

General Description

Fairchild EEPROMs are designed and tested for applications requiring high endurance, high reliability and low power consumption for a continuously reliable non-volatile solution for all markets.

- I²C™ compatible interface
- 4,096 bits organized as 512 x 8
- Extended 2.7V – 5.5V operating voltage
- 100 KHz or 400 KHz operation
- Self timed programming cycle (6ms typical)
- "Programming complete" indicated by ACK polling
- NM24C17U: Memory "Upper Block" Write Protect pin

- The I²C™ interface allows the smallest I/O pincount of any EEPROM interface
- 16 byte page write mode to minimize total write time per byte
- Typical 200μA active current (I_{CCA})
- Typical 1μA standby current (I_{SB}) for "L" devices and 0.1μA standby current for "LZ" devices
- Endurance: Up to 1,000,000 data changes
- Data retention greater than 40 years

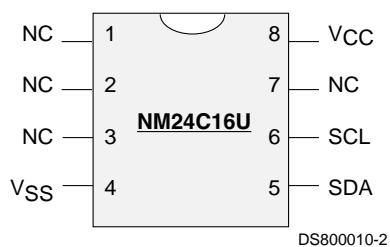
The block diagram illustrates the internal architecture of the 24C02. It features several interconnected functional blocks:

- START STOP LOGIC**: Receives SDA and SCL signals and provides control signals to the CONTROL LOGIC.
- SLAVE ADDRESS REGISTER & COMPARATOR**: Receives SDA and SCL signals and provides control signals to the CONTROL LOGIC.
- CONTROL LOGIC**: The central control unit, receiving signals from the START STOP LOGIC, SLAVE ADDRESS REGISTER & COMPARATOR, and H.V. GENERATION TIMING & CONTROL. It manages the internal operations and provides control signals to the WORD ADDRESS COUNTER, XDEC, YDEC, and DATA REGISTER.
- H.V. GENERATION TIMING & CONTROL**: Provides timing and control signals to the E²PROM ARRAY.
- WORD ADDRESS COUNTER**: Receives control signals from the CONTROL LOGIC and provides an output to the XDEC.
- XDEC**: Receives signals from the WORD ADDRESS COUNTER and the CONTROL LOGIC, and provides an output to the E²PROM ARRAY.
- E²PROM ARRAY**: The memory array that stores data. It receives control signals from the H.V. GENERATION TIMING & CONTROL, XDEC, and YDEC, and provides data to the YDEC.
- YDEC**: Receives control signals from the CONTROL LOGIC and provides an output to the DATA REGISTER.
- DATA REGISTER**: Receives data from the YDEC and provides an output to the DOUT pin. It also receives control signals from the CONTROL LOGIC.
- External Connections**: The diagram shows VCC, VSS, and WP pins at the top. SDA and SCL pins are on the left. D_{IN} and D_{OUT} pins are at the bottom. A ground symbol is shown at the bottom left.

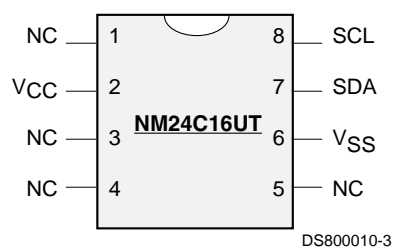
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Connection Diagrams

**Dual-In-Line Package (N),
8-Pin SO Package (M8)**



**8-Pin TSSOP Package (MT8)
Rotated Die (24C16UT)**



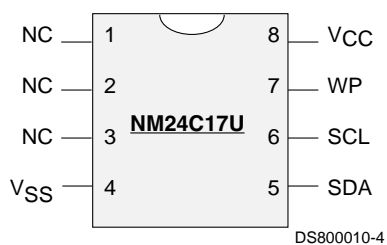
Top View

See Package Number N08E, M08A and MTC08

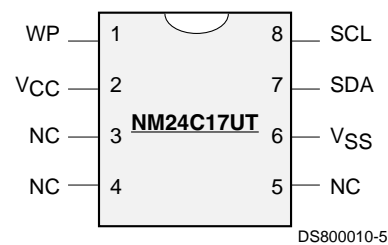
Pin Names

V _{SS}	Ground
SDA	Serial Data I/O
SCL	Serial Clock Input
NC	No Connection
V _{CC}	Power Supply

**Dual-In-Line Package (N),
8-Pin SO Package (M8)**



**8-Pin TSSOP Package (MT8)
Rotated Die (24C17UT)**



Top View

See Package Number N08E, M08A and MTC08

Pin Names

V _{SS}	Ground
SDA	Serial Data I/O
SCL	Serial Clock input
WP	Write Protect
V _{CC}	Power Supply
NC	No Connection

Ordering Information

<u>NM</u>	<u>24</u>	<u>C</u>	<u>XX</u>	<u>U</u>	<u>F</u>	<u>T</u>	<u>LZ</u>	<u>E</u>	<u>XX</u>	Letter	Description
										Package	N 8-pin DIP M8 8-pin SOIC MT8 8-pin TSSOP
										Temp. Range	None 0 to 70°C V -40 to +125°C E -40 to +85°C
										Voltage Operating Range	Blank 4.5V to 5.5V L 2.7V to 5.5V LZ 2.7V to 5.5V and <1µA Standby Current
											Blank Normal Pin Out T Rotated Die Pin Out
										SCL Clock Frequency	Blank 100KHz F 400KHz
											Ultralite CS100UL Process
										Density	16 16K 17 16K with Write Protect
											C CMOS Technology W Total Array Write Protect
										Interface	24 IIC
										NM	Fairchild Non-Volatile Memory

Product Specifications

Absolute Maximum Ratings

Ambient Storage Temperature	−65°C to +150°C
All Input or Output Voltages with Respect to Ground	6.5V to −0.3V
Lead Temperature (Soldering, 10 seconds)	+300°C
ESD Rating	2000V min.

Operating Conditions

Ambient Operating Temperature	0°C to +70°C
NM24C16U/17U	−40°C to +85°C
NM24C16UE/17UE	−40°C to +125°C
NM24C16UV/17UV	
Positive Power Supply	4.5V to 5.5V
NM24C16U/17U	2.7V to 5.5V
NM24C16UL/17UL	2.7V to 5.5V
NM24C16ULZ/17ULZ	2.7V to 5.5V

Standard V_{CC} (4.5V to 5.5V) DC Electrical Characteristics

Symbol	Parameter	Test Conditions	Limits			Units
			Min	Typ (Note 1)	Max	
I_{CCA}	Active Power Supply Current	$f_{SCL} = 400 \text{ KHz}$ $f_{SCL} = 100 \text{ KHz}$		0.2	1.0	mA
I_{SB}	Standby Current	$V_{IN} = \text{GND or } V_{CC}$		10	50	μA
I_{LI}	Input Leakage Current	$V_{IN} = \text{GND to } V_{CC}$		0.1	1	μA
I_{LO}	Output Leakage Current	$V_{OUT} = \text{GND to } V_{CC}$		0.1	1	μA
V_{IL}	Input Low Voltage		−0.3		$V_{CC} \times 0.3$	V
V_{IH}	Input High Voltage		$V_{CC} \times 0.7$		$V_{CC} + 0.5$	V
V_{OL}	Output Low Voltage	$I_{OL} = 3 \text{ mA}$			0.4	V

Low V_{CC} (2.7V to 5.5V) DC Electrical Characteristics

Symbol	Parameter	Test Conditions	Limits			Units
			Min	Typ (Note 1)	Max	
I_{CCA}	Active Power Supply Current	$f_{SCL} = 400 \text{ KHz}$ $f_{SCL} = 100 \text{ KHz}$		0.2	1.0	mA
I_{SB}	Standby Current	$V_{IN} = \text{GND or } V_{CC}$		1 0.1 10	10 1 50	μA μA μA
I_{LI}	Input Leakage Current	$V_{IN} = \text{GND to } V_{CC}$		0.1	1	μA
I_{LO}	Output Leakage Current	$V_{OUT} = \text{GND to } V_{CC}$		0.1	1	μA
V_{IL}	Input Low Voltage		−0.3		$V_{CC} \times 0.3$	V
V_{IH}	Input High Voltage		$V_{CC} \times 0.7$		$V_{CC} + 0.5$	V
V_{OL}	Output Low Voltage	$I_{OL} = 3 \text{ mA}$			0.4	V

Capacitance $T_A = +25^\circ\text{C}$, $f = 100/400 \text{ KHz}$, $V_{CC} = 5\text{V}$ (Note 2)

Symbol	Test	Conditions	Max	Units
$C_{I/O}$	Input/Output Capacitance (SDA)	$V_{I/O} = 0\text{V}$	8	pF
C_{IN}	Input Capacitance (A0, A1, A2, SCL)	$V_{IN} = 0\text{V}$	6	pF

Note 1: Typical values are $T_A = 25^\circ\text{C}$ and nominal supply voltage (5V).

Note 2: This parameter is periodically sampled and not 100% tested.

AC Conditions of Test

Input Pulse Levels	$V_{CC} \times 0.1$ to $V_{CC} \times 0.9$
Input Rise and Fall Times	10 ns
Input & Output Timing Levels	$V_{CC} \times 0.5$
Output Load	1 TTL Gate and $C_L = 100$ pF

Read and Write Cycle Limits (Standard and Low V_{CC} Range 2.7V - 5.5V)

Symbol	Parameter	100 KHz		400 KHz		Units
		Min	Max	Min	Max	
f_{SCL}	SCL Clock Frequency		100		400	KHz
T_I	Noise Suppression Time Constant at SCL, SDA Inputs (Minimum V_{IN} Pulse width)		100		50	ns
t_{AA}	SCL Low to SDA Data Out Valid	0.3	3.5	0.1	0.9	μ s
t_{BUF}	Time the Bus Must Be Free before a New Transmission Can Start	4.7		1.3		μ s
$t_{HD:STA}$	Start Condition Hold Time	4.0		0.6		μ s
t_{LOW}	Clock Low Period	4.7		1.5		μ s
t_{HIGH}	Clock High Period	4.0		0.6		μ s
$t_{SU:STA}$	Start Condition Setup Time (for a Repeated Start Condition)	4.7		0.6		μ s
$t_{HD:DAT}$	Data in Hold Time	0		0		μ s
$t_{SU:DAT}$	Data in Setup Time	250		100		ns
t_R	SDA and SCL Rise Time		1		0.3	μ s
t_F	SDA and SCL Fall Time		300		300	ns
$t_{SU:STO}$	Stop Condition Setup Time	4.7		0.6		μ s
t_{DH}	Data Out Hold Time	300		50		ns
t_{WR} (Note 3)	Write Cycle Time - NM24C16U/17U - NM24C16U/17UL, NM24C16U/17ULZ		10 15		10 15	ms

Note 3: The write cycle time (t_{WR}) is the time from a valid stop condition of a write sequence to the end of the internal erase/program cycle. During the write cycle, the NM24C16U/17U bus interface circuits are disabled, SDA is allowed to remain high per the bus-level pull-up resistor, and the device does not respond to its slave address.

Device Operation

Background Information (IIC Bus)

As mentioned, the IIC bus allows synchronous bidirectional communication between Transmitter/Receiver using the SCL (clock) and SDA (Data I/O) lines. All communication must be started with a valid START condition, concluded with a STOP condition and acknowledged by the Receiver with an ACKNOWLEDGE condition.

As shown below, the EEPROMs on the IIC bus may be configured in any manner required, the total memory addressed can not exceed 16K (16,384 bits). EEPROM memory address programming is controlled by 2 methods:

- **All unused pins must be grounded** (tied to V_{SS}).
- Software addressing the required PAGE BLOCK within the device memory array (as sent in the Slave Address string).

For devices with densities greater than 16K, a different protocol, the Extended IIC protocol, is used. Refer to NM24C32U datasheet (for example) for additional details.

Addressing an EEPROM memory location involves sending a command string with the following information: [DEVICE TYPE]–[DEVICE ADDRESS]–[PAGE BLOCK ADDRESS]–[BYTE ADDRESS]

DEFINITIONS	
WORD	8 bits (byte) of data
PAGE	16 sequential addresses (one byte each) that may be programmed during a 'Page Write' programming cycle
PAGE BLOCK	2048 (2K) bits organized into 16 pages of addressable memory. (8 bits) x (16 pages) = 2048 bits
MASTER	Any IIC device CONTROLLING the transfer of data (such as a microprocessor)
SLAVE	Device being controlled (EEPROMs are always considered Slaves)
TRANSMITTER	Device currently SENDING data on the bus (may be either a Master or Slave).
RECEIVER	Device currently RECEIVING data on the bus (Master or Slave)

Pin Descriptions

Serial Clock (SCL)

The SCL input is used to clock all data into and out of the device.

Serial Data (SDA)

SDA is a bidirectional pin used to transfer data into and out of the device. It is an open drain output and may be wire-ORed with any number of open drain or open collector outputs.

WP Write Protection (NM24C17U Only)

If tied to V_{CC} , PROGRAM operations onto the upper half of the memory will not be executed. READ operations are possible. If tied to V_{SS} , normal operation is enabled, READ/WRITE over the entire memory is possible.

This feature allows the user to assign the upper half of the memory as ROM which can be protected against accidental programming. When write is disabled, slave address and word address will be acknowledged but data will not be acknowledged.

Device Operation

The NM24C16U/17U supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is the master and the device that is controlled is the slave. The master will always initiate data transfers and provide the clock for both transmit and receive operations. Therefore, the NM24C16U/17U will be considered a slave in all applications.

Clock and Data Conventions

Data states on the SDA line can change only during SCL LOW. SDA state changes during SCL HIGH are reserved for indicating start and stop conditions. Refer to *Figure 2* and *Figure 3* on next page.

Start Condition

All commands are preceded by the start condition, which is a HIGH to LOW transition of SDA when SCL is HIGH. The NM24C16U/17U continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met.

Stop Condition

All communications are terminated by a stop condition, which is a LOW to HIGH transition of SDA when SCL is HIGH. The stop condition is also used by the NM24C16U/17U to place the device in the standby power mode.

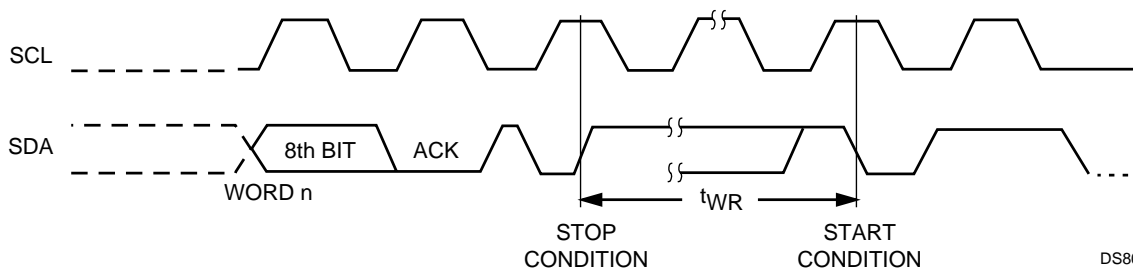
Write Cycle Timing

Acknowledge

Acknowledge is a hardware convention used to indicate successful data transfers. The transmitting device, either master or slave, will release the bus after transmitting eight bits.

During the ninth clock cycle the receiver will pull the SDA line to LOW to acknowledge that it received the eight bits of data. Refer to *Figure 4*.

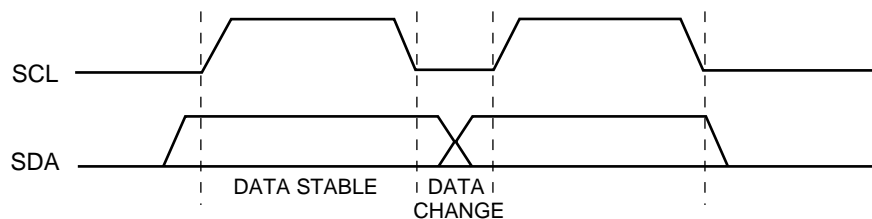
Write Cycle Timing (Figure 1)



Note: The write cycle time (t_{WR}) is the time from a valid stop condition of a write sequence to the end of the internal erase/program cycle.

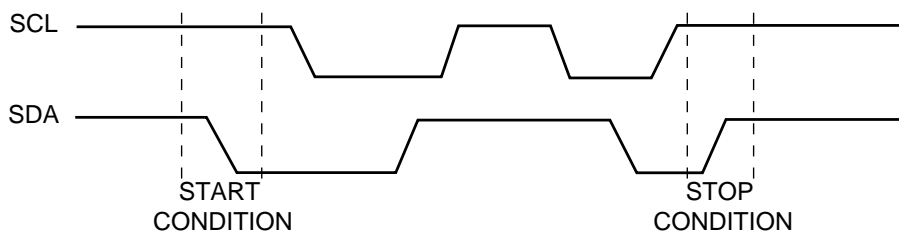
DS800010-10

Data Validity (Figure 2)



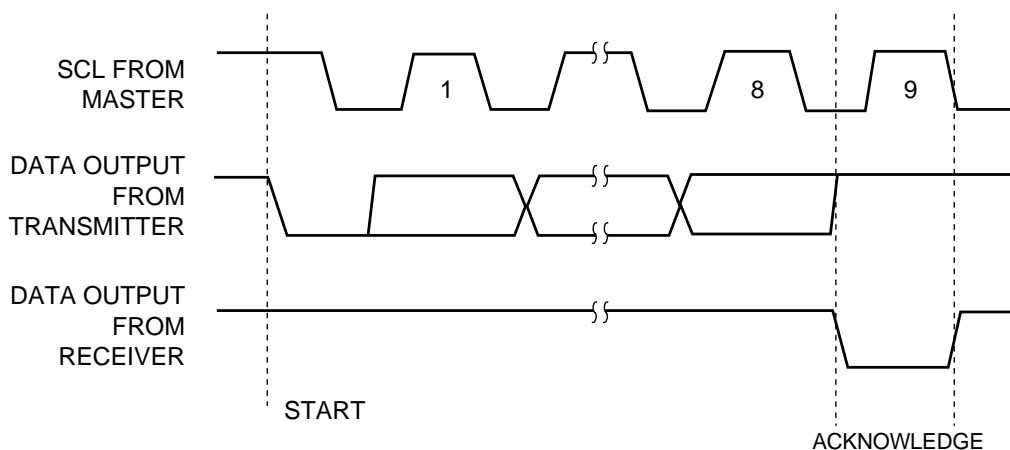
DS800010-11

Start and Stop Definition (Figure 3)



DS800010-12

Acknowledge Response from Receiver (Figure 4)



DS800010-13

Write Cycle Timing (Continued)

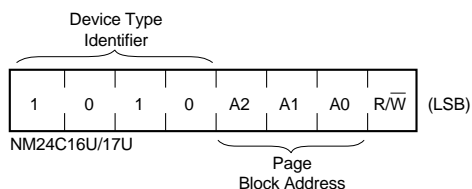
The NM24C16U/17U device will always respond with an acknowledge after recognition of a start condition and its slave address. If both the device and a write operation have been selected, the NM24C16U/17U will respond with an acknowledge after the receipt of each subsequent eight bit byte.

In the read mode the NM24C16U/17U slave will transmit eight bits of data, release the SDA line and monitor the line for an acknowledge. If an acknowledge is detected and no stop condition is generated by the master, the slave will continue to transmit data. If an acknowledge is not detected, the slave will terminate further data transmissions and await the stop condition to return to the standby power mode.

Device Addressing

Following a start condition the master must output the address of the slave it is accessing. The most significant four bits of the slave address are those of the device type identifier (see Figure 5). This is fixed as 1010 for all EEPROM devices.

Slave Addresses (Figure 5)



DS800010-14

Refer to the following table for Slave Addresses string details:

Device	A0	A1	A2	Page Blocks	Page Block Addresses
NM24C16U/17U	P	P	P	8	000 001 010 011 ... 111

P: Refers to an internal PAGE BLOCK memory segment.

All IIC EEPROMs use an internal protocol that defines a PAGE BLOCK size of 2K bits (for Word addresses 0000 through 1111). Therefore, address bits A0, A1, or A2 (if designated 'P') are used to access a PAGE BLOCK in conjunction with the Word address used to access any individual data byte (Word).

The last bit of the slave address defines whether a write or read condition is requested by the master. A '1' indicates that a read operation is to be executed, and a '0' initiates the write mode.

A simple review: After the NM24C16U/17U recognizes the start condition, the devices interfaced to the IIC bus wait for a slave address to be transmitted over the SDA line. If the transmitted slave address matches an address of one of the devices, the designated slave pulls the line LOW with an acknowledge signal and awaits further transmissions.

Write Operations

BYTE WRITE

For a write operation a second address field is required which is a word address that is comprised of eight bits and provides access to any one of the 256 bytes in the selected page of memory. Upon receipt of the byte address the NM24C16U/17U responds with an acknowledge and waits for the next eight bits of data, again, responding with an acknowledge. The master then terminates the transfer by generating a stop condition, at which time the NM24C16U/17U begins the internal write cycle to the nonvolatile memory. While the internal write cycle is in progress the NM24C16U/17U inputs are disabled, and the device will not respond to any requests from the master. Refer to *Figure 6* for the address, acknowledge and data transfer sequence.

PAGE WRITE

The NM24C16U/17U is capable of a sixteen byte page write operation. It is initiated in the same manner as the byte write operation; but instead of terminating the write cycle after the first data byte is transferred, the master can transmit up to fifteen more bytes. After the receipt of each byte, the NM24C16U/17U will respond with an acknowledge.

After the receipt of each byte, the internal address counter increments to the next address and the next SDA data is accepted. If the master should transmit more than sixteen bytes prior to generating the stop condition, the address counter will "roll over" and the previously written data will be overwritten. As with the byte write operation, all inputs are disabled until completion of the internal write cycle. Refer to *Figure 7* for the address, acknowledge, and data transfer sequence.

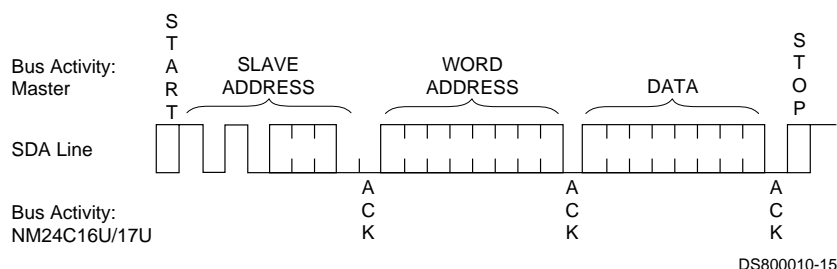
Acknowledge Polling

Once the stop condition is issued to indicate the end of the host's write operation the NM24C16U/17U initiates the internal write cycle. ACK polling can be initiated immediately. This involves issuing the start condition followed by the slave address for a write operation. If the NM24C16U/17U is still busy with the write operation no ACK will be returned. If the NM24C16U/17U has completed the write operation an ACK will be returned and the host can then proceed with the next read or write operation.

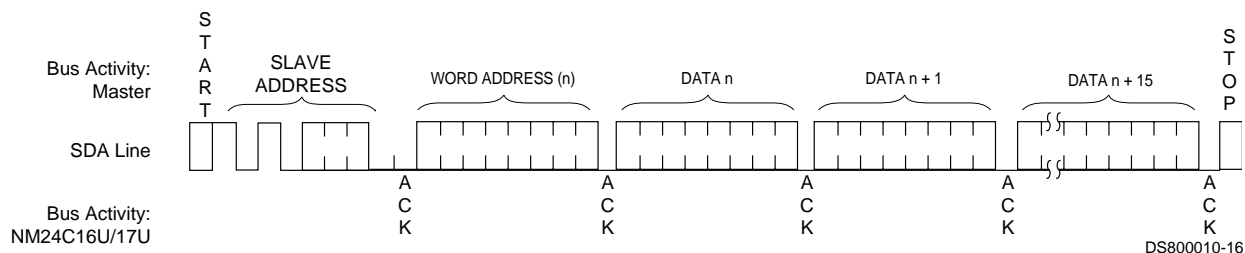
Write Protection (NM24C17U Only)

Programming of the upper half of the memory will not take place if the WP pin of the NM24C17U is connected to V_{CC} . The NM24C17U will accept slave and byte addresses; but if the memory accessed is write protected by the WP pin, the NM24C17U will not generate an acknowledge after the first byte of data has been received, and thus the program cycle will not be started when the stop condition is asserted.

Byte Write (Figure 6)



Page Write (Figure 7)



Read Operations

Read operations are initiated in the same manner as write operations, with the exception that the R/\bar{W} bit of the slave address is set to a one. There are three basic read operations: current address read, random read, and sequential read.

Current Address Read

Internally the NM24C16U/17U contains an address counter that maintains the address of the last byte accessed, incremented by one. Therefore, if the last access (either a read or write) was to address n , the next read operation would access data from address $n + 1$. Upon receipt of the slave address with R/\bar{W} set to one, the NM24C16U/17U issues an acknowledge and transmits the eight bit byte. The master will not acknowledge the transfer but does generate a stop condition, and therefore the NM24C16U/17U discontinues transmission. Refer to *Figure 8* for the sequence of address, acknowledge and data transfer.

Random Read

Random read operations allow the master to access any memory location in a random manner. Prior to issuing the slave address with the R/\bar{W} bit set to one, the master must first perform a "dummy" write operation. The master issues the start condition, slave address and then the byte address it is to read. After the byte address acknowledge, the master immediately reissues the

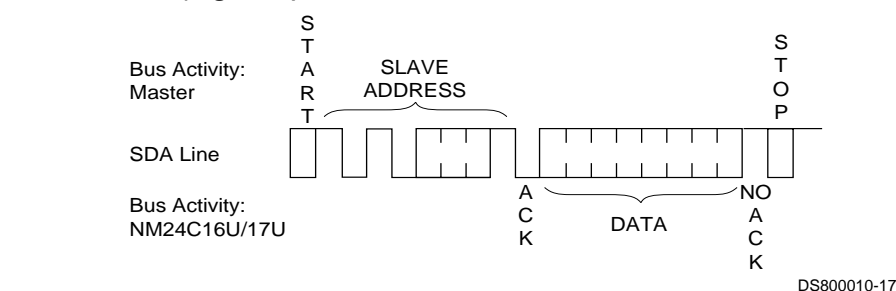
start condition and the slave address with the R/\bar{W} bit set to one. This will be followed by an acknowledge from the NM24C16U/17U and then by the eight bit data. The master will not acknowledge the transfer but does generate the stop condition, and therefore the NM24C16U/17U discontinues transmission. Refer to *Figure 9* for the address, acknowledge and data transfer sequence.

Sequential Read

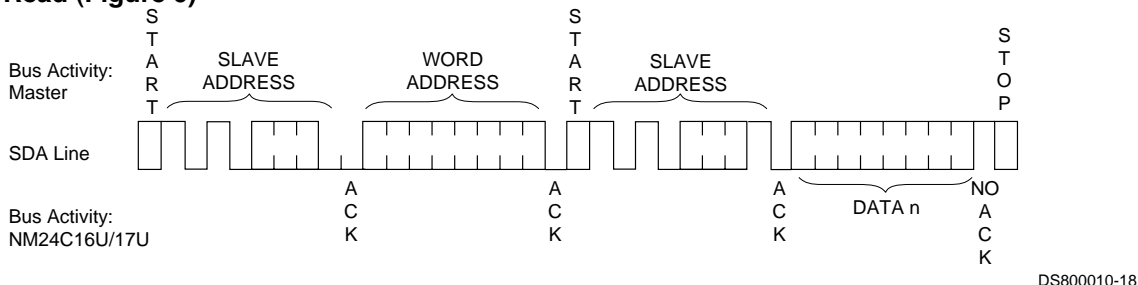
Sequential reads can be initiated as either a current address read or random access read. The first word is transmitted in the same manner as the other read modes; however, the master now responds with an acknowledge, indicating it requires additional data. The NM24C16U/17U continues to output data for each acknowledge received. The read operation is terminated by the master not responding with an acknowledge or by generating a stop condition.

The data output is sequential, with the data from address n followed by the data from $n + 1$. The address counter for read operations increments all word address bits, allowing the entire memory contents to be serially read during one operation. After the entire memory has been read, the counter "rolls over" and the NM24C16U/17U continues to output data for each acknowledge received. Refer to *Figure 10* for the address, acknowledge, and data transfer sequence.

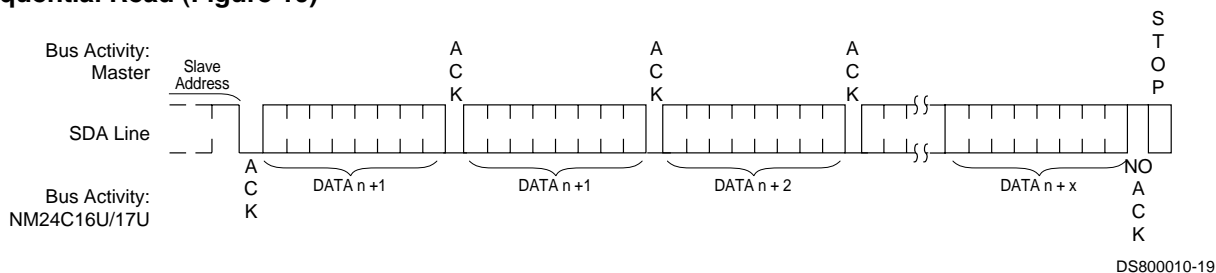
Current Address Read (Figure 8)



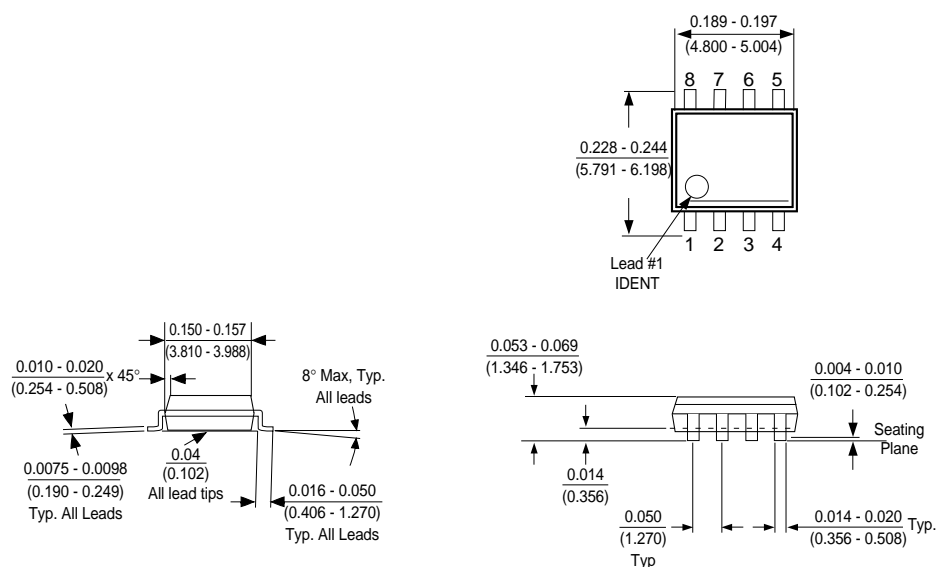
Random Read (Figure 9)



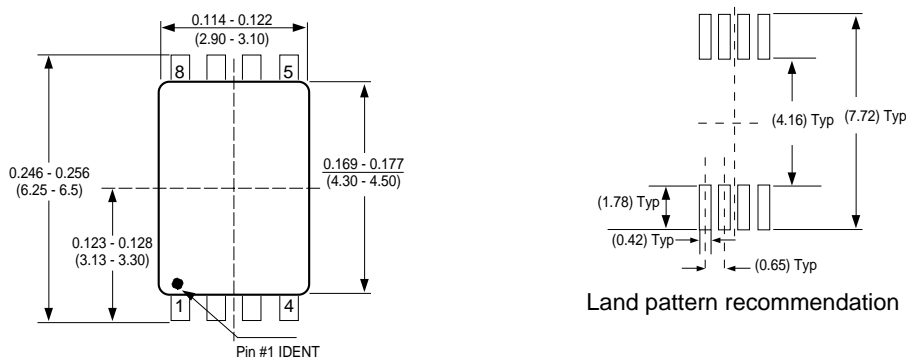
Sequential Read (Figure 10)



Physical Dimensions inches (millimeters) unless otherwise noted



8-Pin Molded Small Outline Package (M8)
Package Number M08A



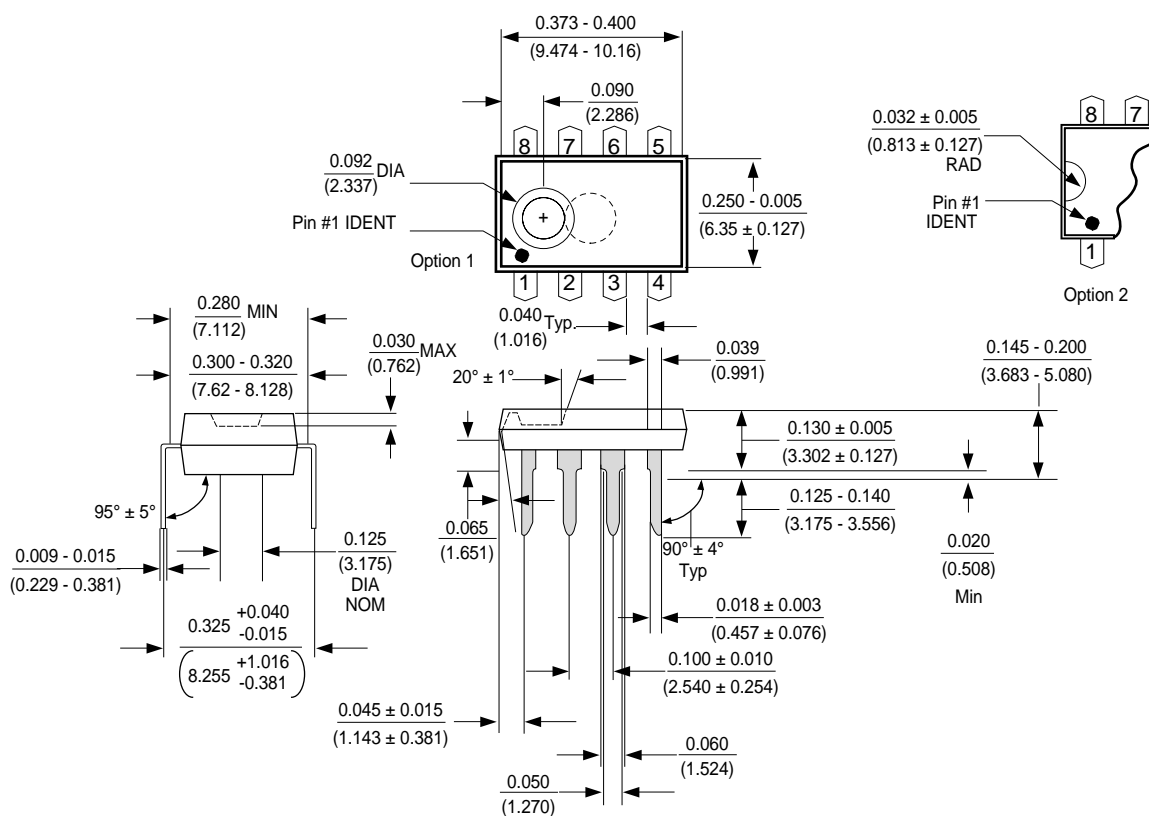
DETAIL A
Typ. Scale: 40X

Notes: Unless otherwise specified

1. Reference JEDEC registration MO153. Variation AA. Dated 7/93

8-Pin Molded Thin Shrink Small Outline Package
Package Number MTC08

Physical Dimensions inches (millimeters) unless otherwise noted



**Molded Dual-In-Line Package (N)
Package Number N08E**

Life Support Policy

Fairchild's products are not authorized for use as critical components in life support devices or systems without the express written approval of the President of Fairchild Semiconductor Corporation. As used herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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