
*DeviceNet Communication
Converter*

COM-JH
[For SRZ]

Instruction Manual

- DeviceNet is a registered trademark of Open DeviceNet Vendor Association, Inc.
- Modbus is a registered trademark of Schneider Electric.
- The name of each programmable controller (PLC) means the products of each manufacturer.
- Company names and product names used in this manual are the trademarks or registered trademarks of the respective companies.
- This product has been self-tested by RKC at DeviceNet Protocol Conformance Test Software Version A-17.

Thank you for purchasing this RKC instrument. In order to achieve maximum performance and ensure proper operation of your new instrument, carefully read all the instructions in this manual. Please place this manual in a convenient location for easy reference.

SYMBOLS

WARNING

: This mark indicates precautions that must be taken if there is danger of electric shock, fire, etc., which could result in loss of life or injury.

CAUTION

: This mark indicates that if these precautions and operating procedures are not taken, damage to the instrument may result.



: This mark indicates that all precautions should be taken for safe usage.



: This mark indicates important information on installation, handling and operating procedures.



: This mark indicates supplemental information on installation, handling and operating procedures.



: This mark indicates where additional information may be located.



WARNING

- An external protection device must be installed if failure of this instrument could result in damage to the instrument, equipment or injury to personnel.
- All wiring must be completed before power is turned on to prevent electric shock, fire or damage to instrument and equipment.
- This instrument must be used in accordance with the specifications to prevent fire or damage to instrument and equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases.
- Do not touch high-voltage connections such as power supply terminals, etc. to avoid electric shock.
- RKC is not responsible if this instrument is repaired, modified or disassembled by other than factory-approved personnel. Malfunction can occur and warranty is void under these conditions.

CAUTION

- This product is intended for use with industrial machines, test and measuring equipment. (It is not designed for use with medical equipment and nuclear energy.)
- This is a Class A instrument. In a domestic environment, this instrument may cause radio interference, in which case the user may be required to take adequate measures.
- This instrument is protected from electric shock by reinforced insulation. Provide reinforced insulation between the wire for the input signal and the wires for instrument power supply, source of power and loads.
- Be sure to provide an appropriate surge control circuit respectively for the following:
 - If input/output or signal lines within the building are longer than 30 meters.
 - If input/output or signal lines leave the building, regardless the length.
- This instrument is designed for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock by operating personnel.
- All precautions described in this manual should be taken to avoid damage to the instrument or equipment.
- All wiring must be in accordance with local codes and regulations.
- All wiring must be completed before power is turned on to prevent electric shock, instrument failure, or incorrect action.

The power must be turned off before repairing work for input break and output failure including replacement of sensor, contactor or SSR, and all wiring must be completed before power is turned on again.
- To prevent instrument damage or failure, protect the power line and the input/output lines from high currents with a protection device such as fuse, circuit breaker, etc.
- Prevent metal fragments or lead wire scraps from falling inside instrument case to avoid electric shock, fire or malfunction.
- Tighten each terminal screw to the specified torque found in the manual to avoid electric shock, fire or malfunction.
- For proper operation of this instrument, provide adequate ventilation for heat dispensation.
- Do not connect wires to unused terminals as this will interfere with proper operation of the instrument.
- Turn off the power supply before cleaning the instrument.
- Do not use a volatile solvent such as paint thinner to clean the instrument. Deformation or discoloration will occur. Use a soft, dry cloth to remove stains from the instrument.
- To avoid damage to instrument display, do not rub with an abrasive material or push front panel with a hard object.
- Do not connect modular connectors to telephone line.

NOTICE

- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for purpose of illustration.
- RKC is not responsible for any damage or injury that is caused as a result of using this instrument, instrument failure or indirect damage.
- RKC is not responsible for any damage and/or injury resulting from the use of instruments made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some components have a limited service life, or characteristics that change over time.
- Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC.

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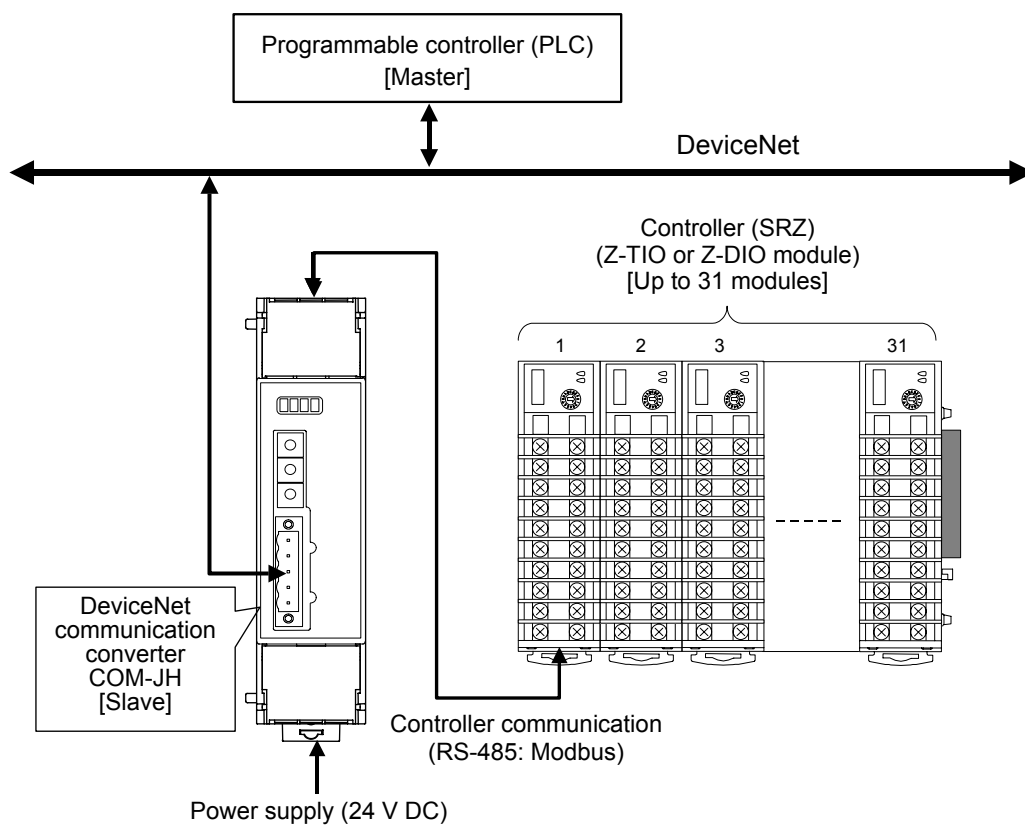
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1. OUTLINE

DeviceNet communication converter COM-JH [For SRZ] (hereafter called COM-JH) is communication converter to connect the RKC module type controller SRZ (hereafter called controller) to a programmable controller (hereafter called PLC) for DeviceNet.

This chapter describes features, package contents, model code, system configuration, etc.

- A combined total of up to 31 Z-TIO and Z-DIO modules can be connected to one COM-JH.
- On DeviceNet, a PLC is a master device, and the COM-JH is a slave device.
- There are two DeviceNet connector types: open-style connector and micro-style connector.



For DeviceNet, see the website of ODVA (Open DeviceNet Vendor Association).

URL: <http://www.odva.org>

1.1 Checking the Product

Before using this product, check each of the following:

- Model code
- Check that there are no scratch or breakage in external appearance (case, front panel, or terminal, etc.)
- Check that all of the items delivered are complete. (See below)

Accessories	Q'TY	Remarks
☐ COM-JH [For SRZ] Installation Manual (IMR01Y24-E□)	1	Enclosed with instrument
☐ COM-JH [For SRZ] Quick Operation Manual (IMR01Y28-E□)	1	Enclosed with instrument
☐ COM-JH [For SRZ] Communication Data List (IMR01Y32-E□)	1	Enclosed with instrument
☐ COM-JH [For SRZ] Instruction Manual (IMR01Y36-E1)	1	This manual (sold separately)
☐ Floppy disk (EDS file *)	1	Enclosed with instrument



If any of the products are missing, damaged, or if your manual is incomplete, please contact RKC sales office or the agent.

* EDS file

The supplied floppy disk contains the EDS file for the COM-JH.

Use the EDS file when recognizing the COM-JH on the DeviceNet by using a configurator (tool used to set a master or slave environment on the DeviceNet) of each manufacturer.



For how to use EDS file, see Configuration Tool Instruction Manual of each company or Instruction Manual of the master product.

1.2 Model Code

Check whether the delivered product is as specified by referring to the following model code list.

If the product is not identical to the specifications, please contact RKC sales office or the agent.

COM- JH - □ * 02
(1) (2)

(1) Connector type

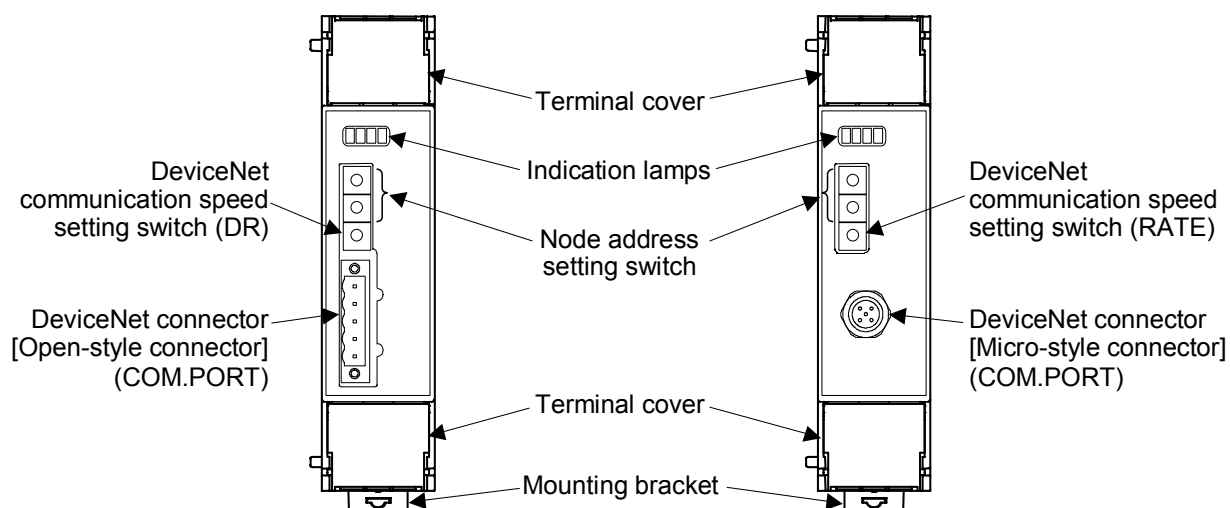
N: Open-style connector (Unshielded type)

1: Micro-style connector (Shield type)

(2) Corresponding to the RKC controller

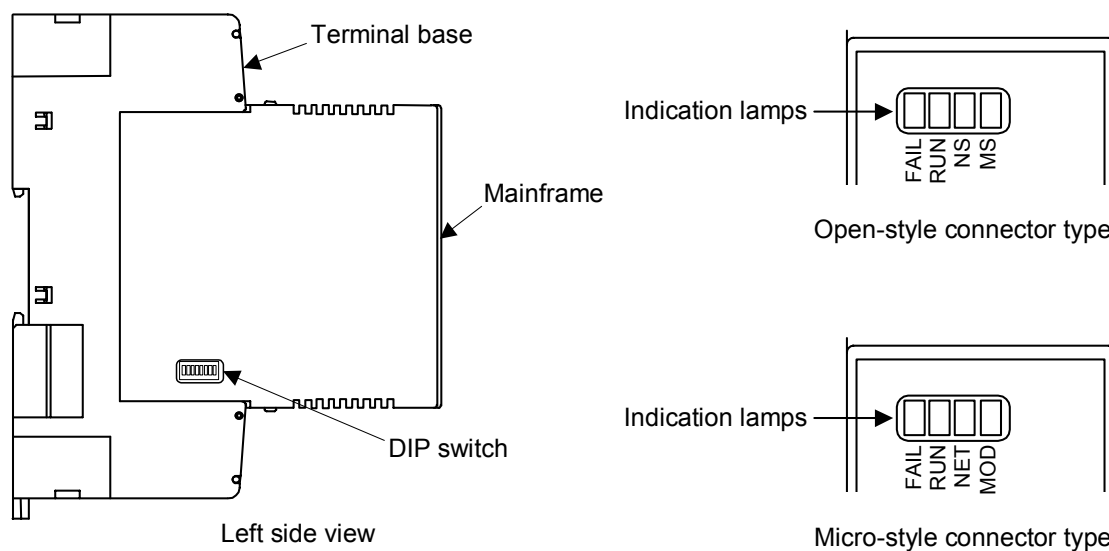
02: SRZ

1.3 Parts Description



Front view of open-style connector type

Front view of micro-style connector type



Left side view

Micro-style connector type

● Indication lamps

FAIL [Red]	- When instrument abnormally: Turns on - Communication environment setting mode by the switch: Flashes
RUN [Green]	- When normally: Turns on - Self-diagnostic error: Flashes slowly - Data collection just after the power is turned on: Flashes rapidly
NS or NET (Network status) [Green/Red]	- Network is operating normally, but communications have not yet been established: A green lamp flashes - Network is operating normally (communications established): A green lamp turns on - I/O connection is timeout: A red lamp flashes - A fatal communications error has occurred, Network communications are not possible: A red lamp turns on
MS or MOD (Module status) [Green/Red]	- When DeviceNet communication is normal: A green lamp turns on - Controller communication error: A green lamp flashes - Memory backup error: A red lamp turns on

● DeviceNet connector

COM. PORT [Open-style or Micro-style connector]	Connector for PLC (Master) connection
--	---------------------------------------

● Switches

Node address setting switch	- Set the node address for DeviceNet - Used for the PLC communication environment setting
DeviceNet communication speed setting switch	- Set the communication speed for DeviceNet - Used for the PLC communication environment setting
DIP switch	- Set the communication speed for controller communication - Set the number of polling I/O communication for DeviceNet

● Others

Terminal cover	Terminal covers above and below the COM-JH
Mounting bracket	- Used for the DIN rail mounting - When panel mounted, two mounting brackets are required for the upper and lower sides (one required for the upper side: separately sold).
Terminal base	Part of the terminal and base of COM-JH (There is the termination resistor setting switch in the inside of terminal base)
Mainframe	Part of the mainframe of COM-JH

2. HANDLING PROCEDURES

Conduct necessary setting before communication according to the procedure described below.

COM-JH
communication setting



Communication
environment setting



Mounting



Wiring and Connection



Power ON



A

Set the node address, DeviceNet communication speed, controller communication speed and number of communication words when conducting DeviceNet polling I/O communication of COM-JH.



See 5. SETTING (P. 20).

Set the Communication environment of DeviceNet polling I/O communication.



See 5.4 Communication Environment Setting by Rotary Switch (P. 23),
■ Number of communication words setting by DIP switch (P. 32),
■ Communication parameter setting by configuration tool (P. 33) or
■ Communication parameter setting by Explicit message communication (P. 43)

Mount the COM-JH, Controller and PLC.



- See 3. MOUNTING (P. 7).
- For controller (SRZ) mounting, see **Z-TIO Instruction Manual (IMS01T01-E□)**.
- For PLC mounting, see Instruction Manual for the used PLC.

Connect power supply wires to the COM-JH, and also connect the COM-JH to the controller and the COM-JH to the PLC, respectively.



- See 4. WIRING (P. 11).
- For controller (SRZ) wiring, see **Z-TIO Instruction Manual (IMS01T01-E□)**.

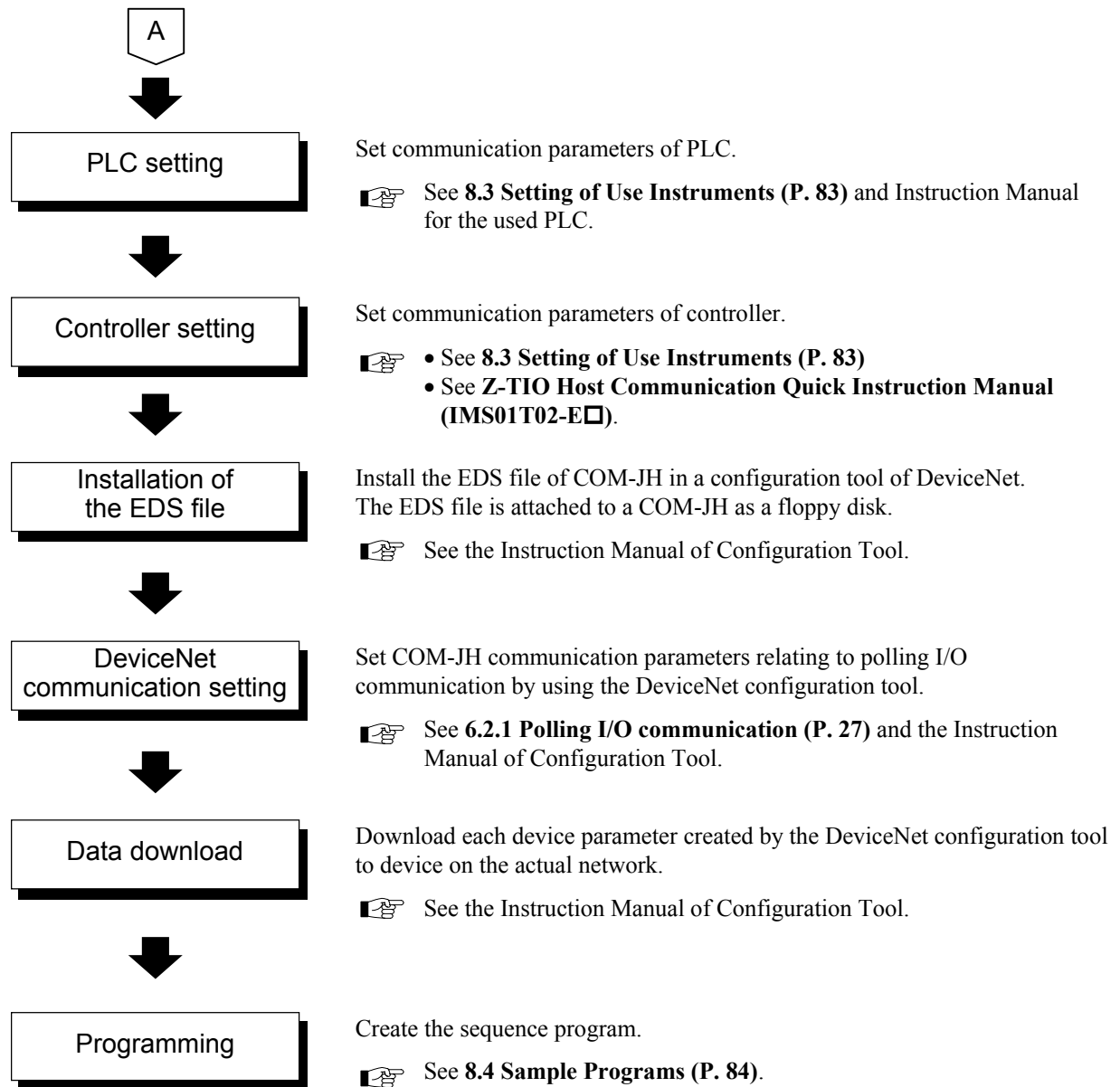


To prevent malfunctioning, turn the power on in order of DeviceNet communication, slave and master.

When turn on the power supply of DeviceNet communication, slave including COM-JH, and master (PLC etc.), the COM-JH performs as follows.

1. The COM-JH starts collecting data on each controller connected from the time when the power is turned on.
2. The RUN lamp flashed at very short intervals.
3. After data collection is finished and DeviceNet communication becomes enabled *, the RUN lamp keeps lighting.

* Time required for enabling DeviceNet communication is about 30 seconds.



3. MOUNTING

This chapter describes installation environment, mounting cautions, dimensions and mounting procedures.



WARNING

To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.

3.1 Mounting Cautions

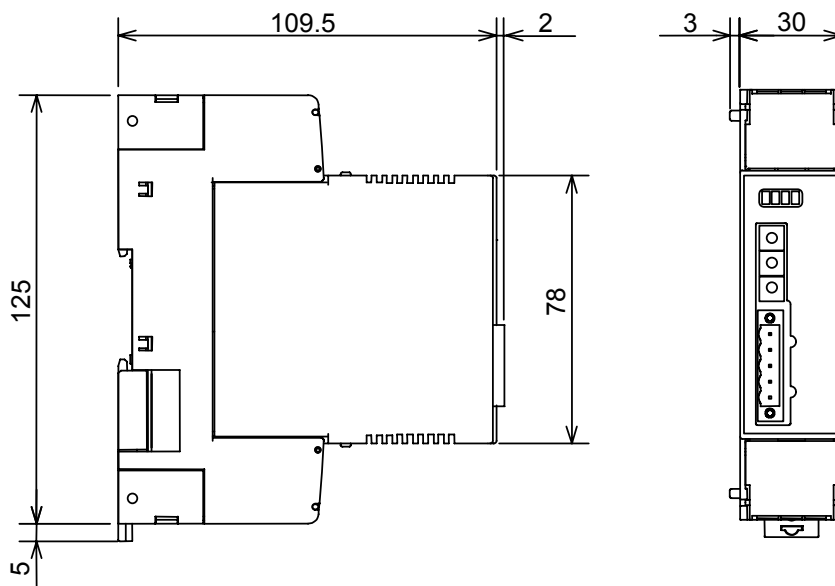
- (1) This instrument is intended to be used under the following environmental conditions. **(IEC61010-1)**
[OVERVOLTAGE CATEGORY II, POLLUTION DEGREE 2]
- (2) Use this instrument within the following environment conditions.
 - Allowable ambient temperature: -10 to $+50$ °C
 - Allowable ambient humidity: 5 to 95 % RH
(Absolute humidity: MAX.W.C 29.3 g/m^3 dry air at 101.3 kPa)
 - Installation environment conditions: Indoor use
Altitude up to 2000 m
- (3) Avoid the following conditions when selecting the mounting location.
 - Rapid changes in ambient temperature which may cause condensation.
 - Corrosive or inflammable gases.
 - Direct vibration or shock to the mainframe.
 - Water, oil, chemicals, vapor or steam splashes.
 - Excessive dust, salt or iron particles.
 - Excessive induction noise, static electricity, magnetic fields or noise.
 - Direct air flow from an air conditioner.
 - Exposure to direct sunlight.
 - Excessive heat accumulation.
- (4) Take the following points into consideration when mounting this instrument.
 - Ensure at least 50 mm space on top and bottom of the instrument for maintenance and environmental reasons.
 - Do not mount this instrument directly above equipment that generates large amount of heat (heaters, transformers, semi-conductor functional devices, large-wattage resistors).
 - If the ambient temperature rises above 50 °C, cool this instrument with a forced air fan, cooler, or the like. However, do not allow cooled air to blow this instrument directly.
 - In order to improve safety and the immunity to withstand noise, mount this instrument as far away as possible from high voltage equipment, power lines, and rotating machinery.
 - High voltage equipment: Do not mount within the same panel.
 - Power lines: Separate at least 200 mm.
 - Rotating machinery: Separate as far as possible.

(5) This instrument is permanently connected to equipment, please take the following points.

- A switch or circuit-breaker shall be included in the building installation.
- It shall be in close proximity to the equipment and within easy reach of the operator.
- It shall be marked as the disconnecting device for the equipment.

3.2 Dimensions

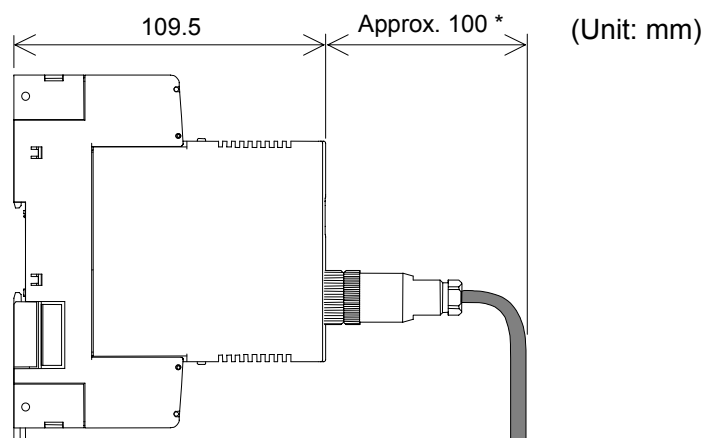
(Unit: mm)



● Depth in connector mounting

Conduct installation in consideration of the sizes of the connector and cable when connector-connected.

[Usage example of micro-style connector]

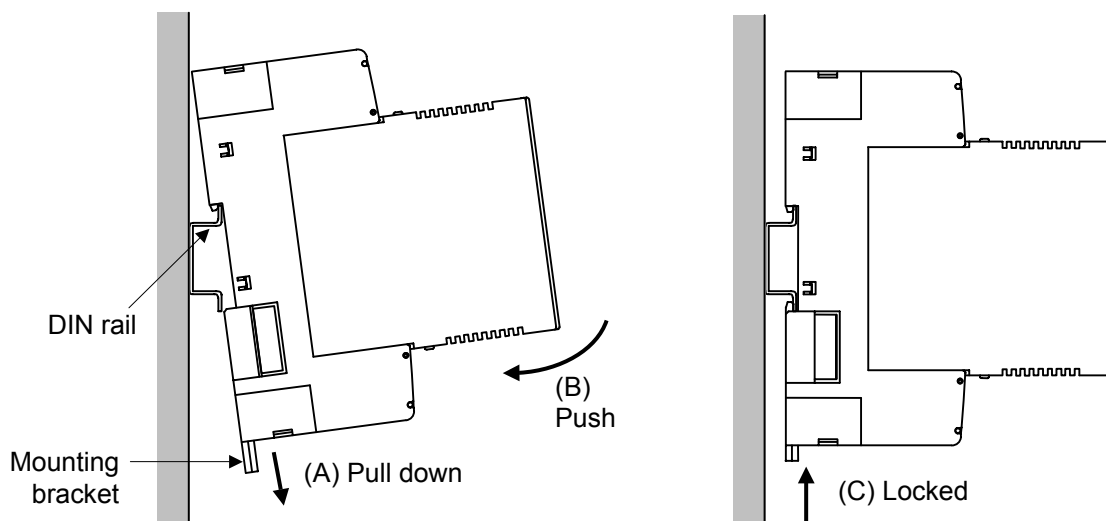


* For open-style connector: Approx. 50 mm

3.3 DIN Rail Mounting

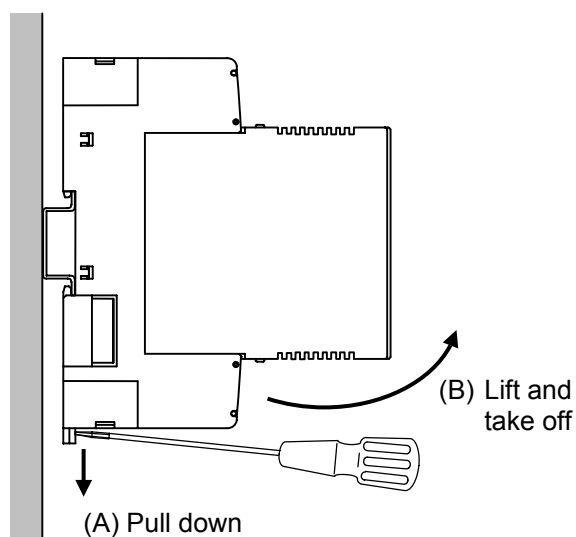
■ Mounting procedures

1. Pull down the mounting bracket at the bottom of the instrument (A). Attach the hooks on the top of the instrument to the DIN rail and push the lower section into place on the DIN rail (B).
2. Slide the mounting bracket up to secure the instrument to the DIN rail (C).



■ Removing procedures

1. Turn the power OFF.
2. Remove the wiring.
3. Pull down a mounting bracket with a blade screwdriver (A). Lift the instrument from bottom, and take it off (B).



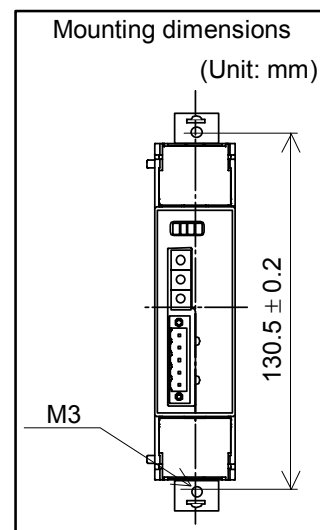
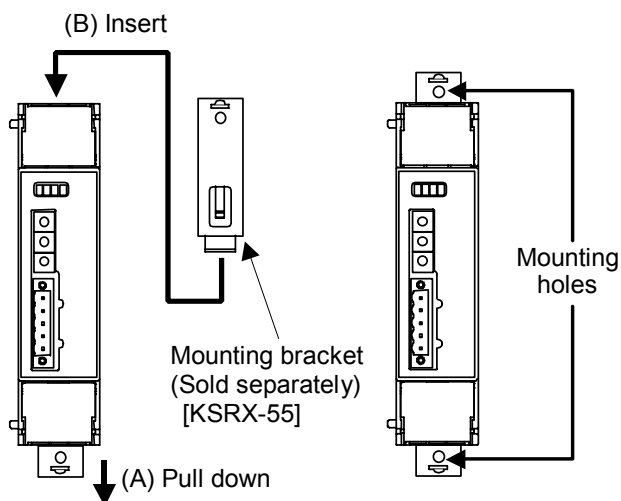
3.4 Panel Mounting

1. Pull down the mounting bracket (A) until locked and that a mounting hole appears.
2. Prepare one mounting bracket per instrument (B) sold separately (KSRX-55) and then insert it in the rear of the terminal board at top of the instrument until locked but a mounting hole does not disappear.
3. Mount each module directly on the panel with screws which are inserted in the mounting holes of the top and bottom mounting brackets.

Recommended tightening torque: 0.3 N·m (3 kgf·cm)



The customer needs to provide the M3 size screws. Select the screw length that matches the mounting panel.



4. WIRING

This chapter describes wiring cautions, wiring layout and wiring of terminals.

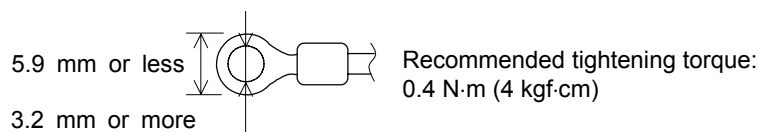
4.1 Wiring Cautions



WARNING

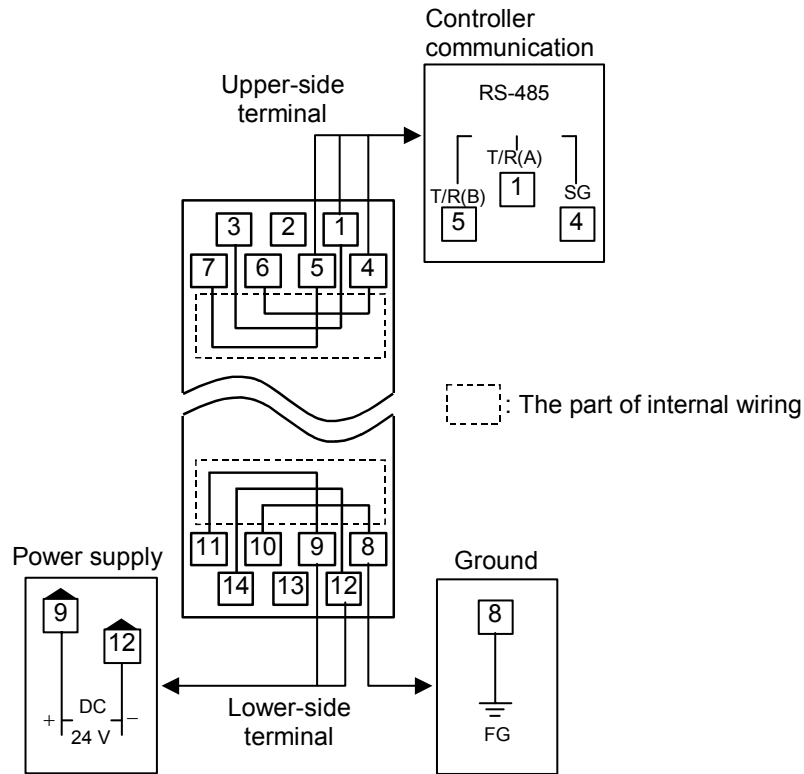
To prevent electric shock or instrument failure, do not turn on the power until all the wiring is completed.

- To avoid noise induction, keep input signal wire away from instrument power line, load lines and power lines of other electric equipment.
- If there is electrical noise in the vicinity of the instrument that could affect operation, use a noise filter.
 - Shorten the distance between the twisted power supply wire pitches to achieve the most effective noise reduction.
 - Always install the noise filter on a grounded panel. Minimize the wiring distance between the noise filter output and the instrument power supply terminals to achieve the most effective noise reduction.
 - Do not connect fuses or switches to the noise filter output wiring as this will reduce the effectiveness of the noise filter.
- Power supply wiring must be twisted and have a low voltage drop.
- For an instrument with 24 V power supply, supply power from a SELV circuit.
- A suitable power supply should be considered in the end-use equipment. The power supply must be in compliance with a limited-energy circuits (maximum available current of 8 A).
- Use the solderless terminal appropriate to the screw size (M3).



4.2 Terminal Configuration

The terminal configuration is as follows.



-  As controller communication terminal Nos. 1, 4 and 5 are internally connected to terminal Nos. 3, 6 and 7, any terminals can be used.
-  As ground and power supply terminal Nos. 8, 9 and 12 are internally connected to terminal Nos. 10, 11 and 14, any terminals can be used.
-  Terminal No. 2 and No. 13 is not used.

4.3 Connection to DeviceNet

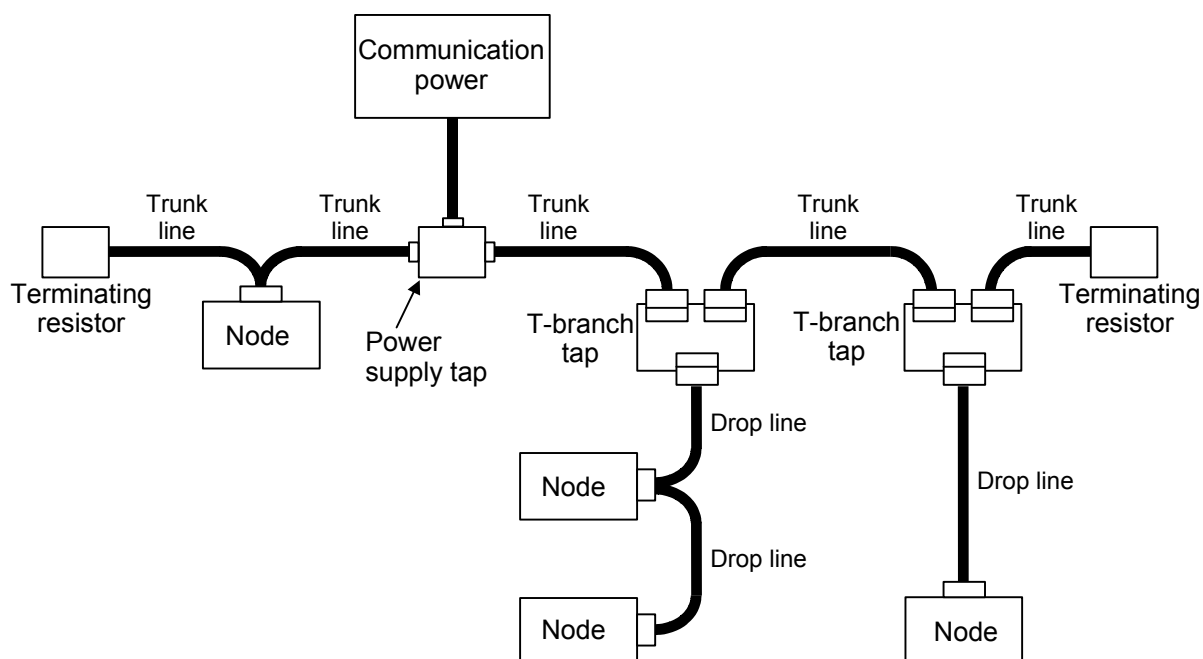


WARNING

To prevent electric shock or instrument failure, turn off the power before connecting or disconnecting the instrument and peripheral equipment.

4.3.1 Connection outline of DeviceNet

The following diagram shows the configuration of a DeviceNet network.



- **Nodes:**
There are two kinds of nodes of master and slave in DeviceNet. The master and slaves can be connected at any location in the network.
- **Trunk/Drop lines:**
The trunk line refers to the cable that has termination resistors on both ends. Cables branching from the trunk line are known as drop lines.
Use the DeviceNet communication cable (thick or thin cable) for Trunk/Drop lines.
- **Connection methods:**
Two methods can be used to connect DeviceNet nodes: The T-branch method and the multi-drop method. With the T-branch method, the node is connected to a drop line created with a T-branch Tap. With the multi-drop method, the node is directly connected to the trunk line or the drop line.

- Termination resistors:

Install termination resistors to both ends of a trunk line in DeviceNet.

Specification of termination resistor: 121 Ω , $\pm 1\%$, 1/4 W (Metal film resistance)

- Communications power supplies:

To use DeviceNet, connect a communications power supply (24 V DC) to the communications connector of each node with a cable.

- Communication length:

Communication speed	Maximum network length *		Maximum drop length	Cumulative drop length
	Thick trunk length	Thin trunk length		
125 kbps	500 m	100 m	6 m	156 m or less
250 kbps	250 m			78 m or less
500 kbps	100 m			39 m or less

* Maximum distance between nodes



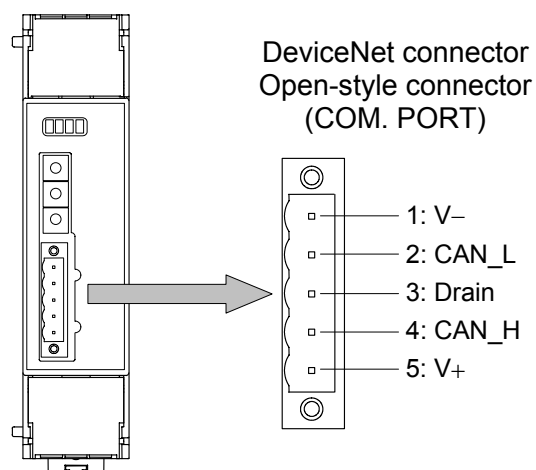
For details of DeviceNet Network installation conditions and methods, refer to the instruction manual of the DeviceNet master unit or DeviceNet Specifications.

DeviceNet specifications are available at ODVA (Open DeviceNet Vendor Association).

URL: <http://www.odva.org>

4.3.2 Pin layout of connector

■ Open-style connector



Pin No. and signal details

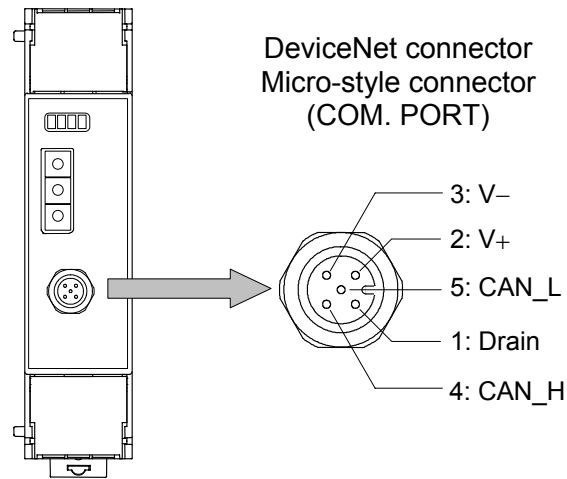
Pin No.	Signal name	Symbol	Cable color
1	Power supply, minus (-)	V-	Black
2	Communication data, low	CAN_L	Blue
3	Shield	Drain	—
4	Communication data, high	CAN_H	White
5	Power supply, plus (+)	V+	Red

● Connection plugs (Recommended model)

MSTB2.5/5-STF-5.08AUM (PHOENIX CONTACT, Inc.)

(Multi-drop type (recommended model)
 TMSTBP2.5/5-STF-5.08AUM (PHOENIX CONTACT, Inc.))

■ Micro-style connector



Pin No. and signal details

Pin No.	Signal name	Symbol	Cable color
1	Shield	Drain	—
2	Power supply, plus (+)	V-	Red
3	Power supply, minus (-)	V+	Black
4	Communication data, high	CAN_H	White
5	Communication data, low	CAN_L	Blue

● Connection socket (Recommended model)

SACC-M12FS-5CON-PG 9-M (PHOENIX CONTACT, Inc.)

(This socket is a type to use thin cable.)

■ Cable

Use the communication cable (thick cable or thin cable) that matched specification of DeviceNet.



By thickness of a cable to use and connection method, usable connection connector type is different.



For cable specifications, connection method and vendor, see the website of ODVA (Open DeviceNet Vendor Association).

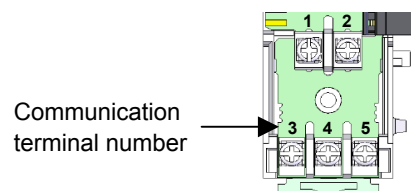
URL: <http://www.odva.org>

4.4 Wiring to the Controllers

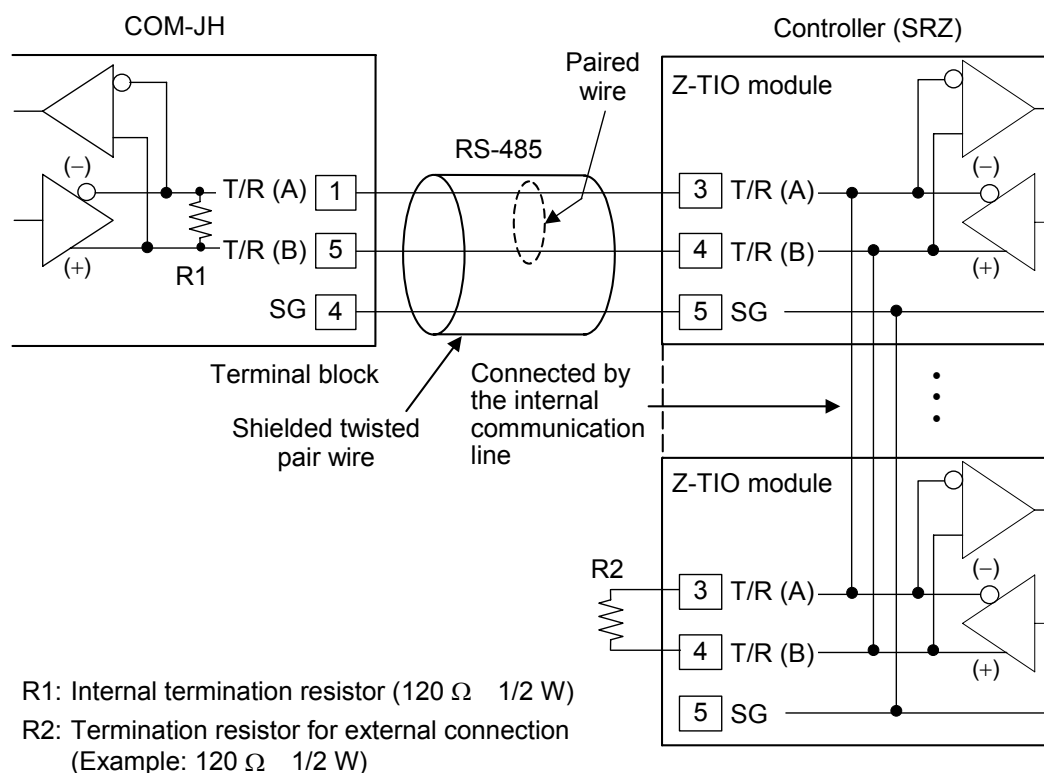
Conduct wiring between the COM-JH and controller (SRZ) as shown in the following.

■ SRZ (Z-TIO/Z-DIO module) communication terminal number and signal details

Terminal No.	Signal name	Symbol
3	Send/receive data	T/R (A)
4	Send/receive data	T/R (B)
5	Signal ground	SG



■ Wiring



Up to 16 Z-TIO modules can be connected.

The maximum number of SRZ modules (including other function modules) on the same communication line is 31.



The cable is provided by the customer.



The termination resistor existing within the COM-JH can be connected or disconnected by the switch. (Factory set value: Termination resistor connected)

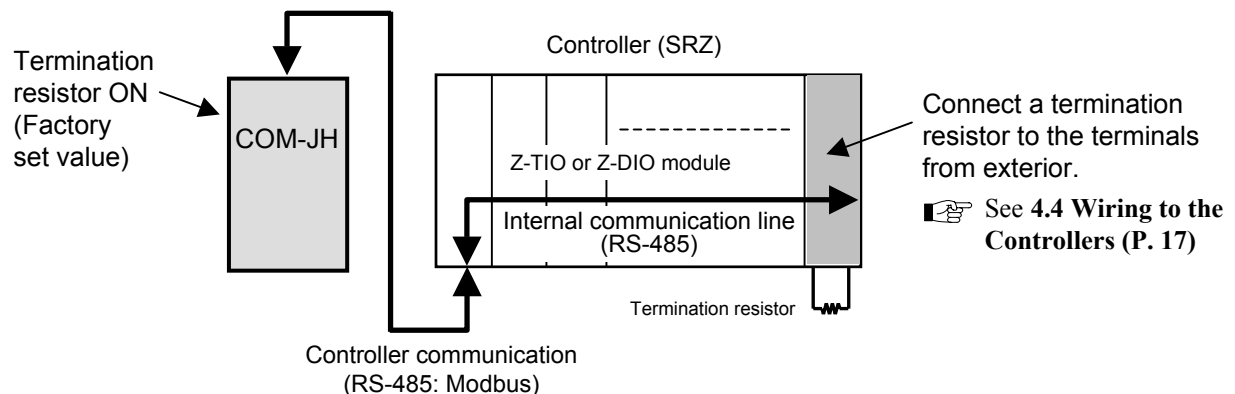
[See 4.5 Termination Resistor (P. 18)]

4.5 Termination Resistor

Procedure for setting a termination resistor to controller communication (RS-485) and its setting position are described in the following.

■ Termination resistor setting position

If the COM-JH is connected to the extreme end of the communication line, install one termination resistor each to the COM-JH and the controller located most distantly from the COM-JH.



■ Setting procedure of termination resistor (COM-JH)

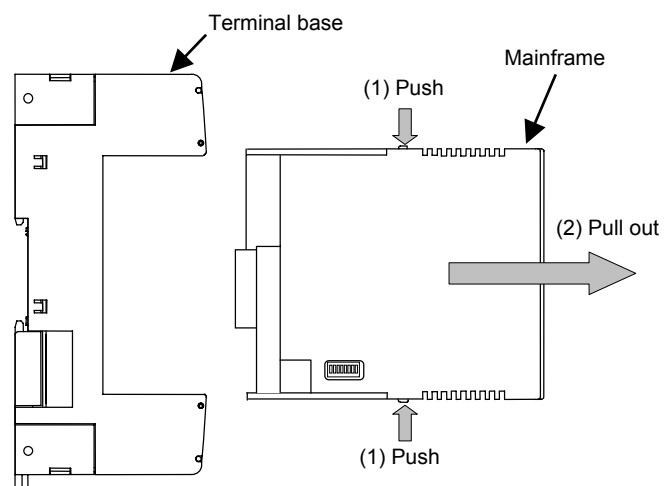
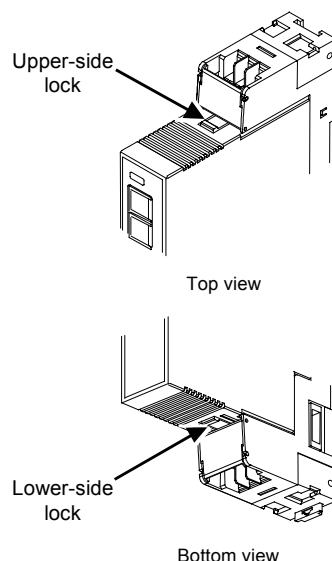
As the COM-JH is internally provided with a selector switch for choosing the ON/OFF of a termination resistor, it is not required to externally install the termination resistor.
(Factory set value: Termination resistor connected)

1. Turn off the power supply of the module.



Do not separate the mainframe from the terminal base with the power turned on. If so, instrument failure may result.

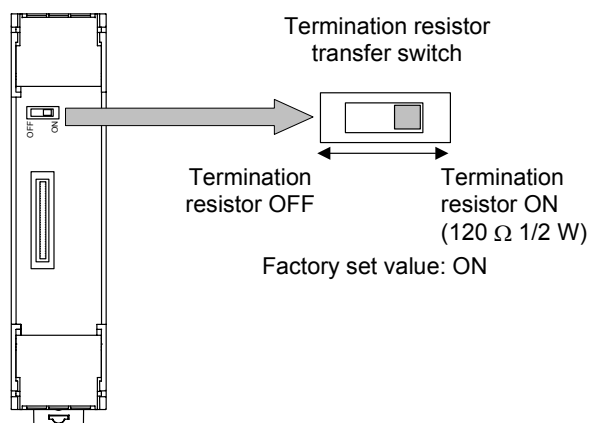
2. Pull out the mainframe itself toward you (2) while pushing the locks at its top and bottom (1), and then separate it from the terminal base.



Removing the module mainframe

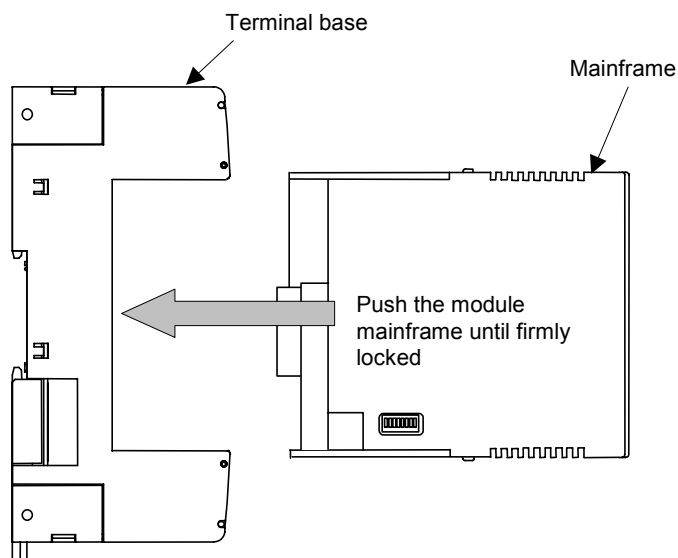
3. Turn on the termination resistor transfer switch in the terminal base.

The COM-JH is shipped from the factory with the selector switch set to “ON: Termination resistor connected.”



A terminal base of the state which removed module mainframe

4. Push the mainframe thus separated in the terminal base until firmly locked.



Mounting the module mainframe

5. SETTING



WARNING

- To prevent electric shock or instrument failure, always turn off the power before setting the switch.
- To prevent electric shock or instrument failure, never touch any section other than those instructed in this manual.

CAUTION

Do not separate the module mainframe from the terminal base with the power turned on. If so, instrument failure may result.

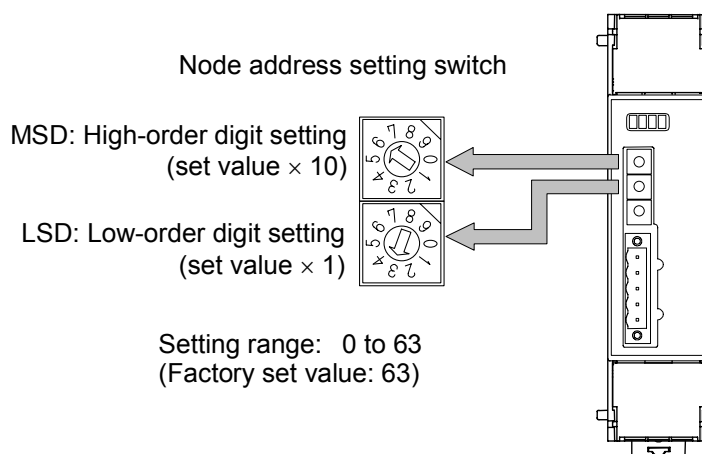
5.1 Node Address Setting

To identify each device connected to the network, it is necessary to set a different address to each device (node). For the DeviceNet, as it is possible to connect up to 64 devices including a master to the network, node address (MAC ID) from 0 to 63 can be set.

For this setting, use a small blade screwdriver.



Set the address such that it is different to the other addresses on the same line. Otherwise, problems or malfunction may result.



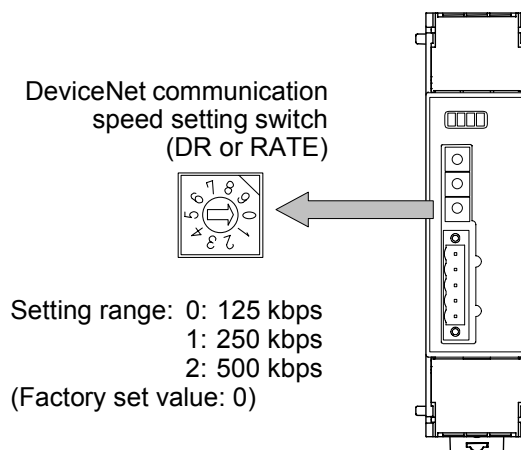
The above figure is open-style connector type. The figure of micro-style connector type is the same as an open-style connector type.



When any number exceeding 64 is set, the node address number becomes “63.”

5.2 DeviceNet Communication Speed Setting

Set a communication speed for the DeviceNet using a small blade screwdriver.



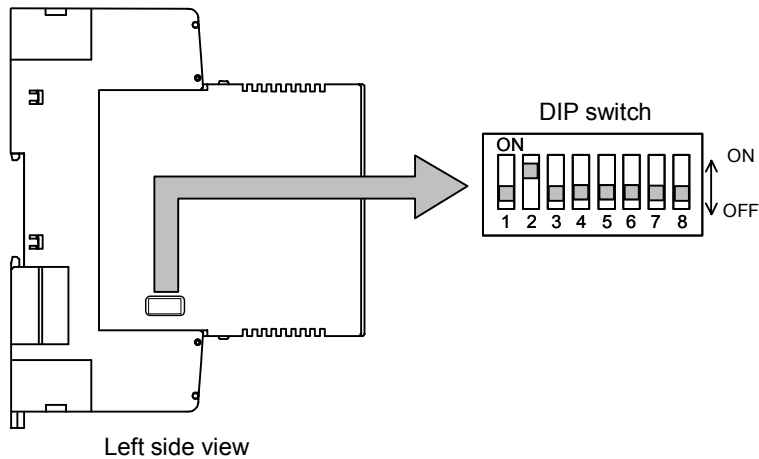
The above figure is open-style connector type. The figure of micro-style connector type is the same as an open-style connector type.



When any number between 3 and 9 is set, the communication speed becomes “500 kbps.”

5.3 DIP Switch Setting

With the DIP switch which there is on the left side of mainframe, set the controller communication speed and set the number of communication words when conducting DeviceNet polling I/O communication.



1	2	Controller communication speed
OFF	OFF	38400 bps
ON	OFF	9600 bps
OFF	ON	19200 bps
ON	ON	38400 bps

Factory set value: 19200 bps

4	5	Number of communication words when conducting DeviceNet polling I/O communication
OFF	OFF	7 words
ON	OFF	25 words
OFF	ON	45 words
ON	ON	100 words

Factory set value: 25 words



Switch No. 3, 6, 7 and 8: OFF fixed. (Don't change this one)



The number of communication words can be calculated from the following equation.

Number of communication words

$$\begin{aligned}
 &= (\text{Number of words of first communication item for one module}^1 \\
 &\quad + \text{Number of words of next communication item for one module}^1 \dots \\
 &\quad + \text{Number of words of last communication item for one module}^1) \\
 &\quad \times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words}^2
 \end{aligned}$$

¹ In the case of two-channel type (Z-TIO-B modules), the number of words per one module is the same as four-channel type (Z-TIO-A modules).

² Measured data items (IN)

Receive counter: 1 word, Alarm state: 2 words, RUN/STOP state: 2 words

Setting data items (OUT)

Setting state selection: 3 words, RUN/STOP transfer: 2 words



The number of communication words when conducting polling I/O communication can also be set via Explicit message communication, or by the configuration tool or rotary switch. However, when the number of communication words is set via Explicit message communication, or by the configuration tool or rotary switch, the value set by the DIP switch may be ignored.

5.4 Communication Environment Setting by Rotary Switch

Set communication environment of polling I/O communication of DeviceNet by using the “Node address setting switch” and the “DeviceNet communication speed setting switch” which are the rotary switch of the COM-JH.

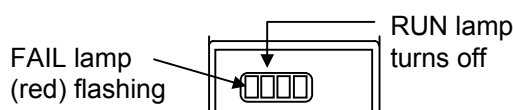
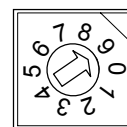


The setting details cannot be check afterwards. When checking the details thus set, check them via Explicit message communication. In addition, as each switch position is moved during the setting, record the switch setting state before making the setting.

● Setting procedure

1. Turn off the power supply.
2. Before communication environment, record the switch positions of node address setting switch and DeviceNet communication speed setting switch. (When this module is used for the first time, no recording is required.)
3. Set all the values of a node address setting switch and a DeviceNet communication speed setting switch to “9.”
4. Turning on the power sets the module to the communication environment setting mode. If set to the communication environment setting mode, the RUN lamp goes off and the FAIL lamp flashes.
5. Select a setting item number with MSD of the node address setting switch, and set data with LSD of the node address setting switch.

Node address setting switch
and
DeviceNet communication speed
setting switch



☞ See ■ **List of communication environment setting items (P. 24).**

6. Set the DeviceNet communication speed setting switch in the order of “9,” “0” and “1.”
The RUN lamp turns on and then it turns off after registration of the set data is complete (after a lapse about 3 seconds).
7. Repeat the steps from 5. to 6. of above, and set other setting items.
However, set the DeviceNet communication speed setting switch in the order of “1,” “0” and “1” from the second setting.
8. First check that the RUN lamp goes off, and then turn off the power.
9. Return the switch positions of node address setting switch and DeviceNet communication speed setting switch to the positions already recorded.
10. Turn on the power again.
The set data valid if the power is turned on again.

■ List of communication environment setting items

Node address setting switch MSD		Node address setting switch LSD	Factory set value
No.	Setting item	Data range	
0	Action mode selection	Address setting method 0: Continuous setting ¹ 1: Free setting ¹ 2: Continuous setting ² 3: Free setting ² 4 to 9: Don't set this one Continuous setting: The addresses that are set in object instances 1 to 31 of the controller address settings * must be set in order from the lowest instance. Free setting: The addresses that are set in object instances 1 to 31 of the controller address settings * can be set freely. * The Attribute ID: 246 of controller object (0x64: 64Hex).	1
1	Number of polling I/O communication controllers	0: 1 controller 1 to 8: 2 to 30 controllers (= set value × 4 – 2) 9: 31 controllers Set the number of controller communicating by polling I/O communication.	10 controllers
2	Unused	Don't set this one	—
3	Unused	Don't set this one	—
4	Number of communication measured data items (IN) when conducting polling I/O communication	0 to 8: 0 to 80 words (= set value × 10) 9: 200 words Set the number of measured data items (IN) communicating via polling I/O communication.	0: Depends on the DIP switch setting (25 words)
5	Number of communication setting data items (OUT) when conducting polling I/O communication	0 to 8: 0 to 80 words (= set value × 10) 9: 200 words Set the number of setting data items (OUT) communicating via polling I/O communication.	0: Depends on the DIP switch setting (25 words)

¹ The PID/AT transfer by polling I/O communication is invalid.

² The PID/AT transfer by polling I/O communication is valid.

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Node address setting switch MSD		Node address setting switch LSD	Factory set value
No.	Setting item	Data range	
6	Controller communication transmission wait time	0 to 5: 0 to 20 ms (= set value × 4) 6: 30 ms 7: 50 ms 8: 70 ms 9: 100 ms Set the standby time until the COM-JH starts sending data after receiving data from the controller.	0
7	Unused	Don't set this one	—
8	Controller address setting	0: Controller 1 to 31: 1 to 31 1: Controller 1: 1 Controller 2 to 31: 0 2~8: Don't set this one 9: Automatic acquisition of controller address Set the address of the controller that is connected to COM-JH to have communication take place with only that address. Set "9: Automatic acquisition of controller address" and turn on the power again to acquire the connected controller address automatically.	0
9	Set value initialization	0 to 8: Unused 9: Communication environment setting initialization execution Initialize each communication environment setting data item which can be set by the rotary switch.	—



The number of communication words can be calculated from the following equation.

Number of communication words

$$= (\text{Number of words of first communication item for one module}^1 + \text{Number of words of next communication item for one module}^1 \dots + \text{Number of words of last communication item for one module}^1) \times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words}^2$$

¹ In the case of two-channel type (Z-TIO-B modules), the number of words per one module is the same as four-channel type (Z-TIO-A modules).

² Measured data items (IN)

Receive counter: 1 word, Alarm state: 2 words, RUN/STOP state: 2 words

Setting data items (OUT)

Setting state selection: 3 words, RUN/STOP transfer: 2 words



The number of polling I/O communication controllers, the number of communication measured data items (IN) and the number of communication setting data items (OUT) can also be set via Explicit message communication, or by the configuration tool.

6. DeviceNet COMMUNICATION

6.1 Features and Functionality

- One DeviceNet Network can have a maximum of 64 Media Access Control Identifiers (MAC ID: Node address).
- Network length changes with communication speed.

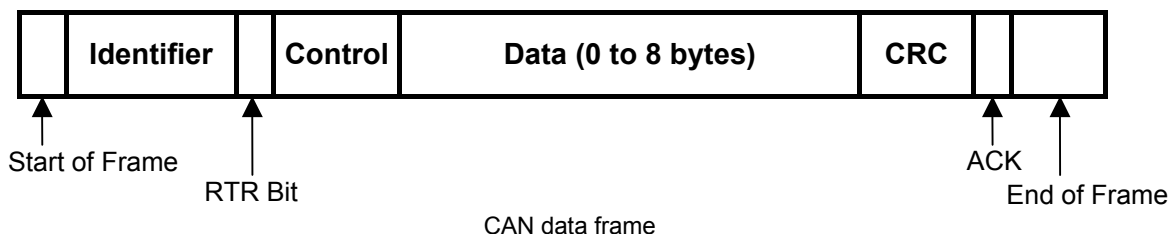
Communication speed	Maximum network length *		Maximum drop length	Cumulative drop length
	Thick trunk length	Thin trunk length		
125 kbps	500 m	100 m	6 m	156 m or less
250 kbps	250 m			78 m or less
500 kbps	100 m			39 m or less

* Maximum distance between nodes

- Install termination resistors to both ends of a trunk line in DeviceNet.
Specification of termination resistor: 121 Ω , $\pm 1\%$, 1/4 W (Metal film resistance)
- A DeviceNet node is modeled as a collection of objects.
The object model provides a template for organizing and implementing the Attributes (data), Services and Behaviors of the components of a DeviceNet product.
This model has represented the construction of address designation to consist of four levels of Node address (MAC ID), Object class ID, Instance ID and Attribute ID.
An address of this 4 level is used as an identification factor of data in Explicit message communication.

Address	Lowest	Highest
Node	0	63
Object class	1	65535
Instance	0	65535
Attribute	1	255

- DeviceNet incorporates CAN (Controller Area Network). CAN defines the syntax or form of the data movement. Data on DeviceNet is transmitted using CAN data frame.



- 📖 For details on the communication specification of DeviceNet, see DeviceNet specifications. DeviceNet specifications are available from ODVA (Open DeviceNet Vendor Association).

URL: <http://www.odva.org>

6.2 Communication Method

COM-JH has supported “Polling I/O communication” and “Explicit message communication” as a communication method of DeviceNet.

6.2.1 Polling I/O communication

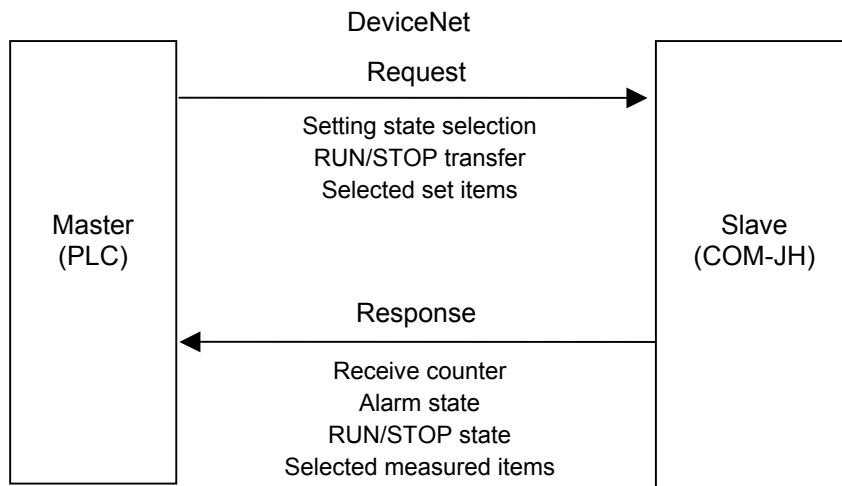
Polling I/O communication is the communication that master and slave always execute transmission and reception of data. Used always when checking data items such as measured values, etc.

Set the following items before communication start.

- Communication data items (setting data items and measured data items)
- Number of communication controllers
- Number of communication words
- Controller address
- Action mode
- Automatic acquisition of controller address

Polling made once enables the following data items to be read or written via polling I/O communication.

Request: setting data items (OUT)	Response: measured data items (IN)
Setting state selection	Receive counter
RUN/STOP transfer	Alarm state
Selected set items	RUN/STOP state
	Selected measured items



Outline of polling I/O communication



For data processed in actual communication, its decimal point is ignored. In addition, data with a minus sign is expressed as 2's complement data.

[Example 1]

For a set value of “120.0,” set “1200.”

[Example 2]

For a set value of “-1,” set “65535.”

(10000H - 1 = FFFFH = 65535)

■ Data to send from a master [Request: setting data items (OUT)]

A master transmits data of the following for slave (COM-JH).

Communication data (setting data items) contents

No.	Items	Data range	Factory set value
1	Setting state selection (All controller)	Bit data b0: Data setting disabled/enabled 0: Depending on the setting contents of communication data No. 2 and No. 3 1: All-controller setting enabled (include RUN/STOP) b1 to 15: Unused [Decimal number: 0 to 1]	0
2	Setting state selection (Controller 1 to 16)	Bit data b0 to 15: Data setting disabled/enabled (Controller 1 to 16) 0: Setting disabled 1: Setting enabled [Decimal number: 0 to 65535]	0
3	Setting state selection (Controller 17 to 31, RUN/STOP)	Bit data b0 to 14: Data setting disabled/enabled (Controller 17 to 31) b15: RUN/STOP transfer disabled/enabled 0: Setting disabled 1: Setting enabled [Decimal number: 0 to 65535]	0
4	RUN/STOP transfer (Controller 1 to 16)	Bit data b0 to 15: RUN/STOP transfer * (Controller 1 to 16) 0: RUN 1: STOP [Decimal number: 0 to 65535]	Same as RUN/STOP state of controller
5	RUN/STOP transfer (Controller 17 to 31)	Bit data b0 to 14: RUN/STOP transfer * (Controller 17 to 31) 0: RUN 1: STOP b15: Unused [Decimal number: 0 to 32767]	Same as RUN/STOP state of controller

* It is possible to change the logic of RUN/STOP by Explicit message communication.



Communication data Nos. 1 to 5 (corresponding to 5 words) are fixed communication data items.

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No.	Items	Data range	Factory set value
On and after 6	Selected set items Setting items are set by the configuration tool or via Explicit message communication are assigned by the number of controllers similarly set. [Factory set value: Set value (SV)]	Same as the range of setting items selected	Same as the factory set value of setting data items selected



In order to validate data after communication data No. 6, it is necessary to set the controllers corresponding to communication data Nos. 2 and 3 to “1: Setting enabled” or to communication data No. 1 to “1: All-controller setting enabled.”



For the setting method of the number of communication words, refer to the following.

- **5.3 DIP Switch Setting (P. 22),**
- **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
- **■ Number of communication words setting by DIP switch (P. 32)**
- **■ Communication parameter setting by configuration tool (P. 33)**
- **■ Communication parameter setting by Explicit message communication (P. 43)**



For the setting method of the number of communication controllers, controller address and automatic acquisition of controller address, refer to the following.

- **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
- **■ Communication parameter setting by configuration tool (P. 33)**
- **■ Communication parameter setting by Explicit message communication (P. 43)**



For the setting method of the action mode, refer to the following.

- **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
- **■ Communication parameter setting by Explicit message communication (P. 43)**



For contents of setting data items, see **7. COMMUNICATION DATA LIST (P. 47)**.

■ Data which a master receives [Response: measured data items (IN)]

A master transmits data of the following for slave (COM-JH).

Communication data (measured data items) contents

No.	Items	Data range
1	Receive counter ¹	0 to 65535 Increments each time the COM-JH receives the setting item (OUT) data.
2	Alarm state (Controller 1 to 16)	Bit data b0 to 15: Alarm state ² (Controller 1 to 16) 0: Alarm OFF 1: Alarm ON [Decimal number: 0 to 65535]
3	Alarm state (Controller 17 to 31, Setting update flag/Flag during polling I/O communication updating)	Bit data b0 to 14: Alarm state ² (Controller 17 to 31) 0: Alarm OFF 1: Alarm ON b15: OR operation is performed to the “Setting update flag ³ ” and the “Flag during polling I/O communication updating.” 0: Setting update is completed 1: During setting update [Decimal number: 0 to 65535]
4	RUN/STOP state (Controller 1 to 16)	Bit data b0 to 15: RUN/STOP state ⁴ (Controller 1 to 16) 0: RUN 1: STOP [Decimal number: 0 to 65535]
5	RUN/STOP state (Controller 17 to 31)	Bit data b0 to 14: RUN/STOP state ⁴ (Controller 17 to 31) 0: RUN 1: STOP b15: Unused [Decimal number: 0 to 32767]

¹ The counter is reset when the power is turned on or when it exceeds 65535.

² Set to “1” if any bit in “Controller state 1” of the controller object (0x64) is set to ON.

³ Set to 1 if the item whose setting was changed from among data items on and after measured item (IN) No.4 is being updated while set to 0 if the same item has been update.

No setting change has been finished as far as this value remains set at 1. In addition, ReadOnly items can always be read regardless of this value.

⁴ It is possible to change the logic of RUN/STOP by Explicit message communication.



Communication data Nos. 1 to 5 (corresponding to 5 words) are fixed communication data items.

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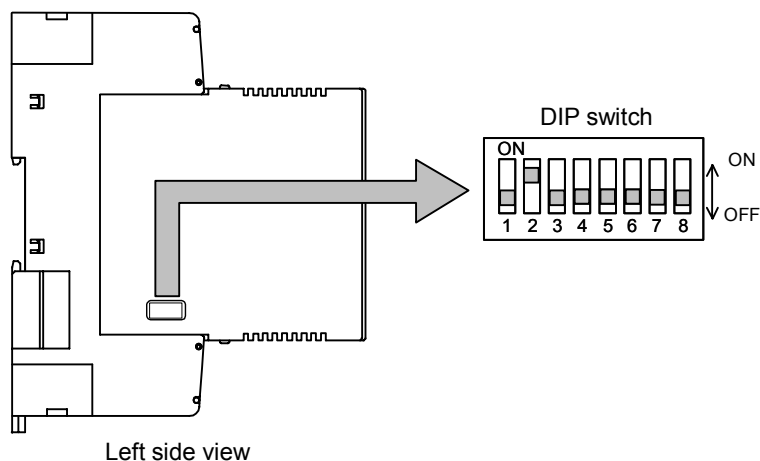
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No.	Items	Data range
On and after 6	Selected measured items Measured items set by the configuration tool or via Explicit message communication are assigned by the number of controllers similarly set. [Factory set value: Measured value (PV)]	Same as the range of measured items selected

-  For the setting method of the number of communication words, refer to the following.
 - **5.3 DIP Switch Setting (P. 22),**
 - **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
 - **■ Number of communication words setting by DIP switch (P. 32)**
 - **■ Communication parameter setting by configuration tool (P. 33)**
 - **■ Communication parameter setting by Explicit message communication (P. 43)**
-  For the setting method of the number of communication controllers, controller address and automatic acquisition of controller address, refer to the following.
 - **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
 - **■ Communication parameter setting by configuration tool (P. 33)**
 - **■ Communication parameter setting by Explicit message communication (P. 43)**
-  For the setting method of the action mode, refer to the following.
 - **5.4 Communication Environment Setting by Rotary Switch (P. 23)**
 - **■ Communication parameter setting by Explicit message communication (P. 43)**
-  For contents of setting data items, see **7. COMMUNICATION DATA LIST (P. 47).**

■ Number of communication words setting by DIP switch

Use the switch Nos. 4 and 5 of the DIP switch which there is on the left side of COM-JH, sets the number of communication words when conducting polling I/O communication.



4	5	Number of communication words when conducting DeviceNet polling I/O communication
OFF	OFF	7 words
ON	OFF	25 words
OFF	ON	45 words
ON	ON	100 words

Factory set value: 25 words



Switch No. 3, 6, 7 and 8: OFF fixed. (Don't change this one)



The number of communication words can be calculated from the following equation.
Number of communication words

$$= (\text{Number of words of first communication item for one module}^1 + \text{Number of words of next communication item for one module}^1 \dots + \text{Number of words of last communication item for one module}^1) \times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words}^2$$

¹ In the case of two-channel type (Z-TIO-B modules), the number of the words per one module is the same as four-channel type (Z-TIO-A modules).

² Measured data items (IN)

Receive counter: 1 word, Alarm state: 2 words, RUN/STOP state: 2 words

Setting data items (OUT)

Setting state selection: 3 words, RUN/STOP transfer: 2 words



The number of communication words when conducting polling I/O communication can also be set via Explicit message communication, or by the configuration tool or rotary switch. However, when the number of communication words is set via Explicit message communication, or by the configuration tool or rotary switch, the value set by the DIP switch may be ignored.



For switch Nos. 1 and 2, see **5.3 DIP Switch Setting (P. 22)**.

■ Communication parameter setting by configuration tool

Set the following items with the configuration tool.

- Communication data items (setting data items and measured data items)
- Number of communication controllers
- Number of communication words
- Controller address
- Automatic acquisition of controller address



Time-out may occur if trying to read any COM-JH parameter from the configuration tool while in polling I/O communication between the master station and COM-JH. When reading or setting the parameters by the configuration tool, stop polling I/O at the master station.



For operation of the configuration tool, see each configuration tool instruction manual.



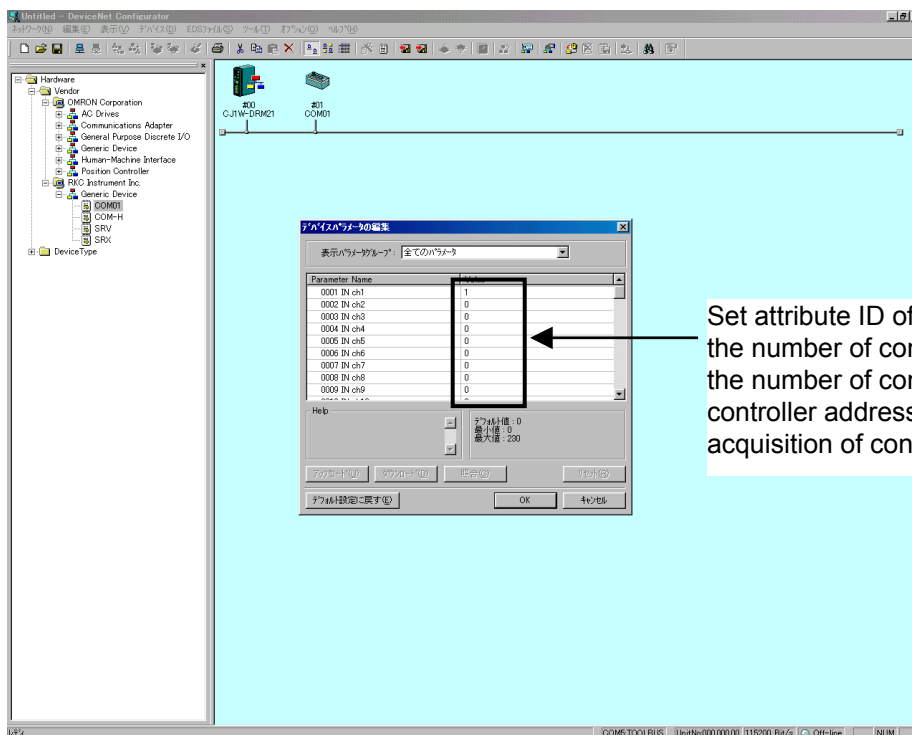
It is also possible to set communication data items, the number of communication controllers, the number of communication words, the controller address and the automatic acquisition of controller address using Explicit message communication.

For details, see ■ **Communication parameter setting by Explicit message communication** (P. 43).

● Setting procedure

1. Connect a personal computer installed with the configuration tool to the COM-JH via DeviceNet.
2. Install the EDS file attached to COM-JH in the configuration tool.
3. Open a parameter setting screen of COM-JH after having added COM-JH to network configuration by using a configuration tool.

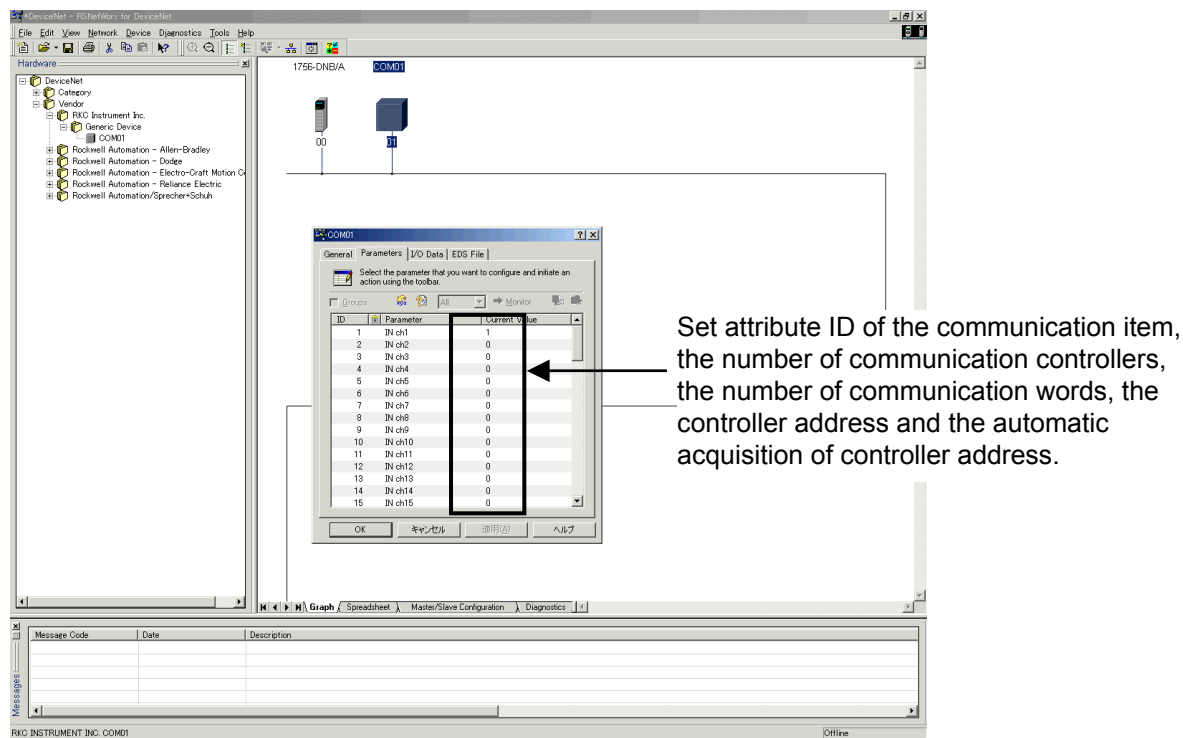
< Reference screen 1: Configuration tool made by OMRON >



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<Reference screen 2: Configuration tool made by Rockwell>



4. Sets the attribute ID of communication data items, the number of communication controllers, the number of communication words, the controller address and the automatic acquisition of controller address with a parameter setting screen.



“The number of communication controllers” corresponds to number of controllers communicating via polling I/O communication.



For the attribute ID of communication data items, see **7. COMMUNICATION DATA LIST (P. 47)**.

● Parameter setting example of polling I/O communication

An example of how to set each parameter for polling of the following data is shown.

- Measured data items (IN): Alarm state } Fixed assignment
 RUN/STOP state }
 Measured value (PV)
 Manipulated output value (MV) monitor [heat-side]
- Setting data items (OUT): Setting state selection } Fixed assignment
 RUN/STOP transfer }
 Set value (SV)
 Event 1 set value
- Number of communication controllers: 2 controllers
 Z-TIO-A module: 1 controller (4-channel type)
 Z-TIO-B module: 1 controller (2-channel type)
- Number of communication words:
 21 words (IN), 21 words (OUT)
- Controller address: 1, 2 (Address of controller 1 and controller 2)
- Automatic acquisition of controller address:
 0 (Do not execute the automatic acquisition)



Fixed five communication data words are assigned to the measured data items of “Alarm state” and “RUN/STOP state.” In addition, fixed five communication data words are assigned to the setting data items of “Setting state selection” and “RUN/STOP transfer.”



The number of communication words can be calculated from the following equation.

Number of communication words

$$\begin{aligned}
 &= (\text{Number of words of first communication item for one module}^1 \\
 &+ \text{Number of words of next communication item for one module}^1 \dots \\
 &+ \text{Number of words of last communication item for one module}^1) \\
 &\times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words}^2
 \end{aligned}$$

¹ In the case of two-channel type (Z-TIO-B modules), the number of the words per one module is the same as four-channel type (Z-TIO-A modules).

² Measured data items (IN)

Receive counter: 1 word, Alarm state: 2 words, RUN/STOP state: 2 words

Setting data items (OUT)

Setting state selection: 3 words, RUN/STOP transfer: 2 words



When the number of communication words is set via Explicit message communication, or by the configuration tool or rotary switch, the value set by the DIP switch may be ignored.

Conduct parameter set according to the procedure described below.

1. Set measured data items (IN) with a parameter setting screen of COM-JH.
 - Set attribute ID “1” of “Measured value (PV)” in “IN ch1 (Parameter 1).”
 - Set attribute ID “14” of “Manipulated output value (MV1) monitor” in “IN ch2 (Parameter 2).”
 - “0” is set to unused IN ch (Parameter 3 to 32).

Parameter	Value	
1 IN ch1	1	← Attribute ID of Measured value (PV): 1
2 IN ch2	14	← Attribute ID of Manipulated output value (MV1) monitor: 14
3 IN ch3	0	} Set “0” in unused items
4 IN ch4	0	
•	•	
•	•	
•	•	
32 IN ch32	0	
•	•	
•	•	
•	•	

-  In addition to “Alarm state” and “RUN/STOP state” assigned as fixed, up to 32 types of measured data items can be selected.
-  Set measured data items in order starting from IN ch1 (Parameter 1). If any of the following values is set, all items from that item to IN ch32 (Parameter 32) are the same as those when set at “0.”
 - If at “0”
 - If set to attribute ID to which no communication data items are assigned
 - If at 231 to 236 or 238 to 243 as attribute ID
-  When setting the communication items of a Z-TIO module extended object (0x65: 65Hex) or Z-DIO module object (0x66: 66Hex), set the attribute ID number with the appropriate offset value (1000 or 2000) added.
 - 0x65: 65Hex: Attribute ID + 1000
 - 0x66: 66Hex: Attribute ID + 2000
-  For attribute ID of the communication data items, see **7. COMMUNICATION DATA LIST (P. 47)**.

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2. Set the setting data item (OUT) on the same COM-JH parameter setting screen.

- Set attribute ID “45” of “Set value (SV)” in “OUT ch1 (Parameter 33).”
- Set attribute ID “39” of “Event 1 set value” in “OUT ch2 (Parameter 34).”
- “0” is set to unused OUT ch (Parameter 35 to 64).

Parameter	Value	
•	•	
•	•	
•	•	
33 OUT ch1	45	← Attribute ID of Set value (SV): 45
34 OUT ch2	39	← Attribute ID of Event 1 set value: 39
35 OUT ch3	0	} Set “0” in unused items
36 OUT ch4	0	
•	•	
•	•	
•	•	
64 OUT ch32	0	
•	•	
•	•	
•	•	



In addition to “Setting state selection” and “RUN/STOP transfer” assigned as fixed, up to 32 types of setting data items can be selected.



Set the setting data items in order starting from OUT ch1 (Parameter 33). If any of the following values is set, all items from that item to OUT ch32 (Parameter 64) are the same as those when set at “0.”

- If at “0”
- If set to attribute ID to which readable communication data items are assigned
- If set to attribute ID to which no communication data items are assigned
- If at 231 to 236 or 238 to 243 as attribute ID
- If at 33 as attribute ID (when “b1: PID/AT transfer by polling I/O communication” of attribute ID “246” (Action mode selection) is “0: Invalid”)



When setting the communication items of a Z-TIO module extended object (0x65: 65Hex) or Z-DIO module object (0x66: 66Hex), set the attribute ID number with the appropriate offset value (1000 or 2000) added.

- 0x65: 65Hex: Attribute ID + 1000
- 0x66: 66Hex: Attribute ID + 2000



For attribute ID of the communication data items, see **7. COMMUNICATION DATA LIST (P. 47)**.

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- Set the number of communication controllers on the same COM-JH parameter setting screen.
Set “2” which is the number of controllers communicating via polling I/O communication to Number of I/O Controllers (Parameter 65).

Parameter	Value
1 IN ch1	1
•	•
•	•
•	•
64 OUT ch32	0
65 Number of I/O Controllers	2
66 I/O IN WORDS	0
67 I/O OUT WORDS	0

← Number of communication controllers: 2

- Set the number of communication words on the same COM-JH parameter setting screen.

Number of communication words

$$= \begin{aligned} & \text{(Number of words of first communication item for one module} \\ & + \text{Number of words of next communication item for one module ...} \\ & + \text{Number of words of last communication item for one module)} \\ & \times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words} \end{aligned}$$



$$(4 + 4) \times 2 + 5 = 21$$

- Set “21 words” which is the number of communication measured data items communicating via polling I/O communication to I/O IN WORDS (Parameter 66).
- Set “21 words” which is the number of communication setting data items communicating via polling I/O communication to I/O OUT WORDS (Parameter 67).

Parameter	Value
1 IN ch1	1
•	•
•	•
•	•
64 OUT ch32	0
65 Number of I/O Controllers	2
66 I/O IN WORDS	21
67 I/O OUT WORDS	21

← Number of communication measured data items: 21 words

← Number of communication setting data items: 21 words

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5. Set the controller address on the same COM-JH parameter setting screen.
 Set address "1" of controller 1 in "Address of Controller 1 (Parameter 68)."
 Set address "2" of controller 2 in "Address of Controller 2 (Parameter 69)."
 Set "0" in non-connected controllers 3 to 31 (Parameters 70 to 98).

Parameter	Value
68 Address of Controller 1	1
69 Address of Controller 2	2
70 Address of Controller 3	0
71 Address of Controller 4	0
⋮	⋮
98 Address of Controller 31	0
99 Auto acquisition of address	0

← Address of controller 1: 1

← Address of controller 2: 2

Set "0" in non-connected controllers *

* Controllers with addresses set to "0" will not perform communication. If a value other than "0" (1 to 31) is set in a non-connected controller, communication will take place, however, all data will be "0."

6. Set the automatic acquisition of controller address on the same COM-JH parameter setting screen.
 Set "0," no automatic acquisition of controller address, in "Auto acquisition of address (Parameter 99)."

Parameter	Value
68 Address of Controller 1	1
69 Address of Controller 2	2
70 Address of Controller 3	0
71 Address of Controller 4	0
⋮	⋮
98 Address of Controller 31	0
99 Auto acquisition of address	0

0: Do not execute the automatic acquisition
 1: Execute the automatic acquisition *

* Automatically reverts to "0: Do not execute the automatic acquisition" after automatic acquisition
 When automatic acquisition of controller address is executed, the "number of communication controllers" and "controller address" parameters are updated.



The controller address automatic acquisition set "1: Execute the automatic acquisition," performs the automatic acquisition of the controller address by turning on the power again.

● Example of communication data list

This is a list of communication data items in the previous parameter setting example (P. 35).
(Communication data items IN and OUT corresponding to 21 words, respectively.)

- Measured and setting data items from No. 1 to 5 (corresponding to 5 words) are those assign as fixed. ( section)
- Communication data items set on and after No. 6 are assigned by the specified number of communication controllers.
- Data of unused items become “0.”

No.	Measured data items (IN)
1	Receive counter
2	Alarm state (Controller 1 to 16)
3	Alarm state (Controller 17 to 31, Setting update flag)
4	RUN/STOP state (Controller 1 to 16)
5	RUN/STOP state (Controller 17 to 31)
6	Measured value (PV) [CH1 of controller 1]
7	Measured value (PV) [CH2 of controller 1]
8	Measured value (PV) [CH3 of controller 1]
9	Measured value (PV) [CH4 of controller 1]
10	Measured value (PV) [CH1 of controller 2]
11	Measured value (PV) [CH2 of controller 2]
12	Measured data is fixed in “0” ¹
13	Measured data is fixed in “0” ¹
14	Manipulated output value (MV) monitor [heat-side] [CH1 of controller 1]
15	Manipulated output value (MV) monitor [heat-side] [CH2 of controller 1]
16	Manipulated output value (MV) monitor [heat-side] [CH3 of controller 1]
17	Manipulated output value (MV) monitor [heat-side] [CH4 of controller 1]
18	Manipulated output value (MV) monitor [heat-side] [CH1 of controller 2]
19	Manipulated output value (MV) monitor [heat-side] [CH2 of controller 2]
20	Measured data is fixed in “0” ¹
21	Measured data is fixed in “0” ¹

No.	Setting data items (OUT)
1	Setting state selection (All controller)
2	Setting state selection (Controller 1 to 16)
3	Setting state selection (Controller 17 to 31, RUN/STOP)
4	RUN/STOP transfer (Controller 1 to 16)
5	RUN/STOP transfer (Controller 17 to 31)
6	Set value (SV) [CH1 of controller 1]
7	Set value (SV) [CH2 of controller 1]
8	Set value (SV) [CH3 of controller 1]
9	Set value (SV) [CH4 of controller 1]
10	Set value (SV) [CH1 of controller 2]
11	Set value (SV) [CH2 of controller 2]
12	Setting data are invalid ²
13	Setting data are invalid ²
14	Event 1 set value [CH1 of controller 1]
15	Event 1 set value [CH2 of controller 1]
16	Event 1 set value [CH3 of controller 1]
17	Event 1 set value [CH4 of controller 1]
18	Event 1 set value [CH1 of controller 2]
19	Event 1 set value [CH2 of controller 2]
20	Setting data are invalid ²
21	Setting data are invalid ²

¹ Because controller 2 is 2-channel type, as for the measurement data, “0” becomes fixed.

² Because controller 2 is 2-channel type, the setting data become invalid.



For details of communication data items, see **7. COMMUNICATION DATA LIST (P. 47)**.

6.2.2 Explicit message communication

Explicit message communication uses an Explicit message defined with DeviceNet, and be communication to execute transmission and reception of data between nodes when it is necessary.

Explicit message communication is executed like the following, when COM-JH (slave) is connected to a master instrument with DeviceNet.

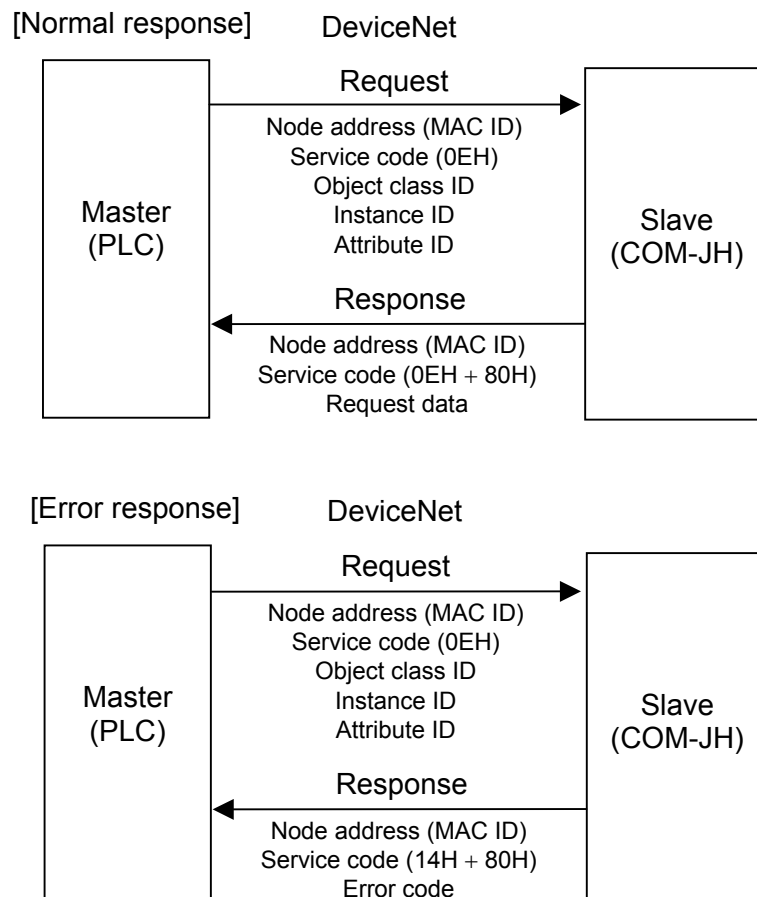


In Explicit message communication, not only data relating to the COM-JH but also all of the attributes (data) described in **APPENDIX A. DEVICE PROFILES (P. 101)** are subject to being sent or received.

■ When read data

If the node address (MAC ID), service code (0EH: Get_Attribute_Single), object class ID, instance ID and attribute ID are sent from the master, the node address (MAC ID) thus sent and service code (0EH + 80H *) as well as the data requested are sent from the slave.

* 80H represents a response message.



Service code 14H of “Error response” has shown that it is error response.

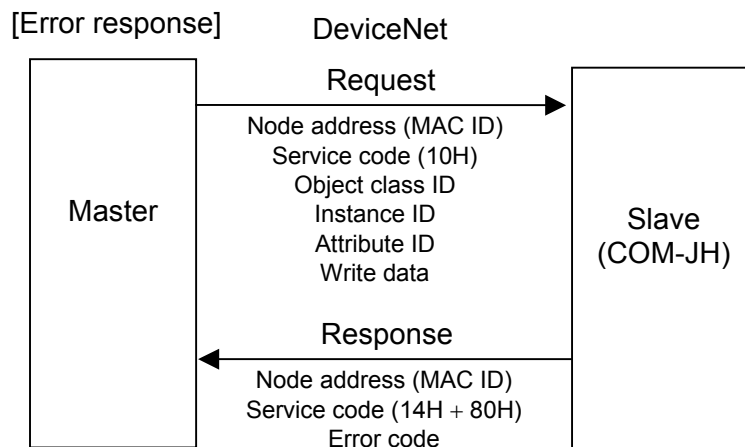
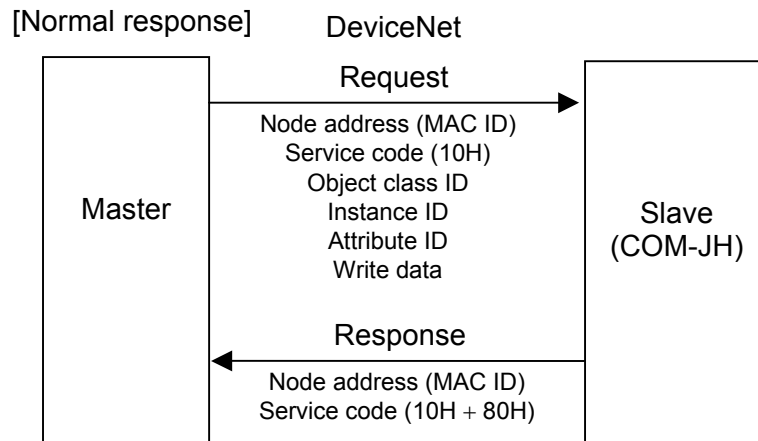


For Error code of “Error response”, see DeviceNet specifications.

■ When write data

If the node address (MAC ID), service code (10H: Set_Attribute_Single), object class ID, instance ID attribute ID and write data are sent from the master, the node address (MAC ID) thus sent and service code (10H + 80H *) are sent from the slave.

* 80H represents a response message.



For data processed in actual communication, its decimal point is ignored. In addition, data with a minus sign is expressed as 2's complement data.

[Example 1] For a set value of "120.0," set "1200."

[Example 2] For a set value of "-1," set "65535."

(10000H - 1 = FFFFH = 65535)



Service code 14H of "Error response" has shown that it is error response.



For Error code of "Error response", see DeviceNet specifications.



For Explicit message communication specification of data relating to COM-JH, see ■ Z-TIO Module Object (0x64: 64Hex) (P. 107), ■ Z-TIO Module Extended Object (0x65: 65Hex) (P. 114), ■ Z-DIO Module Object (0x66: 66Hex) (P. 115) of APPENDIX A. DEVICE PROFILES.

■ Communication parameter setting by Explicit message communication

“Communication data item setting”, “Setting the number of communication controllers”, “Controller address setting”, “Action mode selection” and “Automatic acquisition of controller address” necessary when conducting polling I/O communication are described by referring to the same settings made via Explicit message communication.

● Communication item setting

Each communication data item when conducting polling I/O communication is set by object instance (instance ID) 1 in “Controller communication item setting object (0xC7: C7Hex).”

Controller communication item setting object (0xC7: C7Hex): Object instance 1

Attribute ID	Contents	Data range	Factory set value
1	Measured data item (IN) 1	Select the measured data item and setting data item from among Z-TIO module object (0x64: 64 Hex), Z-TIO module extended object (0x65: 65Hex) *, or Z-DIO module object (0x66: 66Hex) *, and set the corresponding attribute ID. Attribute ID: 1 to 255	1: Measured value (PV)
2	Measured data item (IN) 2		0
3	Measured data item (IN) 3		
4	Measured data item (IN) 4		
5	Measured data item (IN) 5		
•	•		
•	•		
•	•		
32	Measured data item (IN) 32		
33	Setting data item (OUT) 1		45: Set value (SV)
34	Setting data item (OUT) 2		0
35	Setting data item (OUT) 3		
36	Setting data item (OUT) 4		
37	Setting data item (OUT) 5		
•	•		
•	•		
•	•		
64	Setting data item (OUT) 32		

* When setting the communication items of a Z-TIO module extended object (0x65: 65Hex) or Z-DIO module object (0x66: 66Hex), set the attribute ID number with the appropriate offset value (1000 or 2000) added.

- 0x65: 65Hex: Attribute ID + 1000
- 0x66: 66Hex: Attribute ID + 2000



Set measured data items in order starting from “Measured data item (IN) 1.” If any of the following values is set, all items from that item to “Measured data item (IN) 32” are the same as those when set at “0.”

- If at “0”
- If set to attribute ID to which no communication data items are assigned
- If at 231 to 236 or 238 to 243 as attribute ID



Set the setting data items in order starting from “Setting data item (OUT) 1.” If any of the following values is set, all items from that item to “Setting data item (OUT) 32” are the same as those when set at “0.”

- If at “0”
- If set to attribute ID to which readable communication data items are assigned
- If set to attribute ID to which no communication data items are assigned
- If at 231 to 236, or 238 to 243 as attribute ID
- If at 33 as attribute ID (when “b1: PID/AT transfer by polling I/O communication” of attribute ID “246” (Action mode selection) is “0: Invalid”)



For attribute ID of communication item, see **7. COMMUNICATION DATA LIST (P.47)**.

● Number of communication controllers setting

The number of communication controllers when conducting polling I/O communication is set by the attribute ID 236 of object instance (instance ID) 1 in “Z-TIO module object (0x64: 64Hex).”

Corresponding object: Z-TIO module object (0x64: 64Hex)

Object class ID: 64

Instance ID: 1

Attribute ID: 236 (Number of polling I/O communication controllers)

Write data: 1 to 31

● Number of communication words setting

The number of communication words when conducting polling I/O communication is set by the attribute IDs, 240 and 241 of object instance (instance ID) 1 in “Z-TIO module object (0x64: 64Hex).”

Attribute ID 240: Number of communication measured data items (IN)

Attribute ID 241: Number of communication setting data items (OUT)

Corresponding object: Z-TIO module object (0x64: 64Hex)

Object class ID: 64

Instance ID: 1

Attribute ID: 240 (Number of communication measured words)

241 (Number of communication setting words)

Write data: 0 to 200 words



The number of communication words can be calculated from the following equation.

Number of communication words

$$= (\text{Number of words of first communication item for one module}^1 + \text{Number of words of next communication item for one module}^1 \dots + \text{Number of words of last communication item for one module}^1) \times \text{Number of communication controllers} + \text{Fixed communication data items: 5 words}^2$$

¹ In the case of two-channel type (Z-TIO-B modules), the number of the words per one module is the same as four-channel type (Z-TIO-A modules).

² Measured data items (IN)

Receive counter: 1 word, Alarm state: 2 words, RUN/STOP state: 2 words

Setting data items (OUT)

Setting state selection: 3 words, RUN/STOP transfer: 2 words

● Controller address setting

The controller address setting when conducting polling I/O communication is set by the attribute ID 245 of object instance (instance ID) 1 to 31 in “Z-TIO module object (0x64: 64Hex).”

Corresponding object: Z-TIO module object (0x64: 64Hex)

Object class ID: 64

Instance ID: 1 to 31

Attribute ID: 245 (Controller address setting)

Write data: 0 to 32 *

* For a Z-TIO module, set the data within the range 1 to 16. For a Z-DIO module, set the data within the range 17 to 32.

(A combined maximum of 31 modules can be connected, with a maximum of 16 Z-TIO modules and a maximum of 16 Z-DIO modules)



Set “0” in non-connected controllers

Controllers with addresses set to “0” will not perform communication. If a value other than “0” (1 to 32) is set in a non-connected controller, communication will take place, however, all data will be “0.”

● Action mode selection

The action mode selection when conducting polling I/O communication is set by the attribute ID 246 of object instance (instance ID) 1 in “Z-TIO module object (0x64: 64Hex).”

Corresponding object: Z-TIO module object (0x64: 64Hex)

Object class ID: 64

Instance ID: 1

Attribute ID: 246 (Action mode selection)

Write data: Bit data

b0: Address setting method transfer

0: Continuous setting

1: Free setting

b1: PID/AT transfer by polling I/O communication

0: Invalid

1: Valid

[Decimal number: 0 to 3]

● Automatic acquisition of controller address setting

The Automatic acquisition of controller address when conducting polling I/O communication is set by the attribute ID 247 of object instance (instance ID) 1 in “Z-TIO module object (0x64: 64Hex).”

Corresponding object: Z-TIO module object (0x64: 64Hex)

Object class ID: 64

Instance ID: 1

Attribute ID: 247 (Automatic acquisition of controller address)

Write data: 0: Do not execute the automatic acquisition

1: Execute the automatic acquisition *

* Automatically reverts to “0: Do not execute the automatic acquisition” after automatic acquisition.

When automatic acquisition of controller address is executed, the “number of communication controllers” and “controller address” parameters are updated.



The controller address automatic acquisition set “1: Execute the automatic acquisition,” performs the automatic acquisition of the controller address by turning on the power again.

■ Data setting by Explicit message communication

Corresponding object: Controller object: Z-TIO module object (0x64: 64Hex)
 Z-TIO module extended object (0x65: 65Hex)
 Z-DIO module object (0x66: 66Hex)

Object class ID: 64, 65, 66
 Instance ID: 1 to 64 (Z-TIO module)
 1 to 128 (Z-DIO module)
 Attribute ID: 1 to 255

[Example] Node address of COM-JH: 1

- When set in "100" in set value (SV) of CH3 of Z-TIO module 1

Node address (MAC ID)	1
● Service code	10H (Set_Attribute_Single)
Object class ID	64
Instance ID	3 (CH3 of Z-TIO module 1)
Attribute ID	45 (Set value (SV))
● Write data	100

- When set in "50" in proportional band [heat-side] of CH2 of Z-TIO module 2

Node address (MAC ID)	1
● Service code	10H (Set_Attribute_Single)
Object class ID	64
Instance ID	6 (CH2 of Z-TIO module 2)
Attribute ID	46 (Proportional band [heat-side])
● Write data	50

- When set in "Unused" in operation mode of CH4 of Z-TIO module 1

Node address (MAC ID)	1
● Service code	10H (Set_Attribute_Single)
Object class ID	65
Instance ID	4 (CH4 of Z-TIO module 1)
Attribute ID	1022 (Operation mode)
● Write data	0 (Unused)

← Z-TIO module
extended object

← Attribute ID + 1000

- When set in "ON" in DO1 manual output of Z-DIO module 1

Node address (MAC ID)	1
● Service code	10H (Set_Attribute_Single)
Object class ID	66
Instance ID	1 (Z-DIO module 1)
Attribute ID	2007 (DO manual output)
● Write data	1

← Z-DIO module object

← Attribute ID + 2000

7. COMMUNICATION DATA LIST

7.1 Reference to Communication Data List

Attribute contents of the controller object are described to the communication data list.

The controller objects consist of the three types below.

- Z-TIO module object (0x64: 64Hex)
- Z-TIO module extended object (0x65: 65Hex)
- Z-DIO module object (0x66: 66Hex)

(1) ID	(2) Name	(3) Number of data items	(4) Attribute	(5) Data range	(6) Factory set value
1 (0x0001)	Measured value (PV)	64	RO	Input scale low to Input scale high	—
2 (0x0002)	Current transformer (CT) input value monitor	64	RO	CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A	—
3 (0x0003)	Unused	—	—	—	—

(1) ID: Attribute ID
Attribute ID is written using both of decimal and hexadecimal (in parentheses) numbers.

(2) Name: The communication item name is written.

(3) Number of data items: The number of data items is written.

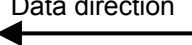
- 1: Only object instance 1 is valid
- 2: Only object instance 1 and 2 are valid
- 16: Valid for object instance 1 to 16
- 31: Valid for object instance 1 to 31
- 64: Valid for object instance 1 to 64
- 128: Valid for object instance 1 to 128

With respect to the following communication data of the Z-TIO module, the data of the indicated channels are “0”.

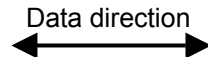
- Two-channel type module:
Data of the 3rd and 4th channels
 - Heat/cool control and position proportioning control:
Data of the 2nd and 4th channels *
 - Cool-only communication data of heat/cool control:
Data of the 2nd and 4th channels *
- * Communication data with a ♣ mark in the name column

(4) Attribute: A method of how communication data items are read or written when viewed from the PLC is described.

RO: Only reading data is possible. (Get: Yes, Set: No)
Correspond to Service code: 0EH (Get_Attribute_Single) of DeviceNet. For data request of a master, data is read from slave.

Master (PLC etc.)  The controller

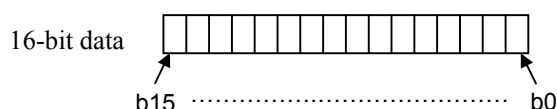
R/W: Reading and writing data is possible. (Get: Yes, Set: Yes)
Correspond to Service code: 0EH (Get_Attribute_Single)/Service code: 10H (Set_Attribute_Single) of DeviceNet.
In Get_Attribute_Single, data is read for data request of a master from Slave.
In Set_Attribute_Single, write in data for Slave from a master.

Master (PLC etc.)  The controller

(5) Data range: The data range of communication item is written.



Bit image of bit data is as follows.



(6) Factory set value: The factory set value of communication item is written.



For controller object (0x64: 64Hex, 0x65: 65Hex, 0x66: 66Hex), see **APPENDIX A. DEVICE PROFILES (P. 101)**.



Communication includes both “Normal setting data” and “Engineering setting data”. During RUN (control), the attribute of engineering setting data is RO. To configure engineering setting data, the RUN/STOP switch must be set to STOP (control stopped).

Z-TIO module object (0x64: 64Hex):

Engineering setting data: ID83 to 203, 205 to 209, 211 to 224

Z-TIO module extended object (0x65: 65Hex):

Engineering setting data: ID24 to 42

Z-DIO module object (0x66: 66Hex):

Engineering setting data: ID13 to 26

The Engineering setting data should be set according to the application before setting any parameter related to operation. Once the Engineering setting data are set correctly, those datas are not necessary to be changed for the same application under normal conditions. If they are changed unnecessarily, it may result in malfunction or failure of the instrument. RKC will not bear any responsibility for malfunction or failure as a result of improper changes in the Engineering setting.



When data is changed using SRZ loader communication, or when data is changed using DI of a Z-DIO module, up to 5 minutes (when 31 modules are connected) may be required for the data to be updated on DeviceNet. In addition, when the engineering setting data in the SRZ is changed from DeviceNet, up to 5 minutes may be required for the data to be updated on DeviceNet, depending on the item. [For example, the set value (SV) and event set value when the input type, input scale upper limit, or input scale lower limit is changed]



If you changed the engineering setting data, turn off the power of the COM-JH and then turn it back on.

7.2 Z-TIO Module Object (0x64: 64Hex)

ID	Name	Number of data items	Attribute	Data range	Factory set value
1 (0x0001)	Measured value (PV)	64	RO	Input scale low to Input scale high	—
2 (0x0002)	Current transformer (CT) input value monitor	64	RO	CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A	—
3 (0x0003)	Unused	—	—	—	—
4 (0x0004)	Set value (SV) monitor	64	RO	Setting limiter (low) to Setting limiter (high)	—
5 (0x0005)	Remote setting (RS) input value monitor	64	RO	Setting limiter (low) to Setting limiter (high)	—
6 (0x0006)	Burnout state monitor	64	RO	0: OFF 1: ON	—
7 (0x0007)	Unused	—	—	—	—
8 (0x0008)	Event 1 state monitor	64	RO	0: OFF 1: ON	—
9 (0x0009)	Event 2 state monitor	64	RO		—
10 (0x000A)	Event 3 state monitor *	64	RO		—
11 (0x000B)	Event 4 state monitor	64	RO		—
12 (0x000C)	Heater break alarm (HBA) state monitor	64	RO	0: OFF 1: ON	—
13 (0x000D)	Unused	—	—	—	—
14 (0x000E)	Manipulated output value (MV) monitor [heat-side] ♣	64	RO	PID control or heat/cool PID control: –5.0 to +105.0 % Position proportioning control with feedback resistance (FBR) input: 0.0 to 100.0 %	—
15 (0x000F)	Manipulated output value (MV) monitor [cool-side] ♣	64	RO	–5.0 to +105.0 %	—
16 (0x0010)	Error code	64	RO	Bit data b0: Adjustment data error b1: Data back-up error b2: A/D conversion error b3, b4: Unused b5: Logic output data error b6 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 63]	—
17 (0x0011)	Unused	—	—	—	—

* If the Event 3 type is temperature rise completion, check the temperature rise completion state in the comprehensive event state [Z-TIO module extended object (0x65: 65Hex) ID: 1]. (The Event 3 state monitor does not turn ON.)

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ID	Name	Number of data items	Attribute	Data range	Factory set value
18 (0x0012)	Output state monitor	64	RO	Bit data b0: The state of OUT1 b1: The state of OUT2 b2: The state of OUT3 b3: The state of OUT4 b4 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15]	—
19 (0x0013)	Operation mode state monitor	64	RO	Bit data b0: Control STOP b1: Control RUN b2: Manual mode b3: Remote mode b4 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15]	—
20 (0x0014)	Memory area soak time monitor	64	RO	0 minutes 00 seconds to 199 minutes 59 seconds: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: 0 to 5999 minutes Data range of Area soak time can be selected on the Soak time unit.	—
21 (0x0015)	Integrated operating time monitor	16	RO	0 to 19999 hours	—
22 (0x0016)	Holding peak value ambient temperature monitor	64	RO	−10.0 to +100.0 °C or 14 to 212 °F	—
23 (0x0017)	Unused	—	—	—	—
24 (0x0018)	Backup memory state monitor	64	RO	0: The content of the backup memory does not coincide with that of the RAM. 1: The content of the backup memory coincides with that of the RAM.	—
25 ⋮ 32 (0x0020)	Unused	—	—	—	—
33 (0x0021)	PID/AT transfer ^{1,2}	64	R/W	0: PID control 1: Autotuning (AT) * * Automatically reverts to 0 after autotuning ends.	0

¹ When used in polling I/O communication, set “PID/AT transfer by polling I/O communication” in the action mode selections (ID: 246) to “1: Valid.”

² When PID/AT transfer is set to “1: Autotuning (AT)” in polling I/O communication, do not change any of the other communication data for controllers with AT set until AT ends, as “1: Autotuning (AT)” may set again when AT ends.

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ID	Name	Number of data items	Attribute	Data range	Factory set value
34 (0x0022)	Auto/Manual transfer	64	R/W	0: Auto mode 1: Manual mode	0
35 (0x0023)	Remote/Local transfer	64	R/W	0: Local mode 1: Remote mode When performing remote control by remote setting input and also performing cascade control and ratio setting, transfer to the remote mode.	0
36 (0x0024)	RUN/STOP transfer	64	R/W	0: STOP mode (Control stop) 1: RUN mode (Control start)	0
37 (0x0025)	Memory area transfer	64	R/W	1 to 8	1
38 (0x0026)	Interlock release	64	R/W	0: Normal state 1: Interlock release execution	0
39 (0x0027)	Event 1 set value (EV1) ★	64	R/W	Deviation action, Deviation action between channels, Temperature rise completion range*: –Input span to +Input span	50
40 (0x0028)	Event 2 set value (EV2) ★	64	R/W	Process action, SV action: Input scale low to Input scale high MV action: –5.0 to +105.0 %	50
41 (0x0029)	Event 3 set value (EV3) ★	64	R/W	* When temperature rise completion is selected at Event 3 action type. If the Event type corresponds to “0: None,” set to RO (Only reading data is possible).	50
42 (0x002A)	Event 4 set value (EV4) ★	64	R/W	If Event 4 corresponds to “9: Control loop break alarm (LBA),” the Event 4 set value becomes RO (Only reading data is possible).	50
43 (0x002B)	Control loop break alarm (LBA) time ★	64	R/W	0 to 7200 seconds (0: Unused) If Event 4 is other than “9: Control loop break alarm (LBA),” set to RO (Only reading data is possible).	480
44 (0x002C)	LBA deadband ★	64	R/W	0 (0.0) to Input span If Event 4 is other than “9: Control loop break alarm (LBA),” set to RO (Only reading data is possible).	0 (0.0)
45 (0x002D)	Set value (SV) ★	64	R/W	Setting limiter (low) to Setting limiter (high)	TC/RTD: 0 °C [°F] V/I: 0.0 %

★: Data related to multi-memory area function

It is possible to change only the data of the control area which is selected by the memory area transfer (ID: 37).

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ID	Name	Number of data items	Attribute	Data range	Factory set value
46 (0x002E)	Proportional band [heat-side] ★ ♣	64	R/W	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/current (I) inputs: 0.0 to 1000.0 % of Input span 0 (0.0): ON/OFF action	TC/RTD: 30 V/I: 30.0
47 (0x002F)	Integral time [heat-side] ★ ♣	64	R/W	PID control or heat/cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Position proportioning control: 1 to 3600 seconds or 0.1 to 1999.9 seconds Varies with the setting of the integral/derivative time decimal point position selection.	240
48 (0x0030)	Derivative time [heat-side] ★ ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) Varies with the setting of the integral/derivative time decimal point position selection.	60
49 (0x0031)	Control response parameter ★ ♣	64	R/W	0: Slow 1: Medium 2: Fast [P or PD action: 2 (Fast) fixed]	PID control, Position proportioning control: 0 Heat/cool PID control: 2
50 (0x0032)	Proportional band [cool-side] ★ ♣	64	R/W	TC/RTD inputs: 1 (0.1) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/current (I) inputs: 0.1 to 1000.0 % of Input span If control is other than heat/cool PID control, set to RO (Only reading data is possible).	TC/RTD: 30 V/I: 30.0
51 (0x0033)	Integral time [cool-side] ★ ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Varies with the setting of the integral/derivative time decimal point position selection. If control is other than heat/cool PID control, set to RO (Only reading data is possible).	240

★: Data related to multi-memory area function

It is possible to change only the data of the control area which is selected by the memory area transfer (ID: 37).

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ID	Name	Number of data items	Attribute	Data range	Factory set value
52 (0x0034)	Derivative time [cool-side] ★ ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) Varies with the setting of the integral/derivative time decimal point position selection. If control is other than heat/cool PID control, set to RO (Only reading data is possible).	60
53 (0x0035)	Overlap/Deadband ★ ♣	64	R/W	TC/RTD inputs: –Input span to +Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: –100.0 to +100.0 % of Input span Minus (–) setting results in overlap. However, the overlapping range is within the proportional range. If control is other than heat/cool PID control, set to RO (Only reading data is possible).	0
54 (0x0036)	Manual reset ★	64	R/W	–100.0 to +100.0 % If the integral function is valid, set to RO (Only reading data is possible). When integral action (heating or cooling side) is zero, manual reset value is added to the control output.	0.0
55 (0x0037)	Setting change rate limiter (up) ★	64	R/W	0 (0.0) to Input span/unit time * (0 (0.0): Unused)	0 (0.0)
56 (0x0038)	Setting change rate limiter (down) ★	64	R/W	* Unit time: 60 seconds (factory set value)	0 (0.0)
57 (0x0039)	Area soak time ★	64	R/W	0 minutes 00 seconds to 199 minutes 59 seconds: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: 0 to 5999 minutes Data range of Area soak time can be selected on the Soak time unit.	0
58 (0x003A)	Link area number ★	64	R/W	0 to 8 (0: No link)	0
59 (0x003B)	Heater break alarm (HBA) set value	64	R/W	When CT is CTL-6-P-N: 0.0 to 30.0 A (0.0: Not used) When CT is CTL-12-S56-10L-N: 0.0 to 100.0 A (0.0: Not used) If there is no current transformer (CT) or CT is assigned to “0: None,” set to RO (Only reading data is possible).	0.0

★: Data related to multi-memory area function

It is possible to change only the data of the control area which is selected by the memory area transfer (ID: 37).

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ID	Name	Number of data items	Attribute	Data range	Factory set value
60 (0x003C)	Heater break determination point	64	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater break determination is invalid) If there is no current transformer (CT) or CT is assigned to "0: None," set to RO (Only reading data is possible). If Heater break alarm (HBA) corresponds to "0: Type A," set to RO (Only reading data is possible).	30.0
61 (0x003D)	Heater melting determination point	64	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater melting determination is invalid) If there is no current transformer (CT) or CT is assigned to "0: None," set to RO (Only reading data is possible). If Heater break alarm (HBA) corresponds to "0: Type A," set to RO (Only reading data is possible).	30.0
62 (0x003E)	Unused	—	—	—	—
63 (0x003F)	Unused	—	—	—	—
64 (0x0040)	Unused	—	—	—	—
65 (0x0041)	PV bias	64	R/W	–Input span to +Input span	0
66 (0x0042)	PV digital filter	64	R/W	0.0 to 100.0 seconds (0.0: Unused)	0.0
67 (0x0043)	PV ratio	64	R/W	0.500 to 1.500	1.000
68 (0x0044)	PV low input cut-off	64	R/W	0.00 to 25.00 % of input span If the Input square root extraction corresponds to "0: Unused," set to RO (Only reading data is possible).	0.00
69 (0x0045)	RS bias *	64	R/W	–Input span to +Input span	0
70 (0x0046)	RS digital filter *	64	R/W	0.0 to 100.0 seconds (0.0: Unused)	0.0
71 (0x0047)	RS ratio *	64	R/W	0.001 to 9.999	1.000

* Data on RS bias, RS ratio and RS digital filter is that in cascade control or ratio setting.

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ID	Name	Number of data items	Attribute	Data range	Factory set value
72 (0x0048)	Proportional cycle time	64	R/W	0.1 to 100.0 seconds M: Relay contact output V: Voltage pulse output T: Triac output D: Open collector output This item becomes RO (Only reading data is possible) for the voltage/current output specification. This parameter is valid when "0: control output" has been selected at "ID96: Output assignment."	M output: 20.0 V, T, D output: 2.0
73 (0x0049)	Unused	—	—	—	—
74 (0x004A)	Manual manipulated output value ♣	64	R/W	PID control: Output limiter (low) to Output limiter (high) Heat/cool PID control: –Cool-side output limiter (high) to +Heat-side output limiter (high) Position proportioning control: When there is feedback resistance (FBR) input and it does not break: Output limiter (low) to Output limiter (high) When there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected: 0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON	0.0
75 (0x004B) ⋮ 82 (0x0052)	Unused	—	—	—	—

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ID	Name	Number of data items	Attribute	Data range	Factory set value
ID83 to ID203 are engineering setting data. [Writable in the STOP mode]					
83 (0x0053)	Input type	64	R/W	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PLII 12: RTD input Pt100 13: RTD input JPt100 14: Current input 0 to 20 mA DC 15: Current input 4 to 20 mA DC 16: Voltage (high) input 0 to 10 V DC 17: Voltage (high) input 0 to 5 V DC 18: Voltage (high) input 1 to 5 V DC 19: Voltage (low) input 0 to 1 V DC 20: Voltage (low) input 0 to 100 mV DC 21: Voltage (low) input 0 to 10 mV DC 22: Feedback resistance input 100 to 150 Ω 23: Feedback resistance input 151 Ω to 6 k Ω If changed to voltage (high) input from TC/RTD/current/voltage (low)/feedback resistance input, select the hardware by the input selector switch at the side of the module. For the selecting procedure, see SRZ Instruction Manual (IMS01T04-E□) .	Depends on model code. When not specifying: 0
84 (0x0054)	Display unit	64	R/W	0: °C 1: °F The engineering unit for voltage/current input is expressed as %.	0
85 (0x0055)	Decimal point position	64	R/W	0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places TC input: • K, J, T, E: Only 0 or 1 can be set. • R, S, B, N, PLII, W5Re/W26Re: Only 0 can be set. RTD input: Only 0 or 1 can be set. V/I inputs: From 0 to 4 can be set.	Depends on model code. When not specifying: TC/RTD: 0 V/I: 1

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ID	Name	Number of data items	Attribute	Data range	Factory set value
86 (0x0056)	Input scale high	64	R/W	TC/RTD inputs: Input scale low to Maximum value of the selected input range Voltage (V)/current (I) inputs: –19999 to +19999 (Varies with the setting of the decimal point position)	TC/RTD: Maximum value of the selected input range V/I: 100.0
87 (0x0057)	Input scale low	64	R/W	TC/RTD inputs: Minimum value of the selected input range to Input scale high Voltage (V)/current (I) inputs: –19999 to +19999 (Varies with the setting of the decimal point position)	TC/RTD: Minimum value of the selected input range V/I: 0.0
88 (0x0058)	Input error determination point (high)	64	R/W	Input error determination point (low) to (Input range high + 5 % of input span)	Input scale high + (5 % of input span)
89 (0x0059)	Input error determination point (low)	64	R/W	(Input range low – 5 % of input span) to Input error determination point (high)	Input scale low – (5 % of input span)
90 (0x005A)	Burnout direction	64	R/W	0: Upscale 1: Downscale Valid only when the TC input and voltage (low) input are selected.	0
91 (0x005B)	Square root extraction	64	R/W	0: Unused 1: Used	0
92 (0x005C) ⋮ 95 (0x005F)	Unused	—	—	—	—
96 (0x0060)	Output assignment (Logic output selection function)	64	R/W	0: Control output 1: Logic output result 2: FAIL output	0
97 (0x0061) ⋮ 100 (0x0064)	Unused	—	—	—	—
101 (0x0065)	Energized/De-energized (Logic output selection function)	64	R/W	0: Energized 1: De-energized	0
102 (0x0066) ⋮ 113 (0x0071)	Unused	—	—	—	—

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ID	Name	Number of data items	Attribute	Data range	Factory set value
114 (0x0072)	Event 1 type	64	R/W	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Unused 10: MV high [heat-side] ^{1,2} 11: MV low [heat-side] ^{1,2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV) ¹ 15: Deviation low (Using local SV) ¹ 16: Deviation high/low (Using local SV) ¹ 17: Deviation (Using local SV) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in position proportioning control, set to the feedback resistance (FBR) input value.	Depends on model code. When not specifying: 0
115 (0x0073)	Event 1 hold action	64	R/W	0: OFF 1: Hold action ON (At power turned on) 2: Re-hold action ON (At power turned on and SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Depends on model code. When not specifying: 0
116 (0x0074)	Event 1 interlock	64	R/W	0: Unused 1: Used	0
117 (0x0075)	Event 1 differential gap	64	R/W	① Deviation, process, set value or Deviation action between channels: 0 to Input span (Unit: °C [°F]) ② MV: 0.0 to 110.0 %	① TC/RTD: 1 °C [°F] V/I: 0.1 % ② 0.1 %
118 (0x0076)	Event 1 delay timer	64	R/W	0 to 18000 seconds	0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
119 (0x0077)	Force ON of Event 1 action	64	R/W	Bit data b0: Event output turned on at input error occurrence b1: Event output turned on in manual mode b2: Event output turned on during the autotuning (AT) function is being executed b3: Event output turned on during the setting change rate limiter is being operated b4 to b15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15]	0
120 (0x0078)	Event 2 type	64	R/W	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Unused 10: MV high [heat-side] ^{1,2} 11: MV low [heat-side] ^{1,2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV) ¹ 15: Deviation low (Using local SV) ¹ 16: Deviation high/low (Using local SV) ¹ 17: Deviation (Using local SV) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in position proportioning control, set to the feedback resistance (FBR) input value.	Depends on model code. When not specifying: 0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
121 (0x0079)	Event 2 hold action	64	R/W	0: OFF 1: Hold action ON (At power turned on) 2: Re-hold action ON (At power turned on and SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Depends on model code. When not specifying: 0
122 (0x007A)	Event 2 interlock	64	R/W	0: Unused 1: Used	0
123 (0x007B)	Event 2 differential gap	64	R/W	① Deviation, process, set value or Deviation action between channels: 0 to Input span (Unit: °C [°F]) ② MV: 0.0 to 110.0 %	① TC/RTD: 1 °C [°F] V/I: 0.1 % ② 0.1 %
124 (0x007C)	Event 2 delay timer	64	R/W	0 to 18000 seconds	0
125 (0x007D)	Force ON of Event 2 action	64	R/W	Bit data b0: Event output turned on at input error occurrence b1: Event output turned on in manual mode b2: Event output turned on during the autotuning (AT) function is being executed b3: Event output turned on during the setting change rate limiter is being operated b4 to b15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15]	0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
126 (0x007E)	Event 3 type	64	R/W	0: None 1: Deviation high (SV monitor value used) ¹ 2: Deviation low (SV monitor value used) ¹ 3: Deviation high/low (SV monitor value used) ¹ 4: Band (SV monitor value used) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Temperature rise completion 10: MV high [heat-side] ^{1, 2} 11: MV low [heat-side] ^{1, 2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Local SV value used) ¹ 15: Deviation low (Local SV value used) ¹ 16: Deviation high/low (Local SV value used) ¹ 17: Deviation (Local SV value used) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in position proportioning control, set to the feedback resistance (FBR) input value.	Depends on model code. When not specifying: 0
127 (0x007F)	Event 3 hold action	64	R/W	0: OFF 1: Hold action ON (At power turned on) 2: Re-hold action ON (At power turned on and SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Depends on model code. When not specifying: 0
128 (0x0080)	Event 3 interlock	64	R/W	0: Unused 1: Used	0
129 (0x0081)	Event 3 differential gap	64	R/W	① Deviation, process, set value or Deviation action between channels: 0 to Input span (Unit: °C [°F]) ② MV: 0.0 to 110.0 %	① TC/RTD: 1 °C [°F] V/I: 0.1 % ② 0.1 %

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ID	Name	Number of data items	Attribute	Data range	Factory set value
130 (0x0082)	Event 3 delay timer	64	R/W	0 to 18000 seconds If Event 3 corresponds to “9: Temperature rise completion,” the Event 3 delay timer becomes the temperature rise completion soak time.	0
131 (0x0083)	Force ON of Event 3 action	64	R/W	Bit data b0: Event output turned on at input error occurrence b1: Event output turned on in manual mode b2: Event output turned on during the autotuning (AT) function is being executed b3: Event output turned on during the setting change rate limiter is being operated b4 to b15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15]	0
132 (0x0084)	Event 4 type	64	R/W	0: None 1: Deviation high (SV monitor value used) ¹ 2: Deviation low (SV monitor value used) ¹ 3: Deviation high/low (SV monitor value used) ¹ 4: Band (SV monitor value used) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Control loop break alarm (LBA) 10: MV high [heat-side] ^{1, 2} 11: MV low [heat-side] ^{1, 2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Local SV value used) ¹ 15: Deviation low (Local SV value used) ¹ 16: Deviation high/low (Local SV value used) ¹ 17: Deviation (Local SV value used) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in position proportioning control, set to the feedback resistance (FBR) input value.	Depends on model code. When not specifying: 0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
133 (0x0085)	Event 4 hold action	64	R/W	0: OFF 1: Hold action ON (At power turned on) 2: Re-hold action ON (At power turned on and SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Depends on model code. When not specifying: 0
134 (0x0086)	Event 4 interlock	64	R/W	0: Unused 1: Used	0
135 (0x0087)	Event 4 differential gap	64	R/W	① Deviation, process, set value or Deviation action between channels: 0 to Input span (Unit: °C [°F]) ② MV: 0.0 to 110.0 % Becomes invalid when the Event 4 type corresponds to “9: Control loop break alarm (LBA).”	① TC/RTD: 1 °C [°F] V/I: 0.1 % ② 0.1 %
136 (0x0088)	Event 4 delay timer	64	R/W	0 to 18000 seconds	0
137 (0x0089)	Force ON of Event 4 action	64	R/W	Bit data b0: Event output turned on at input error occurrence b1: Event output turned on in manual mode b2: Event output turned on during the autotuning (AT) function is being executed b3: Event output turned on during the setting change rate limiter is being operated b4 to b15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15]	0
138 (0x008A)	CT ratio	64	R/W	0 to 9999	CTL-6-P-N: 800 CTL-12-S56- 10L-N: 1000
139 (0x008B)	CT assignment	64	R/W	0: None 1: OUT1 2: OUT2 3: OUT3 4: OUT4	1

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ID	Name	Number of data items	Attribute	Data range	Factory set value
140 (0x008C)	Heater break alarm (HBA) type	64	R/W	0: Heater break alarm (HBA) type A (Time-proportional control output) 1: Heater break alarm (HBA) type B (Continuous control output and time-proportional control output)	1
141 (0x008D)	Number of heater break alarm (HBA) delay times	64	R/W	0 to 255 times	5
142 (0x008E) ⋮ 145 (0x0091)	Unused	—	—	—	—
146 (0x0092)	Hot/Cold start	64	R/W	0: Hot start 1 1: Hot start 2 2: Cold start	0
147 (0x0093)	Start determination point	64	R/W	0 to Input span (The unit is the same as input value.) (0: Action depending on the Hot/Cold start selection)	Depends on specifications.
148 (0x0094)	Unused	—	—	—	—
149 (0x0095)	Unused	—	—	—	—
150 (0x0096)	SV tracking	64	R/W	0: Unused 1: Used	1
151 (0x0097)	MV transfer function [Action taken when changed to Manual mode from Auto mode]	64	R/W	0: MV in Auto mode is used. [Balanceless-bumpless function] 1: MV in previous Manual mode is used.	0
152 (0x0098)	Control action	64	R/W	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action) 2: Brilliant II Heat/Cool PID control [water cooling] 3: Brilliant II Heat/Cool PID control [air cooling] 4: Brilliant II Heat/Cool PID control [Cooling gain linear type] 5: Position proportioning control Odd channel: From 0 to 5 can be set. Even channel: Only 0 or 1 can be set.	Depends on model code. When not specifying: 1
153 (0x0099)	Integral/derivative time decimal point position ♣	64	R/W	0: 1 second setting (No decimal place) 1: 0.1 seconds setting (One decimal place)	0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
154 (0x009A)	Derivative action ♣	64	R/W	0: Measured value derivative 1: Deviation derivative	0
155 (0x009B)	Undershoot suppression factor ♣	64	R/W	0.000 to 1.000	Water cooling: 0.100 Air cooling: 0.250 Cooling gain linear type: 1.000
156 (0x009C)	Derivative gain ♣	64	R/W	0.1 to 10.0	6.0
157 (0x009D)	ON/OFF action differential gap (upper) ♣	64	R/W	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: 0.0 to 100.0 % of input span	TC/RTD: 1 °C [°F] V/I: 0.1 %
158 (0x009E)	ON/OFF action differential gap (lower) ♣	64	R/W		TC/RTD: 1 °C [°F] V/I: 0.1 %
159 (0x009F)	Action (high) at input error ♣	64	R/W	0: Normal control 1: Manipulated output value at input error	0
160 (0x00A0)	Action (low) at input error ♣	64	R/W		0
161 (0x00A1)	Manipulated output value at input error ♣	64	R/W	–105.0 to +105.0 % Actual output values become those restricted by the output limiter. Position proportioning control: If there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected, an action taken when abnormal is in accordance with the value action setting during STOP.	0.0
162 (0x00A2)	Manipulated output value at STOP mode [heat-side] ♣	64	R/W	–5.0 to +105.0 % Position proportioning control: Only when there is feedback resistance (FBR) input and it does not break, the manipulated output value [heat-side] at STOP is output.	–5.0
163 (0x00A3)	Manipulated output value at STOP mode [cool-side] ♣	64	R/W		–5.0
164 (0x00A4)	Output change rate limiter (up) [heat-side] ♣	64	R/W	0.0 to 100.0 %/seconds (0.0: OFF)	0.0
165 (0x00A5)	Output change rate limiter (down) [heat-side] ♣	64	R/W		0.0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
166 (0x00A6)	Output limiter (high) [heat-side] ♣	64	R/W	Output limiter (low) [heat-side] to 105.0 % Position proportioning control: Becomes valid only when there is feedback resistance (FBR) input and no feedback resistance (FBR) input is disconnected.	105.0
167 (0x00A7)	Output limiter (low) [heat-side] ♣	64	R/W	–5.0 % to Output limiter (high) [heat-side] Position proportioning control: Becomes valid only when there is feedback resistance (FBR) input and no feedback resistance (FBR) input is disconnected.	–5.0
168 (0x00A8)	Output change rate limiter (up) [cool-side] ♣	64	R/W	0.0 to 100.0 %/seconds (0.0: OFF)	0.0
169 (0x00A9)	Output change rate limiter (down) [cool-side] ♣	64	R/W	Becomes invalid when in position proportioning control.	0.0
170 (0x00AA)	Output limiter (high) [cool-side] ♣	64	R/W	Output limiter (low) [cool-side] to 105.0 %	105.0
171 (0x00AB)	Output limiter (low) [cool-side] ♣	64	R/W	–5.0 % to Output limiter (high) [cool-side]	–5.0
172 (0x00AC)	Unused	—	—	—	—
173 (0x00AD)	Unused	—	—	—	—
174 (0x00AE)	AT bias ♣	64	R/W	–Input span to +Input span	0
175 (0x00AF)	AT cycles ♣	64	R/W	0: 1.5 cycles 1: 2.0 cycles 2: 2.5 cycles 3: 3.0 cycles	1
176 (0x00B0)	Output value with AT turned on ♣	64	R/W	Output value with AT turned off to + 105.0 % Actual output values become those restricted by the output limiter. Position proportioning control: Becomes valid only when there is feedback resistance (FBR) input and no feedback resistance (FBR) input is disconnected (high limit of feedback resistance input at AT).	105.0
177 (0x00B1)	Output value with AT turned off ♣	64	R/W	–105.0 % to Output value with AT turned on Actual output values become those restricted by the output limiter. Position proportioning control: Becomes valid only when there is feedback resistance (FBR) input and no feedback resistance (FBR) input is disconnected (low limit of feedback resistance input at AT).	–105.0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
178 (0x00B2)	AT differential gap time ♣	64	R/W	0.0 to 50.0 seconds	10.0
179 (0x00B3)	Proportional band adjusting factor [heat-side] ♣	64	R/W	0.01 to 10.00 times	1.00
180 (0x00B4)	Integral time adjusting factor [heat-side] ♣	64	R/W		1.00
181 (0x00B5)	Derivative time adjusting factor [heat-side] ♣	64	R/W		1.00
182 (0x00B6)	Proportional band adjusting factor [cool-side] ♣	64	R/W		1.00
183 (0x00B7)	Integral time adjusting factor [cool-side] ♣	64	R/W		1.00
184 (0x00B8)	Derivative time adjusting factor [cool-side] ♣	64	R/W		1.00
185 (0x00B9)	Proportional band limiter (high) [heat-side] ♣	64	R/W	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/current (I) inputs: 0.0 to 1000.0 % of input span	TC/RTD: Input span V/I: 1000.0 %
186 (0x00BA)	Proportional band limiter (low) [heat-side] ♣	64	R/W	0 (0.0): ON/OFF action (ON/OFF action for both heat and cool actions in case of a heat/cool control type.)	TC/RTD: 0 V/I: 0.0 %
187 (0x00BB)	Integral time limiter (high) [heat-side] ♣	64	R/W	PID control or heat/cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds	3600
188 (0x00BC)	Integral time limiter (low) [heat-side] ♣	64	R/W	Position proportioning control: 1 to 3600 seconds or 0.1 to 1999.9 seconds Varies with the setting of the integral/derivative time decimal point position selection.	PID control, Heat/cool PID control: 0 Position proportioning control: 1
189 (0x00BD)	Derivative time limiter (high) [heat-side] ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds	3600
190 (0x00BE)	Derivative time limiter (low) [heat-side] ♣	64	R/W	Varies with the setting of the integral/derivative time decimal point position selection.	0
191 (0x00BF)	Proportional band limiter (high) [cool-side] ♣	64	R/W	TC/RTD inputs: 1 to input span or 0.1 to input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection.	TC/RTD: Input span V/I: 1000.0 %
192 (0x00C0)	Proportional band limiter (low) [cool-side] ♣	64	R/W	Voltage (V)/current (I) inputs: 0.1 to 1000.0 % of input span	TC/RTD: 1 (0.1) V/I: 0.1 %

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ID	Name	Number of data items	Attribute	Data range	Factory set value
193 (0x00C1)	Integral time limiter (high) [cool-side] ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds	3600
194 (0x00C2)	Integral time limiter (low) [cool-side] ♣	64	R/W	Varies with the setting of the integral/derivative time decimal point position selection.	0
195 (0x00C3)	Derivative time limiter (high) [cool-side] ♣	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds	3600
196 (0x00C4)	Derivative time limiter (low) [cool-side] ♣	64	R/W	Varies with the setting of the integral/derivative time decimal point position selection. If control is other than heat/cool PID control, set to RO (Only reading data is possible).	0
197 (0x00C5)	Open/Close output neutral zone ♣	64	R/W	0.1 to 10.0 % of output	2.0
198 (0x00C6)	Unused	—	—	—	—
199 (0x00C7)	Action at feedback resistance (FBR) input break ♣	64	R/W	0: Action depending on the valve action at STOP 1: Control action continued	0
200 (0x00C8)	Feedback adjustment ♣	64	R/W	0: Adjustment end 1: Open-side adjustment start 2: Close-side adjustment start	—
201 (0x00C9)	Control motor time ♣	64	R/W	5 to 1000 seconds	10
202 (0x00CA)	Integrated output limiter ♣	64	R/W	0.0 to 200.0 % of control motor time (0.0: OFF) Becomes invalid when there is feedback resistance (FBR) input.	150.0
203 (0x00CB)	Valve action at STOP ♣	64	R/W	0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON Becomes valid when there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected.	0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
ID204 is normal setting data.					
204 (0x00CC)	Startup tuning (ST)	64	R/W	0: Startup tuning (ST) unused 1: Execute once * 2: Execute always * Automatically reverts to "0" after Startup tuning (ST) ends. The startup tuning (ST) function is activated according to the ST start condition selected. If control is other than position proportioning control, set to RO (Only reading data is possible).	0
ID205 to ID209 are engineering setting data. [Writable in the STOP mode]					
205 (0x00CD)	ST proportional band adjusting factor ♣	64	R/W	0.01 to 10.00 times	1.00
206 (0x00CE)	ST integral time adjusting factor ♣	64	R/W		1.00
207 (0x00CF)	ST derivative time adjusting factor ♣	64	R/W		1.00
208 (0x00D0)	ST start condition ♣	64	R/W	0: Activate the startup tuning (ST) function when the power is turned on; when transferred from STOP to RUN; or when the set value (SV) is changed. 1: Activate the startup tuning (ST) function when the power is turned on; or when transferred from STOP to RUN. 2: Activate the startup tuning (ST) function when the set value (SV) is changed.	0
209 (0x00D1)	Automatic temperature rise group ♣	64	R/W	0 to 16 (0: Automatic temperature rise function OFF)	0
ID210 is normal setting data.					
210 (0x00D2)	Automatic temperature rise learning	64	R/W	0: Unused 1: Learning * * Automatically reverts to 0 after automatic temperature rise learning ends. If the Automatic temperature rise group corresponds to "0: Automatic temperature rise function OFF," set to RO (Only reading data is possible).	1

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ID	Name	Number of data items	Attribute	Data range	Factory set value
ID211 to ID224 are engineering setting data. [Writable in the STOP mode]					
211 (0x00D3)	Automatic temperature rise dead time ♣	64	R/W	0.1 to 1999.9 seconds	10.0
212 (0x00D4)	Automatic temperature rise gradient data ♣	64	R/W	0.1 to Input span/minutes	1.0
213 (0x00D5)	Unused	—	—	—	—
214 (0x00D6)	Setting change rate limiter unit time	64	R/W	1 to 3600 seconds	60
215 (0x00D7)	Soak time unit	64	R/W	0: 0 to 5999 minutes [0 hours 00 minutes to 99 hours 59 minutes] 1: 0 to 11999 seconds [0 minutes 00 seconds to 199 minutes 59 seconds:] Set the data range of Memory area soak time monitor and Area soak time.	1
216 (0x00D8)	Setting limiter (high)	64	R/W	Setting limiter (low) to Input scale high	Input scale high
217 (0x00D9)	Setting limiter (low)	64	R/W	Input scale low to Setting limiter (high)	Input scale low
218 (0x00DA)	PV transfer function ♣	64	R/W	0: Unused 1: Used	0
219 (0x00DB) ⋮ 224 (0x00E0)	Unused	—	—	—	—
ID225 to ID235 are normal setting data.					
225 (0x00E1)	Controller state 1	31	RO	Bit data Z-TIO module: b0: Burnout state b1: Unused b2: Event 1 state b3: Event 2 state b4: Event 3 state b5: Event 4 state b6: Heater break alarm (HBA) state b7 to b15: Unused OR data for each Z-TIO module. Z-DIO module: b0 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 125]	—

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ID	Name	Number of data items	Attribute	Data range	Factory set value
226 (0x00E2)	Controller state 2	31	RO	Bit data Z-TIO module: b0: Adjustment data error b1: Data back-up error b2: A/D conversion error b3: Unused b4: Unused b5: Logic output data error b6 to b14: Unused b15: Controller communication error Z-DIO module: b0: Unused b1: Data back-up error b2 to b14: Unused b15: Controller communication error Data 0: OFF 1: ON [Decimal number: 0 to 32807]	—
227 (0x00E3) ⋮ 230 (0x00E6)	Unused	—	—	—	—
231 (0x00E7)	Comprehensive alarm state ¹	1	RO	Bit data b0: Burnout state b1: Unused b2: Event 1 state b3: Event 2 state b4: Event 3 state b5: Event 4 state b6: Heater break alarm (HBA) state b7 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 127]	—
232 (0x00E8)	Controller alarm state ¹	2	RO	Bit data Object instance 1: b0 to b15: Controller 1 to 16 Object instance 2: b0 to b14: Controller 17 to 31 Data 0: OFF 1: ON [Decimal number: 0 to 65535] OR of Controller state 1 (ID: 225)	—
233 (0x00E9)	Error state ¹	2	RO	Bit data Object instance 1: b0 to b15: Controller 1 to 16 Object instance 2: b0 to b14: Controller 17 to 31 Data 0: OFF 1: ON [Decimal number: 0 to 65535] OR of Controller state 2 (ID: 226)	—

¹ Valid only when Explicit message communication is used.

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ID	Name	Number of data items	Attribute	Data range	Factory set value
234 (0x00EA)	RUN/STOP ¹	2	R/W	Bit data Object instance 1: b0 to b15: Controller 1 to 16 Object instance 2: b0 to b14: Controller 17 to 31 Data RUN/STOP state is depending on the value of RUN/STOP logic selection (ID: 242) • ID: 242 = 0 0: RUN (control start) 1: STOP (control stop) • ID: 242 = 1 0: STOP (control stop) 1: RUN (control start) [Decimal number: 0 to 65535] Link RUN/STOP transfer (ID: 36)	0
235 (0x00EB)	Setting update flag ¹	1	RO	0: Setting update is completed 1: During setting update	—
ID236, ID237 are communication environment setting data.					
236 (0x00EC)	Number of polling I/O communication controllers ¹	1	R/W	1 to 31	10
237 (0x00ED)	Unused	—	—	—	—
ID238 is normal setting data.					
238 (0x00EE)	COM-JH error code ¹	1	RO	Bit data b0: Back-up error b1: Controller communication error b2 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 3]	—
After ID239 are communication environment setting data.					
239 (0x00EF)	Number of connected controller in controller communication ¹	1	RO	0 to 31	—
240 (0x00F0)	Number of communication measured data items (IN) when conducting polling I/O communication ^{1,2}	1	R/W	0: Depends on the DIP switch setting 1 to 5: 5 words 6 to 200: 6 to 200 words	0
241 (0x00F1)	Number of communication setting data items (OUT) when conducting polling I/O communication ^{1,2}	1	R/W	0: Depends on the DIP switch setting 1 to 5: 5 words 6 to 200: 6 to 200 words	0

¹ Valid only when Explicit message communication is used.² The setting is validated when the power is turned off once after the setting is changed and it is turned on again.

 : It is possible to set in the communication environment setting by the rotary switch of COM-JH (See P. 23) or configuration tool (See P. 33).

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ID	Name	Number of data items	Attribute	Data range	Factory set value
242 (0x00F2)	RUN/STOP logic selection ^{1,2}	1	R/W	0: RUN = 0, STOP = 1 1: RUN = 1, STOP = 0 Valid to RUN/STOP (ID: 234) and the 4th word and the 5th word in the polling I/O communication setting item (OUT). However, invalid to the RUN/STOP transfer (ID: 36) and the ID6 of Z-DIO module object (0x66: 66Hex).	0
243 (0x00F3)	Setting validity selection ¹	1	R/W	0: The setting is validated when the power is turned off once after the setting is changed and it is turned on again. 1: The setting is validated just after the setting is changed. Object data • The data of "Controller communication item setting object (0xC7)" • The data of "Number of polling I/O communication controllers (ID: 236)"	0
244 (0x00F4)	Unused	—	—	—	—
245 (0x00F5)	Controller address setting ^{1,2}	1	R/W	0 to 32 (0: No communication)	1 to 31
246 (0x00F6)	Action mode selection ^{1,2} , ◆	1	R/W	Bit data b0: Address setting method transfer 0: Continuous setting 1: Free setting b1: PID/AT transfer polling I/O communication 0: Invalid 1: Valid b2 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 3]	1
247 (0x00F7)	Automatic acquisition of controller address ^{1,2}	1	R/W	0: Do not execute the automatic acquisition 1: Execute the automatic acquisition	0
248 (0x00F8) ⋮ 255 (0x00FF)	Unused	—	—	—	—

¹ Valid only when Explicit message communication is used.² The setting is validated when the power is turned off once after the setting is changed and it is turned on again.

□ : It is possible to set in the communication environment setting by the rotary switch of COM-JH (See P. 23) or configuration tool (See P. 33).

◆: Communication environment setting by rotary switch of COM-JH is possible.

7.3 Z-TIO Module Extended Object (0x65: 65Hex)

ID	Name	Number of data items	Attribute	Data range	Factory set value
1 (0x0001)	Comprehensive event state	64	RO	Bit data b0: Event 1 state b1: Event 2 state b2: Event 3 state b3: Event 4 state b4: Heater break alarm state b5: Temperature rise completion b6: Burnout b7 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 127]	—
2 (0x0002)	Logic output monitor			Bit data b0: Logic output 1 b1: Logic output 2 b2: Logic output 3 b3: Logic output 4 b4: Logic output 5 b5: Logic output 6 b6: Logic output 7 b7: Logic output 8 b8 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255]	—
3 (0x0003)	Output distribution selection	64	R/W	0: Control output 1: Distribution output	0
4 (0x0004)	Output distribution bias	64	R/W	−100.0 to +100.0 %	0.0
5 (0x0005)	Output distribution ratio	64	R/W	−9.999 to +9.999	1.000
6 (0x0006)	Minimum ON/OFF time of proportioning cycle	64	R/W	0 to 1000 ms This item becomes RO (Only reading data is possible) for the voltage/current output specification.	0
7 (0x0007)	Area soak time stop function	64	R/W	0: No function 1: Event 1 2: Event 2 3: Event 3 4: Event 4	0
8 (0x0008)	EDS mode (for disturbance 1)	64	R/W	0: No function 1: EDS function mode 2: Learning mode 3: Tuning mode	0
9 (0x0009)	EDS mode (for disturbance 2)	64	R/W	EDS function: External disturbance suppression function	0
10 (0x000A)	EDS value 1 (for disturbance 1)	64	R/W	−100.0 to +100.0 %	0.0
11 (0x000B)	EDS value 1 (for disturbance 2)	64	R/W		0.0
12 (0x000C)	EDS value 2 (for disturbance 1)	64	R/W		0.0
13 (0x000D)	EDS value 2 (for disturbance 2)	64	R/W		0.0

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ID	Name	Number of data items	Attribute	Data range	Factory set value
14 (0x000E)	EDS transfer time (for disturbance 1)	64	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds	0
15 (0x000F)	EDS transfer time (for disturbance 2)	64	R/W		0
16 (0x0010)	EDS action time (for disturbance 1)	64	R/W	1 to 3600 seconds	600
17 (0x0011)	EDS action time (for disturbance 2)	64	R/W		600
18 (0x0012)	EDS action wait time (for disturbance 1)	64	R/W	0.0 to 600.0 seconds	0.0
19 (0x0013)	EDS action wait time (for disturbance 2)	64	R/W		0.0
20 (0x0014)	EDS value learning times	64	R/W	0 to 10 times (0: No learning mode)	1
21 (0x0015)	EDS start signal	64	R/W	0: EDS start signal OFF 1: EDS start signal ON (for disturbance 1) 2: EDS start signal ON (for disturbance 2)	0
22 (0x0016)	Operation mode	64	R/W	0: Unused 1: Monitor 2: Monitor + Event function 3: Control	3
23 (0x0017)	Communication switch for logic	16	R/W	Bit data b0: Communication switch 1 b1: Communication switch 2 b2: Communication switch 3 b3: Communication switch 4 b4 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15]	0
After ID24 are engineering setting data. [Writable in the STOP mode]					
24 (0x0018)	Event 1 channel setting	64	R/W	1: Channel 1 2: Channel 2 3: Channel 3 4: Channel 4 This function is valid when "deviation between channels" is selected	1
25 (0x0019)	Event 2 channel setting	64	R/W		1
26 (0x001A)	Event 3 channel setting	64	R/W		1
27 (0x001B)	Event 4 channel setting	64	R/W		1
28 (0x001C)	EDS transfer time decimal point position ♣	64	R/W	0: 1 second setting (No decimal place) 1: 0.1 seconds setting (One decimal place)	0
29 (0x001D)	Output average processing time for EDS ♣	64	R/W	0.1 to 200.0 seconds	1.0
30 (0x001E)	Responsive action trigger point for EDS ♣	64	R/W	0 to Input span (Unit: °C [°F], %)	1

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ID	Name	Number of data items	Attribute	Data range	Factory set value
31 (0x001F)	Operation mode assignment 1 (Logic output selection function) Logic output 1 to 4	64	R/W	0: No assignment 1: Operation mode (monitor, control) 2: Operation mode (monitor, event function, control) 3: Auto/Manual 4: Remote/Local 5: Interlock release	0
32 (0x0020)	Operation mode assignment 2 (Logic output selection function) Logic output 5 to 8	64	R/W		0
33 (0x0021)	SV select function	64	R/W	0: Remote SV function 1: Cascade control function 2: Ratio setting function 3: Cascade control 2 function	0
34 (0x0022)	Remote SV function master channel module address	64	R/W	–1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	–1
35 (0x0023)	Remote SV function master channel selection	64	R/W	1 to 99	1
36 (0x0024)	Output distribution master channel module address	64	R/W	–1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	–1
37 (0x0025)	Output distribution master channel selection	64	R/W	1 to 99	1
38 (0x0026)	Address of interacting modules	64	R/W	–1 (Interact with its own module address) 0 to 99 (Interact with the addresses of other modules)	–1
39 (0x0027)	Channel selection of interacting modules	64	R/W	1 to 99 Becomes valid when the selected module is “Z-TIO module”.	1
40 (0x0028)	Selection switch of interacting modules	64	R/W	Bit data b0: Memory area number b1: Operation mode b2: Auto/Manual b3: Remote/Local b4: EDS start signal b5: Interlock release b6: Suspension of area soak time b7 to b15: Unused Data 0: No interaction 1: Interact with other channels [Decimal number: 0 to 127]	0
41 (0x0029)	Control RUN/STOP holding setting	16	R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1
42 (0x002A)	Interval time	16	R/W	0 to 250 ms	10
43 (0x002B) ⋮ 255 (0x00FF)	Unused	—	—	—	—

7.4 Z-DIO Module Object (0x66: 66Hex)

ID	Name	Number of data items	Attribute	Data range	Factory set value
1 (0x0001)	Digital input (DI) state	16	RO	Bit data b0: DI1 state b1: DI2 state b2: DI3 state b3: DI4 state b4: DI5 state b5: DI6 state b6: DI7 state b7: DI8 state b8 to b15: Unused Data 0: Contact open 1: Contact closed [Decimal number: 0 to 255]	—
2 (0x0002)	Digital output (DO) state	16	RO	Bit data b0: DO1 state b1: DO2 state b2: DO3 state b3: DO4 state b4: DO5 state b5: DO6 state b6: DO7 state b7: DO8 state b8 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255]	—
3 (0x0003)	Error code	16	RO	Bit data b1: Data back-up error b0, b2 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 2]	—
4 (0x0004)	Integrated operating time monitor	16	RO	0 to 19999 hours	—
5 (0x0005)	Backup memory state monitor	16	RO	0: The content of the backup memory does not coincide with that of the RAM. 1: The content of the backup memory coincides with that of the RAM.	—
6 (0x0006)	RUN/STOP transfer	16	R/W	0: STOP (Control stop) 1: RUN (Control start)	0
7 (0x0007)	DO manual output	16	R/W	Bit data b0: DO1 manual output b1: DO2 manual output b2: DO3 manual output b3: DO4 manual output b4: DO5 manual output b5: DO6 manual output b6: DO7 manual output b7: DO8 manual output b8 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255]	0
8 (0x0008)	DO output distribution selection	128	R/W	0: DO output 1: Distribution output	0

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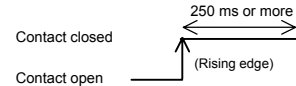
ID	Name	Number of data items	Attribute	Data range	Factory set value
9 (0x0009)	DO output distribution bias	128	R/W	−100.0 to +100.0 %	0.0
10 (0x000A)	DO output distribution ratio	128	R/W	−9.999 to +9.999	1.000
11 (0x000B)	DO proportional cycle time	128	R/W	0.1 to 100.0 seconds	Depends on specification.
12 (0x000C)	DO minimum ON/OFF time of proportioning cycle	128	R/W	0 to 1000 ms	0
After ID13 are engineering setting data. [Writable in the STOP mode]					
13 (0x000D)	DI function assignment	16	R/W	0 to 29 (See P. 79)	Depends on model code. When not specifying: 0
14 (0x000E)	Memory area setting signal	16	R/W	0: Valid 1: Invalid	1
15 (0x000F)	DO signal assignment module address 1	16	R/W	−1, 0 to 99 When “-1” is selected, all of the signals of the same type (except temperature rise completion and DO manual output value) are <i>OR</i> -operated and produced as outputs from DO.	−1
16 (0x0010)	DO signal assignment module address 2	16	R/W		−1
17 (0x0011)	DO output assignment 1 [DO1 to DO4]	16	R/W	0 to 13 (See P. 80)	Depends on model code. When not specifying: 0
18 (0x0012)	DO output assignment 2 [DO5 to DO8]	16	R/W		Depends on model code. When not specifying: 0
19 (0x0013)	DO energized/de-energized	128	R/W	0: Energized 1: De-energized	0
20 (0x0014)	DO output distribution master channel module address	128	R/W	−1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	−1
21 (0x0015)	DO output distribution master channel selection	128	R/W	1 to 99	1
22 (0x0016)	DO manipulated output value (MV) at STOP mode	128	R/W	−5.0 to +105.0 %	−5.0
23 (0x0017)	DO output limiter (high)	128	R/W	DO output limiter (low) to 105.0 %	105.0
24 (0x0018)	DO output limiter (low)	128	R/W	−5.0 % to DO output limiter (high)	−5.0
25 (0x0019)	Control RUN/STOP holding setting	16	R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1
26 (0x001A)	Interval time	16	R/W	0 to 250 ms	10
27 (0x001B) ⋮ 255 (0x00FF)	Unused	—	—	—	—

● DI assignment table

Set value	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8
0	No assignment							
1	Memory area transfer (1 to 8) ¹				Operation mode ³		Interlock release	AUTO/MAN ⁴
2								REM/LOC ⁴
3								EDS start signal 1
4								Soak stop
5							AUTO/MAN ⁴	RUN/STOP ⁴
6								REM/LOC ⁴
7								EDS start signal 1
8								Soak stop
9							REM/LOC ⁴	RUN/STOP ⁴
10								EDS start signal 1
11								Soak stop
12								RUN/STOP ⁴
13							EDS start signal 1	Soak stop
14								RUN/STOP ⁴
15								EDS start signal 1
16								Soak stop
17					Interlock release	AUTO/MAN ⁴	REM/LOC ⁴	EDS start signal 1
18								Soak stop
19								RUN/STOP ⁴
20								EDS start signal 1
21					AUTO/MAN	REM/LOC	EDS start signal 1	Soak stop
22								RUN/STOP ⁴
23								Soak stop
24								RUN/STOP ⁴
25					REM/LOC	EDS start signal 1	Soak stop	RUN/STOP ⁴
26	Memory area transfer (1, 2) ¹	Area set ²	Interlock release	RUN/STOP ⁴	AUTO/MAN ⁴	REM/LOC ⁴	Operation mode ³	
27	Memory area transfer (1 to 8) ¹			Area set ²	Operation mode ³			
28	Memory area transfer (1, 2) ¹	Area set ²	Interlock release	RUN/STOP ⁴	AUTO/MAN ⁴	REM/LOC ⁴	EDS start signal 1	EDS start signal 2
29	EDS start signal 1	EDS start signal 2					Operation mode ³	

RUN/STOP: RUN/STOP transfer (Contact closed: RUN)
 AUTO/MAN: Auto/Manual transfer (Contact closed: Manual mode)
 REM/LOC: Remote/Local transfer (Contact closed: Remote mode)
 Interlock release (Contact closed: Interlock release)
 EDS start signal 1 (Contact closed: EDS start signal ON [for disturbance 1])
 EDS start signal 2 (Contact closed: EDS start signal ON [for disturbance 2])
 Soak stop (Contact closed: Soak stop)

DI signal will become valid at rising edge after the closed contact is held for 250ms.

¹ Memory area transfer

(x: Contact open - : Contact closed)

	Memory area number							
	1	2	3	4	5	6	7	8
DI1	x	-	x	-	x	-	x	-
DI2	x	x	-	-	x	x	-	-
DI3	x	x	x	x	-	-	-	-

² Area set becomes invalid prior to factory shipment.³ Operation mode transfer

(x: Contact open - : Contact closed)

	Operation mode			
	Unused	Monitor	Monitor + Event function	Control
DI5 (DI7)	x	-	x	-
DI6 (DI8)	x	x	-	-

⁴ Actual device states (AUTO/MAN, REM/LOC, RUN/STOP)

	DI-switched state	Communication-switched state	Actual device state
Auto/Manual transfer ^a (AUTO/MAN)	Manual (Contact closed)	Manual → Auto	Manual mode
		Auto → Manual	
	Auto (Contact open)	Manual → Auto	Auto mode
		Auto → Manual	
Remote/Local transfer ^a (REM/LOC)	Remote (Contact closed)	Remote → Local	Remote mode
		Local → Remote	
	Local (Contact open)	Remote → Local	Local mode
		Local → Remote	
RUN/STOP ^b	RUN (Contact closed)	STOP → RUN	RUN
		RUN → STOP	
	STOP (Contact open)	STOP → RUN	STOP

^a Device state when AUTO/MAN or REM/LOC assigned to DI is set so that the Z-TIO module and Z-DIO module are linked using the Master-slave mode of the Z-TIO module.

^b STOP of RUN/STOP switching is given priority regardless of communication or DI switching.

7. COMMUNICATION DATA LIST

● DO assignment table

[DO1 to DO4]

Set value	DO1	DO2	DO3	DO4
0	No assignment			
1	DO1 manual output	DO2 manual output	DO3 manual output	DO4 manual output
2	Event 1 comprehensive output ¹	Event 2 comprehensive output ²	Event 3 comprehensive output ³	Event 4 comprehensive output ⁴
3	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)
4	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)
5	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)
6	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)
7	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)
8	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)
9	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)
11	HBA (CH1)	HBA (CH2)	HBA (CH3)	HBA (CH4)
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)
13	Temperature rise completion ⁵	HBA comprehensive output ⁶	Burnout state comprehensive output ⁷	DO4 manual output

[DO5 to DO8]

Set value	DO5	DO6	DO7	DO8
0	No assignment			
1	DO5 manual output	DO6 manual output	DO7 manual output	DO8 manual output
2	Event 1 comprehensive output ¹	Event 2 comprehensive output ²	Event 3 comprehensive output ³	Event 4 comprehensive output ⁴
3	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)
4	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)
5	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)
6	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)
7	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)
8	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)
9	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)
11	HBA (CH1)	HBA (CH2)	HBA (CH3)	HBA (CH4)
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)
13	Temperature rise completion ⁵	HBA comprehensive output ⁶	Burnout state comprehensive output ⁷	DO8 manual output

¹ Logical OR of Event 1 (ch1 to ch4)

² Logical OR of Event 2 (ch1 to ch4)

³ Logical OR of Event 3 (ch1 to ch4)

⁴ Logical OR of Event 4 (ch1 to ch4)

⁵ Temperature rise completion status (ON when temperature rise completion occurs for all channels for which event 3 is set to temperature rise completion.)

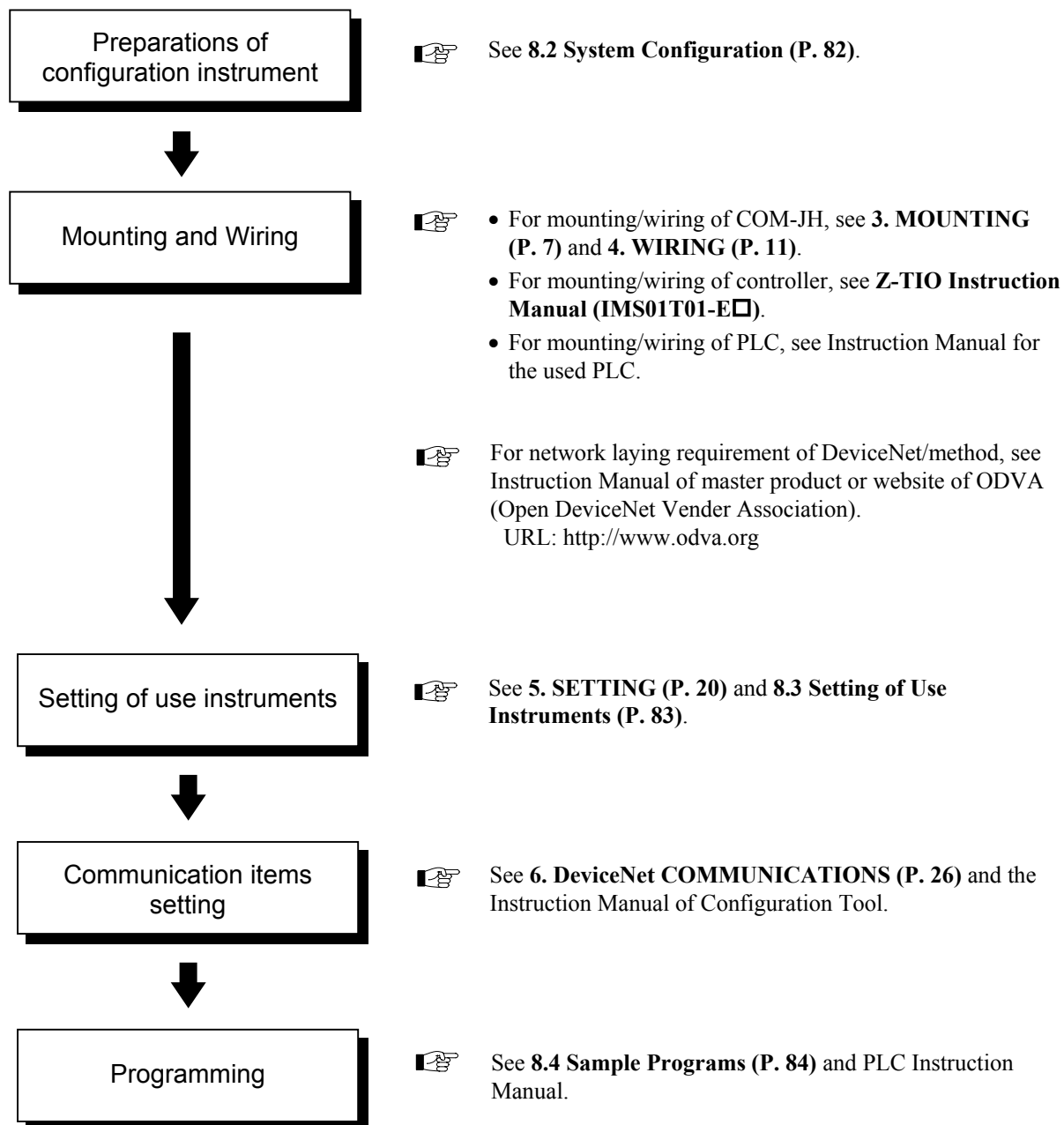
⁶ Logical OR of HBA (ch1 to ch4)

⁷ Logical OR of burnout state (ch1 to ch4)

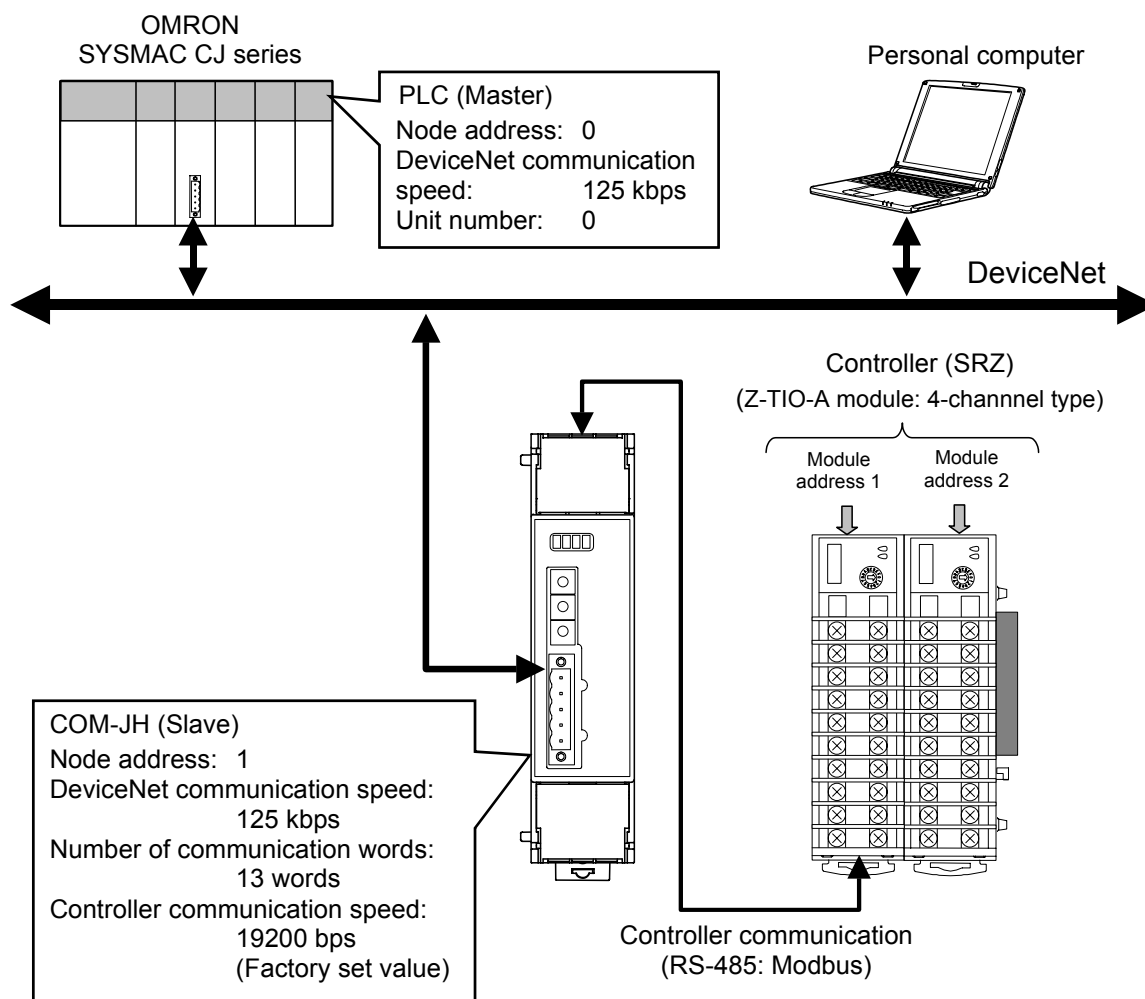
8. USAGE EXAMPLE

This chapter describes a usage example of DeviceNet communication when connected with the COM-JH and controller (SRZ) with the PLC set to a master.

8.1 Handling Procedures



8.2 System Configuration



■ Use instruments

- **DeviceNet communication converter:** COM-JH × 1
- **Controller (SRZ):** Z-TIO-A module (4-channel type) × 2
- **PLC**
 - SYSMAC CJ (OMRON product)
CPU unit: CJ1M, DeviceNet master unit: CJ1W-DRM21
 - or
 - Control Logix 5550 [Rockwell Inc. (Allen-Bradley)]
CPU module: 1756-L1, LINK module (DeviceNet): 1756-DNB
- **Personal computer**
The configuration tool must be installed in a personal computer.
- **DeviceNet communication cable (thick cable)**
- **Connection cable for connecting COM-JH and controller**

8.3 Setting of Use Instruments

Setting of the PLC, COM-JH and controller is shown in the following.

■ PLC setting

[DeviceNet communication requirement]

- Node address: 0
- DeviceNet communication speed: 125 kbps
- Unit number: 0
- Communication cycle time: (Number of COM-JH communication words $\times$ 1.2 + 50) [ms]
or more
 $= 13 \times 1.2 + 50 = 65.6$ [ms] or more

 For setting procedure, see **PLC Instruction Manual**.

■ COM-JH setting

[DeviceNet communication requirement]

- Node address: 1
- DeviceNet communication speed: 125 kbps
- Number of communication words: 13 words
- Controller address: 1, 2 (Module address 1 and Module address 2)
- Action mode: 0
(Address setting method Continuous setting, PID/AT transfer by polling I/O communication: Invalid)
- Automatic acquisition of controller address: 0: Do not execute the automatic acquisition

 For setting procedure, see **5. SETTING (P. 20)** and **6.2 Communication Method (P. 27)**.

[Controller communication requirement]

- Communication speed: 19200 bps

 For setting procedure, see **5.3 DIP Switch Setting (P. 22)**.

■ Controller (SRZ Z-TIO-A module) setting

- Module address: 1 (Address setting switch: 0) and 2 (Address setting switch: 1)
- Communication protocol: Modbus-RTU
- Communication speed: 19200 bps (factory set value)
- Data bit configuration: Data 8-bit, without parity, stop 1-bit

 For setting procedure, see **Z-TIO Host Communication Quick Instruction Manual (IMS01T02-E□)**.

8.4 Sample Programs

8.4.1 Polling I/O communication (When the SYSMAC CJ)



Polling I/O communication is called “Remote I/O communication” in OMRON PLC related instruction manuals.

■ Communication requirement

● Contents of communication parameter setting

Communication data items: Measured data item (IN): Measured value (PV) [Attribute ID: 1]

Set data item (OUT): Set value (SV) [Attribute ID: 45]

Number of communication controllers: 2 modules

Number of communication words: 13 words

Controller address: 1, 2 (Factory set value: 1 to 31)

Module address 1 and Module address 2

Action mode: 1 (Factory set value)

Address setting method: Free setting

PID/AT transfer polling I/O communication: Invalid

Automatic acquisition of controller address:

0 (Factory set value)

Do not execute the automatic acquisition



The above communication parameters can be set via Explicit message communication or by the configuration tool *. For details, see ■ **Communication parameter setting by configuration tool (P. 33)**, or ■ **Communication parameter setting by Explicit message communication (P. 43)**.

* Except the setting of the action mode.

● Memory allocation

Allocate the memory by using the configuration tool.

Allocation method: User-set

Data area: Measured data item (IN) area: D00000 to D00012 (13 words)

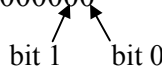
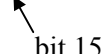
Setting data item (OUT) area: D10000 to D10012 (13 words)

- **Data which a master receives [Response: measured data items (IN)]**

No.	Items	Storage location of read data
1	Receive counter	D00000
2	Alarm state (Controller 1 to 16)	D00001
3	Alarm state (Controller 17 to 31, Setting update flag)	D00002
4	RUN/STOP state (Controller 1 to 16)	D00003
5	RUN/STOP state (Controller 17 to 31)	D00004
6	Measured value (PV) [CH1 of controller 1]	D00005
7	Measured value (PV) [CH2 of controller 1]	D00006
8	Measured value (PV) [CH3 of controller 1]	D00007
9	Measured value (PV) [CH4 of controller 1]	D00008
10	Measured value (PV) [CH1 of controller 2]	D00009
11	Measured value (PV) [CH2 of controller 2]	D00010
12	Measured value (PV) [CH3 of controller 2]	D00011
13	Measured value (PV) [CH4 of controller 2]	D00012

Communication data Nos. 1 to 5 (corresponding to 5 words) are fixed communication data items.

- **Data to send from a master [Request: setting data items (OUT)]**

No.	Items	Data contents	Storage location of write data
1	Setting state selection (All controller)	0	D10000
2	Setting state selection (Controller 1 to 16)	As there are two controllers, only bit 0 (controller 1) and bit 1 (controller 2) can be used. 0000000000000000  [Decimal number: 0 to 3]	D10001
3	Setting state selection (Controller 17 to 31, RUN/STOP)	Only bit 15 (RUN/STOP transfer disabled/enabled) can be used. 0000000000000000  [Decimal number: 0 to 32768]	D10002

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No.	Items	Data contents	Storage location of write data
4	RUN/STOP transfer (Controller 1 to 16)	As there are two controllers, only bit 0 (controller 1) and bit 1 (controller 2) can be used. 0000000000000000 ↑ ↑ bit 1 bit 0 [Decimal number: 0 to 3]	D10003
5	RUN/STOP transfer (Controller 17 to 31)	0	D10004
6	Set value (SV) [CH1 of controller 1]	100	D10005
7	Set value (SV) [CH2 of controller 1]	120	D10006
8	Set value (SV) [CH3 of controller 1]	150	D00007
9	Set value (SV) [CH4 of controller 1]	150	D00008
10	Set value (SV) [CH1 of controller 2]	180	D00009
11	Set value (SV) [CH2 of controller 2]	180	D00010
12	Set value (SV) [CH3 of controller 2]	200	D00011
13	Set value (SV) [CH4 of controller 2]	250	D00012



Communication data Nos. 1 to 5 (corresponding to 5 words) are fixed communication data items.

■ Sample program (ladder)

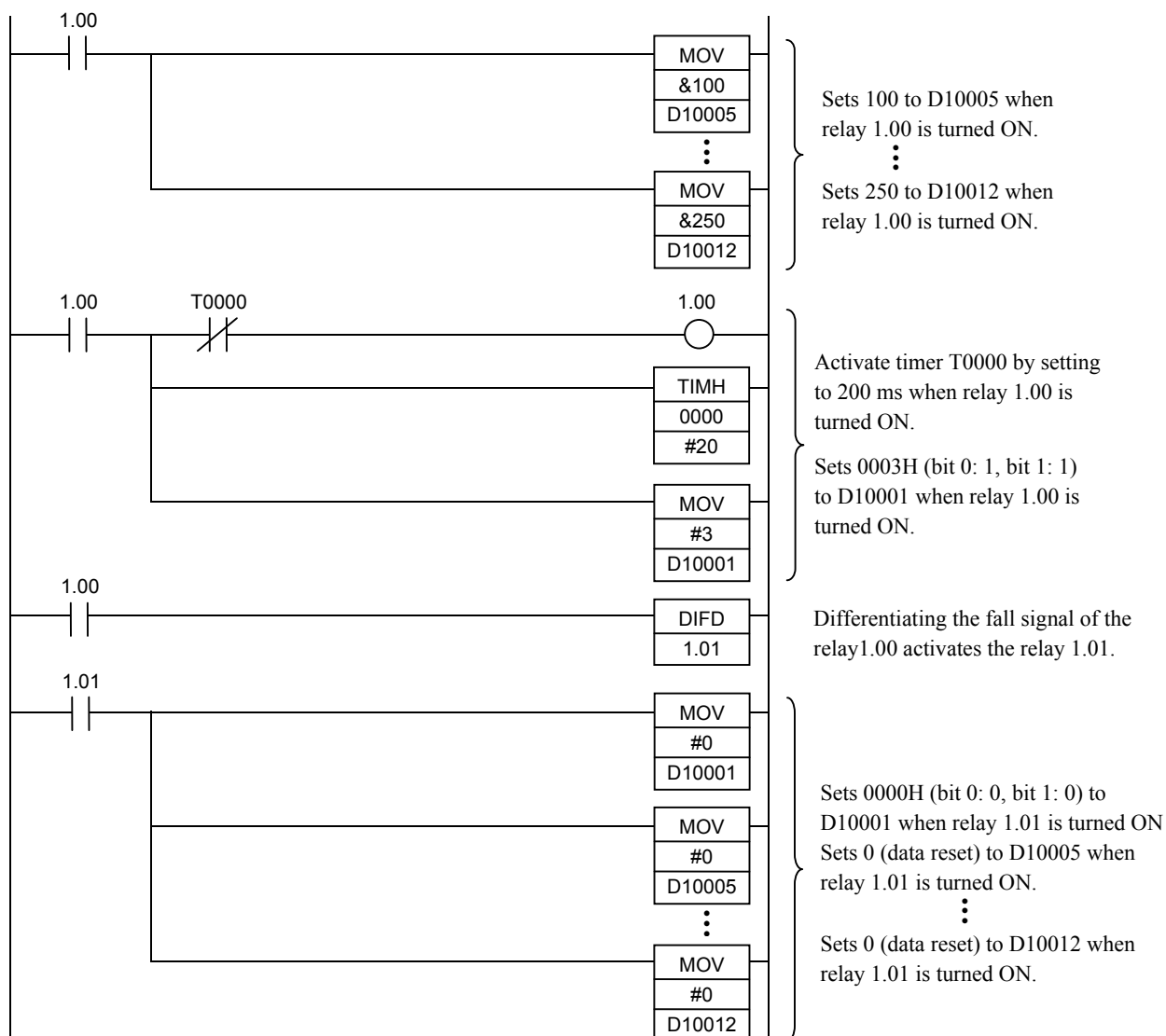
● Measured data items (IN)

Data corresponding to the measured data item (IN) can be checked only by reading the data storage register assigned by the configuration tool.

● Setting data items (OUT)

The following procedure is required for setting data to the controller.

1. Sets 100 to CH1 “Set value (SV): D10005” of Controller 1.
⋮
Sets 250 to CH4 “Set value (SV): D10006” of Controller 2.
2. Set bit 0 (Controller 1) and bit 1 (Controller 2) for “Setting state selection: D10001” to “1: Setting enabled.”
3. Set bit 0 (Controller 1) and bit 1 (Controller 2) for “Setting state selection: D10001” to “0: Setting disabled” after a lapse of preset time* (Example: 200 ms).
* Sets any time longer than the “communication cycle time” set to the PLC.
4. Sets 0 (reset) to CH1 “Set value (SV): D10005” of Controller 1.
⋮
Sets 0 (reset) to CH4 “Set value (SV): D10012” of Controller 2.



8.4.2 Explicit message communication (When the SYSMAC CJ)



In order to conduct Explicit message communication using the OMRON SYSMAC CJ PLC, the FINS command for FINS communication (communication protocol developed by OMRON) is used.

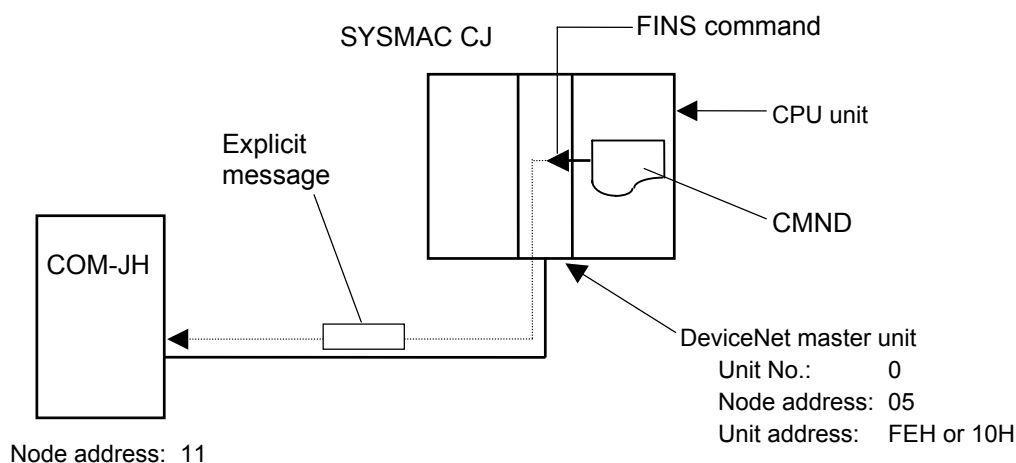


For the FINS command and the CMND instruction, see the Instruction Manual of OMRON SYSMAC CJ PLC.

■ Communication requirement

The vendor code is read from the COM-JH (slave). (RKC vendor code: 394 = 018AH)

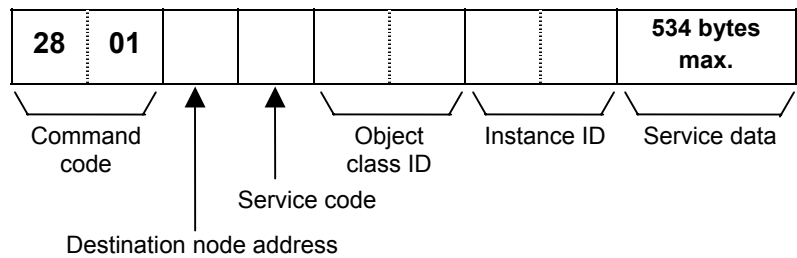
- Using the “Explicit message send” command (2801) of FINS command.
- The “CMND instruction” is used to send FINS commands.
- Write location of request data from the PLC (master): On and after D01000
- Storage location of response data from the COM-JH (slave): On and after D02000
- The completion code is stored in D00006 when execution of CMND has been completed abnormally and then the command is executed again.
- When an Explicit message is sent by the SYSMAC CJ, the send location of the FINS command is assigned to the DeviceNet master unit of its own node instead of the actual send location (COM-JH). The COM-JH node address is specified within Explicit message send command data.



● **Command data format**

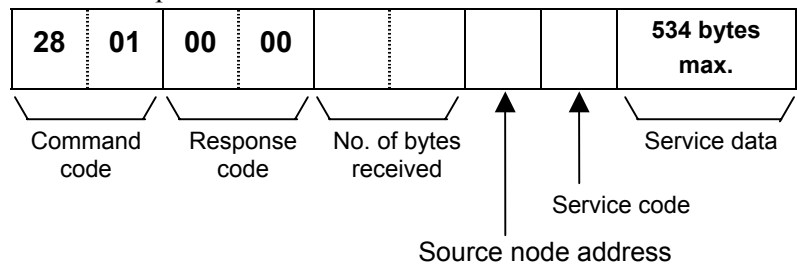
Command data format at communicating by an Explicit message with SYSMAC CJ is shown with the following.

[Request data format from the PLC (master)]

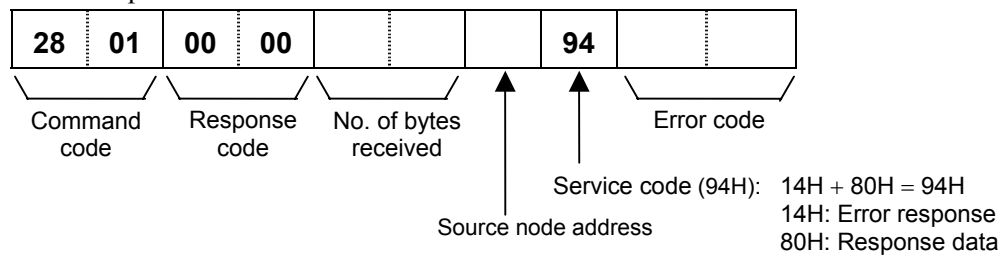


[Response data format]

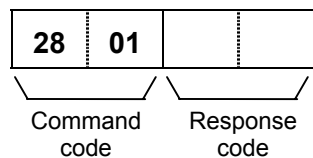
● **Normal response**



● **Error response**



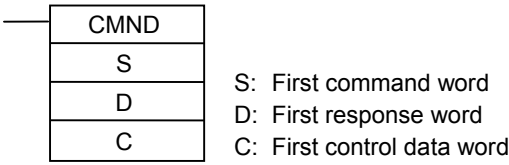
● **Cannot be sent/Timeout**



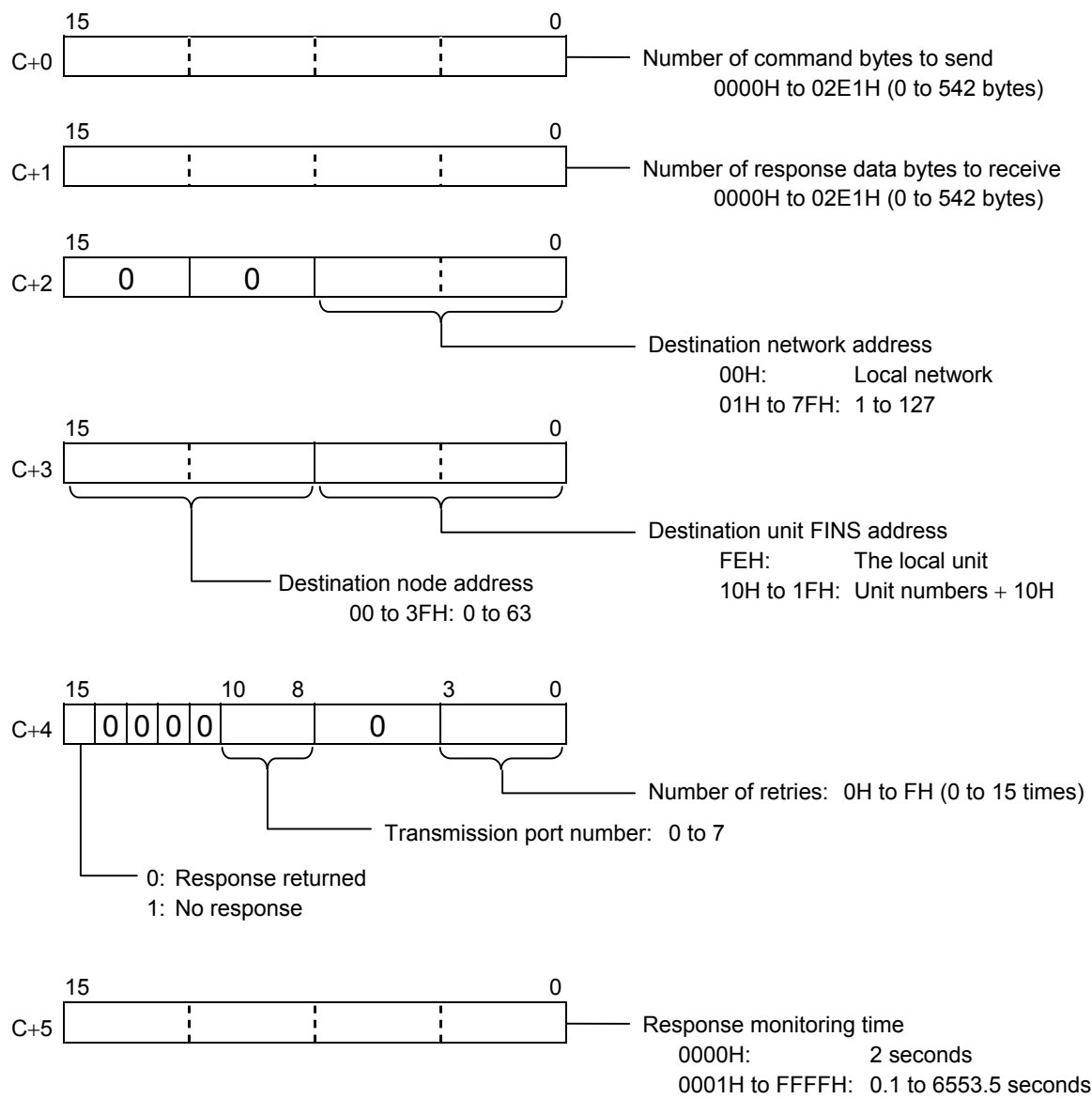
As this response (Cannot be sent/Timeout) is an error response sent to the CPU unit from the DeviceNet master unit of the SYSMAC CJ, this is not an error in DeviceNet communication.

● Description of CMND

[CMND S D C]



Command data is set in order starting with the word specified for the CMND operand S (first command word) and continuing with words with higher addresses in I/O memory in the command block format.



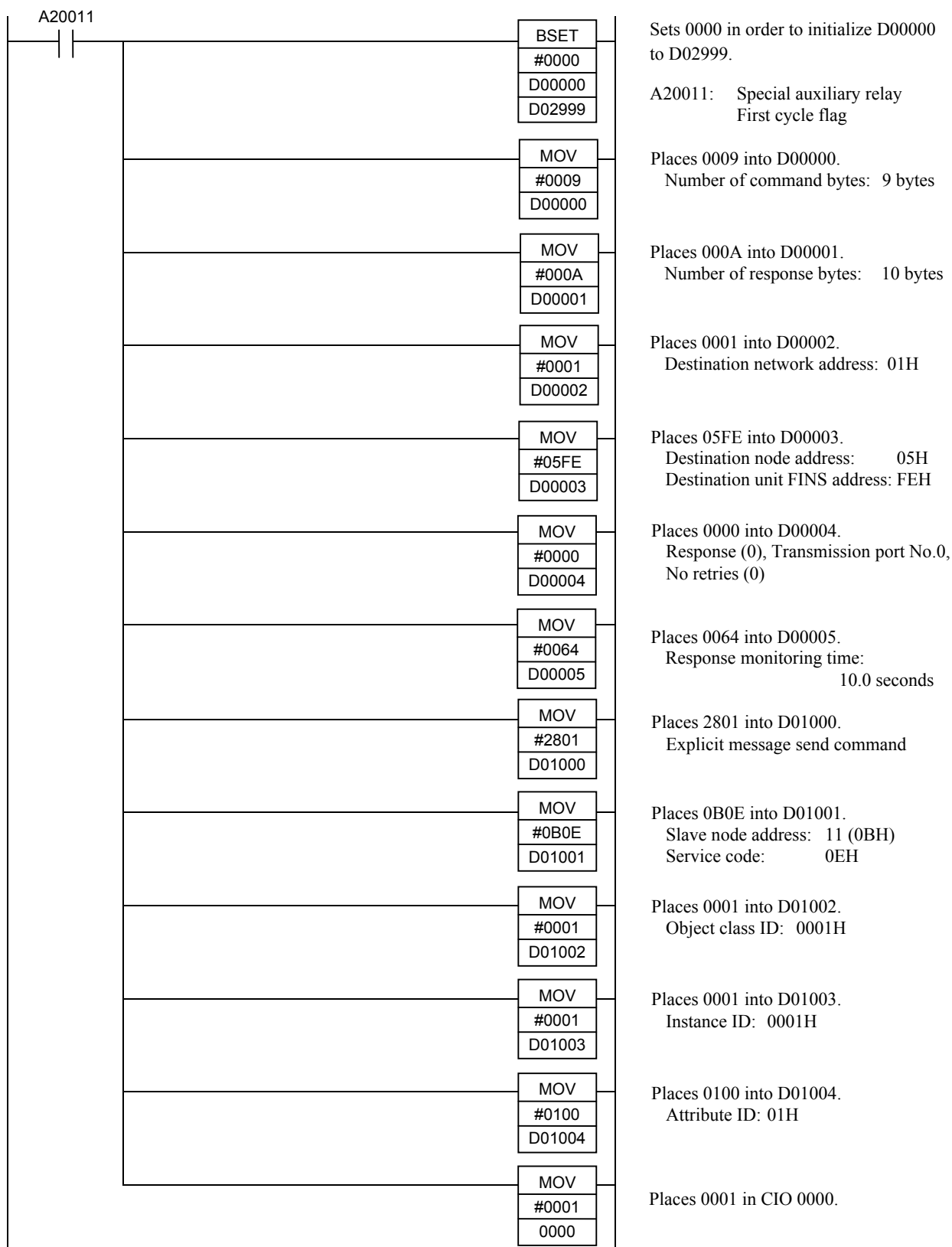
[Sample program]

S	D01000+ 0	2801H	Command code (2801H)
	+ 1	0B0EH	Slave node address: 11 (0BH), Service code (0EH)
	+ 2	0001H	Object class ID (0001H)
	+ 3	0001H	Instance ID (0001H)
	+ 4	0100H	Attribute ID (01H)
D	D02000		First response word at local node
C	D00000+ 0	0009H	Number of command bytes (9 bytes)
	+ 1	000AH	Number of response bytes (10 bytes)
	+ 2	0001H	Destination network address 1 (01H)
	+ 3	05FEH	Destination node address 5 (05H), Destination unit address: FEH (or 10H)
	+ 4	0000H	Response (0), Transmission port No.0 (0H), No retries (0H)
	+ 5	0064H	Response monitoring time: 10.0 seconds (64H)

● Response

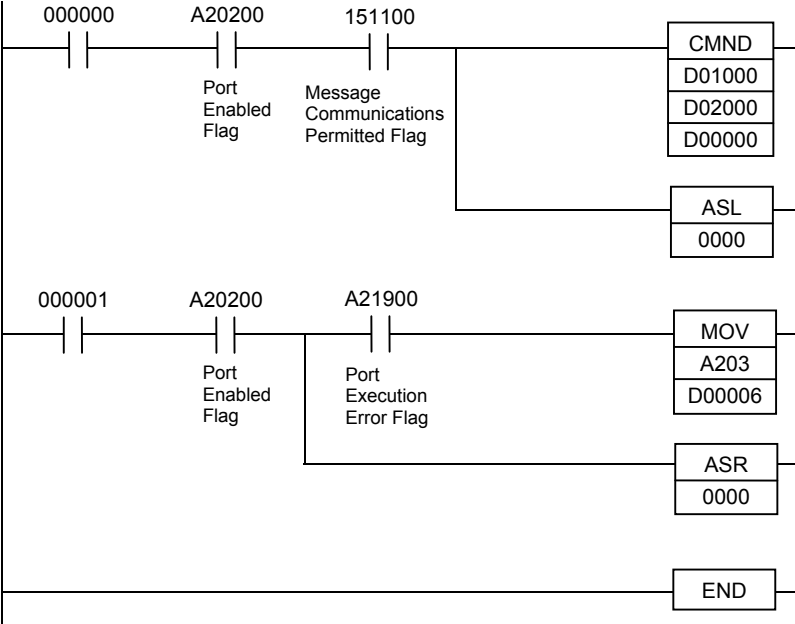
D02000+ 0	2801H	Command code (2801H)
+ 1	0000H	Response code (0000H)
+ 2	0004H	Number of bytes received (0004H)
+ 3	0B8EH	Response source node address: 11 (0BH), Normal completion (8EH)
+ 4	8A01H	Vendor code stored from high to low byte (RKC vendor code: 394 = 018AH)

■ Sample program (ladder)



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Sends 9 bytes of command data to node 05 (unit FE) on network 01 and receives 10 bytes of response data and stores it in D02000.

Shifts the contents of CIO 0000 one bit to the left (CIO 000001 ON).

Stores the completion code in A203 to D00006.

Shifts the contents of CIO 0000 one bit to the right and retry at next cycle (CIO 000000 ON).

9. TROUBLESHOOTING

This section explains probable causes and treatment procedures if any abnormality occurs in the instrument. For any inquiries, please contact RKC sales office or the agent, to confirm the specifications of the product.

If it is necessary to replace a device, always strictly observe the warnings below.



WARNING

- To prevent electric shock or instrument failure, always turn off the system power before replacing the instrument.
- To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.
- To prevent electric shock or instrument failure, do not turn on the power until all the wiring is completed.
- To prevent electric shock or instrument failure, do not touch the inside of the instrument.
- All wiring must be performed by authorized personnel with electrical experience in this type of work.

CAUTION

Do not separate the mainframe from the terminal base with the power turned on. If so, instrument failure may result.

■ COM-JH

Problem	Probable cause	Solution
RUN lamp does not light up	Power not being supplied	Check external breaker etc.
	Appropriate power supply voltage not being supplied	Check the power supply
	Power supply terminal contact defect	Retighten the terminals
	Power supply section defect	Replace COM-JH
RUN lamp flashes rapidly	Data collection just after the power is turned on	After data collection, the lamp goes on, if normal
RUN lamp flashes slowly	Memory backup error	Replace COM-JH
	Controller communication error Controller is not connected	Confirm the controller connection condition and connect correctly
FAIL lamp is lit	Hardware error	Replace COM-JH
FAIL lamp flashes	Communication environment setting mode by the switch	Return the switch to its original position  For the communication environment setting mode by the switch, see 5.4 Communication Environment Setting by Rotary Switch (P. 23) .

■ DeviceNet

Problem	Probable cause	Solution
No response (DeviceNet)	Wrong connection, no connection or disconnection of the DeviceNet communication cable	Confirm the connection method or condition and connect correctly
	Breakage, wrong wiring, or imperfect contact of the DeviceNet communication cable	Confirm the wiring or connector and repair or replace the wrong one
	Communication speed setting of master (PLC) and the slave (COM-JH) is mismatch	Confirm the communication speed setting and set that correctly
	Wrong node address setting	Confirm the address setting and set that correctly

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Problem	Probable cause	Solution
• NS (or NET) lamp OFF • MS (or MOD) lamp ON (Green)	Wait for completion of node address duplication check with a master	If only the COM-JH is in this state though both of the NS/MS (NET/MOD) lamps are lit in green, re-start after checking that each communication speed is the same
MS (or MOD) lamp flashes (Green)	Controller communication error	Remove error factors from the connection with the controller and then make a re-start.
MS (or MOD) lamp ON (Red)	Memory backup error	Replace COM-JH
• NS (or NET) lamp ON (Red) • MS (or MOD) lamp ON (Green)	Node address duplication	Re-start after the re-setting is made so that no node address is duplicated
	Bus off status (communication stop by data abnormality frequent occurrence)	Re-start after checking the following items. • Does the speed coincide with the master communication speed ? • Is not the DeviceNet communication cable connected yet, incorrectly connected or removed ? • Is the length of the DeviceNet communication cable appropriate ? • Are termination resistors (121 Ω) connected only to both ends of the trunk line ? • Does much noise exist ?
	Breakdown of communication device	Replace COM-JH
• NS (or NET) lamp flashes (Red) • MS (or MOD) lamp ON (Green)	DeviceNet communication I/O connection time-out state	• Set the I/O connection Expected packet rate (class: 0x05, instance: 2, attribute: 9) to 0 (No time-out) or set it to a sufficiently large value. • Lengthen the master I/O message communication cycle time.

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Problem	Probable cause	Solution
• NS (or NET) lamp flashes (Green) • MS (or MOD) lamp ON (Green)	DeviceNet communication Communication have not yet been established	It is checked whether or not the COM-JH is registered to the master as a slave. Re-start after checking the following items. • Does the speed coincide with the master communication speed ? • Is not the DeviceNet communication cable connected yet, incorrectly connected or removed ? • Is the length of the DeviceNet communication cable appropriate ? • Are termination resistors (121 Ω) connected only to both ends of the trunk line ? • Does much noise exist ?

10. SPECIFICATIONS

■ DeviceNet communication

Protocol:	DeviceNet
Supported connection:	Polling I/O, Explicit message
Connection method:	Multi-drop connection, T-branch connection (Terminating resistor is necessary)
Communication speed:	125 kbps, 250 kbps, 500 kbps (Communication speed can be selected with switch) Factory set value: 125 kbps

Communication length:

Communication speed	Maximum network length *		Maximum drop length	Cumulative drop length
	Thick trunk length	Thin trunk length		
125 kbps	500 m	100 m	6 m	156 m or less
250 kbps	250 m			78 m or less
500 kbps	100 m			39 m or less

* The maximum of length between nodes

Maximum number of connection nodes:

64 (including master)

Error control: CRC error, Node address (MAC ID) duplication check

Conforms to DeviceNet specification:

Volume I –Release2.0

Volume II –Release2.0

Device profile name: Generic Device

Connection cable: Use the special cable

Connector type: Open-style connector or Micro-style connector

Termination resistor: 121 Ω, 1/4 W (externally connected)

 For details of the device profile, see the **APPENDIX A. DEVICE PROFILES (P. 101)**.

■ Controller communication

Interface: Base on RS-485, EIA standard
Multi-drop connection is available.

Protocol: Modbus-RTU

Synchronous method: Half-duplex start-stop synchronous type

Connection method: 2-wire system, half-duplex multi-drop connection

Communication speed: 9600 bps, 19200 bps, 38400 bps

Data bit configuration: Data 8-bit, Without parity, Stop 1-bit

Maximum connections: 31 controllers (SRZ module) *

* A combined total of up to 31 Z-TIO and Z-DIO modules can be connected in the SRZ.
However, the maximum joinable number of functional modules of the same type is 16.

Connection method: Terminals

Termination resistor: Built-in terminal base of COM-JH [ON/OFF select with switch (120 Ω)]

■ Self-diagnostic function

- Hardware error:** Display: FAIL lamp ON
- Memory backup error:** Display: RUN lamp flashes, MS lamp (Red) ON
 If any error occurs, bit 7 of attribute ID: 5 in Identity object (0x01: 01Hex) is set to 1.
 If any error occurs, bit 0 of attribute ID: 238 in Controller object (0x64: 64Hex) is set to 1.
- Controller communication error:**
 Display: RUN lamp flashes, MS lamp (Green) flashes
 If any error occurs, bit 7 of attribute ID: 5 in Identity object (0x01: 01Hex) is set to 1.
 If any error occurs, bit 2 of attribute ID: 238 in Controller object (0x64: 64Hex) is set to 1.

■ General specifications

- Power supply voltage:** 21.6 to 26.4 V DC [Including power supply voltage variation]
 (Rating 24 V DC)
- Current consumption:** 80 mA max.
- Rush current:** 12 A or less
- Insulation resistance:** Between communication terminal and grounding:
 20 MΩ or more at 500 V DC
 Between power supply terminal and grounding:
 20 MΩ or more at 500 V DC
 Between power supply and communication terminals:
 20 MΩ or more at 500 V DC
- Withstand voltage:** See table

Time: 1 min.	Grounding terminal	Power terminal
Grounding terminal		
Power terminal	600 V AC	
Communication terminal	600 V AC	600 V AC

- Power failure:** A power failure of 20 ms or less will not affect the control action.
- Memory backup:** Backed up by non-volatile memory
 Number of writing: Approx. 100,000 times
 Data storage period: Approx. 10 years
- Vibration:** Amplitude: < 1.5 mm (5 to 9 Hz)
 Acceleration: < 5 m/s² (9 to 150 Hz)
 Each direction of XYZ axes
- Shock:** Height 50 mm or less
 Each direction of XYZ axes (de-energized state)
- Allowable ambient temperature:**
 -10 to +50 °C
- Allowable ambient humidity:**
 5 to 95 % RH
 (Absolute humidity: MAX.W.C 29.3 g/m³ dry air at 101.3 kPa)

Installation environment conditions:

Indoor use
Altitude up to 2000 m

Operating environment:

Avoid the following conditions when selecting the mounting location.

- Rapid changes in ambient temperature which may cause condensation.
- Corrosive or inflammable gases.
- Direct vibration or shock to the mainframe.
- Water, oil, chemicals, vapor or steam splashes.
- Excessive dust, salt or iron particles.
- Excessive induction noise, static electricity, magnetic fields or noise.
- Direct air flow from an air conditioner.
- Exposure to direct sunlight.
- Excessive heat accumulation.

Weight:

Open-style connector type: Approx. 170 g
Micro-style connector type: Approx. 200 g

Dimensions:

30 × 125 × 109.5 mm (W×H×D)

■ Standard**Safety standards:**

UL: UL61010-1
cUL: CAN/CSA-C22.2 No.61010-1

CE marking:

LVD: EN61010-1
EMC: EN61326

C-Tick:

AS/NZS CISPR 11 (equivalent to EN55011)

APPENDIX

A. DEVICE PROFILES

A device profile is the specification that defined each necessary parameter with DeviceNet.
Use it after understanding contents of a device profile of COM-JH fully when connected to a master.

A.1 Basic Data

■ General device data

Conforms to DeviceNet specification	Volume I -Release 2.0 Volume II -Release 2.0
Vender name	RKC INSTRUMENT INC. (Vendor ID = 394)
Device profile name	Generic Device
Product catalog number	Instruction manual number: English: IMR01Y24-E□, IMR01Y28-E□, IMR01Y32-E□, IMR01Y36-E□ Japanese: IMR01Y24-J□, IMR01Y28-J□, IMR01Y32-J□, IMR01Y36-J□
Product revision	2.1

■ Physical conformance data

Network power consumption	2 mA @ 11 V DC 4 mA @ 24 V DC
Connector type	Open-style connector or Micro-style connector
Insulated physical layer	Provided
LEDs supported	Module, Network
MAC ID setting	Rotary switch (Node address setting)
Default MAC ID	63
Communication speed setting	Rotary switch (DeviceNet communication speed setting)
Communication speed supported	125 kbps, 250 kbps, 500 kbps

■ Communication data

Predefined master/slave connection set	Group 2 Only server
Dynamic connection supported (UCMM)	Not supported
Fragmented Explicit Messaging	None

A.2 Object Mounting

■ Identity Object (0x01: 01Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance 1

	ID	Description	Get	Set	Type	Value
Attributes	1	Vendor ID	Yes	No	UINT	394
	2	Product type	Yes	No	UINT	0
	3	Product code	Yes	No	UINT	3
	4	Revision	Yes	No		
		Major revision			USINT	2
		Minor revision			USINT	1
	5	Status (bits supported)	Yes	No	WORD	Note
	6	Serial number	Yes	No	UDINT	
	7	Product name	Yes	No		
		Length			USINT	5
		Name			STRING	COM01
DeviceNet service			Parameter option			
Services	0x05	Reset	0			
	0x0E	Get_Attribute_Single	None			

Note: A bit layout of “Status”

bit 0: Owned

bit 7: Become 1 when controller state of COM-JH become abnormal

Memory backup error, Controller communication error

[Z-TIO Module Object (0x64), Attribute ID 238: COM-JH error code]

bit 1 to 6 and bit 8 to 15: Unused

■ Message Router Object (0x02: 02Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance

Attributes	Not supported
Services	Not supported

■ DeviceNet Object (0x03: 03Hex)

● Object class

	ID	Description	Get	Set	Type	Value
Attributes	1	Revision	Yes	No	UINT	2
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			

● Object instance 1

	ID	Description	Get	Set	Type	Value
Attributes	1	MAC ID	Yes	No	USINT	0 to 63
	2	Baud rate	Yes	No	USINT	0 to 2
	3	BOI	Yes	No	BOOL	0
	4	Bus-off counter	Yes	Yes	USINT	
	5	Allocation information	Yes	No		
		Allocation choice byte			BYTE	
		Master's MAC ID			USINT	
	6	MAC ID switch changed	Yes	No	BOOL	0, 1
	7	Baud rate switch changed	Yes	No	BOOL	0, 1
	8	MAC ID switch value	Yes	No	USINT	0 to 63
	9	Baud rate switch value	Yes	No	USINT	0 to 2
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			
	0x4B	Allocate_Master/Slave_Connection_Set	None			
	0x4C	Release_Group_2_Identifire_Set	None			

■ Assembly Object (0x04: 04Hex)

● Object class

	ID	Description	Get	Set	Type	Value
Attributes	1	Revision	Yes	No	UINT	2
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			

● Object instance 100

	ID	Description	Get	Set	Type	Value
Attributes	3	Data	Yes	No	INT	Measured value (PV) [CH1 of controller 1]
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			

● Object instance 101

	ID	Description	Get	Set	Type	Value
Attributes	3	Data	Yes	Yes	INT	Set value (SV) [CH1 of controller 1]
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			

■ Connection Object (0x05: 05Hex)

● Object class

Attributes	Not supported
Services	Not supported
Number of maximum possible active connection	1

● Object instance 1

Section			Information			Number of maximum instance
	Instance type		Explicit Message			1
	Production trigger		Cyclic			
	Transport type		Server			
	Transport class		3			
	ID	Description	Get	Set	Type	Value
Attributes	1	State	Yes	No	USINT	
	2	Instance type	Yes	No	USINT	0x00
	3	Transport class trigger	Yes	No	BYTE	0x83
	4	Produced connection ID	Yes	No	UINT	
	5	Consumed connection ID	Yes	No	UINT	
	6	Initial comm. Characteristics	Yes	No	BYTE	0x21
	7	Produced connection size	Yes	No	UINT	7
	8	Consumed connection size	Yes	No	UINT	7
	9	Expected packet rate	Yes	Yes	UINT	Default: 2500
	12	Watchdog time-out action	Yes	Yes	USINT	1, 3
	13	Produced connection path length	Yes	No	UINT	0
	14	Produced connection path	Yes	No	(null)	
	15	Consumed connection path length	Yes	No	UINT	0
	16	Consumed connection path	Yes	No	(null)	
DeviceNet service			Parameter option			
Services	0x05	Reset	None			
	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			

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● **Object instance 2**

Section		Information		Number of maximum instance	
Instance type		Polled I/O		1	
Production trigger		Cyclic			
Transport type		Server			
Transport class		2			
ID	Description	Get	Set	Type	Value
Attributes	1 State	Yes	No	USINT	
	2 Instance type	Yes	No	USINT	0x01
	3 Transport class trigger	Yes	No	BYTE	0x82
	4 Produced connection ID	Yes	No	UINT	
	5 Consumed connection ID	Yes	No	UINT	
	6 Initial comm. Characteristics	Yes	No	BYTE	0x01
	7 Produced connection size	Yes	No	UINT	Note
	8 Consumed connection size	Yes	No	UINT	Note
	9 Expected packet rate	Yes	Yes	UINT	Default: 0
	12 Watchdog time-out action	Yes	No	USINT	0
	13 Produced connection path length	Yes	No	UINT	6
	14 Produced connection path	Yes	No		
	Logic Segment, Class			USINT	0x20
	Class Number			USINT	0x04
	Logic Segment, Instance			USINT	0x24
	Instance Number			USINT	0x64
	Logic Segment, Attributes			USINT	0x30
	Attributes Number			USINT	0x03
	15 Consumed connection path length	Yes	No	UINT	6
	16 Consumed connection path	Yes	No		
	Logic Segment, Class			USINT	0x20
	Class Number			USINT	0x04
	Logic Segment, Instance			USINT	0x24
	Instance Number			USINT	0x65
	Logic Segment, Attributes			USINT	0x30
	Attributes Number			USINT	0x03
DeviceNet service		Parameter option			
Services	0x05 Reset	None			
	0x0E Get_Attribute_Single	None			
	0x10 Set_Attribute_Single	None			

Note: Make the setting by any of the following methods. (The value is validated with the power turned on)

- Select with the DIP switch 1. [14 (7 words), 50 (25 words), 90 (45 words) or 200 (100 words)]
- Set with the number of communication data items (attribute ID: 240 and 241) of the Z-TIO module object (0x64: 64Hex).

■ Z-TIO Module Object (0x64: 64Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance □ (□: 1 to 64)

 Object instances 1 to 64 correspond to channels 1 to 4 of controllers (TIO modules of SRZ) 1 to 16.

 If Get is made to the instance No. corresponding to the nonexistent controller No. in communication items other than “unused,” “0” is read while no error occurs if set is made (no data is written).

	ID	Description	Get	Set	Type	Value
Attributes	1	Measured value (PV)	Yes	No	INT	See P. 49
	2	Current transformer (CT) input value monitor	Yes	No	INT	See P. 49
	3	Unused	No	No	UINT	—
	4	Set value (SV) monitor	Yes	No	INT	See P. 49
	5	Remote setting (RS) input value monitor	Yes	No	INT	See P. 49
	6	Burnout state monitor	Yes	No	WORD	See P. 49
	7	Unused	No	No	UINT	—
	8	Event 1 state monitor	Yes	No	WORD	See P. 49
	9	Event 2 state monitor	Yes	No	WORD	See P. 49
	10	Event 3 state monitor	Yes	No	WORD	See P. 49
	11	Event 4 state monitor	Yes	No	WORD	See P. 49
	12	Heater break alarm (HBA) state monitor	Yes	No	WORD	See P. 49
	13	Unused	No	No	UINT	—
	14	Manipulated output value (MV) monitor [heat-side]	Yes	No	INT	See P. 49
	15	Manipulated output value (MV) monitor [cool-side]	Yes	No	INT	See P. 49
	16	Error code	Yes	No	WORD	See P. 49
	17	Unused	No	No	UINT	—
	18	Output state monitor	Yes	No	WORD	See P. 50
	19	Operation mode state monitor	Yes	No	WORD	See P. 50
	20	Memory area soak time monitor	Yes	No	INT	See P. 50
	21	Integrated operating time monitor	Yes	No	INT	See P. 50
	22	Holding peak value ambient temperature monitor	Yes	No	INT	See P. 50
	23	Unused	No	No	UINT	—
	24	Backup memory state monitor	Yes	No	INT	See P. 50
	25	Unused	No	No	UINT	—
	26	Unused	No	No	UINT	—
	27	Unused	No	No	UINT	—
	28	Unused	No	No	UINT	—
	29	Unused	No	No	UINT	—
	30	Unused	No	No	UINT	—

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	ID	Description	Get	Set	Type	Value
Attributes	31	Unused	No	No	UINT	0 to 65535
	32	Unused	No	No	UINT	0 to 65535
	33	PID/AT transfer ^{1,2}	Yes	Yes	INT	See P. 50
	34	Auto/Manual transfer	Yes	Yes	INT	See P. 51
	35	Remote/Local transfer	Yes	Yes	INT	See P. 51
	36	RUN/STOP transfer ³	Yes	Yes	INT	See P. 51
	37	Memory area transfer	Yes	Yes	INT	See P. 51
	38	Interlock release	Yes	Yes	INT	See P. 51
	39	Event 1 set value (EV1)	Yes	Yes	INT	See P. 51
	40	Event 2 set value (EV2)	Yes	Yes	INT	See P. 51
	41	Event 3 set value (EV3)	Yes	Yes	INT	See P. 51
	42	Event 4 set value (EV4)	Yes	Yes	INT	See P. 51
	43	Control loop break alarm (LBA) time	Yes	Yes	INT	See P. 51
	44	LBA deadband	Yes	Yes	INT	See P. 51
	45	Set value (SV)	Yes	Yes	INT	See P. 51
	46	Proportional band [heat-side]	Yes	Yes	INT	See P. 52
	47	Integral time [heat-side]	Yes	Yes	INT	See P. 52
	48	Derivative time [heat-side]	Yes	Yes	INT	See P. 52
	49	Control response parameter	Yes	Yes	INT	See P. 52
	50	Derivative time [cool-side]	Yes	Yes	INT	See P. 52
	51	Proportional band [cool-side]	Yes	Yes	INT	See P. 52
	52	Integral time [cool-side]	Yes	Yes	INT	See P. 52
	53	Overlap/Deadband	Yes	Yes	INT	See P. 53
	54	Manual reset	Yes	Yes	INT	See P. 53
	55	Setting change rate limiter (up)	Yes	Yes	INT	See P. 53
	56	Setting change rate limiter (down)	Yes	Yes	INT	See P. 53
	57	Area soak time	Yes	Yes	INT	See P. 53
	58	Link area number	Yes	Yes	INT	See P. 53
	59	Heater break alarm (HBA) set value	Yes	Yes	INT	See P. 53
	60	Heater break determination point	Yes	Yes	INT	See P. 54
	61	Heater melting determination point	Yes	Yes	INT	See P. 54
	62	Unused	No	No	UINT	—
	63	Unused	No	No	UINT	—
	64	Unused	No	No	UINT	—
	65	PV bias	Yes	Yes	INT	See P. 54
	66	PV digital filter	Yes	Yes	INT	See P. 54
	67	PV ratio	Yes	Yes	INT	See P. 54
	68	PV low input cut-off	Yes	Yes	INT	See P. 54

¹ It is validated only via Explicit message communication. If “PID/AT transfer” is set as the setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” If set as the measured data item (IN), it can be used as is.

² When using PID/AT transfer by polling I/O communication, it is necessary to set action mode selection (Attributes ID: 246) to “PID/AT transfer by polling I/O communication is valid.”

³ If “RUN/STOP transfer” is set as the setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” If set as the measured data item (IN), it can be used as is.

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	ID	Description	Get	Set	Type	Value
Attributes	69	RS bias	Yes	Yes	INT	See P. 54
	70	RS digital filter	Yes	Yes	INT	See P. 54
	71	RS ratio	Yes	Yes	INT	See P. 54
	72	Proportional cycle time	Yes	Yes	INT	See P. 55
	73	Unused	No	No	UINT	—
	74	Manual manipulated output value	Yes	Yes	INT	See P. 55
	75	Unused	No	No	UINT	—
	76	Unused	No	No	UINT	—
	77	Unused	No	No	UINT	—
	78	Unused	No	No	UINT	—
	79	Unused	No	No	UINT	—
	80	Unused	No	No	UINT	—
	81	Unused	No	No	UINT	—
	82	Unused	No	No	UINT	—
	83	Input type	Yes	Yes	INT	See P. 56
	84	Display unit	Yes	Yes	INT	See P. 56
	85	Decimal point position	Yes	Yes	INT	See P. 56
	86	Input scale high	Yes	Yes	INT	See P. 57
	87	Input scale low	Yes	Yes	INT	See P. 57
	88	Input error determination point (high)	Yes	Yes	INT	See P. 57
	89	Input error determination point (low)	Yes	Yes	INT	See P. 57
	90	Burnout direction	Yes	Yes	INT	See P. 57
	91	Square root extraction	Yes	Yes	INT	See P. 57
	92	Unused	No	No	UINT	—
	93	Unused	No	No	UINT	—
	94	Unused	No	No	UINT	—
	95	Unused	No	No	UINT	—
	96	Output assignment	Yes	Yes	INT	See P. 57
	97	Unused	No	No	UINT	—
	98	Unused	No	No	UINT	—
	99	Unused	No	No	UINT	—
	100	Unused	No	No	UINT	—
	101	Energized/De-energized	Yes	Yes	WORD	See P. 57
	102	Unused	No	No	UINT	—
	103	Unused	No	No	UINT	—
	104	Unused	No	No	UINT	—
	105	Unused	No	No	INT	—
	106	Unused	No	No	INT	—
	107	Unused	No	No	INT	—
	108	Unused	No	No	INT	—
	109	Unused	No	No	INT	—
	110	Unused	No	No	INT	—
	111	Unused	No	No	UINT	—
	112	Unused	No	No	UINT	—
	113	Unused	No	No	UINT	—
	114	Event 1 type	Yes	Yes	INT	See P. 58
	115	Event 1 hold action	Yes	Yes	INT	See P. 58
	116	Event 1 interlock	Yes	Yes	INT	See P. 58
	117	Event 1 differential gap	Yes	Yes	INT	See P. 58

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	ID	Description	Get	Set	Type	Value
Attributes	118	Event 1 delay timer	Yes	Yes	INT	See P. 58
	119	Force ON of Event 1 action	Yes	Yes	WORD	See P. 59
	120	Event 2 type	Yes	Yes	INT	See P. 59
	121	Event 2 hold action	Yes	Yes	INT	See P. 60
	122	Event 2 interlock	Yes	Yes	INT	See P. 60
	123	Event 2 differential gap	Yes	Yes	INT	See P. 60
	124	Event 2 delay timer	Yes	Yes	INT	See P. 60
	125	Force ON of Event 2 action	Yes	Yes	WORD	See P. 60
	126	Event 3 type	Yes	Yes	INT	See P. 61
	127	Event 3 hold action	Yes	Yes	INT	See P. 61
	128	Event 3 interlock	Yes	Yes	INT	See P. 61
	129	Event 3 differential gap	Yes	Yes	INT	See P. 61
	130	Event 3 delay timer	Yes	Yes	INT	See P. 62
	131	Force ON of Event 3 action	Yes	Yes	WORD	See P. 62
	132	Event 4 type	Yes	Yes	INT	See P. 62
	133	Event 4 hold action	Yes	Yes	INT	See P. 63
	134	Event 4 interlock	Yes	Yes	INT	See P. 63
	135	Event 4 differential gap	Yes	Yes	INT	See P. 63
	136	Event 4 delay timer	Yes	Yes	INT	See P. 63
	137	Force ON of Event 4 action	Yes	Yes	WORD	See P. 63
	138	CT ratio	Yes	Yes	INT	See P. 63
	139	CT assignment	Yes	Yes	INT	See P. 63
	140	Heater break alarm (HBA) type	Yes	Yes	INT	See P. 64
	141	Number of heater break alarm (HBA) delay times	Yes	Yes	INT	See P. 64
	142	Unused	No	No	UINT	—
	143	Unused	No	No	UINT	—
	144	Unused	No	No	UINT	—
	145	Unused	No	No	UINT	—
	146	Hot/Cold start	Yes	Yes	INT	See P. 64
	147	Start determination point	Yes	Yes	INT	See P. 64
	148	Unused	No	No	UINT	—
	149	Unused	No	No	UINT	—
	150	SV tracking	Yes	Yes	INT	See P. 64
	151	MV transfer function	Yes	Yes	INT	See P. 64
		[Action taken when changed to Manual mode from Auto mode]				
	152	Control action	Yes	Yes	INT	See P. 64
	153	Integral/derivative time decimal point position	Yes	Yes	INT	See P. 64
	154	Derivative action	Yes	Yes	INT	See P. 65
	155	Undershoot suppression factor	Yes	Yes	INT	See P. 65
	156	Derivative gain	Yes	Yes	INT	See P. 65
	157	ON/OFF action differential gap (upper)	Yes	Yes	INT	See P. 65
	158	ON/OFF action differential gap (lower)	Yes	Yes	INT	See P. 65
	159	Action (high) at input error	Yes	Yes	INT	See P. 65
	160	Action (low) at input error	Yes	Yes	INT	See P. 65
	161	Manipulated output value at input error	Yes	Yes	INT	See P. 65

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	ID	Description	Get	Set	Type	Value
Attributes	162	Manipulated output value (MV) at STOP mode [heat-side]	Yes	Yes	INT	See P. 65
	163	Manipulated output value (MV) at STOP mode [cool-side]	Yes	Yes	INT	See P. 65
	164	Output change rate limiter (up) [heat-side]	Yes	Yes	INT	See P. 65
	165	Output change rate limiter (down) [heat-side]	Yes	Yes	INT	See P. 65
	166	Output limiter (high) [heat-side]				See P. 66
	167	Output limiter (low) [heat-side]				See P. 66
	168	Output change rate limiter (up) [cool-side]	Yes	Yes	INT	See P. 66
	169	Output change rate limiter (down) [cool-side]	Yes	Yes	INT	See P. 66
	170	Output limiter (high) [cool-side]	Yes	Yes	INT	See P. 66
	171	Output limiter (low) [cool-side]	Yes	Yes	INT	See P. 66
	172	Unused	No	No	UINT	—
	173	Unused	No	No	UINT	—
	174	AT bias	Yes	Yes	INT	See P. 66
	175	AT cycles	Yes	Yes	INT	See P. 66
	176	Output value with AT turned on	Yes	Yes	INT	See P. 66
	177	Output value with AT turned off	Yes	Yes	INT	See P. 66
	178	AT differential gap time	Yes	Yes	INT	See P. 67
	179	Proportional band adjusting factor [heat-side]	Yes	Yes	INT	See P. 67
	180	Integral time adjusting factor [heat-side]	Yes	Yes	INT	See P. 67
	181	Derivative time adjusting factor [heat-side]	Yes	Yes	INT	See P. 67
	182	Proportional band adjusting factor [cool-side]	Yes	Yes	INT	See P. 67
	183	Integral time adjusting factor [cool-side]	Yes	Yes	INT	See P. 67
	184	Derivative time adjusting factor [cool-side]	Yes	Yes	INT	See P. 67
	185	Proportional band limiter (high) [heat-side]	Yes	Yes	INT	See P. 67
	186	Proportional band limiter (low) [heat-side]	Yes	Yes	INT	See P. 67
	187	Integral time limiter (high) [heat-side]	Yes	Yes	INT	See P. 67
	188	Integral time limiter (low) [heat-side]	Yes	Yes	INT	See P. 67
	189	Derivative time limiter (high) [heat-side]	Yes	Yes	INT	See P. 67
	190	Derivative time limiter (low) [heat-side]	Yes	Yes	INT	See P. 67
	191	Proportional band limiter (high) [cool-side]	Yes	Yes	INT	See P. 67
	192	Proportional band limiter (low) [cool-side]	Yes	Yes	INT	See P. 67
	193	Integral time limiter (high) [cool-side]	Yes	Yes	INT	See P. 68
	194	Integral time limiter (low) [cool-side]	Yes	Yes	INT	See P. 68
	195	Derivative time limiter (high) [cool-side]	Yes	Yes	INT	See P. 68
	196	Derivative time limiter (low) [cool-side]	Yes	Yes	INT	See P. 68
	197	Open/Close output neutral zone	Yes	Yes	INT	See P. 68
	198	Unused	No	No	UINT	—
	199	Action at feedback resistance (FBR) input break	Yes	Yes	INT	See P. 68
	200	Feedback adjustment	Yes	Yes	INT	See P. 68
	201	Control motor time	Yes	Yes	INT	See P. 68
	202	Integrated output limiter	Yes	Yes	INT	See P. 68
	203	Valve action at STOP	Yes	Yes	INT	See P. 68
	204	Startup tuning (ST)	Yes	Yes	INT	See P. 69
	205	ST proportional band adjusting factor	Yes	Yes	INT	See P. 69
	206	ST integral time adjusting factor	Yes	Yes	INT	See P. 69
	207	ST derivative time adjusting factor	Yes	Yes	INT	See P. 69

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	ID	Description	Get	Set	Type	Value
Attributes	208	ST start condition	Yes	Yes	INT	See P. 69
	209	Automatic temperature rise group	Yes	Yes	INT	See P. 69
	210	Automatic temperature rise learning	Yes	Yes	INT	See P. 69
	211	Automatic temperature rise dead time	Yes	Yes	INT	See P. 70
	212	Automatic temperature rise gradient data	Yes	Yes	INT	See P. 70
	213	Unused	No	No	UINT	—
	214	Setting change rate limiter unit time	Yes	Yes	INT	See P. 70
	215	Soak time unit	Yes	Yes	INT	See P. 70
	216	Setting limiter (high)	Yes	Yes	INT	See P. 70
	217	Setting limiter (low)	Yes	Yes	INT	See P. 70
	218	PV transfer function	Yes	Yes	INT	See P. 70
	219	Unused	No	No	UINT	—
	220	Unused	No	No	UINT	—
	221	Unused	No	No	UINT	—
	222	Unused	No	No	UINT	—
	223	Unused	No	No	UINT	—
	224	Unused	No	No	INT	—
	225	Controller state 1	Yes	No	WORD	See P. 70
	226	Controller state 2	Yes	No	WORD	See P. 71
	227	Unused ¹	No	No	UINT	—
	228	Unused ¹	No	No	UINT	—
	229	Unused ¹	No	No	UINT	—
	230	Unused ¹	No	No	UINT	—
	231	Comprehensive alarm state ^{2,3}	Yes	No	WORD	See P. 71
	232	Controller alarm state ^{2,4}	Yes	No	WORD	See P. 71
	233	Error state ^{2,4}	Yes	No	WORD	See P. 71
	234	RUN/STOP ^{2,4}	Yes	Yes	WORD	See P. 72
	235	Setting change flag ^{2,3}	Yes	No	WORD	See P. 72
	236	Number of polling I/O communication controllers ^{2,3,5}	Yes	Yes	UNIT	See P. 72
	237	Unused	No	No	UINT	—
	238	COM-JH error code ^{2,3,6}	Yes	No	WORD	See P. 72

¹ If this data item is set as a measured data item (IN) or setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” In addition, any data item set hereafter is invalidated.

² It is validated only via Explicit message communication. If this data item is set as a measured data item (IN) or setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” In addition, any data item set hereafter is invalidated.

³ Only object instances 1 is valid.

⁴ Only object instances 1 and 2 are valid.

⁵ Data for the set number of controllers is assigned by polling I/O communication. The number of assigned data items is the number of data items for the set number of modules in each item of the attributes set in “Controller communication item setting object (0xC7: C7Hex).”

⁶ Causes of controller communication errors

- No controllers are connected.
- “0” is set for all controller addresses.
- The controller timed out after recognition.
- An abnormal condition exists in communication.

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	ID	Description	Get	Set	Type	Value
Attributes	239	Number of connected controller in controller communication ^{1,2,3}	Yes	No	UNIT	See P. 72
	240	Number of communication measured data items (IN) when conducting polling I/O communication ^{1,2,4}	Yes	Yes	UNIT	See P. 72
	241	Number of communication setting data items (OUT) when conducting polling I/O communication ^{1,2,4}	Yes	Yes	UNIT	See P. 72
	242	RUN/STOP logic selection ^{1,2}	Yes	Yes	WORD	See P. 73
	243	Setting validity selection ^{1,2}	Yes	Yes	WORD	See P. 73
	244	Unused	No	No	UINT	—
	245	Controller address setting ^{5,6}	Yes	Yes	WORD	See P. 73
	246	Action mode selection ²	Yes	Yes	WORD	See P. 73
	247	Automatic acquisition of controller address ^{2,7}	Yes	Yes	UNIT	See P. 73
	249	Unused ⁸	No	No	UINT	—
	250	Unused ⁸	No	No	UINT	—
	251	Unused ⁸	No	No	UINT	—
	252	Unused ⁸	No	No	UINT	—
	253	Unused ⁸	No	No	UINT	—
	254	Unused ⁸	No	No	UINT	—
	255	Unused ⁸	No	No	UINT	—

	DeviceNet service	Parameter option
Services	0x0E Get_Attribute_Single	None
	0x10 Set_Attribute_Single	None

¹ It is validated only via Explicit message communication. If this data item is set as a measured data item (IN) or setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” In addition, any data item set hereafter is invalidated.

² Only object instances 1 is valid.

³ The COM-JH starts collecting data on connected modules just after the power is turned on, and communication is validated after data collection is finished. If “Number of connected controller in controller communication” is read during data collection, “0” is returned. Therefore, the communication enable state after the power is turned on can be checked as far as “the number of connected controllers” is monitored.

⁴ When the set value is “0”, the number of data is the value set by DIP switch. When the set value is 1 to 5, the number of data is 5. When the set value is 6 to 200, the number of data is the set number of data.

⁵ Only object instances 1 to 31 are valid.

⁶ Set the address (0 to 99) of the controller connected to the COM-JH. Communication will only be performed with the controller whose address is set. If 0 or an address outside the setting range is set, communication will not take place with that controller and each of the communication item parts will be filled without spaces. If the address is other than “0” and a controller is not connected, the data will be “0.”

⁷ When the setting is set to “1: Execute the automatic acquisition” and the power of the COM-JH is turned off and then on, the address of the controller is automatically acquired. The address acquisition range is 1 to 99, and when automatic acquisition ends, the automatic acquisition of controller setting reverts to “0: Do not execute the automatic acquisition.”

When automatic acquisition of controller address is performed, the set value of the controller address setting (attribute ID: 245) changes. Controller addresses are set without spaces from the lowest address, and “0” is set for parts that do not have a controller connected.

⁸ If this data item is set as a measured data item (IN) or setting data item (OUT) by the “Controller communication item setting object (0xC7: C7Hex)” which sets communication data items via polling I/O communication, it becomes the same as that when set at “0.” In addition, any data item set hereafter is invalidated.

■ Z-TIO Module Extended Object (0x65: 65Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance □ (□: 1 to 64)



Object instances 1 to 64 correspond to channels 1 to 4 of controllers (TIO modules of SRZ) 1 to 16.



If Get is made to the instance No. corresponding to the nonexistent controller No. in communication items other than “unused,” “0” is read while no error occurs if set is made (no data is written).

	ID	Description	Get	Set	Type	Value
Attributes	1	Comprehensive event state	Yes	No	WORD	See P. 74
	2	Logic output monitor	Yes	No	WORD	See P. 74
	3	Output distribution selection	No	No	UINT	See P. 74
	4	Output distribution bias	Yes	Yes	INT	See P. 74
	5	Output distribution ratio	Yes	Yes	INT	See P. 74
	6	Minimum ON/OFF time of proportioning cycle	Yes	Yes	INT	See P. 74
	7	Area soak time stop function	No	Yes	INT	See P. 74
	8	EDS mode (for disturbance 1)	Yes	Yes	INT	See P. 74
	9	EDS mode (for disturbance 2)	Yes	Yes	INT	See P. 74
	10	EDS value 1 (for disturbance 1)	Yes	Yes	INT	See P. 74
	11	EDS value 1 (for disturbance 2)	Yes	Yes	INT	See P. 74
	12	EDS value 2 (for disturbance 1)	Yes	Yes	INT	See P. 74
	13	EDS value 2 (for disturbance 2)	Yes	Yes	INT	See P. 74
	14	EDS transfer time (for disturbance 1)	Yes	Yes	INT	See P. 75
	15	EDS transfer time (for disturbance 2)	Yes	Yes	INT	See P. 75
	16	EDS action time (for disturbance 1)	Yes	Yes	INT	See P. 75
	17	EDS action time (for disturbance 2)	Yes	Yes	INT	See P. 75
	18	EDS action wait time (for disturbance 1)	Yes	Yes	INT	See P. 75
	19	EDS action wait time (for disturbance 2)	Yes	Yes	INT	See P. 75
	20	EDS value learning times	Yes	Yes	INT	See P. 75
	21	EDS start signal	Yes	Yes	INT	See P. 75
	22	Operation mode	Yes	Yes	INT	See P. 75
	23	Communication switch for logic	Yes	Yes	WORD	See P. 75
	24	Event 1 channel setting	Yes	Yes	INT	See P. 75
	25	Event 2 channel setting	Yes	Yes	INT	See P. 75
	26	Event 3 channel setting	Yes	Yes	INT	See P. 75
	27	Event 4 channel setting	Yes	Yes	INT	See P. 75
	28	EDS transfer time decimal point position	Yes	Yes	INT	See P. 75
	29	Output average processing time for EDS	Yes	Yes	INT	See P. 75
	30	Responsive action trigger point for EDS	Yes	Yes	INT	See P. 75

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	ID	Description	Get	Set	Type	Value
Attributes	31	Operation mode assignment 1	Yes	Yes	INT	See P. 76
	32	Operation mode assignment 2	Yes	Yes	INT	See P. 76
	33	SV select function	Yes	Yes	INT	See P. 76
	34	Remote SV function master channel module address	Yes	Yes	INT	See P. 76
	35	Remote SV function master channel selection	Yes	Yes	INT	See P. 76
	36	Output distribution master channel module address	Yes	Yes	INT	See P. 76
	37	Output distribution master channel selection	Yes	Yes	INT	See P. 76
	38	Address of interacting modules	Yes	Yes	INT	See P. 76
	39	Channel selection of interacting modules	Yes	Yes	INT	See P. 76
	40	Selection switch of interacting modules	Yes	Yes	WORD	See P. 76
	41	Control RUN/STOP holding setting	Yes	Yes	INT	See P. 76
	42	Interval time	Yes	Yes	INT	See P. 76
	43	Unused	No	No	UINT	—
	⋮		⋮	⋮	⋮	⋮
	255	Unused	No	No	UINT	—
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			

■ Z-DIO Module Object (0x66: 66Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance □ (□: 1 to 128)

-  Object instances 1 to 128 correspond to channels 1 to 8 of controllers (TIO modules of SRZ) 1 to 16.
-  If Get is made to the instance No. corresponding to the nonexistent controller No. in communication items other than “unused,” “0” is read while no error occurs if set is made (no data is written).

	ID	Description	Get	Set	Type	Value
Attributes	1	Digital input (DI) state	Yes	No	WORD	See P. 77
	2	Digital output (DO) state	Yes	No	WORD	See P. 77
	3	Error code	Yes	No	INT	See P. 77
	4	Integrated operating time monitor	Yes	No	INT	See P. 77
	5	Backup memory state monitor	Yes	No	INT	See P. 77
	6	RUN/STOP transfer	Yes	Yes	INT	See P. 77
	7	DO manual output	Yes	Yes	INT	See P. 77
	8	DO output distribution selection	Yes	Yes	INT	See P. 77
	9	DO output distribution bias	Yes	Yes	INT	See P. 78
	10	DO output distribution ratio	Yes	Yes	INT	See P. 78
	11	DO proportional cycle time	Yes	Yes	INT	See P. 78
	12	DO minimum ON/OFF time of proportioning cycle	Yes	Yes	INT	See P. 78
	13	DI function assignment	Yes	Yes	INT	See P. 78
	14	Memory area setting signal	Yes	Yes	INT	See P. 78
	15	DO signal assignment module address 1	Yes	Yes	INT	See P. 78
	16	DO signal assignment module address 2	Yes	Yes	INT	See P. 78
	17	DO output assignment 1 [DO1 to DO4]	Yes	Yes	INT	See P. 78
	18	DO output assignment 2 [DO5 to DO8]	Yes	Yes	INT	See P. 78
	19	DO energized/de-energized	Yes	Yes	INT	See P. 78
	20	DO output distribution master channel module address	Yes	Yes	INT	See P. 78
	21	DO output distribution master channel selection	Yes	Yes	INT	See P. 78
	22	DO manipulated output value (MV) at STOP mode	Yes	Yes	INT	See P. 78
	23	DO output limiter (high)	Yes	Yes	INT	See P. 78
	24	DO output limiter (low)	Yes	Yes	INT	See P. 78
	25	Control RUN/STOP holding setting	Yes	Yes	INT	See P. 78
	26	Interval time	Yes	Yes	INT	See P. 78
	27	Unused	No	No	UINT	—
	⋮		⋮	⋮	⋮	⋮
	255	Unused	No	No	UINT	—
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			

■ Controller Communication Item Setting Object (0xC7: C7Hex)

● Object class

Attributes	Not supported
Services	Not supported

● Object instance 1



Measured data items (IN) and setting data items (OUT) communicating via polling I/O communication are set by the attribute ID in “Z-TIO module object (0x64: 64Hex), Z-TIO module extended object (0x65: 65Hex) *, Z-DIO module object (0x66: 66Hex) *.”

* When setting the communication items of a Z-TIO module extended object (0x65: 65Hex) or Z-DIO module object (0x66: 66Hex), set the attribute ID number with the appropriate offset value (1000 or 2000) added.

- 0x65: 65Hex: Attribute ID + 1000

- 0x66: 66Hex: Attribute ID + 2000



If not used, 0 is set. Any measured data item (IN) or setting data item (OUT) after the item to which 0 is set is invalidated.

	ID	Description	Get	Set	Type	Value (Default)
Attributes	1	Measured data item (IN) 1	Yes	Yes	UINT	1: Measured value (PV)
	2	Measured data item (IN) 2	Yes	Yes	UINT	0
	3	Measured data item (IN) 3	Yes	Yes	UINT	0
	4	Measured data item (IN) 4	Yes	Yes	UINT	0
	5	Measured data item (IN) 5	Yes	Yes	UINT	0
	6	Measured data item (IN) 6	Yes	Yes	UINT	0
	7	Measured data item (IN) 7	Yes	Yes	UINT	0
	8	Measured data item (IN) 8	Yes	Yes	UINT	0
	9	Measured data item (IN) 9	Yes	Yes	UINT	0
	10	Measured data item (IN) 10	Yes	Yes	UINT	0
	11	Measured data item (IN) 11	Yes	Yes	UINT	0
	12	Measured data item (IN) 12	Yes	Yes	UINT	0
	13	Measured data item (IN) 13	Yes	Yes	UINT	0
	14	Measured data item (IN) 14	Yes	Yes	UINT	0
	15	Measured data item (IN) 15	Yes	Yes	UINT	0
	16	Measured data item (IN) 16	Yes	Yes	UINT	0
	17	Measured data item (IN) 17	Yes	Yes	UINT	0
	18	Measured data item (IN) 18	Yes	Yes	UINT	0
	19	Measured data item (IN) 19	Yes	Yes	UINT	0
	20	Measured data item (IN) 20	Yes	Yes	UINT	0
	21	Measured data item (IN) 21	Yes	Yes	UINT	0
	22	Measured data item (IN) 22	Yes	Yes	UINT	0
	23	Measured data item (IN) 23	Yes	Yes	UINT	0
	24	Measured data item (IN) 24	Yes	Yes	UINT	0
	25	Measured data item (IN) 25	Yes	Yes	UINT	0
	26	Measured data item (IN) 26	Yes	Yes	UINT	0

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	ID	Description	Get	Set	Type	Value (Default)
Attributes	27	Measured data item (IN) 27	Yes	Yes	UINT	0
	28	Measured data item (IN) 28	Yes	Yes	UINT	0
	29	Measured data item (IN) 29	Yes	Yes	UINT	0
	30	Measured data item (IN) 30	Yes	Yes	UINT	0
	31	Measured data item (IN) 31	Yes	Yes	UINT	0
	32	Measured data item (IN) 32	Yes	Yes	UINT	0
	33	Setting data item (OUT) 1	Yes	Yes	UINT	45: Set value (SV)
	34	Setting data item (OUT) 2	Yes	Yes	UINT	0
	35	Setting data item (OUT) 3	Yes	Yes	UINT	0
	36	Setting data item (OUT) 4	Yes	Yes	UINT	0
	37	Setting data item (OUT) 5	Yes	Yes	UINT	0
	38	Setting data item (OUT) 6	Yes	Yes	UINT	0
	39	Setting data item (OUT) 7	Yes	Yes	UINT	0
	40	Setting data item (OUT) 8	Yes	Yes	UINT	0
	41	Setting data item (OUT) 9	Yes	Yes	UINT	0
	42	Setting data item (OUT) 10	Yes	Yes	UINT	0
	43	Setting data item (OUT) 11	Yes	Yes	UINT	0
	44	Setting data item (OUT) 12	Yes	Yes	UINT	0
	45	Setting data item (OUT) 13	Yes	Yes	UINT	0
	46	Setting data item (OUT) 14	Yes	Yes	UINT	0
	47	Setting data item (OUT) 15	Yes	Yes	UINT	0
	48	Setting data item (OUT) 16	Yes	Yes	UINT	0
	49	Setting data item (OUT) 17	Yes	Yes	UINT	0
	50	Setting data item (OUT) 18	Yes	Yes	UINT	0
	51	Setting data item (OUT) 19	Yes	Yes	UINT	0
	52	Setting data item (OUT) 20	Yes	Yes	UINT	0
	53	Setting data item (OUT) 21	Yes	Yes	UINT	0
	54	Setting data item (OUT) 22	Yes	Yes	UINT	0
	55	Setting data item (OUT) 23	Yes	Yes	UINT	0
	56	Setting data item (OUT) 24	Yes	Yes	UINT	0
	57	Setting data item (OUT) 25	Yes	Yes	UINT	0
	58	Setting data item (OUT) 26	Yes	Yes	UINT	0
	59	Setting data item (OUT) 27	Yes	Yes	UINT	0
	60	Setting data item (OUT) 28	Yes	Yes	UINT	0
	61	Setting data item (OUT) 29	Yes	Yes	UINT	0
	62	Setting data item (OUT) 30	Yes	Yes	UINT	0
	63	Setting data item (OUT) 31	Yes	Yes	UINT	0
	64	Setting data item (OUT) 32	Yes	Yes	UINT	0
DeviceNet service			Parameter option			
Services	0x0E	Get_Attribute_Single	None			
	0x10	Set_Attribute_Single	None			



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