3-Bit Scannable Registered Bus Transceiver

The MC10E/100E337 is a 3-bit registered bus transceiver with scan. The bus outputs (BUS0–BUS2) are specified for driving a 25Ω bus; the receive outputs (Q0 – Q2) are specified for 50Ω . The bus outputs feature a normal HIGH level (V_{OH}) and a cutoff LOW level — when LOW, the outputs go to – 2.0V and the output emitter-follower is "off", presenting a high impedance to the bus. The bus outputs also feature edge slow-down capacitors.

- Scannable Version of E336
- 25Ω Cutoff Bus Outputs
- 50Ω Receiver Outputs
- Scannable Registers
- Sync. and Async. Bus Enables
- Non-inverting Data Path
- 1500ps Max. Clock to Bus (Data Transmit)
- 1000ps Max. Clock to Q (Data Receive)
- Bus Outputs Feature Internal Edge Slow-Down Capacitors
- Additional Package Ground Pins
- Extended 100E V_{EE} Range of 4.2V to 5.46V
- 75kΩ Input Pulldown Resistors



MC10E337

MC100E337

3-BIT SCANNABLE

REGISTERED

BUS TRANSCEIVER

Both drive and receive sides feature the same logic, including a loopback path to hold data. The HOLD/LOAD function is controlled by Transmit Enable (TEN) and Receive Enable (REN) on the transmit and receive sides respectively, with a HIGH selecting LOAD. Note that the implementation of the E337 Receive Enable differs from that of the E336.

A synchronous bus enable (SBUSEN) is provided for normal, non-scan operation. The asynchronous bus disable (ABUSDIS) disables the bus immediately for scan mode.

The SYNCEN input is provided for flexibility when re-enabling the bus after disabling with A<u>BUSDIS</u>, allowing either <u>synchron</u>ous or asynchronous re-enabling. An alternative use is asynchronous-only operation with ABUSDIS, in which case SYNCEN is tied LOW, or left open. SYNCEN is implemented as an overriding SET control (active-LOW) to the enable flip-flop.

Scan mode is selected by a HIGH at the SCAN input. Scan input data is shifted in through S_IN and output data appears at the Q2 output.

All registers are clocked on the positive transition of CLK. Additional lead-frame grounding is provided through the Ground pins (GND) which should be connected to 0V. The GND pins are not electrically connected to the chip.

PIN NAMES

Pin	Function
$A_0 - A_2$	Data Inputs A
B ₀ – B ₂	Data Inputs B
S-IN	Serial (Scan) Data Input
TEN, REN	HOLD/LOAD Controls
SCAN	Scan Control
ABUSDIS	Asynchronous Bus Disable
SBUSEN	Synchronous Bus Enable
SYNCEN	Synchronous Enable Control
CLK	Clock
BUS0 – BUS2	25Ω Cutoff Bus Outputs
$Q_0 - Q_2$	Receive Data Outputs (Q2 serves as SCAN_OUT in scan mode)

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 * All V_{CC} and V_{CCO} pins are tied together on the die.



DC CHARACTERISTICS (V_{EE} = V_{EE}(min) to V_{EE}(max); V_{CC} = V_{CCO} = GND)

		0°C			25°C			85°C				
Symbol	Characteristic	min	typ	max	min	typ	max	min	typ	max	Unit	Condition
VCUT	Cut-off Output Voltage1	- 2.10		- 2.03	- 2.10		- 2.03	- 2.10		- 2.03	V	
ін	Input HIGH Current All Other Inputs			150			150			150	μA	
IEE	Power Supply Current										mA	
	10E		145	174		145	174		145	174		
	100E		145	174		145	174		167	200		

1. measured with $V_{TT} = -2.10V$

AC CHARACTERISTICS ($V_{EE} = V_{EE}(min)$ to $V_{EE}(max)$; $V_{CC} = V_{CCO} = GND$)

		0°C		25°C			85°C					
Symbol	Characteristic	min	typ	max	min	typ	max	min	typ	max	Unit	Condition
^t PLH	Propagation Delay to Output										ps	
^t PHL	Clk to Q	450		1000	450		1000	450		1000		
	Clk to BUS	800		1800	800		1800	800		1800		
	ABUSDIS	500		1500	500		1500	500		1500		
	SYNCEN	800		1800	800		1800	800		1800		
t _S	Setup Time										ps	
	BUS	350			350			350				
	SBUSEN	100			100			100				
	Data, S-IN	400			400			400				
	TEN, REN, SCAN	550			550			550				
th	Hold TIme										ps	
	BUS	350			350			350				
	SBUSEN	500			500			500				
	Data, S-IN	350			350			350				
	TEN, REN, SCAN	200			200			200				
tpw	Minimum Pulse Width										ps	
	CLk	400			400			400				
t _r	Rise/Fall Times										ps	
tf	20 - 80% (Qn)	300		800	300		800	300		800		
	20 - 80% (BUSn Rise)	500		1000	500		1000	500		1000		
	20 - 80% (BUSn Fall)	300		800	300		800	300		800		



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