

# SRM20116LFT85/10

### **1M-Bit Static RAM**

- Low Supply Current
- Access Time 85ns/100ns
- 65,536 Words×16-Bit Asynchronous
- Industrial Temperature Range

#### **■** DESCRIPTION

The SRM20116LFT85/10 is a 65,536 words×16-bit asynchronous, static, random access memory on a monolithic CMOS chip. Its very low standby power requirement makes it ideal for applications requiring non-volatile storage with back-up batteries. The asynchronous and static nature of the memory requires no external clock or refreshing circuit. It is possible to control the data width by the data byte control. Both the input and output ports are TTL compatible and the 3-state output allows easy expansion of memory capacity.

The temperature range of the SRM20116LFT85/10 is from –40 to +85 degree C, and it is suitable for the industrial products.

#### **■** FEATURES

● Fast Access time ...... SRM20116LFT85 85ns

SRM20116LFT10 100ns

• Low supply current ...... standby: 2μA (Typ.)

operation: 35mA/MHz (Typ.)

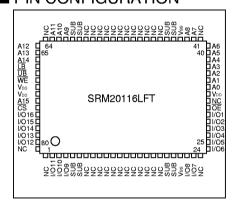
● Completely static ...... No clock required

● Single power supply ...... 5V±10%

TTL compatible inputs and outputs

- 3-state output with wired-OR capability
- Non-volatile storage with back-up batteries
- Package ...... QFP5-80pin (plastic)

#### **■ PIN CONFIGURATION**



#### ■ BLOCK DIAGRAM

#### A1 A2 A3 A4 A5 A6 A7 X Decoder 512 Memory Cell Array Address Buffer 512×128×16 Α9 A10 A11 A12 A13 128×16 Column Gate Chip Contr $\overline{\mathsf{cs}}$ 16 ŌE OE, WE Chip Control WE I/O Buffer ĹΒ

#### ■ PIN DESCRIPTION

A0 to A15 WE OE CS LB UB I/O1 to 16 VDD VSS SUB (VDD) NC	Address Input Write Enable Output Enable Chip Select LOWER byte Enable UPPER byte Enable Data I/O Power Supply (+5V) Power Supply (0V) Substrate No connection

#### ■ ABSOLUTE MAXIMUM RATINGS

(Vss = 0V)

Parameter	Symbol	Ratings	Unit
Supply voltage	$V_{DD}$	–0.5 to 7.0	٧
Input voltage	V <sub>I</sub>	−0.5*to 7.0	V
Input/Output voltage	V <sub>I/O</sub>	–0.5 <sup>*</sup> to V <sub>DD</sub> +0.3	٧
Power dissipation	P <sub>D</sub>	1.0	W
Operating temperature	T <sub>opr</sub>	-40 to 85	°C
Storage temperature	T <sub>stg</sub>	-65 to 150	°C
Soldering temperature and time	T <sub>sol</sub>	260°C, 10s (at lead)	

<sup>\*</sup>VI,  $V_{I/O}$  Min. = -3.0V (Pulse width is 50ns)

#### ■ DC RECOMMENDED OPERATING CONDITIONS

 $(Ta = -40 \text{ to } 85^{\circ}C)$ 

Parameter	Symbol	Min.	Тур.	Max.	Unit
Cumply yeltono	$V_{DD}$	V <sub>DD</sub> 4.5 5.0		5.5	٧
Supply voltage	V <sub>SS</sub>	0	0	0	V
input voltage	V <sub>IH</sub>	2.2	_	VDD+0.3	V
Input voitage	VII	-0.3*	_	0.8	V

<sup>\*</sup>if pulse width is less than 50ns it is -3.0V

#### ■ ELECTRICAL CHARACTERISTICS

#### DC Electrical Characteristics

 $(V_{DD} = 5V\pm10\%, V_{SS} = 0V, Ta = -40 \text{ to } 85^{\circ}C)$ 

				( • DL			30 - 1	,	10 to 00 0 <sub>j</sub>
Parameter	Cumbal	Conditions	SRM20116LFT85			SRM20116LFT10			Limit
rarameter	Symbol	Conditions	Min.	Тур.*	Max.	Min.	Typ.*	Max.	Unit
Input leakage	Lu	$V_{I} = 0$ to $V_{DD}$	<b>–1</b>	_	1	1	_	1	μΑ
Standby supply current	$I_{DDS}$	<del>CS</del> = V <sub>IH</sub>	_	1.0	3.0	1	1.0	3.0	mA
Standby supply current	I <sub>DDS1</sub>	<del>CS</del> ≥V <sub>DD</sub> –0.2V	_	2	200		2	200	μΑ
	$I_{DDA}$	$V_{I} = V_{IL}, V_{IH}$	_	60	100	_	60	100	mA
Average operating current	IDDA	I <sub>I/O</sub> = 0mA, tcyc = Min.							
Average operating current	I <sub>DDA1</sub>	$V_{I} = V_{IL}, V_{IH}$	_	35	70	-	35	70	mA
		$I_{I/O} = 0$ mA, tcyc = $1\mu$ A							11173
Operating supply current	I <sub>DDO</sub>	$V_{l} = V_{lL}, V_{lH}$		35	70		35	70	mA
Sperating supply current		I <sub>I/O</sub> = 0mA		35	70	_	33	70	1117
		CS = V <sub>IH</sub>							
Output leakage	<b>I</b> LO	or $\overline{WE} = V_{\parallel}$ or $\overline{OE} = V_{\parallel}$	<b>–</b> 1	_	1	<b>–</b> 1	_	-1	μΑ
		$V_{I/O} = 0$ to $V_{DD}$							
High level output voltage	V <sub>OH</sub>	I <sub>OH</sub> = -1.0mA	2.4		_	2.4			V
Low level output voltage	$V_{OL}$	I <sub>OL</sub> = 2.1mA	_	_	0.4	_	_	0.4	V

<sup>\*</sup>Typical values are measured at Ta =  $25^{\circ}$ C and V<sub>DD</sub> = 5.0V

### ■ Terminal Capacitance

 $(f = 1MHz, Ta = 25^{\circ}C)$ 

				,		,
Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Address Capacitance	C <sub>ADD</sub>	$V_{ADD} = 0V$	_	_	9	рF
Input Capacitance	Cı	$V_1 = 0V$	_	_	10	рF
I/O Capacitance	C <sub>1/O</sub>	$V_{I/O} = 0V$	_	_	10	pF

### SRM20116LFT85/10

#### AC Electrical Characteristics

#### ORead Cycle

 $(V_{DD} = 5V\pm10\%, V_{SS} = 0V, Ta = -40 \text{ to } 85^{\circ}C)$ 

Davanatav	0	O	SRM20	1 <b>16LFT</b> 85	SRM201	Limit		
Parameter	Symbol	Condition	Min.	Max.	Min.	Max.	Unit	
Read cycle time	t <sub>RC</sub>		85	_	100	_	ns	
Address access time	t <sub>ACC</sub>		_	85	_	100	ns	
CS access time	t <sub>ACS</sub>	*1	_	85	_	100	ns	
OE access time	toE		_	45	_	50	ns	
LB, UB access time	t <sub>AB</sub>		_	45	_	50	ns	
CS output st time	t <sub>CLZ</sub>		10	_	10	_	ns	
CS output foating	t <sub>CHZ</sub>		_	30	_	35	ns	
LB, UB output set time	t <sub>BLZ</sub>		0	_	0	_	ns	
LB, UB output floating	t <sub>BHZ</sub>	*2	_	30	_	35	ns	
OE output set time	toLZ		0	_	0	_	ns	
OE output floating	t <sub>OHZ</sub>		_	30	_	35	ns	
Output hold time	t <sub>OH</sub>	*1	10	_	10	_	ns	

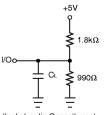
#### **OWrite Cycle**

 $(V_{DD} = 5V\pm10\%, V_{SS} = 0V, Ta = -40 \text{ to } 85^{\circ}C)$ 

Parameter		0 111	SRM20	116LFT85	SRM201	11	
Parameter	Symbol	Condition	Min.	Max.	Min.	Max.	Unit
Write cycle time	twc		85	_	100	_	ns
Chip select time	t <sub>CW</sub>		70	_	80	_	ns
Address enable time	t <sub>AW</sub>		70	_	80	_	ns
Address setup time	t <sub>AS</sub>		0	_	0	_	ns
Write pulse width	twp	*1	65	_	75	_	ns
LB, UB select time	t <sub>BW</sub>	'	65	_	75	_	ns
Address hold time	twR		0	_	0	_	ns
Data setup time	t <sub>DW</sub>		40	_	40	_	ns
Data hold time	t <sub>DH</sub>		0	_	0	_	ns
WE output floating	t <sub>wHZ</sub>	*0	_	30	_	35	ns
WE output set time	tow	*2	5	_	5	_	ns

#### \*1 Test Conditions

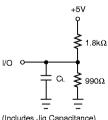
- Input pulse level: 0.6V to 2.4V
- 2. tr = tf = 5ns
- Input and output timing reference levels: 1.5V
- 4. Output load  $C_L = 100pF$



 $C_L = 100 pF$  (Includes Jig Capacitance)

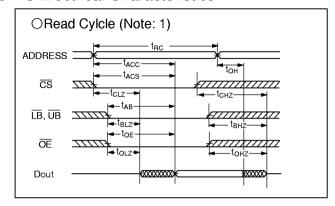
- \*2 Test Conditions
- 1. Input pulse level: 0.6V to 2.4V
- 2. tr = tf = 5ns
- 3. Input timing reference levels: 1.5V
- Output timing reference levels: ±200mA (the level displaced from stable output voltage level)

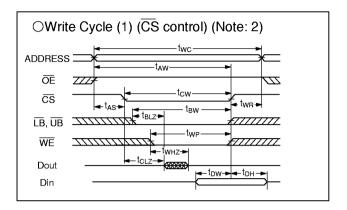
5. Output load C<sub>L</sub> = 5pF

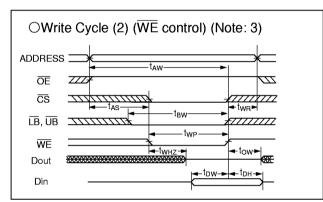


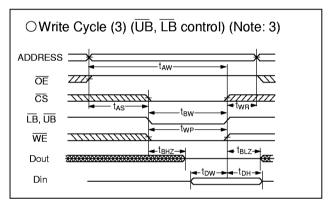
C<sub>L</sub> = 5pF (Includes Jig Capacitance)

#### AC Electrical Characteristics









Note: 1. During read cycle time, WE is to be "High" level.

- 2. In write cycle time that is controlled by  $\overline{\text{CS}}$ , output buffer is to be "Hi-Z" state if  $\overline{\text{OE}}$  is "Low" level.
- 3. When output buffer is in output state, be careful that do not input the opposite signals to the output data.

#### **■** FUNCTIONS

#### Truth Table

CS	LB	ŪB	ŌĒ	WE	I/O1 to 8	I/O9 to 16	MODE	I <sub>DD</sub>
Н	Х	Χ	Χ	Х	Hi–Z	Hi–Z	Standby	I <sub>DDS</sub> , I <sub>DDS1</sub>
L	L	I	Χ	L	Input data	Hi–Z	Write (Lower byte)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	Н	L	Χ	L	Hi–Z	Input data	Write (Upper byte)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	L	L	Χ	L	Input data	Input data	Write (All data)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	L	H	L	Н	Output data	Hi–Z	Read (Lower byte)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	Η	L	١	Ι	Hi–Z	Output data	Read (Upper byte)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	L	┙	L	Ι	Output data	Output data	Read (All data)	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	Ĺ	Ĺ	Н	Η	Hi–Z	Hi–Z	Output disable	I <sub>DDA</sub> , I <sub>DDA1</sub>
L	H	Ι	Χ	Χ	Hi-Z	Hi–Z	Output disable	I <sub>DDA</sub> , I <sub>DDA1</sub>

X : High or Low

#### Reading data

It is possible to control the data width by  $\overline{LB}/\overline{UB}$ .

(1) Reading data from lower

Data is able to be read when the address is set while holding  $\overline{CS}$  = "Low",  $\overline{OE}$  = "Low",  $\overline{LB}$  = "Low" and  $\overline{WE}$  = "High".

(2) Reading data from upper byte

Data is able to be read when the address is set while holding  $\overline{CS}$  = "Low",  $\overline{OE}$  = "Low",  $\overline{UB}$  = "Low" and  $\overline{WE}$  = "High".

(3) Reading all data

Data is able to be read when the address is set while holding  $\overline{CS}$  = "Low",  $\overline{OE}$  = "Low",  $\overline{UB}$  = "Low"  $\overline{LB}$  = "Low" and  $\overline{WE}$  = "High".

Since I/O pins are in "Hi-Z" state when  $\overline{OE}$  = "High", the data bus line can be used for any other objective, then access time apparently is able to be cut down.

#### Writing data

(1) Writing data into lower byte

There are the following three ways of writing data into the memory.

- i) Hold  $\overline{WE}$  = "Low" and  $\overline{LB}$  = "Low", set address and give "Low" pulse to  $\overline{CS}$ .
- ii) Hold  $\overline{CS}$  = "Low" and  $\overline{LB}$  = "Low", set address and give "Low" pulse to  $\overline{WE}$ .
- iii) Set address and give "Low" pulse to CS, WE and LB.

Anyway, data on I/O pins are latched up into the memory cell during  $\overline{CS}$ , WE, and  $\overline{LB}$  are "Low".

(2) Writing data into upper byte

There are the following three ways of writing data into the memory.

- i) Hold  $\overline{WE}$  = "Low" and  $\overline{UB}$  = "Low", set address and give "Low" pulse to  $\overline{CS}$ .
- ii) Hold  $\overline{CS}$  = "Low" and  $\overline{UB}$  = "Low", set address and give "Low" pulse to  $\overline{WE}$ .
- iii) Set address and give "Low" pulse to  $\overline{CS}$ ,  $\overline{WE}$  and  $\overline{UB}$ .

Anyway, data on I/O pins are latched up into the memory cell during  $\overline{CS}$ , WE, and  $\overline{UB}$  are "Low".

(3) Writing all data

There are the following three ways of writing data into the memory.

i) Hold  $\overline{WE}$  = "Low",  $\overline{LB}$  = "Low" and  $\overline{UB}$  = "Low", set address and give "Low" pulse to  $\overline{CS}$ .

- ii) Hold  $\overline{\text{CS}}$  = "Low",  $\overline{\text{LB}}$  = "Low" and  $\overline{\text{UB}}$  = "Low", set address and give "Low" pulse to  $\overline{\text{WE}}$ .
- iii) Set address and give "Low" pulse to  $\overline{CS}$ ,  $\overline{WE}$ ,  $\overline{LB}$  and  $\overline{UB}$ .

Anyway, data on I/O pins are latched up into the memory cell during  $\overline{CS}$ ,  $\overline{WE}$ ,  $\overline{LB}$  and  $\overline{UB}$  are "Low". As data I/O pins are in "Hi-Z" when any of  $\overline{CS}$  or  $\overline{OE}$  is "High" level, the contention on the data bus can be avoided. But during I/O pins are in the output state, the data that is opposite to the output data should not be given.

#### Standby mode

When  $\overline{CS}$  is "High" level, the chip is in the standby mode which has retaining data operation. In this case data I/O pins are Hi-Z, and all inputs of addresses,  $\overline{WE}$ ,  $\overline{OE}$  and all input data are inhibited. When  $\overline{CS}$  level are in the range over VDD-0.2V, there is almost no current flow except through the high resistance parts of the memory.

#### Data retention at low voltage

In case of the data retention in the standby mode, the power supply can be gone down till the specified voltage. But it is impossible to write or read in this mode.

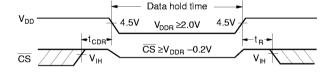
#### ■ DATA RETENTION CHARACTERISTIC WITH LOW VOLTAGE POWER SUPPLY

 $(V_{SS} = 0V, Ta = -40 \text{ to } 85^{\circ}C)$ 

Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
Data retention supply voltage	$V_{DDR}$		2.0	_	5.5	V
Data retention current	I <sub>DDR</sub>	$V_{DD} = 3V$ $\overline{CS} \ge V_{DD} - 0.2V$	_	1*	100	μА
Chip select • data hold time	t <sub>CDR</sub>		0	_	_	ns
Operation recovery time	t <sub>R</sub>		5	_	_	ms

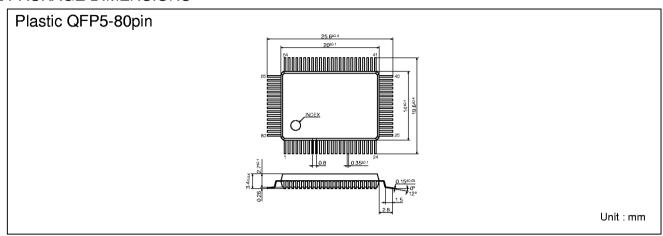
<sup>\*</sup> Ta = 25°C

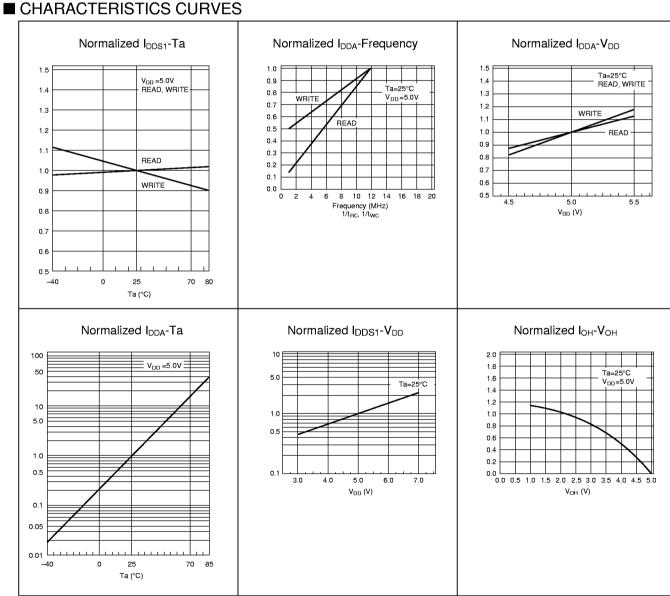
#### Data retention timing (CS Control)



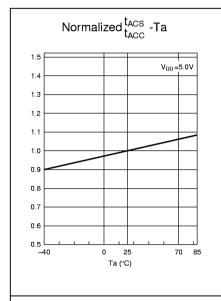
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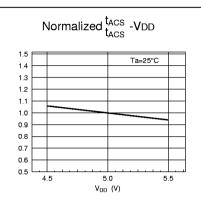
#### ■ PACKAGE DIMENSIONS

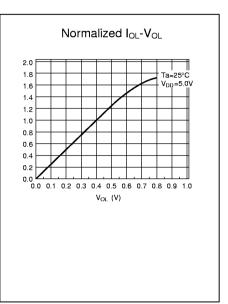


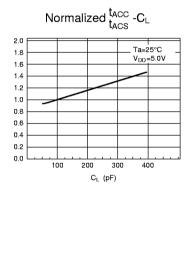


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