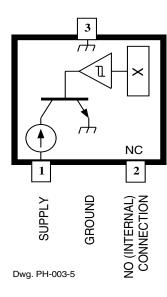
3260

Data Sheet **27631.50**

2-WIRE, CHOPPER-STABILIZED, PRECISION HALL-EFFECT BIPOLAR SWITCH

Suffix Code 'LH' Pinning



Pinning is shown viewed from branded side.

ADVANCE INFORMATION (subject to change without notice)
June 30, 2000

ABSOLUTE MAXIMUM RATINGS at T_A =+25°C

Supply Voltage, V_{CC} 27 V
Reverse Battery Voltage, V _{RCC} 16 V
Magnetic Flux Density, B Unlimited
Package Power Dissipation, P _D . See Graph
Junction Temperature, T _J +170°C
Operating Temperature Range, T _A
Suffix 'E-'40°C to +85°C
Suffix 'L-' -40° C to $+150^{\circ}$ C
Storage Temperature Range,
T_S 65°C to +170°C

The A3260-- Hall-effect bipolar switch is an extremely temperature-stable and stress-resistant sensor especially suited for operation over extended temperature ranges to +150°C. Superior high-temperature performance is made possible through dynamic offset cancellation, which reduces the residual offset voltage normally caused by device overmolding, temperature dependencies, and thermal stress.

The device includes on a single silicon chip a voltage regulator, Hall-voltage generator, small-signal amplifier, chopper stabilization, Schmitt trigger, and a constant-current open-collector output. A south pole of sufficient strength will turn the output OFF. An on-board regulator permits operation with supply voltages of 3.5 to 24 volts. Noise radiation is limited by control of the output current slew rate.

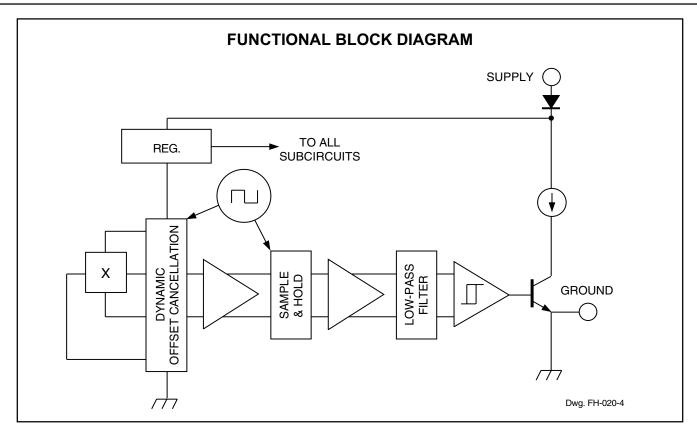
The first character of the part number suffix determines the device operating temperature range; suffix 'E–' is -40°C to +85°C and 'L–' is -40°C to +150°C. Three package styles provide a magnetically optimized package for most applications. Suffix '–LH' is a miniature low-profile surface-mount package, '–LT' is a miniature SOT-89/TO-243AA transistor package for surface-mount applications; while suffix '–UA' is a three-lead ultra-mini-SIP for through-hole mounting.

FEATURES

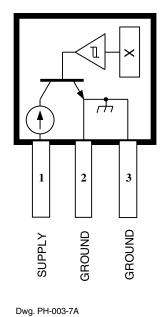
- Internal Current Regulator for 2-Wire Operation
- Output Slew Rate Controlled
- Resistant to Physical Stress
- Superior Temperature Stability
- Operation From Unregulated Supply
- Reverse Battery Protection
- Solid-State Reliability
- Small Size

Always order by complete part number: the prefix 'A' + the basic four-digit part number + a suffix to indicate operating temperature range + a suffix to indicate package style, e.g., A3260ELH.

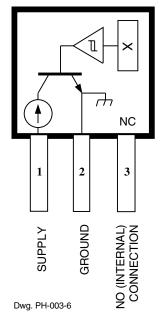




Suffix Code 'UA' Pinning (SIP)



Suffix Code 'LT' Pinning (SOT-89/TO-243AA)



Pinning is shown viewed from branded side.



ELECTRICAL CHARACTERISTICS over operating temperature range.

			Limits			
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Supply Voltage	V _{cc}	Operating	3.5	12	24	V
Output Current	I _{GND(L)}	B > B _{OP}	-4.0	-6.5	-8.0	mA
	I _{GND(H)}	B < B _{RP}	-11	-14.5	-18	mA
Chopping Frequency	f _C		-	340	-	kHz
Output Slew Rate	di/dt	C _L = 20 pF	0.5	_	2.0	mA/μs
Output Settling Time	t _{sd}	C _L = 20 pF	_	_	20	μs
Reverse Battery Current	I _{cc}	V _{RCC} = -16 V	_	_	-15	mA

NOTES:1. . B_{OP} = operate point (output turns OFF); B_{RP} = release point (output turns ON). 2. Typical Data is at T_A = +25°C and V_{CC} = 12 V and is for design information only.

MAGNETIC CHARACTERISTICS over operating supply voltage and temperature ranges.

			Limits			
Characteristic	Symbol	Test Conditions	Min.	Тур.	Max.	Units
Operate Point	B _{OP}		_	10	30	G
Release Point	B _{RP}		-30	-10	_	G
Hysteresis	B _{hys}	B _{OP} - B _{RP}	_	20	_	G

NOTE — Typical Data is at $T_A = +25^{\circ}C$ and $V_{CC} = 12 \text{ V}$ and is for design information only.

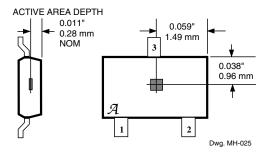
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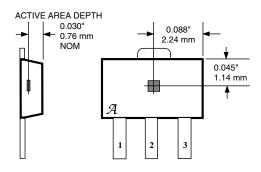
SENSOR LOCATIONS

(±0.005" [0.13 mm] die placement)

Package Designator "LH"

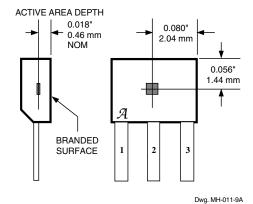


Package Designator "LT"

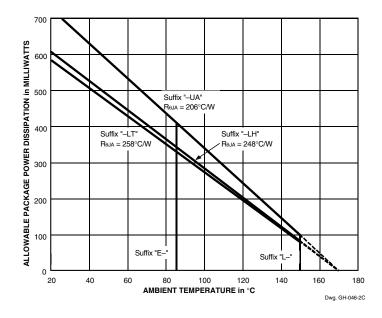


Dwg. MH-008-8

Package Designators "UA" and "UA-TL"



Although sensor location is accurate to three sigma for a particular design, product improvements may result in small changes to sensor location.



CRITERIA FOR DEVICE QUALIFICATION

All Allegro sensors are subjected to stringent qualification requirements prior to being released to production. To become qualified, except for the destructive ESD tests, no failures are permitted.

Qualification Test	Test Method and Test Conditions	Test Length	Samples	Comments
Biased Humidity (HAST)	T _A = 130°C, RH = 85%	50 hrs	77	V _{CC} = V _{OUT} = 5 V
High-Temperature Operating Life (HTOL)	JESD22-A108, T _A = 150°C, T _J ≤ 165°C	408 hrs	77	V _{CC} = 24 V, V _{OUT} = 20 V
Accelerated HTOL	T _A = 175°C, T _J = 190°C	504 hrs	77	V _{CC} = 24 V, V _{OUT} = 20 V
Autoclave, Unbiased	JESD22-A102, Condition C, $T_A = 121^{\circ}C$, 15 psig	96 hrs	77	
High-Temperature (Bake) Storage Life	MIL-STD-883, Method 1008, T _A = 170°C	1000 hrs	77	
Temperature Cycle	MIL-STD-883, Method 1010, -65°C to +150°C	500 cycles	77	
Latch-Up	_	Pre/Post Reading	6	
Electro-Thermally Induced Gate Leakage	_	Pre/Post Reading	6	
ESD, Human Body Model	CDF-AEC-Q100-002	Pre/Post Reading	x per test	Test to failure, All leads > TBD
Electrical Distributions	Per Specification		30	



BIPOLAR SWITCH

FUNCTIONAL DESCRIPTION

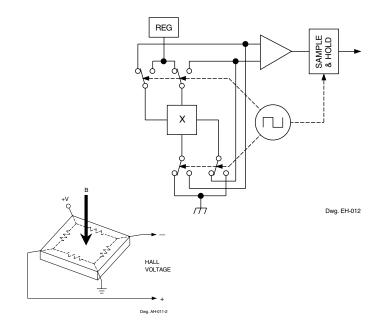
Chopper-Stabilized Technique. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. This technique will also slightly degrade the device output repeatability.

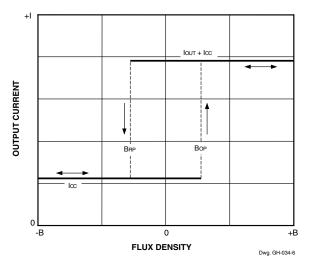
The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. The chopper-stabilizing technique cancels the mismatching of the resistors by changing the direction of the current flowing through the Hall plate and Hall voltage measurement taps, while maintaining the Hall-voltage signal that is induced by the external magnetic flux. The signal is, then, captured by a sample-and-hold circuit.

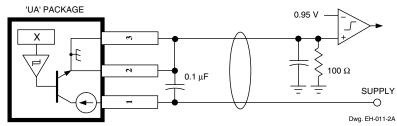
Operation. The output of these devices turns ON when a magnetic field (north pole) perpendicular to the Hall sensor exceeds the release point threshold (B_{RP}). After turn-ON, the output will source current equal to the device operating current plus a current source ($I_{GND(H)}$). When the magnetic field is increased (south pole) above the operate point (B_{OP}), the output will source current equal to the Hall-effect sensor operating current with the current source turned OFF ($I_{GND(L)}$). The difference in the magnetic operate and release points is the hysteresis (B_{hys}) of the device. The hysteresis allows clean switching of the output even in the presence of external mechanical vibration or electrical noise.

Applications. It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique.

Extensive applications information on magnets and Hall-effect sensors is also available in the *Allegro Electronic Data Book* AMS-702 or *Application Note* 27701.







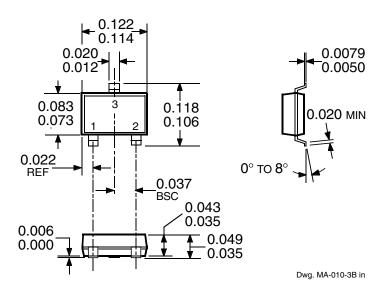
PACKAGE DESIGNATOR 'LH'

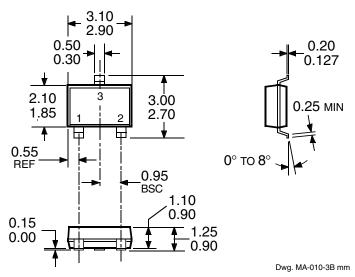
(fits SC-74A solder-pad layout)

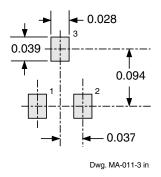
Dimensions in Inches

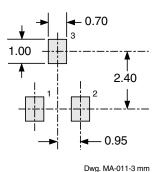
(for reference only)

Dimensions in Millimeters (controlling dimensions)









NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).

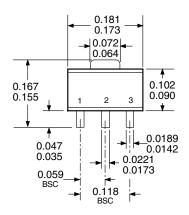
- 2. Exact body and lead configuration at vendor's option within limits shown.
- 3. Height does not include mold gate flash.
- 4. Where no tolerance is specified, dimension is nominal.

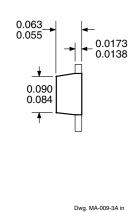


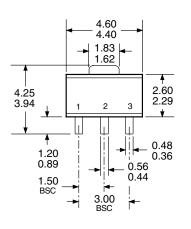
PACKAGE DESIGNATOR 'LT' (SOT-89/TO-243AA)

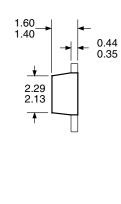
Dimensions in Inches (for reference only)

Dimensions in Millimeters (controlling dimensions)

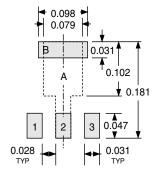








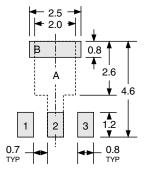
Dwg. MA-009-3A mm



Pads 1, 2, 3, and A — Standard SOT-89 Layout Pads 1, 2, 3, and B — Low-Stress Version

Pads 1, 2, and 3 only — Lowest Stress, But Not Self Aligning

Dwg. MA-012-3 in



Pads 1, 2, 3, and A — Standard SOT-89 Layout

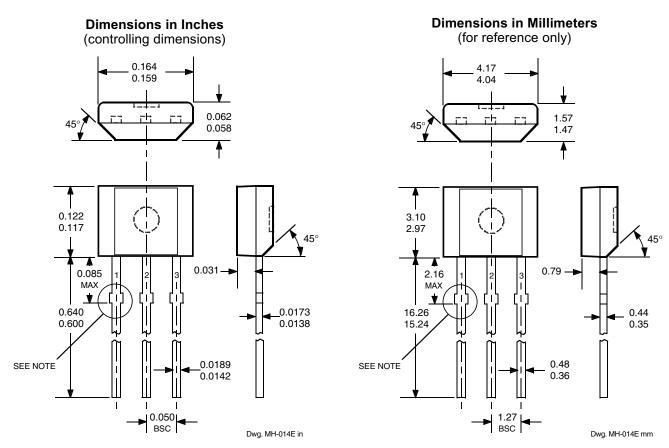
Pads 1, 2, 3, and B — Low-Stress Version

Pads 1, 2, and 3 only — Lowest Stress, But Not Self Aligning

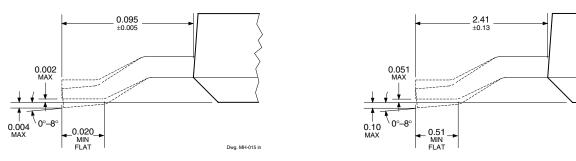
Dwg. MA-012-3 mm

NOTE: Exact body and lead configuration at vendor's option within limits shown.

PACKAGE DESIGNATOR 'UA'



Surface-Mount Lead Form (Suffix '-TL')



- NOTES: 1. Tolerances on package height and width represent allowable mold offsets. Dimensions given are measured at the widest point (parting line).
 - 2. Exact body and lead configuration at vendor's option within limits shown.
 - 3. Height does not include mold gate flash.
 - 4. Recommended minimum PWB hole diameter to clear transition area is 0.035" (0.89 mm).
 - 5. Where no tolerance is specified, dimension is nominal.



Dwg. MH-015 mm

The products described herein are manufactured under one or more of the following U.S. patents: 5,045,920; 5,264,783; 5,442,283; 5,389,889; 5,581,179; 5,517,112; 5,619,137; 5,621,319; 5,650,719; 5,686,894; 5,694,038; 5,729,130; 5,917,320; and other patents pending.

Allegro MicroSystems, Inc. reserves the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the performance, reliability, or manufacturability of its products. Before placing an order, the user is cautioned to verify that the information being relied upon is current.

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The information included herein is believed to be accurate and reliable. However, Allegro MicroSystems, Inc. assumes no responsibility for its use; nor for any infringements of patents or other rights of third parties that may result from its use.

HALL-EFFECT SENSORS

Partial Part	Avail. Ope	er. Charac	cteristics at	T _A = +25°C				
Number	Temp.	BOP(max)	B _{RP(min)}	B _{hys(typ)}	Features	Notes		
HALL-EFFECT UNIPOLAR SWITCHES in order of BOP and Bhys								
3240	E/L	+50	+5.0	10	chopper stabilized	1		
3209	E E	±60	±5.0	7.7	400 μW, chopper stabilized			
3210	Ē	±60	±5.0	7.7	25 μW, chopper stabilized			
3361	Е	+55*	+110‡	5.0*	2-wire, chopper stabilized			
3362	E	+110	+55	5.0*	2-wire, chopper stabilized			
3161	E	+160	+30	20	2-wire			
3141	E/L	+160	+10	55				
3235	S	+175	+25	15*	output 1	2		
		-25	-175	15*	output 2	2		
5140	E	+200	+50	55	300 mA output	2 2 1, 3		
3142	E/L	+230	+75	55				
3143	E/L	+340	+165	55				
3144	E/L	+350	+50	55				
3122	E/L	+400	+140	105				
3123	E/L	+440	+180	105				
3121	E/L	+450	+125	105				
3150	J	+40 to +850	_	20	programmable, chopper stabilized	1		
	HALL-EF	FECT LATCHE	S & BIPOLA	R SWITCHES	in order of BOP and Bhys			
3260	E/L	+30	-30	20	bipolar, chopper stabilized			
3280	E/L	+40	-40	45	chopper stabilized			
3134	E/L	+50	-50	27	bipolar switch			
3133	K/L/S	+75	-75	52	bipolar switch			
3281	E/L	+90	-90	100	chopper stabilized			
3132	K/L/S	+95	-95	52	bipolar switch			
3187	E/L	+150	-150	100*	•			
3177	S	+150	-150	200				
3625	S	+150	-150	200	900 mA outputs	1, 3, 5		
3626	S	+150	-150	200	400 mA outputs	1, 3, 5		
3195	E/L	+160	-160	220		1. 4		
3197	L, L	+160	-160	230		1, 4 1		
3175	S	+170	-170	200		•		
3188	E/L	+180	-180	200*				
3283	E/L	+180	-180	300	chopper stabilized			
3189	E/L	+230	-230	100*	csppor otasinzou			
3275	S	+250	-250	100*		5		
3185	E/L	+270	-270	340*		Ū		
On antin a Tamanan	L/L	.210	-210					

Operating Temperature Ranges:

 $S = -20^{\circ}C$ to $+85^{\circ}C$, $E = -40^{\circ}C$ to $+85^{\circ}C$, $J = -40^{\circ}C$ to $+115^{\circ}C$, $K = -40^{\circ}C$ to $+125^{\circ}C$, $L = -40^{\circ}C$ to $+150^{\circ}C$

Notes 1. Protected.

[†] Latches will <u>not</u> switch on removal of magnetic field; bipolar switches <u>may</u> switch on removal of field but require field reversal for reliable operation over operating temperature range.



^{2.} Output 1 switches on south pole, output 2 switches on north pole for 2-phase, bifilar-wound, unipolar-driven brushless dc motor control.

^{3.} Power driver output.

^{4.} Active pull down.

^{5.} Complementary outputs for 2-phase bifilar-wound, unipolar-driven brushless dc motor control.

^{*} Minimum. ‡ Maximum