖:



5.3.5 速度-方向-點數圖:



5.3.6 方向-距離-里程圖:



#### 5.3.7高度-速度-旅程圖:



5.3.8 速度分佈圖:



Speed

#### 5.3.9 軌跡向量圖:



5.3.10 製作報告與儲存:可於此頁面將網路上的相片加入至地圖 及製作報告與儲存報告。



#### 報告製作完成後,可儲存報告。

秋田楼 过度机 秋田地區 秋田田 建定石皮林管 进度方向和来 为内容和圣经 高度进度经经 建生分布 秋田央县 梨作粉色白色彩

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- 6. Jpeg相片Geotagging:
  - \*詳細使用說明請詳見TimeMachineX之Q&A
  - 6.1 需先將軌跡轉換為TK2格式。
  - 6.2 將TimeMachineX切換至相片工具頁面/相片項目以選擇欲作 GeoTagging之相片。



# 6.3 將TimeMachineX切換至相片工具頁面/執跡項目以選擇欲對選入相片作Geotagging之對應TK2執跡檔。

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## 6.4 選擇軌跡後TimeMachineX會自動依據相片時間對所選擇之相片 作Geotagging。

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## 6.5 將已完成Geotagging之相片與對應之軌跡轉換成GoogleEarth 格式。

6.5.1 僅含已定位相片之KMZ檔案。

6.5.2 包含已定位相片及選定軌跡之KMZ檔案。

6.5.3 僅含選定軌跡之KMZ檔案。

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## 7.注意事項

7.1 TimeMachineX詳細使用說明請詳見TimeMachineX之Q&A。

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## 7.2 TimeMachineX之裝置設定頁面所有功能皆無法作用於Easy



## 第八章 疑難排解

- 當位於隧道、建築物內可能會收不到任何訊號,由於GPS信號 理論上來說必須是直線方能收到。
- 在高樓林立的道路、山區樹木遮蔽天空的道路,可能會有收訊 不良的情況,雖然Easy Showily可接收反射的甚至很微弱的 GPS衛星信號,但是在此狀況下,定位的精確度也勢必會受到 一定的影響。
- 若將GPS 接收器置於車內,某些隔熱紙會阻斷GPS 訊號,影響 訊號接收品質。由於GPS 衛星是由美國政府所提供,有時因某 種因素降低其精準度(如在戰時或刻意封鎖某一區域時),在 這種情況下,定位點有可能偏離其正確的位置。
- 假設您在甲地有使用Easy Showily並且定位成功後,當您攜帶 Easy Showily且在未使用的情況下移動到乙地(超過500公 里),您的Easy Showily可能無法在乙地順利定位,主要是由 於GPS接收機根據最後的有效位置、時間、與衛星資料所算出 來的甲地的衛星與乙地的當地衛星不同,所以你可能需要較久 的時間方能順利定位並更新最後有效位置。
- 當低電壓警示圖示出現時時,請盡速更換電池,低電壓警示後 如未更換電池,將使GPS工作效能降低(無法定位、定位精確 度下降)或停止工作。
- 定位時請盡量避開同時有兩台以上GPS接收機靠近會影響收 訊。
- 使用USB連結電腦時,若無法正常使用內建存取工具存取軌跡時請先拔除裝置後再重新插入裝置。
- 若無法Auto Run請參閱MSDN: Enabling and Disabling Auto Run:

http://msdn2.microsoft.com/en-us/library/Aa969329.aspx

PK MADE IN TAIWAN