

Door actuator driver

Features

- Three half bridges for 0.75A loads (R_{DSon}=1600mΩ)
- Two configurable high side driver for up to 1.5A load (R_{DSon} =500m Ω) or 0.35A load (R_{on} =1800m Ω)
- One full bridge for 6A load (R_{on} =150m Ω)
- One highside driver for 6A load (R_{on} =100m Ω)
- Programmable soft start function to drive loads with higher inrush currents (i.e. current >6A, >1.5A)
- Very low current consumption in standby mode (I_S < 6µA typ; T_i ≤ 85 °C)
- All outputs short circuit protected
- Current monitor output for highside OUT1, OUT4, OUT5 and OUT8
- All outputs over temperature protected
- Open-load diagnostic for all outputs
- Overload diagnostic for all outputs
- Separated half bridges for door lock motor
- PWM control of all outputs
- Charge pump output for reverse polarity protection



Applications

Door actuator driver with bridges for door lock, mirror axis control, mirror fold and highside driver for mirror defroster and two 10W-light bulbs and/or LEDs.

Description

The L9953LXP is a microcontroller driven multifunctional door actuator driver for automotive applications. Up to three DC motors and three grounded resistive loads can be driven with five half bridges and three highside drivers. The integrated standard serial peripheral interface (SPI) controls all operation modes (forward, reverse, brake and high impedance). All diagnostic informations are available via SPI.

Table 1. Device summary

Pookage	Order codes	
Package	Tube	Tape and reel
PowerSSO-36	L9953LXP	L9953LXPTR

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1 Block diagram and pin description

Figure 1. Block diagram

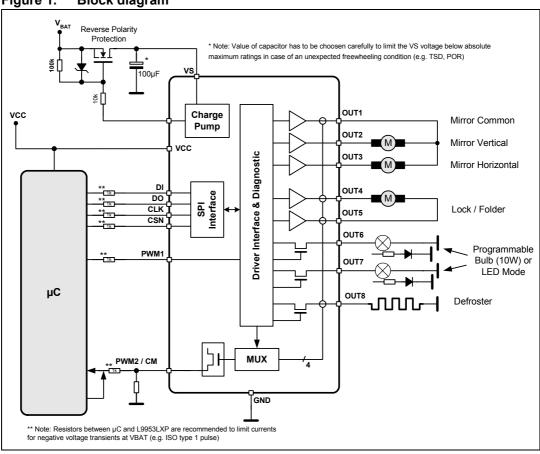


Table 2. Pin definitions and functions

Pin	Symbol	Function
1, 18, 19, 36	GND	Ground: reference potential. Important: for the capability of driving the full current at the outputs all pins of GND must be externally connected.
2, 35	OUT8	Highside-driver-output 8 The output is built by a highside switch and is intended for resistive loads, hence the internal reverse diode from GND to the output is missing. For ESD reason a diode to GND is present but the energy which can be dissipated is limited. The highside driver is a power DMOS transistor with an internal parasitic reverse diode from the output to VS (bulk-drain-diode). The output is over-current and openload protected. Important: for the capability of driving the full current at the outputs both pins of OUT8 must be externally connected.

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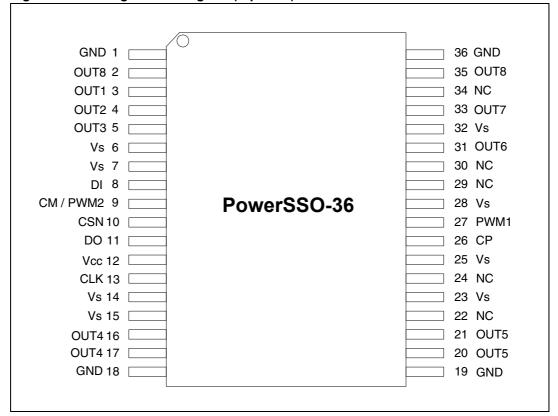
Table 2. Pin definitions and functions (continued)

Pin	Symbol	Function
3 4 5	OUT1 OUT2 OUT3	Half-bridge-output 1,2,3 The output is built by a highside and a lowside switch, which are internally connected. The output stage of both switches is a power DMOS transistor. Each driver has an internal parasitic reverse diode (bulk-drain-diode: highside driver from output to VS, lowside driver from GND to output). This output is over-current and open-load protected.
6, 7, 14, 15, 23, 25, 28, 32	VS	Power supply voltage (external reverse protection required) For this input a ceramic capacitor as close as possible to GND is recommended. Important: for the capability of driving the full current at the outputs all pins of VS must be externally connected.
8	DI	Serial data input The input requires CMOS logic levels and receives serial data from the microcontroller. The data is an 24bit control word and the least significant bit (LSB, bit 0) is transferred first.
9	CM/PWM2	Current monitor output/PWM2 input Depending on the selected multiplexer bits of input data register this output sources an image of the instant current through the corresponding highside driver with a ratio of 1/10.000. This pin is bidirectional. The microcontroller can overdrive the current monitor signal to provide a second PWM input for the output OUT7.
10	CSN	Chip select not input / test mode This input is low active and requires CMOS logic levels. The serial data transfer between L9953LXP and micro controller is enabled by pulling the input CSN to low level. If an input voltage of more than 7.5V is applied to CSN pin the L9953LXP will be switched into a test mode.
11	DO	Serial data output The diagnosis data is available via the SPI and this 3-state output. The output will remain in 3-state, if the chip is not selected by the input CSN (CSN = high)
12	VCC	Logic supply voltage For this input a ceramic capacitor as close as possible to GND is recommended.
13	CLK	Serial clock input This input controls the internal shift register of the SPI and requires CMOS logic levels.
16, 17, 20, 21	OUT4 OUT5	Half-bridge-output 4,5: → see OUT1 (pin 3). Important: for the capability of driving the full current at the outputs both pins of OUT4 (OUT5, respectively) must be externally connected.
26	СР	Charge pump output This output is provided to drive the gate of an external n-channel PowerMOS used for reverse polarity protection
27	PWM1	PWM1 input: This input signal can be used to control the drivers OUT1-OUT6 and OUT8 by an external PWM signal.

Table 2. Pin definitions and functions (continued)

Pin	Symbol	Function
31 33	OUT6, OUT7	Highside-driver-output 6,7: Each output is built by a highside switch and is intended for resistive loads, hence the internal reverse diode from GND to the output is missing. For ESD reason a diode to GND is present but the energy which can be dissipated is limited. Each highside driver is a power DMOS transistor with an internal parasitic reverse diode from each output to VS (bulk-drain-diode). Each output is over-current and openload protected.
22, 24, 29, 30, 34	NC	Not connected pins.

Figure 2. Configuration diagram (top view)



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2 Electrical specifications

2.1 Absolute maximum ratings

Stressing the device above the rating listed in the "Absolute maximum ratings" table may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality document

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V.	DC supply voltage	-0.3 to28	V
V _S	Single pulse t _{max} < 400ms	40	V
V _{CC}	Stabilized supply voltage, logic supply	-0.3 to 5.5	V
V_{DI} , V_{DO} , V_{CLK} , V_{CSN} , V_{pwm1}	Digital input / output voltage	-0.3 to V _{CC} + 0.3	V
V _{CM}	Current monitor output	-0.3 to V _{CC} + 0.3	V
V _{CP}	Charge pump output	-25 to V _S + 11	V
I _{OUT1,2,3,6,7}	Output current	±5	Α
I _{OUT4,5,8}	Output current	±10	Α

2.2 ESD protection

Table 4. ESD protection

Parameter	Value	Unit
All pins	± 2 ⁽¹⁾	kV
Output pins: OUT1 - OUT8	± 8 ⁽²⁾	kV

^{1.} HBM according to MIL 883C, Method 3015.7 or EIA/JESD22-A114-A.

2.3 Thermal data

Table 5. Operating junction temperature

Symbol	Parameter	Value	Unit
T _j	Operating junction temperature	-40 to 150	°C

^{2.} HBM with all unzapped pins grounded.

Table 6. Temperature warning and thermal shutdown

Symbol	Parameter			Тур.	Max.	Unit
T _{jTW On}	Temperature warning threshold junction temperature	Tj	130		150	°C
T _{jSD On}	Thermal shutdown threshold junction temperature	T _j increasing			170	°C
T _{jSD Off}	Thermal shutdown threshold junction temperature	T _j decreasing	150			°C
T _{jSD Hys}	Thermal shutdown hysteresis			5		°K

2.4 Electrical characteristics

 V_S = 8 to 16V, V_{CC} = 4.5 to 5.3V, T_j = -40 to 150°C, unless otherwise specified.

Table 7. Supply

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V _S	Operating supply voltage range		7		28	V
	V _S DC supply current	$V_S = 16V$, $V_{CC} = 5.3V$ active mode OUT1 - OUT8 floating		7	20	mA
I _S	V _S quiescent supply current	$V_S = 16V$, $V_{CC} = 0V$ standby mode OUT1 - OUT8 floating $T_{test} = -40^{\circ}C$, 25°C		4	12	μΑ
		$T_{test} = 85^{\circ}C^{(1)}$		6	25	μΑ
	V _{CC} DC supply current	$V_S = 16V$, $V_{CC} = 5.3V$ CSN = V_{CC} , active mode		1	3	mA
I _{CC}	V _{CC} quiescent supply current	$V_S = 16V$, $V_{CC} = 5.3V$ $CSN = V_{CC}$ standby mode OUT1 - OUT8 floating		25	50	μА
Is+Icc	Sum quiescent supply current	$V_S = 16V$, $V_{CC} = 5.3V$ $CSN = V_{CC}$ standby mode OUT1 - OUT8 floating $T_{test} = 130^{\circ}C$		50	200	μΑ

^{1.} Guaranteed by design.

Table 8. Overvoltage and under voltage detection

Symbol	Parameter	Test condition	Min.	Тур.	Max	Unit
V _{SUV On}	VS UV-threshold voltage	V _S increasing	5.7		7.2	V
V _{SUV Off}	VS UV-threshold voltage	V _S decreasing	5.5		6.9	V
V _{SUV Hyst}	VS UV-hysteresis	V _{SUV On} - V _{SUV Off}		0.5		V
V _{SOV Off}	VS OV-threshold voltage	V _S increasing	18		24.5	٧
V _{SOV On}	VS OV-threshold voltage	V _S decreasing	17.5		23.5	V
V _{SOV Hyst}	VS OV-hysteresis	V _{SOV Off} - V _{SOV On}		1		V
V _{POR Off}	Power-on reset threshold	V _{CC} increasing			4.4	V
V _{POR On}	Power-on reset threshold	V _{CC} decreasing	3.1			V
V _{POR Hyst}	Power-on reset hysteresis	V _{POR Off} - V _{POR On}		0.3		٧

Table 9. Current monitor output

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V_{CM}	Functional voltage range	V _{CC} = 5V	0		4	V
I _{CM,r}	Current monitor output ratio: I _{CM} / I _{OUT 4,5,8}	- 0V ≤ V _{CM} ≤ 4V, V _{CC} =5V		1 10000		-
	Current monitor output ratio: ICM / IOUT1			1 4000		-
I _{CM acc}	Current monitor accuracy Acc I _{CM} / I _{OUT 4,5,8}	$ \begin{aligned} 0 \ V &\leq V_{CM} \leq 3.8V, \\ V_{CC} &= 5V, \\ I_{Out,min~4,5,8} &= 0.5A, \\ I_{Out~max~4,5,8} &= 5.9A \end{aligned} $		4%+	8% + 2%FS	
	Current monitor accuracy Acc I _{CM} / I _{OUT 1}	$0 \text{ V} \leq \text{V}_{CM} \leq 3.8 \text{V},$ $\text{V}_{CC} = 5 \text{V},$ $\text{I}_{Out,min 1} = 60 \text{mA},$ $\text{I}_{Out max 1} = 0.6 \text{A}$		1%FS		

Table 10. Charge pump output

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
	Charge pump output voltage	$V_S = 8V$, $I_{CP} = -60\mu A$	V _S +6		V _S +13	V
V_{CP}		$V_S = 10V, I_{CP} = -80\mu A$	V _S +8		V _S +13	V
		$V_S \ge 12V, I_{CP} = -100\mu A$	V _S +10		V _S +13	V
I _{CP}	Charge pump output current	$V_{CP} = V_S + 10V, V_S = 13.5V$	95	150	300	μΑ

Table 11. OUT1 - OUT8

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
R _{DSon OUT1,}		$V_S = 13.5 \text{ V}, T_j = 25 \text{ °C},$ $I_{OUT1,2,3} = \pm 0.4 \text{A}$		1600	2200	mΩ
R _{DSon OUT2} R _{DSon OUT3}	On resistance to supply or GND	$V_S = 13.5 \text{ V}, T_j = 125 \text{ °C},$ $I_{OUT1,2,3} = \pm 0.4 \text{ A}$		2500	3400	mΩ
		$V_S = 13.5 \text{ V}, T_j = 25 ^{\circ}\text{C},$ $I_{OUT4,5} = \pm 3 \text{ A}$		150	200	mΩ
R _{DSon OUT4} , R _{DSon OUT5}	On resistance to supply or GND	$V_S = 13.5 \text{ V}, T_j = 125 \text{ °C},$ $I_{OUT4,5} = \pm 3 \text{ A}$		225	300	mΩ
R _{DSon OUT6,} R _{DSon OUT7}	On resistance to supply in low R _{DSon} mode	$VS = 13.5 \text{ V}, T_j = 25 \text{ °C},$ $I_{OUT6,7} = -0.8 \text{A}$		500	700	mΩ
		$V_S = 13.5 \text{ V}, T_j = 125 \text{ °C},$ $I_{OUT6,7} = -0.8 \text{ A}$		700	950	mΩ
	On resistance in high	T _j = 25 °C, I _{OUT6,7} = - 0.2 A		1800	2500	mΩ
	R _{DSon} mode	T _j = 125 °C,I _{OUT6,7} = - 0.2 A		2700	3700	mΩ
	On resistance to supply	$V_S = 13.5 \text{ V}, T_j = 25 ^{\circ}\text{C},$ $I_{OUT8} = -3 \text{ A}$		100	150	mΩ
R _{DSon OUT8}		$V_S = 13.5 \text{ V}, T_j = 125 \text{ °C},$ $I_{OUT8} = -3 \text{ A}$		150	200	mΩ
I _{OUT1} I _{OUT2} I _{OUT3}	Output current limitation to GND	Source, V _S =13.5 V	-1.25		-0.75	А
I _{OUT1} I _{OUT2} I _{OUT3}	Output current limitation to supply	Sink, V _S =13.5 V	0.75		1.25	Α
I _{OUT4} I _{OUT5}	Output current limitation to GND	Source, V _S =13.5 V	-10.5		-6	Α
I _{OUT4} I _{OUT5}	Output current limitation to supply	Sink, V _S =13.5 V	6		10.5	А
loure	Output current limitation to GND	Source, V _S =13.5 V	-3.0		-1.4	Α
I _{OUT6} I _{OUT7}	Output current limitation to GND in high R _{DSon} mode		-0.65		-0.35	Α

Table 11. OUT1 - OUT8 (continued)

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
I _{OUT8}	Output current limitation to GND	Source, V _S =13.5 V	-10.5		-6	Α
t _{d On H}	Output delay time, highside driver on	V _S =13.5 V, Rload= ⁽¹⁾ corresponding lowside driver is not active	10	40	80	μs
t _{d Off H}	Output delay time, highside driver off	V _S =13.5 V, Rload= ⁽¹⁾	15	150	300	μs
t _d On L	Output delay time, lowside driver on	V _S =13.5 V, Rload= ⁽¹⁾ corresponding highside driver is not active	15	30	70	μs
t _{d Off L}	Output delay time, lowside driver off	V _S =13.5 V, Rload= ⁽¹⁾	20	100	200	μs
t _{d HL}	Cross current protection time, source to sink	t _{CC ONLS_OFFHS} - t _{d Off H} ⁽²⁾		200	400	μs
t _{d LH}	Cross current protection time, sink to source	tCC ONHS_OFFLS - td Off L (2)		200	400	μs
		V _{OUT1-8} =0V, standby mode	-3	0	3	μΑ
I _{QLH}	Switched off output current highside drivers of OUT1-8	V _{OUT1-2-3-4-5-8} =0V, active mode	-40	-15	0	μΑ
		V _{OUT6-7} =0V, active mode	-10	-8	0	μΑ
L	Switched off output current lowside drivers of OUT1-5	V _{OUT1-5} = V _S , standby mode	0	80	120	μΑ
I _{QLL}		V _{OUT1-5} = V _S , active mode	-40	-15	0	μA
I _{OLD123}	Open-load detection current of OUT1, OUT2 and OUT3	Source and sink	10	20	30	mA
I _{OLD45}	Open-load detection current of OUT4 and OUT5	Source and sink	60	150	300	mA
	Open-load detection current of OUT6 and OUT7		15	40	60	mA
I _{OLD67}	Open-load detection current of OUT6 and OUT7 in high R _{DSon} mode	Source	5	10	15	mA
I _{OLD8}	Open-load detection current of OUT8	Source	30	150	300	mA
t _{d OL}	Minimum duration of open-load condition to set the status bit		500		3000	μs
t _{ISC}	Minimum duration of over- current condition to switch off the driver		10		100	μs

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Table 11. OUT1 - OUT8 (continued)

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
f _{rec0}	Recovery frequency for OC recovery duty cycle bit=0		2		8	kHz
f _{rec1}	Recovery frequency for OC recovery duty cycle bit=1		3		16	kHz
dV _{OUT123} /dt dV _{OUT67} /dt	Slew rate of OUT ₁₂₃ and OUT ₆₇	V _S =13.5 V, Rload= ⁽¹⁾	0.1	0.4	0.9	V/µs
dV _{OUT45} /dt	Slew rate of OUT ₄ and OUT ₅	V _S =13.5 V, Rload= ⁽¹⁾	0.08	0.2	0.4	V/µs
dV _{OUT8} /dt	Slew rate of OUT ₈	V _S =13.5 V, Rload= ⁽¹⁾	0.08	0.2	0.4	V/µs

^{1.} OUT1,2,3 320hm OUT4,5 40hm OUT6,7 160hm OUT6,7 high RDSon mode 630hm OUT8 40hm

^{2.} $t_{CC\ ON}$ is the switch On delay time $t_{d\ ON}$ if complement in half bridge has to switch off.

2.5 SPI - electrical characteristics

 V_S = 8 to 16V, V_{CC} = 4.5 to 5.3V, T_j = - 40 to 150°C, unless otherwise specified. The voltages are referred to GND and currents are assumed positive, when the current flows into the pin).

Table 12. Delay time from standby to active mode

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
t _{set}	Delay time	Switching from standby to active mode. Time until output drivers are enabled		160	300	μs

Table 13. Inputs: CSN, CLK, PWM1/2 and DI

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V_{inL}	Input low level	$V_{CC} = 5V$	1.5	2.0		V
V _{inH}	Input high level	V _{CC} = 5V		3.0	3.5	V
V _{inHyst}	Input hysteresis	V _{CC} = 5V	0.5			V
I _{CSN in}	Pull up current at input CSN	$V_{CSN} = 3.5V V_{CC} = 5V$	-40	-20	-5	μΑ
I _{CLK in}	Pull down current at input CLK	V _{CLK} = 1.5V	10	25	50	μΑ
I _{DI in}	Pull down current at input DI	V _{DI} = 1.5V	10	25	50	μΑ
I _{PWM1 in}	Pull down current at input PWM1	V _{PWM} = 1.5V	10	25	50	μΑ
C _{in} ⁽¹⁾	Input capacitance at input CSN, CLK, DI and PWM1/2	0 V < V _{CC} < 5.3V		10	15	pF

^{1.} Value of input capacity is not measured in production test. Parameter guaranteed by design.

Table 14. DI timing ⁽¹⁾

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
t _{CLK}	Clock period	$V_{CC} = 5V$	1000			ns
t _{CLKH}	Clock high time	$V_{CC} = 5V$	400			ns
t _{CLKL}	Clock low time	V _{CC} = 5V	400			ns
t _{set CSN}	CSN setup time, CSN low before rising edge of CLK	V _{CC} = 5V	400			ns
t _{set CLK}	CLK setup time, CLK high before rising edge of CSN	V _{CC} = 5V	400			ns
t _{set DI}	DI setup time	V _{CC} = 5V	200			ns
t _{hold time}	DI hold time	V _{CC} = 5V	200			ns
t _{r in}	Rise time of input signal DI, CLK, CSN	V _{CC} = 5V			100	ns
t _{f in}	Fall time of input signal DI, CLK, CSN	V _{CC} = 5V			100	ns

^{1.} DI timing parameters tested in production by a passed / failed test:

Tj= -40°C / +25°C: SPI communication @ 2MHz. Tj= +125°C SPI communication @ 1.25 MHz.



Table 15. DO

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V _{DOL}	Output low level	$VCC = 5 \text{ V}, I_D = -2\text{mA}$		0.2	0.4	V
V _{DOH}	Output high level	$VCC = 5 \text{ V}, I_D = 2 \text{ mA}$	V _{CC} -0.4	V _{CC} -0.2		V
I _{DOLK}	3-state leakage current	$V_{CSN} = V_{CC},$ $0V < V_{DO} < V_{CC}$	-10		10	μΑ
C _{DO} (1)	3-state input capacitance	$V_{CSN} = V_{CC},$ $0V < V_{CC} < 5.3V$		10	15	pF

^{1.} Value of input capacity is not measured in production test. Parameter guaranteed by design.

Table 16. DO timing

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
t _{r DO}	DO rise time	$C_L = 100 \text{ pF}, I_{load} = -1 \text{mA}$		80	140	ns
t _{f DO}	DO fall time	$C_L = 100 \text{ pF}, I_{load} = 1 \text{mA}$		50	100	ns
t _{en DO tri L}	DO enable time $C_L = 100 \text{ pF}, I_{load} = 1 \text{mA}$ from 3-state to low level pull-up load to V_{CC}			100	250	ns
t _{dis DO L tri}	DO disable time from low level to 3-state	C_L = 100 pF, I_{load} = 4 mA pull-up load to V_{CC}		380	450	ns
t _{en DO tri H}	DO enable time C _L =100 pF, I _{load} = -1mA from 3-state to high level pull-down load to GND			100	250	ns
t _{dis DO H tri}	DO disable time from high level to 3-state	C _L = 100 pF, I _{load} = -4mA pull-down load to GND		380	450	ns
t _{d DO}	DO delay time	$V_{DO} < 0.3 V_{CC}, V_{DO} > 0.7 V_{CC},$ $C_L = 100 pF$		50	250	ns

Table 17. CSN timing

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
t _{CSN_HI,stb}	CSN HI time, switching from standby mode	Transfer of SPI command to input register	20			μs
t _{CSN_HI,min}	CSN HI time, active mode	Transfer of SPI command to input register	4			μs

Figure 3. SPI - transfer timing diagram

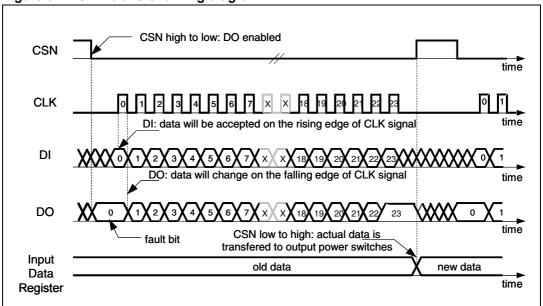
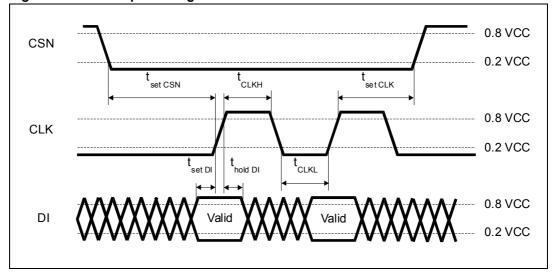
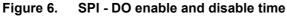


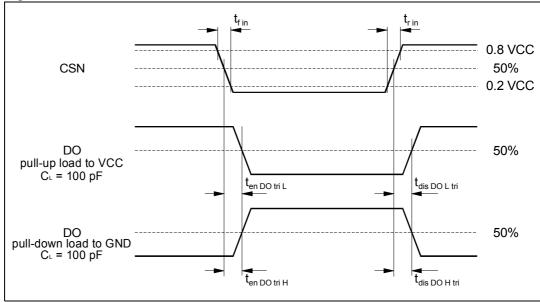
Figure 4. SPI - input timing



 $\mathsf{t}_{\mathsf{fin}}$ $\mathsf{t}_{_{\text{rin}}}$ 0.8 VCC CLK 0.5 VCC 0.2 VCC t_{rDO} DO 0.8 VCC (low to high) 0.2 VCC t_{dDO} t_{fDO} 0.8 VCC DO (high to low) 0.2 VCC

Figure 5. SPI - DO valid data delay time and valid time





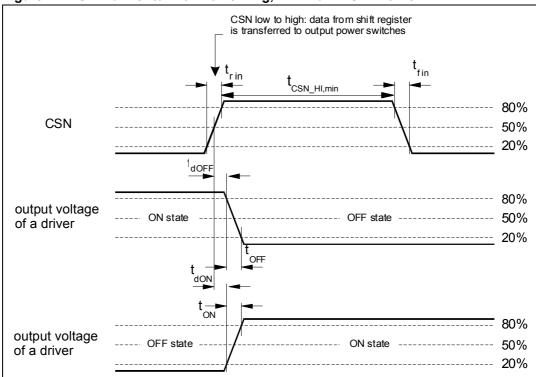
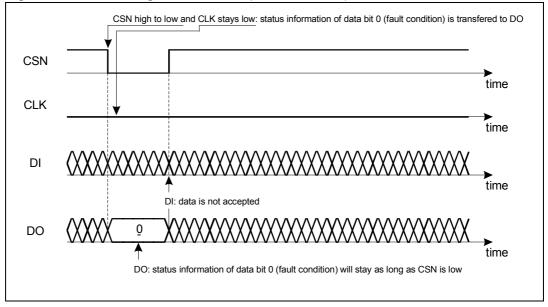


Figure 7. SPI - driver turn on / off timing, minimum CSN hi time





3 **Application information**

3.1 Dual power supply: V_S and V_{CC}

The power supply voltage V_S supplies the half bridges and the highside drivers. An internal charge-pump is used to drive the highside switches. The logic supply voltage V_{CC} (stabilized 5 V) is used for the logic part and the SPI of the device.

Due to the independent logic supply voltage the control and status information will not be lost, if there are temporary spikes or glitches on the power supply voltage. In case of poweron (V_{CC} increases from under voltage to $V_{POR\ Off} = 4.2\ V$) the circuit is initialized by an internally generated power-on-reset (POR). If the voltage V_{CC} decreases under the minimum threshold (V_{POR ON} = 3.4 V), the outputs are switched to 3-state (high impedance) and the status registers are cleared.

3.2 Standby mode

The standby mode of the L9953LXP is activated by clearing the bit 23 of the input data register 0. All latched data will be cleared and the inputs and outputs are switched to high impedance. In the standby mode the current at V_S (V_{CC}) is less than 6 μA (50 μA) for CSN = high (DO in 3-state). By switching the V_{CC} voltage a very low quiescent current can be achieved. If bit 23 is set, the device will be switched to active mode.

3.3 Inductive loads

Each half bridge is built by an internally connected highside and a lowside power DMOS transistor. Due to the built-in reverse diodes of the output transistors, inductive loads can be driven at the outputs OUT1 to OUT5 without external free-wheeling diodes. The highside drivers OUT6 to OUT8 are intended to drive resistive loads. Hence only a limited energy (E<1mJ) can be dissipated by the internal ESD diodes in freewheeling condition. For inductive loads (L>100µH) an external free-wheeling diode connected to GND and the corresponding output is needed.

3.4 **Diagnostic functions**

All diagnostic functions (over/open-load, power supply over-/under voltage, temperature warning and thermal shutdown) are internally filtered and the condition has to be valid for at least 32 µs (open-load: 1ms, respectively) before the corresponding status bit in the status registers will be set. The filters are used to improve the noise immunity of the device. Openload and temperature warning function are intended for information purpose and will not change the state of the output drivers. On contrary, the overload condition will disable the corresponding driver (over-current) and overtemperature will switch off all drivers (thermal shutdown). Without setting the over-current recovery bits in the input data register, the microcontroller has to clear the over-current status bits to reactivate the corresponding drivers.

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3.5 Overvoltage and under voltage detection

If the power supply voltage V_S rises above the overvoltage threshold $V_{SOV\ Off}$ (typical 21 V), the outputs OUT1 to OUT8 are switched to high impedance state to protect the load. When the voltage V_S drops below the under voltage threshold $V_{SUV\ Off}$ (UV-switch-Off voltage), the output stages are switched to the high impedance to avoid the operation of the power devices without sufficient gate driving voltage (increased power dissipation). If the supply voltage V_S recovers to normal operating voltage the outputs stages return to the programmed state (input register 0: bit 20=0).

If the under voltage/overvoltage recovery disable bit is set, the automatic turn-On of the drivers is deactivated. The microcontroller needs to clear the status bits to reactivate the drivers. It is recommended to set bit 20 to avoid a possible high current oscillation in case of a shorted output to GND and low battery voltage.

3.6 Charge pump

The charge pump runs under all conditions in normal mode. In standby the charge pump is disabled.

3.7 Temperature warning and thermal shutdown

If junction temperature rises above $T_{j TW}$ a temperature warning flag is set and is detectable via the SPI. If junction temperature increases above the second threshold $T_{j SD}$, the thermal shutdown bit will be set and power DMOS transistors of all output stages are switched Off to protect the device. Temperature warning flag and thermal shutdown bit are latched and must be cleared by the microcontroller. The related bit is only cleared if the temperature decreases below the trigger temperature. If the thermal shutdown bit has been cleared the output stages are reactivated.

3.8 Open-load detection

The open-load detection monitors the load current in each activated output stage. If the load current is below the open-load detection threshold for at least 1 ms (t_{dOL}) the corresponding open-load bit is set in the status register. Due to mechanical/electrical inertia of typical loads a short activation of the outputs (e.g. 3ms) can be used to test the open-load status without changing the mechanical/electrical state of the loads.

3.9 Over load detection

In case of an over-current condition a flag is set in the status register in the same way as open-load detection. If the over-current signal is valid for at least $t_{\rm ISC}=32~\mu s$, the over-current flag is set and the corresponding driver is switched off to reduce the power dissipation and to protect the integrated circuit. If the over-current recovery bit of the output is zero the microcontroller has to clear the status bits to reactivate the corresponding driver.

3.10 Current monitor

The current monitor output sources a current image at the current monitor output which has a fixed ratio (1/10000) of the instantaneous current of the selected highside driver. The bits 18 and 19 of the input data register 0 control which of the outputs OUT1, OUT4, OUT5, and OUT8 will be multiplexed to the current monitor output. The current monitor output allows a more precise analysis of the actual state of the load rather than the detection of an open- or overload condition. For example this can be used to detect the motor state (starting, free-running, stalled). Moreover, it is possible to regulate the power of the defroster more precise by measuring the load current. The current monitor output is bidirectional (c.f. PWM inputs).

3.11 PWM inputs

Each driver has a corresponding PWM enable bit which can be programmed by the SPI interface. If the PWM enable bit in input data register 1 is set, the output is controlled by the logically AND-combination of the PWM signal and the output control bit in input data register 0. The outputs OUT1-OUT6 and OUT8 are controlled by the PWM1 input and the output OUT7 is controlled by the bidirectional input CM/PMW2. For example, the two PWM inputs can be used to dim two lamps independently by external PWM signals.

3.12 Cross-current protection

The six half-bridges of the device are cross-current protected by an internal delay time. If one driver (LS or HS) is turned-off the activation of the other driver of the same half bridge will be automatically delayed by the cross-current protection time. After the cross-current protection time is expired the slew-rate limited switch-off phase of the driver will be changed to a fast turn-off phase and the opposite driver is turned-on with slew-rate limitation. Due to this behavior it is always guaranteed that the previously activated driver is totally turned-off before the opposite driver will start to conduct.

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3.13 Programmable soft start function to drive loads with higher inrush current

Loads with start-up currents higher than the over-current limits (e.g. inrush current of lamps, start current of motors and cold resistance of heaters) can be driven by using the programmable soft start function (i.e. overcurrent recovery mode). Each driver has a corresponding over-current recovery bit. If this bit is set, the device will automatically switch-on the outputs again after a programmable recovery time. The duty cycle in over-current condition can be programmed by the SPI interface to be about 12% or 25%. The PWM modulated current will provide sufficient average current to power up the load (e.g. heat up the bulb) until the load reaches operating condition. The PWM frequency settles at 3kHz or 6kHz. The device itself cannot distinguish between a real overload and a non linear load like a light bulb. A real overload condition can only be qualified by time. As an example the microcontroller can switch on light bulbs by setting the over-current recovery bit for the first 50ms. After clearing the recovery bit the output will be automatically disabled if the overload condition still exits.

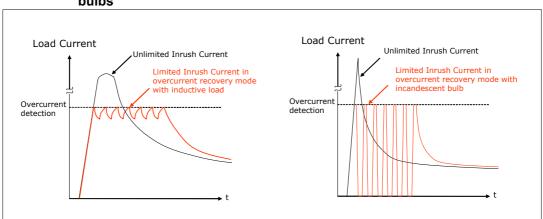


Figure 9. Programmable soft start function for inductive loads and incandescent bulbs

4 Functional description of the SPI

4.1 Serial Peripheral Interface (SPI)

This device uses a standard SPI to communicate with a microcontroller. The SPI can be driven by a microcontroller with its SPI peripheral running in following mode: CPOL = 0 and CPHA = 0.

For this mode, input data is sampled by the low to high transition of the clock CLK, and output data is changed from the high to low transition of CLK.

This device is not limited to microcontroller with a build-in SPI. Only three CMOS-compatible output pins and one input pin will be needed to communicate with the device. A fault condition can be detected by setting CSN to low. If CSN = 0, the DO-pin will reflect the status bit 0 (fault condition) of the device which is a logical-or of all bits in the status registers 0 and 1. The microcontroller can poll the status of the device without the need of a full SPI-communication cycle.

Note: In contrast to the SPI-standard the least significant bit (LSB) will be transferred first (see Figure 3).

4.2 Chip Select Not (CSN)

The input pin is used to select the serial interface of this device. When CSN is high, the output pin (DO) will be in high impedance state. A low signal will activate the output driver and a serial communication can be started. The state when CSN is going low until the rising edge of CSN will be called a communication frame. If the CSN-input pin is driven above 7.5V, the L9953LXP will go into a test mode. In the test mode the DO will go from 3-state to active mode.

4.3 Serial Data In (DI)

The input pin is used to transfer data serial into the device. The data applied to the DI will be sampled at the rising edge of the CLK signal and shifted into an internal 24 bit shift register. At the rising edge of the CSN signal the contents of the shift register will be transferred to data input register. The writing to the selected data input register is only enabled if exactly 24 bits are transmitted within one communication frame (i.e. CSN low). If more or less clock pulses are counted within one frame the complete frame will be ignored. This safety function is implemented to avoid an activation of the output stages by a wrong communication frame.

Due to this safety functionality a daisy chaining of SPI is not possible. Instead, a parallel operation of the SPI bus by controlling the CSN signal of the connected ICs is recommended.

4.4 Serial Data Out (DO)

Note:

The data output driver is activated by a logical low level at the CSN input and will go from high impedance to a low or high level depending on the status bit 0 (fault condition). The first rising edge of the CLK input after a high to low transition of the CSN pin will transfer the

content of the selected status register into the data out shift register. Each subsequent falling edge of the CLK will shift the next bit out.

4.5 Serial clock (CLK)

The CLK input is used to synchronize the input and output serial bit streams. The data input (DI) is sampled at the rising edge of the CLK and the data output (DO) will change with the falling edge of the CLK signal.

4.6 Input data register

The device has two input registers. The first bit (bit 0) at the DI-input is used to select one of the two Input Registers. All bits are first shifted into an input shift register. After the rising edge of CSN the contents of the input shift register will be written to the selected Input Data Register only if a frame of exact 24 data bits are detected. Depending on bit 0 the contents of the selected status register will be transferred to DO during the current communication frame. Bit 1-17 controls the behavior of the corresponding driver.

If bit 23 is zero, the device will go into the standby-mode. The bits 18 and 19 are used to control the current monitor multiplexer. Bit 22 is used to reset all status bits in both status registers. The bits in the status registers will be cleared after the current communication frame (rising edge of CSN).

4.7 Status register

This devices uses two status registers to store and to monitor the state of the device. Bit 0 is used as a fault bit and is a logical-NOR combination of bits 1-22 in both status registers. The state of this bit can be polled by the microcontroller without the need of a full SPI communication cycle. If one of the over-current bits is set, the corresponding driver will be disabled. If the over-current recovery bit of the output is not set the microcontroller has to clear the over-current bit to enable the driver. If the thermal shutdown bit is set, all drivers will go into a high impedance state. Again the microcontroller has to clear the bit to enable the drivers.

4.8 SPI - input data and status registers

Table 18. SPI - input data and status registers 0

Dit	Bit		registe	r 0 (wri	ite)	Statı	ıs register 0 (read)	
Біі	Na	me	Comment		Name	Comment		
23	Enable bit		device active is clear into sta bits are power-	will be mode. red the andby recleares	s set the switched in If enable bit device go node and all ed. After et device dby mode.	Always 1	A broken VCC-or SPI- connection of the L9953LXP can be detected by the microcontroller, because all 24 bits low or high is not a valid frame.	
22	Reset bit		status	registe d after r	set both rs will be ising edge of	V _S overvoltage	In case of an overvoltage or undervoltage event the corresponding bit is set and the outputs are deactivated. If	
	OC red			t define nation v	es in vith the over-		VS voltage recovers to norma operating conditions outputs	
21	1		current recovery bit (Input register 1) the duty cycle		V _S undervoltage	are reactivated automatically (if Bit 20 of status register 0 is not set).		
20	Overvoltage/ undervoltage recovery disable		microc clear th after underv	ne statu oltage/ o enab	er has to us register overvoltage	Thermal shutdown	In case of a thermal shutdown all outputs are switched off. The microcontroller has to clear the TSD bit by setting the reset bit to reactivate the outputs.	
19			combir 19 the (1/10.0 HS-out	current 000) of tput wil	n of bit 18 and t image the selected I be multi- CM output:	Temperature warning	This TW bit is for information purpose only. It can be used for a thermal management by the microcontroller to avoid a thermal shutdown.	
			Bit 19	Bit 18	Output		After switching the device from standby mode to active mode	
	Current monitor select bits			an internal timer is started to allow charge pump to settle				
			1	0	OUT1		before the outputs can be activated. This bit is cleared	
18	18		0	1	OUT5	Not ready bit	automatically after start up	
			1	1	OUT4		time has finished. Since this bit is controlled by internal clock it	
							can be used for synchronizing testing events (e.g. measuring filter times).	

Table 18. SPI - input data and status registers 0 (continued)

D:4	Input	Input register 0 (write)		us register 0 (read)
Bit	Name	Comment	Name	Comment
17	OUT8 – HS on/off		OUT8 – HS over-current	
16	x (don't care)		0	
15	OUT7 – HS on/off		OUT7 – HS over-current	
14	OUT6 – HS on/off		OUT6 – HS over-current	
13	x (don't care)		0	
12	x (don't care)	If a bit is set the selected output driver is switched	0	In case of an over-current
11	x (don't care)	On. If the corresponding		event the corresponding status bit is set and the output driver
10	OUT5 – HS on/off	PWM enable bit is set (input register 1) the driver is only activated if PWM1	OUT5 – HS over-current	is disabled. If the over-current recovery enable bit is set
9	OUT5 – LS on/off	(PWM2) input signal is high. The outputs of	OUT5 – LS over-current	(input register 1) the output will be automatically reactivated after a delay time resulting in a
8	OUT4 – HS on/off	OUT1-OUT5 are half bridges. If the bits of HS-and LS-driver of the same half bridge are set, the internal logic prevents that both drivers of this output stage can be switched on simultaneously in order to	OUT4 – HS over-current	PWM modulated current with a programmable duty cycle (bit
7	OUT4 – LS on/off		OUT4 – LS over-current	21). If the over-current recovery bit
6	OUT3 – HS on/off		OUT3 – HS over-current	is not set the microcontroller has to clear the over-current
5	OUT3 – LS on/off	avoid a high internal current from VS to GND.	OUT3 – LS over-current	bit (reset bit) to reactivate the output driver.
4	OUT2 – HS on/off		OUT2 – HS over-current	
3	OUT2 – LS on/off		OUT2 – LS over-current	
2	OUT1 – HS on/off		OUT1 – HS over-current	
1	OUT1 – LS on/off		OUT1 – LS over-current	
0		0	No error bit	A logical NOR-combination of all bits 1 to 22 in both status registers.

Table 19. SPI - input data and status registers 1

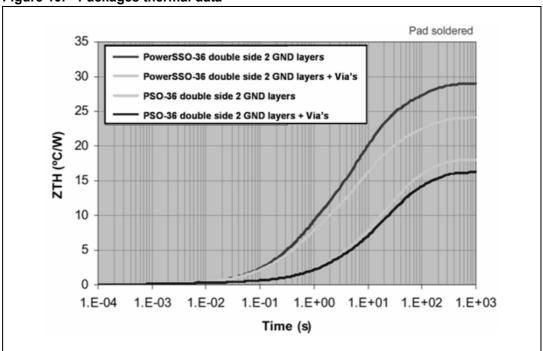
Bit	Inp	ut register 1 (write)	Status re	egister 1 (read)
DIL	Name	Comment	Name	Comment
23	Enable bit	If enable bit is set the device will be switched in active mode. If enable bit is cleared device goes into standby mode and all bits are cleared. After poweron reset device starts in standby mode.	Always 1	A broken VCC or SPI connection of the L9953LXP can be detected by the microcontroller, because all 24 bits low or high is not a valid frame.
22	OUT8 OC recovery enable		VS overvoltage	In case of an overvoltage or under voltage event the corresponding bit is
21	0/1	In case of an over-current event the over-current status bit (status register 0) is set and the output is switched off. If the over-current recovery enable bit is set the output will be automatically reactivated after a delay time resulting in a PWM modulated current with a programmable duty cycle (bit 21 of input data register 0). Depending on occurrence of	VS undervoltage	set and the outputs are deactivated. If Vs voltage recovers to normal operating conditions outputs are reactivated automatically.
20	OUT7 OC recovery enable		Thermal shutdown	In case of a thermal shutdown all outputs are switched off. The microcontroller has to clear the TSD bit by setting the reset bit to reactivate the outputs.
19	OUT6 OC recovery enable		Temperature warning	The TW bit can be used for thermal management by the microcontroller to avoid a thermal shutdown. The microcontroller has to clear the TW bit.
18	0/1	over-current event and internal clock phase it is possible that one recovery cycle is executed even if this bit is set to zero.	Not ready bit	After switching the device from standby mode to active mode an internal timer is started to allow charge pump to settle before the outputs can be activated. This bit is only present during start up time Since this bit is controlled by internal clock it can be used for synchronizing testing events(e.g. measuring filter times).

Table 19. SPI - input data and status registers 1 (continued)

D:4	Inp	ut register 1 (write)	Status r	register 1 (read)
Bit	Name	Comment	Name	Comment
17	Enable high		OUT8 – HS	
	R _{DSon} OUT7		open-load	
16	OUT5 OC recovery enable		0	
4.5	OUT4 OC		OUT7 – HS	
15	recovery enable	After 50ms the bit can be	open-load	
	OUT3 OC	cleared. If over-current condition still exists, a wrong	OUT6 – HS	
14	recovery	load can be assumed.	open-load	
	enable			
13	OUT2 OC recovery enable		0	The open-load detection monitors the load current
12	OUT1 OC recovery enable		0	in each activated output stage. If the load current is below the open-load
11	OUT8 PWM1 enable		0	detection threshold for at least 1 ms (t _{dOL}) the
10	0 / 1		OUT5 – HS	corresponding open-load bit is set. Due to
10	071		open-load	mechanical/electrical
9	OUT7 PWM2		OUT5 – LS	inertia of typical loads a
	enable		open-load	short activation of the outputs (e.g. 3ms) can
8	OUT6 PWM1		OUT4 – HS	be used to test the open-
	enable	If the PWM1/2 enable bit is set	open-load	load status without
7		and the output is enabled	OUT4 – LS	changing the mechanical/electrical
		(input register 0) the output is switched On if PWM1/2 input is	open-load	state of the loads.
6	Enable high R _{DSon} OUT6	high and switched off if	OUT3 – HS open-load	
	OUT5 PWM1	PWM1/2 input is low. OUT7 is controlled by PWM2 input. All	OUT3 – LS	
5	enable	other outputs are controlled by	open-load	
	OUT4 PWM1	PWM1 input.	OUT2 –HS	
4	enable		open-load	
	OUT3 PWM1		OUT2- LS	
3	enable		open-load	
2	OUT2 PWM1		OUT1 - HS	
-	enable		open-load	
1	OUT1 PWM1		OUT1 – LS	
	enable		open-load	
0		1	No error bit	A logical NOR- combination of all bits 1 to 22 in both status registers.

5 Packages thermal data





6 Package and packing information

6.1 ECOPACK® packages

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com.

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6.2 PowerSSO-36 package information

Figure 11. PowerSSO-36 package dimensions

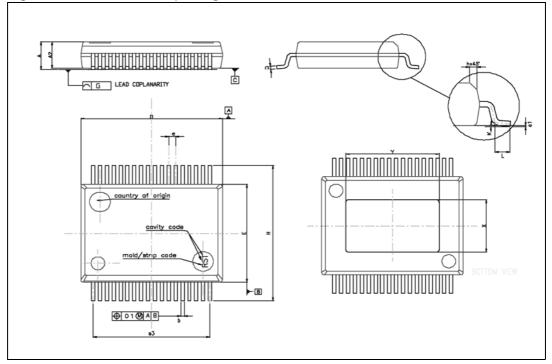


Table 20. PowerSSO-36 mechanical data

Symbol		Millimeters	
Symbol	Min.	Тур.	Max.
А	2.15	-	2.47
A2	2.15	-	2.40
a1	0	-	0.075
b	0.18	-	0.36
С	0.23	-	0.32
D	10.10	-	10.50
E	7.4	-	7.6
е	-	0.5	-
e3	-	8.5	-
G	-	-	0.1
G1	-	-	0.06
Н	10.1	-	10.5
h	-	-	0.4
L	0.55	-	0.85
N	-	-	10 deg
Х	4.3	-	5.2
Υ	6.9	-	7.5

6.3 PowerSSO-36 packing information

Figure 12. PowerSSO-36 tube shipment (no suffix)

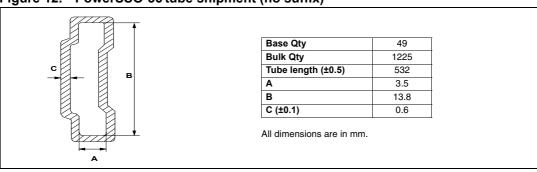
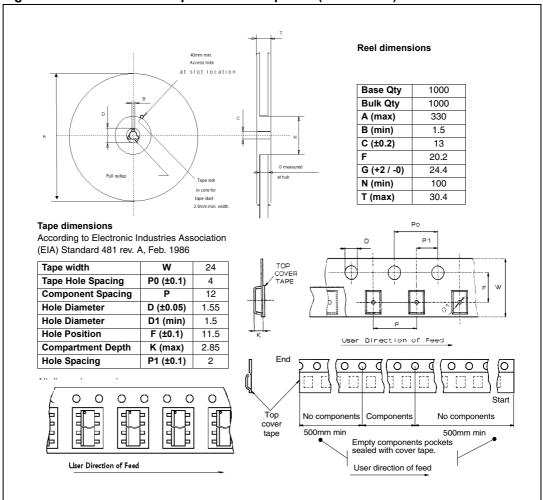


Figure 13. PowerSSO-36 tape and reel shipment (suffix "TR")



Revision history L9953LXP

7 Revision history

Table 21. Document revision history

Date	Revision	Description of changes
31-Aug-2009	1	Initial release.
14-May-2010	2	Table 20: PowerSSO-36 mechanical data: - Changed X: minimum value from 4.1 to 4.3 and maximum value from 4.7 to 5.2 - Changed Y: minimum value from 6.5 to 6.9 and maximum value from 7.1 to 7.5

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