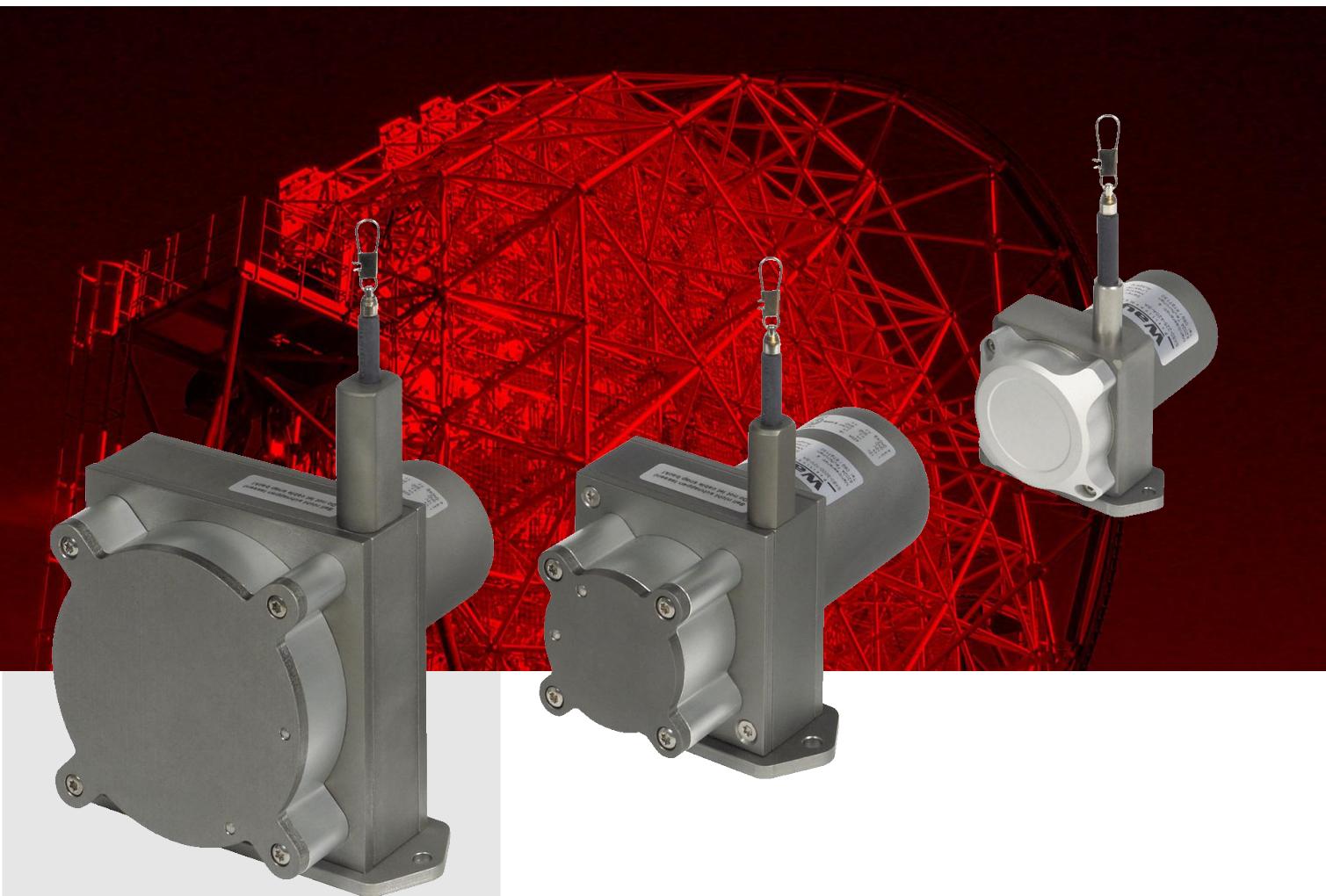


# DRAWWIRE SENSOR



## SX120 / SX80 / SX50

### Key-Features:

- Ranges 50...6000 mm
- Analogue - Digital - Absolute - Bus
- Linearity up to 0,02 %
- Protection class up to IP67
- High dynamics
- Off-shore sensors
- High EMC-grade
- Customised versions available

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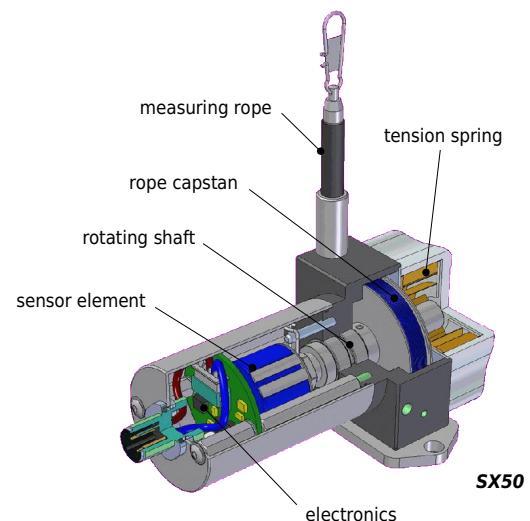
14.06.10

## INTRODUCTION

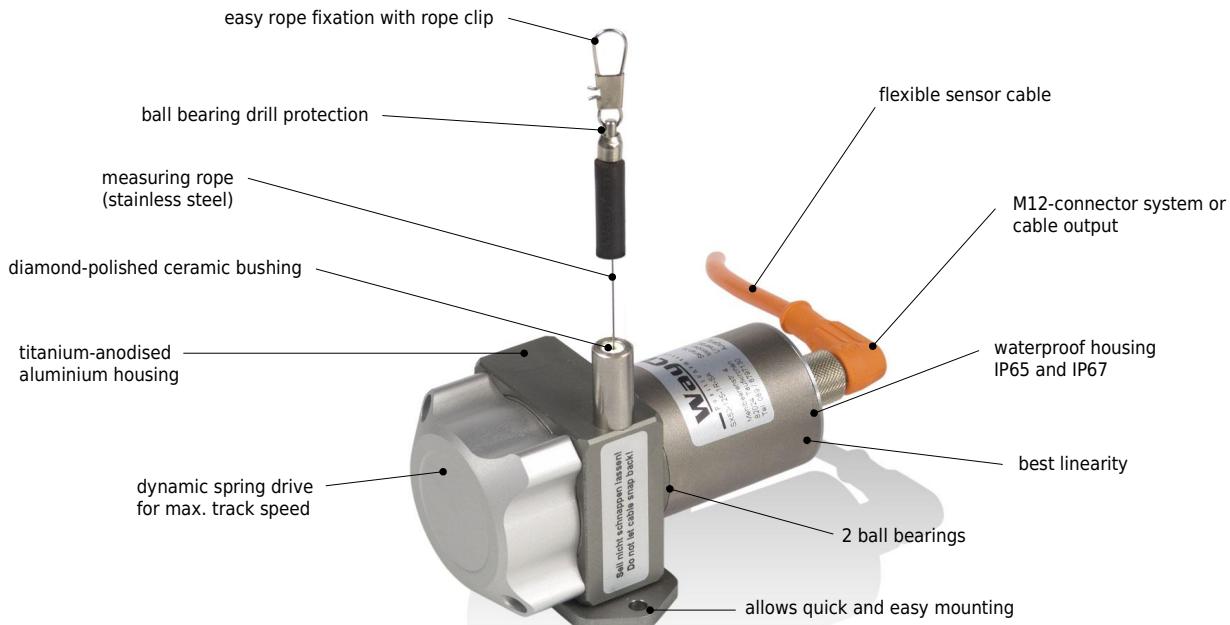
WayCon Positionsmesstechnik GmbH is a manufacturer of high quality draw wire position transducers for industrial use. Due to its small overall size, its short assembly time and its possible customisation, the SX sensor technology is a cost-effective and flexible solution for a wide range of industrial applications. The dynamics of the draw wire transducer allows a high motion speed and acceleration of the measuring target. Its rugged design and high quality makes applications in harsh industrial environments possible. Sensors specifically designed for off-shore use receive a HARTCOAT surface, which makes them resistant to e. g. sea water. Special instruments are available with mounting service of encoder on site, as well as customised versions of housing.

### Sensor principle:

A constant spring force coils the measuring rope accurately, single-layered on an ultralight rope capstan, so that its linear motion is converted into rotation. The sensor element (encoder) provides the output signal required.



## OUTLINE



## APPLICATIONS

- lifting tables and platforms
- suspension of vehicles
- positioning of fork-lifts
- level control system
- portal frames and gantry cranes
- medical technology
- lifting and rescue technology
- x-y-axis positioning
- pneumatic cylinder
- hydraulic cylinder and press slit
- injection moulding machine
- crash-tests
- air frame load testing
- auto body/ carriage deformation
- robot application
- property management
- linear guides
- pipe displacement

## OPTIONS

### HG

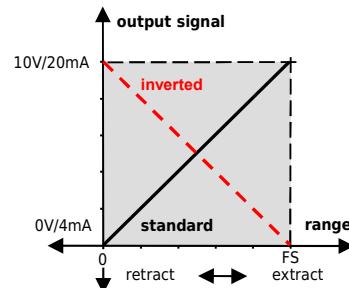
A reinforced spring drive provides a greater rope tension and allows a higher rope acceleration. Please note the different dimensions of the housing and the higher traction of the rope. This option is only available for the series SX50.

### CO

By the use of a special technology all components of the housing and the inner mechanics become HARTCOAT® coated. This coating is a hartanodic oxidation that protects the sensor from corrosion by aggressive media (e. g. sea water) with a hard ceramics-like layer. The sensor can thus be used off-shore.

### IN

The analogue signal of the sensor is increasing by extracting the rope (standard). Option IN inverts the signal, i. e. the signal of the sensor declines by extracting the rope.



### L25 / L10 / L05 / L02

Improved linearity on 0,25 %, 0,10 % or 0,05 % of measuring range. Resolution, repeatability and sensibility remain unchanged.

L02: Improved linearity on 0,02 % of measuring range. Resolution, repeatability and sensibility remain unchanged. This option is only available for incremental sensors.

### IP67

Use option IP67, if sensor is fully immersed in water (temporarily). Note that with this option there may occur a light hysteresis in the output signal due to the special sealing. The max. acceleration is reduced to 60 % of the specified value.

### S1 / S2 / S3

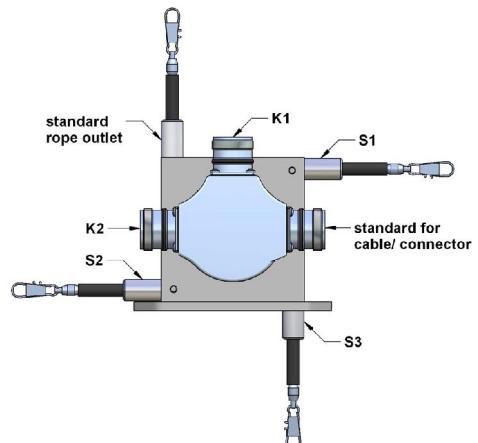
Optional rope outlet (see diagram)

S1 rope outlet on up

S2 rope outlet on down

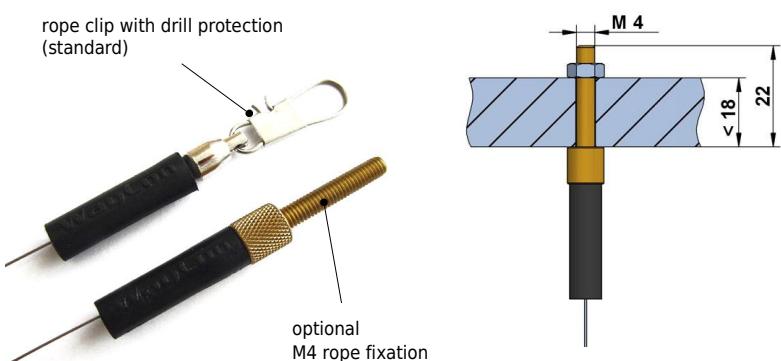
S3 rope outlet at bottom

(S2/ S3 with different mounting plate)



### K1 / K2

Optional cable/ connector orientation for sensors with digital output/ encoder (see diagram)



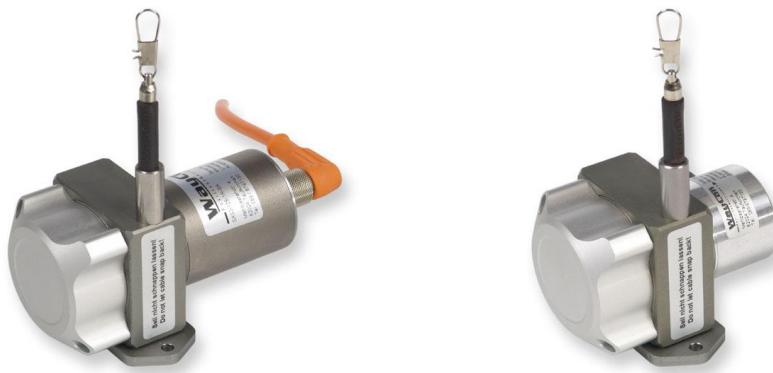
### M4 rope fixation

Optional rope fixation with screw thread M4.

Ideal for attachment to through holes or thread holes M4.

## SERIES SX50

**max. 1250 mm  
analogue/ digital  
digital-absolute  
bus systems**



output	analogue	digital output / digital-absolute / bus systems
	potentiometer/ 0...10 V/ 4...20 mA (page 10)	A/B-pulse, 90° phase-delayed (page 11-12)
sensor element	hybrid potentiometer	incremental encoder/ optical code disc
connection	M12-connector or cable output	connector or cable output
protection class	IP65, optional IP67	IP65, optional IP67
humidity	max. 90 % relative, not condensating	max. 90 % relative, not condensating
life time	approx. 2 million full cycles	approx. 2 million full cycles
weight	approx. 330 g	approx. 330 g
housing	aluminium, titanium-grey anodised	aluminium, titanium-grey anodised

### Technical data - analogue output

measurement range [mm] *	50	75	100	125	150	225	250	300	375	500	625	750	1000	1250
linearity [%]	0,50	0,50	0,50	0,50	0,15	0,15	0,15	0,15	0,15	0,15	0,15	0,10	0,10	0,10
linearity optional [%]	0,25	0,25	0,25	0,25	0,10	0,10	0,10	0,10	0,10	0,10	0,10	0,05	0,05	0,05
linearity optional [%]	0,10**	0,10**	0,10**	0,10**	-	-	-	-	-	-	-	-	-	-

### Technical data - digital output

measurement range [mm] *	500	750	1250
linearity [%]	0,05, independent from measurement range		
linearity optional [%]	0,02, independent from measurement range		
available resolution [pulses/ mm]	1	4	8
Z-pulse-distance [mm]	125		

\* other measurement ranges on request

\*\* special version with unprotected potentiometer, protection class IP40 (please ask for technical drawing)

\*\*\* special version (please ask for technical drawing)

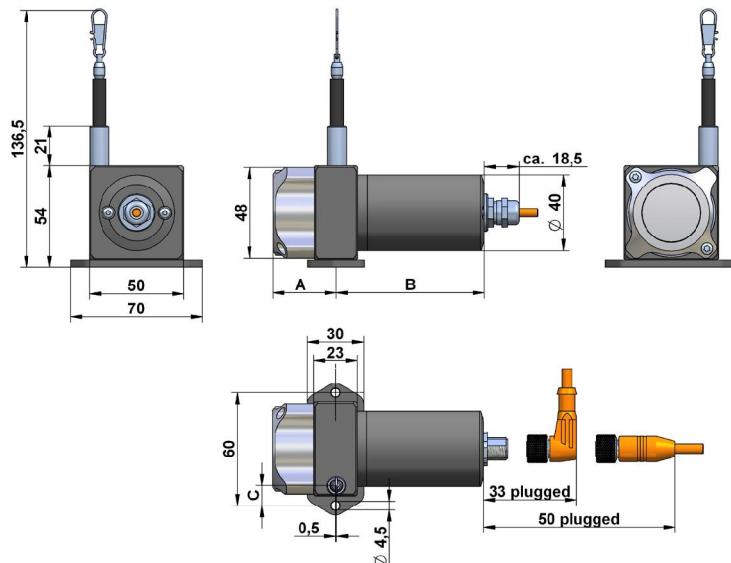
### Mechanical data

range [mm]	rope tension		velocity $V_{\max}$ [m/s]	acceleration* $a_{\max}$ [m/s <sup>2</sup> ]	rope tension HG		acceleration HG* $a_{\max}$ [m/s <sup>2</sup> ]
	$F_{\min}$ [N]	$F_{\max}$ [N]			$F_{\min}$ [N]	$F_{\max}$ [N]	
50	6,8	6,8	5,6	480	13,2	13,7	660
75	3,9	4,4	5,6	480	7,3	7,9	900
100	3,4	3,4	5,0	360	5,9	6,4	660
125	4,9	5,4	6,3	600	6,9	7,9	900
150	6,8	7,9	5,6	480	13,2	13,7	660
225	3,9	4,6	5,6	480	7,3	8,3	900
250	6,8	7,9	5,6	480	13,2	13,7	660
300	3,2	4,0	5,0	360	5,9	6,7	660
375	4,7	5,4	6,3	600	6,9	7,9	900
500	3,4	4,0	5,0	360	5,9	6,9	660
625	4,4	5,4	6,3	600	6,9	7,9	900
750	3,9	5,4	5,6	480	7,3	9,8	900
1000	3,1	4,0	5,0	360	5,9	7,9	660
1250	4,1	5,4	6,3	600	6,9	8,3	900

\* reduced to 60 % with option IP67

## TECHNICAL DRAWING SX50

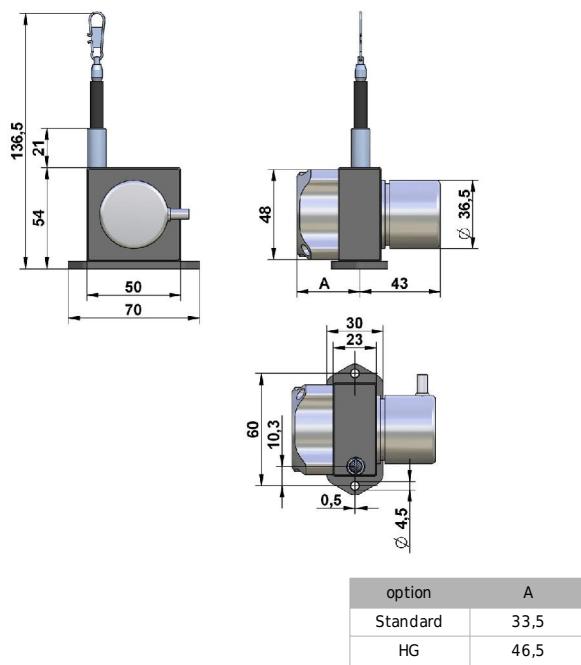
### analogue output



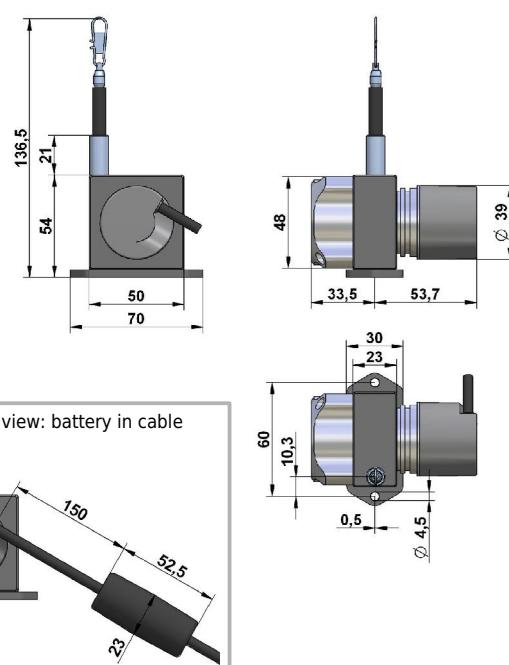
	output	B
	potentiometer	65
	10V / 420A	78,5

range	option	A	C
50 / 150 / 250 mm	Standard	26,5	21,3
75 / 225 / 750 mm	Standard	26,5	17
100 / 300 / 500 / 1000 mm	Standard	26,5	12,75
125 / 375 / 625 / 1250 mm	Standard	33,5	10,3
50 / 150 / 250 mm	HG	33,5	21,3
75 / 225 / 750 mm	HG	33,5	17
100 / 300 / 500 / 1000 mm	HG	33,5	12,75
125 / 375 / 625 / 1250 mm	HG	46,5	10,3

### digital output incremental



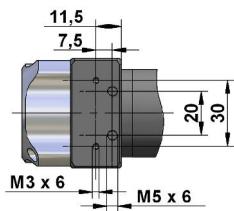
### digital-absolute: SSI, CAN



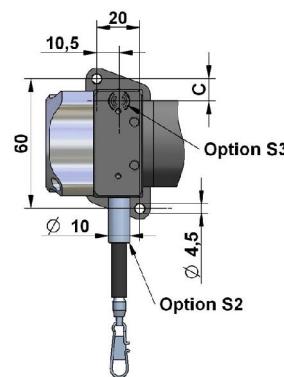
### mounting

The sensor can be installed by using the mounting plate (see drawing above).

By disassembling the mounting plate, there are 4 threads (2 x M3, 2 x M5) in the sensor housing for installing.



Sensors with option rope outlet S2 and S3 have a different base plate.



## SERIES SX80

**max. 3000 mm  
analogue/ digital  
digital-absolute  
bus systems**



output	analogue	digital output / digital-absolute / bus systems
	potentiometer/ 0...10 V/ 4...20 mA (page 10)	A/B-pulse, 90° phase-delayed (page 11-12)
sensor element	hybrid potentiometer	incremental encoder/ optical code disc
connection	M12-connector or cable output	connector or cable output
protection class	IP65, optional IP67	IP65, optional IP67
humidity	max. 90 % relative, not condensating	max. 90 % relative, not condensating
life time	approx. 2 million full cycles	approx. 2 million full cycles
weight	approx. 750 g	approx. 750 g
housing	aluminium, titanium-grey anodised	aluminium, titanium-grey anodised

### Technical data - analogue output

measurement range [mm] *	1000	1500	2000	2500	3000
linearity [%]	0,15	0,15	0,10	0,10	0,10
linearity optional [%]	0,10	0,10	0,05	0,05	0,05

### Technical data - digital output

measurement range [mm] *	1000	1500	2000	2500	3000
linearity [%]	0,05, independent from measurement range				
linearity optional [%]	0,02, independent from measurement range				
available resolution [pulses/ mm]	0,5	1	2,5	5	10
Z-pulse-distance [mm]	200				

\* other measurement ranges on request

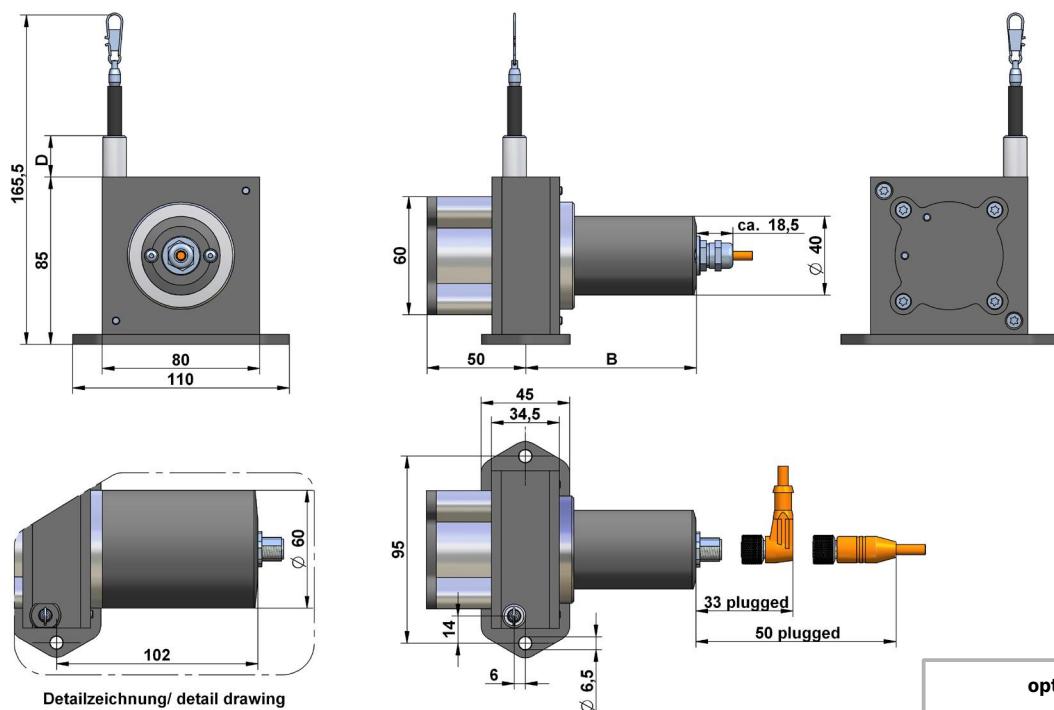
### Mechanical data

range [mm]	rope tension		velocity $V_{\max}$ [m/s]	acceleration* $a_{\max}$ [m/s <sup>2</sup> ]
	F <sub>min</sub> [N]	F <sub>max</sub> [N]		
1000	5,4	6,6	10	140
1500	5,4	7,1	10	140
2000	5,4	7,8	10	140
2500	5,4	8,5	10	140
3000	5,4	9,1	10	140

\* reduced to 60 % with option IP67

## TECHNICAL DRAWING SX80

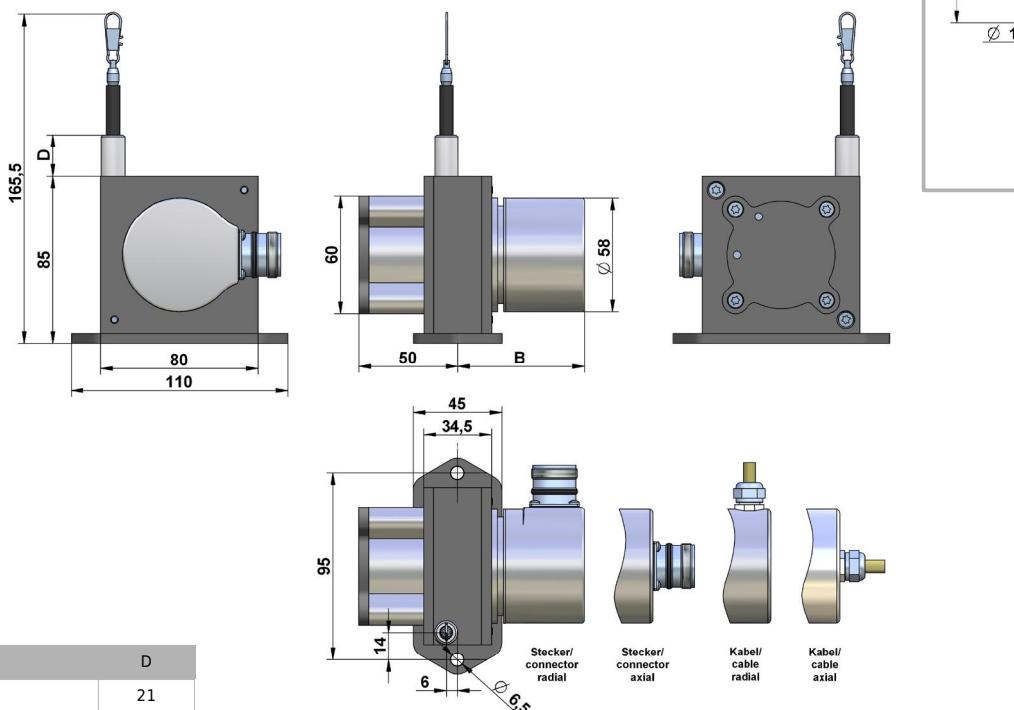
### analogue output



Detailzeichnung/ detail drawing

range	output	B	D
1000/ 2000 mm	potentiometer	74	21
1000/ 2000 mm	10V / 420A	87,5	21
1500/ 2500/ 3000 mm, see detailed view		35	

### digital output

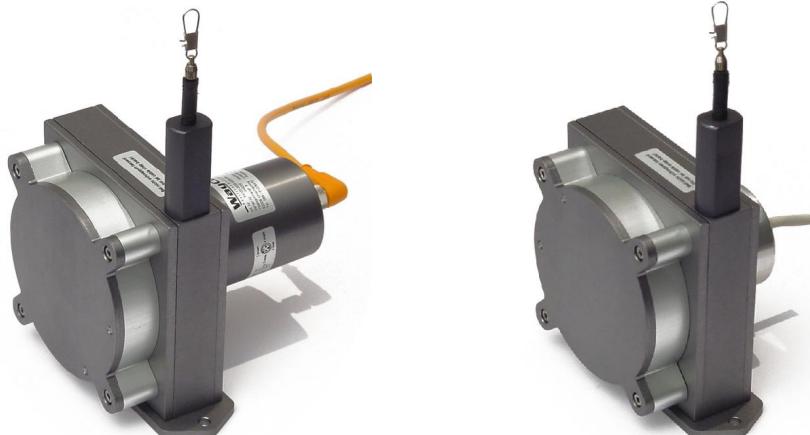


range	D
1000/ 2000 mm	21
1500/ 2500/ 3000 mm	35

option	B
cable/ connector axial, cable radial	54,3
connector radial	64,3

## SERIES SX120

**max. 6000 mm  
analogue/ digital  
digital-absolute  
bus systems**



output	analogue	digital output / digital-absolute / bus systems
	potentiometer/ 0...10 V/ 4...20 mA (page 10)	A/B-pulse, 90° phase-delayed (page 11-12)
sensor element	hybrid potentiometer	incremental encoder/ optical code disc
connection	M12-connector or cable output	connector or cable output
protection class	IP65, optional IP67	IP65, optional IP67
humidity	max. 90 % relative, not condensating	max. 90 % relative, not condensating
weight	approx. 1625 g	approx. 1625 g
housing	aluminium, titanium-grey anodised	aluminium, titanium-grey anodised

### Technical data - analogue output

measurement range [mm] \* 3125 4000 5000 6000

linearity [%] 0,10 0,10 0,10 0,10

linearity optional [%] 0,05 0,05 0,05 0,05

### Technical data - digital output

measurement range [mm] \* 3125 4000 5000 6000

linearity [%] 0,05, independent from measurement range

linearity optional [%] 0,02, independent from measurement range

available resolution [pulses/ mm] 0,3 1,6 3,1 6,3 16

Z-pulse-distance [mm] 317,68

\* other measurement ranges on request

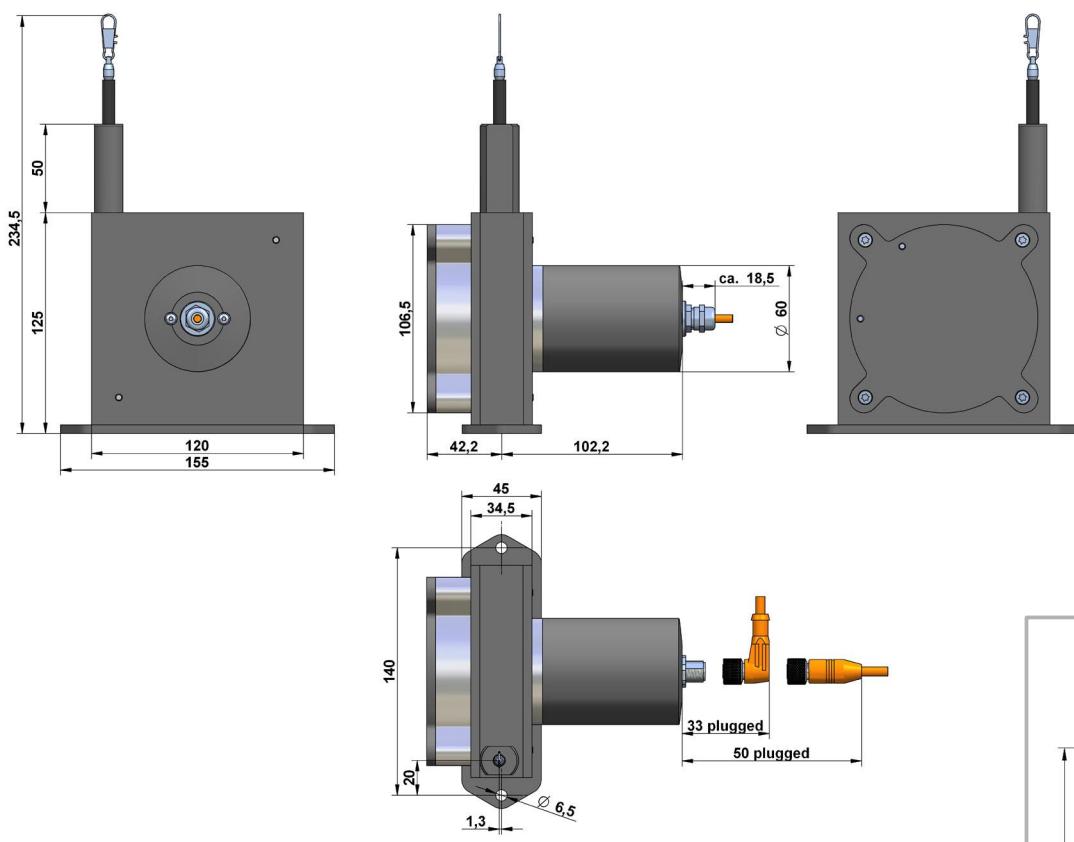
### Mechanical data

range [mm]	rope tension		velocity $V_{\max}$ [m/s]	acceleration* $a_{\max}$ [m/s <sup>2</sup> ]
	$F_{\min}$ [N]	$F_{\max}$ [N]		
3125	7,8	16,2	10	140
4000	7,8	18,5	10	140
5000	7,8	20,0	10	140
6000	7,8	21,0	10	140

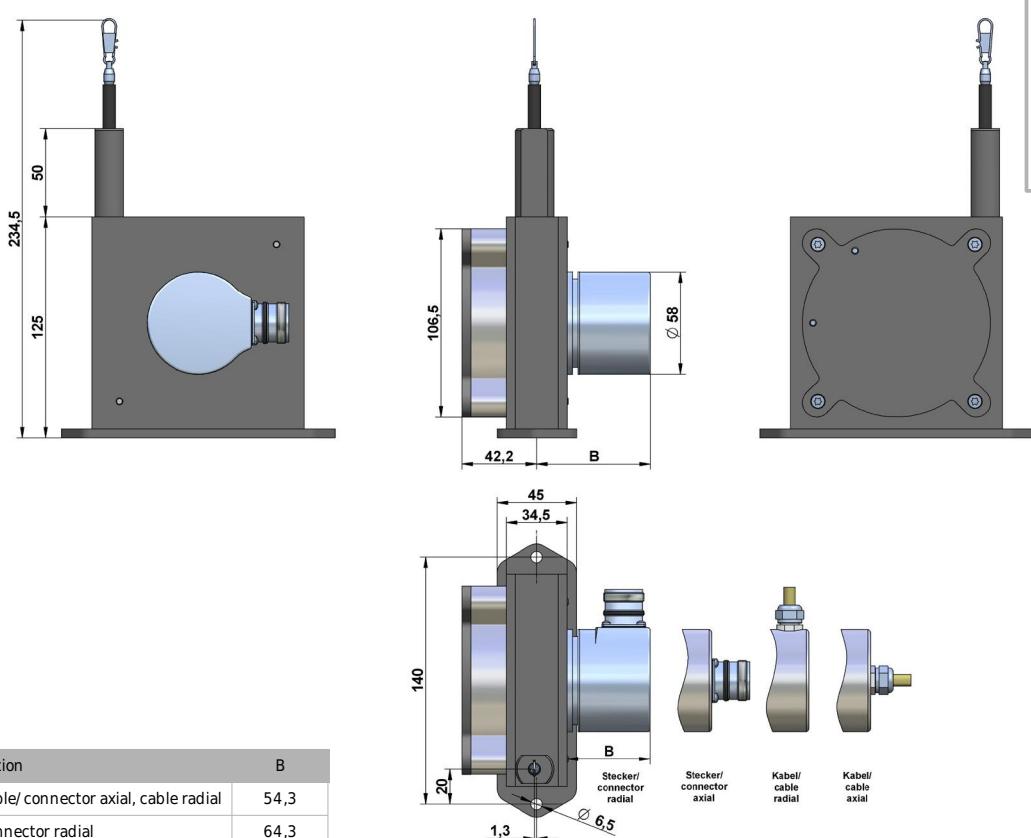
\* reduced to 60 % with option IP67

## TECHNICAL DRAWING SX120

### analogue output



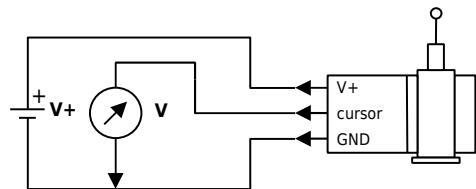
### digital output



## ANALOGUE OUTPUT

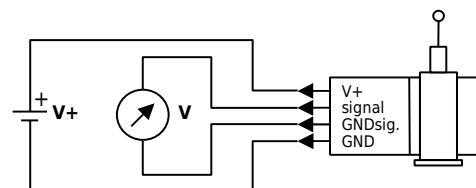
### Potentiometer (voltage divider)

output	1 kOhm
supply voltage	max. 30 V
recommended cursor current	< 1 µA
noise	depending on supply
working temperature	-20...+85 °C
temperature coefficient	± 0,0025 %/K



### 0...10 V voltage output

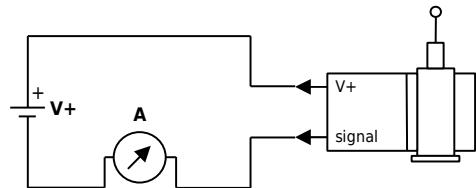
output	0...10 V, galvanically isolated, 4 conductors
supply voltage	12...30 VDC
max. current consumption	22,5 mA (unloaded)
output current	max. 10 mA, min. load 1 kOhm
dynamics	< 3 ms from 0...100 % and 100...0 %
noise	3 mV <sub>pp</sub> typically, max. 37 mV <sub>pp</sub>
inverse-polarity protection	yes, infinite
short-circuit proof	yes, permanent
working temperature	-20...+85 °C
temperature coefficient	0,0037 %/K
electromagnetic compatibility (EMC)	according to EN 61326-1:2006



note: GNDsignal and GND may be connected in 3-wire system.

### 4...20 mA current output

output	4...20 mA, 2 conductors
voltage supply	12...30 VDC
output current	max. 50 mA in case of error
dynamics	< 1 ms from 0...100 % and 100...0 %
noise	0,03 mA <sub>pp</sub> = 6 mV <sub>pp</sub> at 200 Ohm
inverse-polarity protection	yes, infinite
working temperature	-20...+85 °C
temperature coefficient	0,0079 %/K
electromagnetic compatibility (EMC)	according to EN 61326-1:2006



## CONNECTION

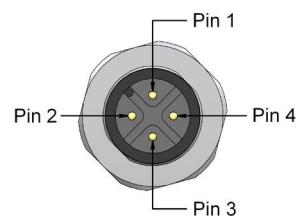
### cable output:

axial 2,0 metre standard, other cable length optional  
 type: TPE, flexible  
 diameter: ø 4,5 mm  
 stranded wire: 0,25 mm<sup>2</sup>  
 temperature range: fixed installation -30...+85 °C, flexible installation -20...+85 °C

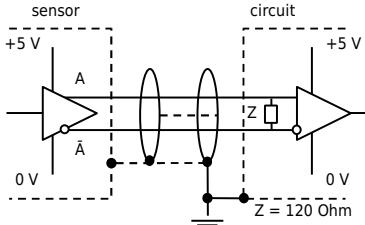
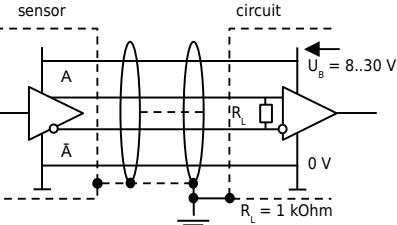
pin	wire colour	10 V	420 mA	1 kOhm
1	brown	V +	V +	V +
2	white	signal	n. c.	cursor
3	blue	GND	signal	GND
4	black	GND signal	n. c.	n. c.

### 4-pin M12 connector output (socket):

profile/ view on solder side of mating connector



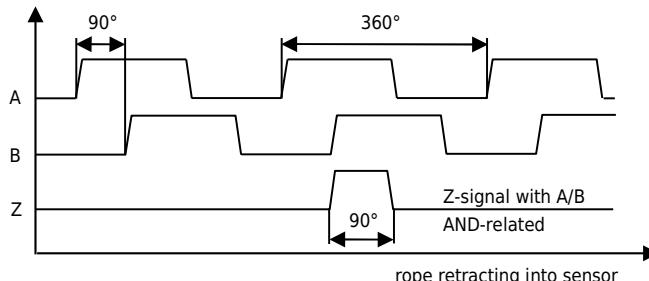
## DIGITAL OUTPUT INCREMENTAL

Electrical data	Linedriver L RS422 (TTL-compatible)	Push Pull G
supply voltage	5 VDC, $\pm 5\%$	8...30 VDC
current consumption (no load)	typical 70 mA, max. 100 mA	typical 80 mA, max. 150 mA
max. load/ channel SX50	$\pm 10$ mA	$\pm 30$ mA
max. load/ channel SX80/ 120	$\pm 20$ mA	$\pm 30$ mA
max. pulse frequency SX50	125 kHz	100 kHz
max. pulse frequency SX80/ 120	300 kHz	300 kHz
min. signal level high	2,5 V	$U_B - 3$ V
max. signal level low	0,5 V	2,5 V
recommended circuit		
connection	connector 12-pin (counterclockwise), cable output 1,5 m	connector 12-pin (counterclockwise), cable output 1,5 m
protection class	IP65, optional IP67	IP65, optional IP67
max. cable length	up to 1000 m	up to 250 m

### output signal

Pulses A and B are 90° phase-delayed (detection of direction). The Z-signal recurs with pulse distance Z and may be used as point of reference.

Diagramm shows the signal without inverted signals; timeline for return of rope.



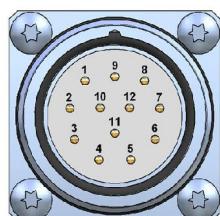
## CONNECTION

Assignment												
signal	0 V	$U_B +$	$0 V_{sens}^*$	$U_{Bsens}^+ *$	A	A -	B	B -	Z	Z -	screen	
12-pin connector	10	12	11	2	5	6	8	1	3	4	housing	
wire colours	white	brown	black	violet	green	yellow	grey	pink	blue	red	housing	

\* For Linedriver L only. For long cable lengths it may occur that the operating voltage at the sensor does not suffice due to the output resistance. With the sensor lines  $0V_{sens}$  and  $+UB_{sens}$  the operating voltage can be checked and, if necessary, be readjusted at the input connection.

### 12-pin connector output (socket)

Profile/ view on solder side of mating connector (only SX80/ SX120)



### cable output

radial/ axial 1,5 metre standard

other cable length optional

type: UL2464/ 1061, LIYY, flexible

outer diameter:  $\varnothing 6,5$  mm

stranded wire:  $0,25$  mm $^2$

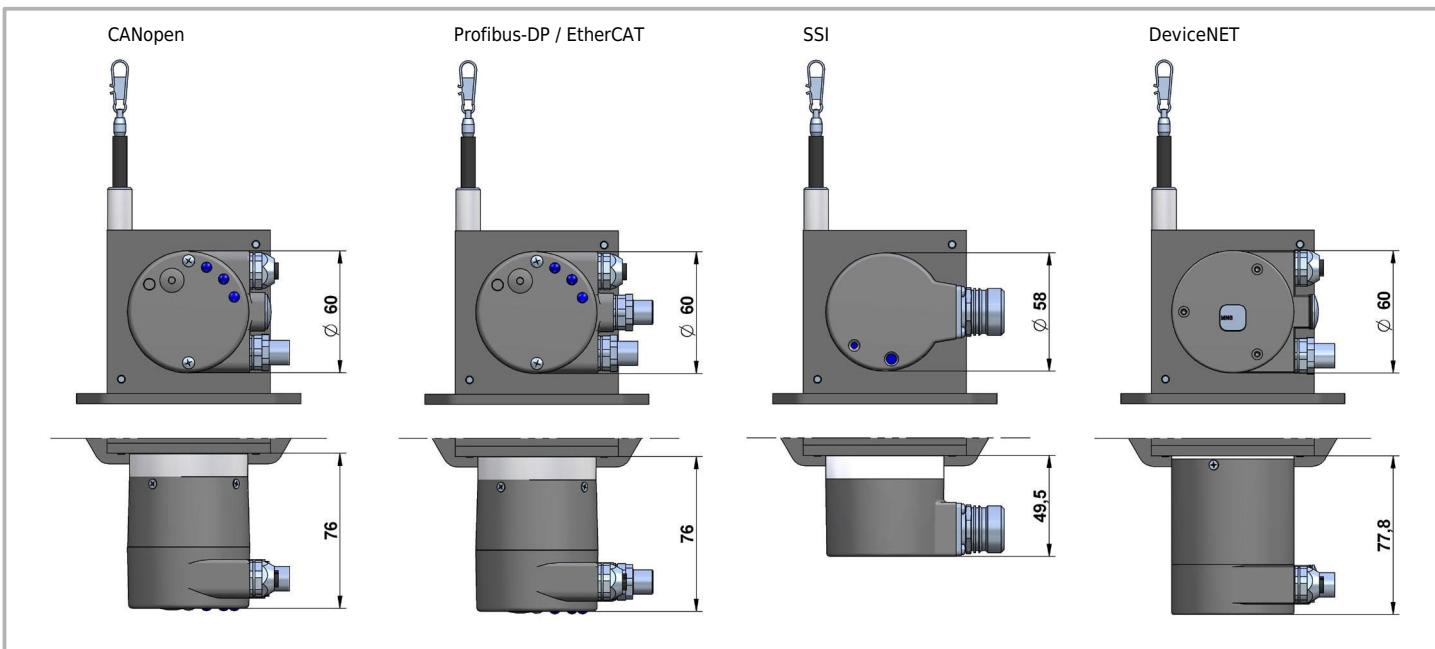
temperature range: fixed installation -30...+80 °C,  
flexible installation -20...+80 °C

## DIGITAL-ABSOLUTE / BUS SYSTEMS

output	Profibus-DP	CANopen	DeviceNet	EtherCAT	SSI
available for series	SX80/ 120	SX50/ 80/ 120	SX80/ 120	SX80/ 120	SX50/ 80/ 120
scalable resolution	yes	yes	yes	yes	no
standard resolution SX50 [pulses/ mm]	-	65,54	-	-	32,77
max. resolution SX50 [pulses/ mm]	-	524,29	-	-	-
standard resolution SX80 [pulses/ mm]	40,96	40,96	20,48	40,96	40,96
max. resolution SX80 [pulses/ mm]	327,68	327,68	20,48	327,68	-
standard resolution SX120 [pulses/ mm]	25,79	25,79	12,89	25,79	25,79
max. resolution SX120 [pulses/ mm]	206,3	206,3	12,89	206,3	-
supply voltage	10...30 VDC	10...30 VDC	10...30 VDC	10...30 VDC	10...30 VDC
current consumption (no load, at 24 VDC)	90 mA	65 mA	max. 290 mA	90 mA	25 mA
protection class	IP65	IP65	IP65	IP65	IP65
protection class optional	IP67	IP67	-	IP67	IP67
working temperature	-20...+80 °C	-20...+80 °C	-20...+80 °C	-20...+80 °C	-20...+80 °C

Other encoder types (supply voltage, resolution, cable/ connector output) are available on request.

## TECHNICAL DRAWING (ADDITION)



## CONNECTION

<b>encoder type</b>	(other connection variants and protocols on request)
Profibus-DP	bus terminal cover, 3 x M12-connector (2 x male, 1 x female)
CANopen	removable bus terminal cover, 2 x M12-connector (1 x male, 1 x female)
DeviceNET	bus terminal cover, 2 x M12-connector (1 x male, 1 x female)
EtherCAT	bus terminal cover, 3 x M12-connector (1 x male, 2 x female)
SSI	12-pin M23-connector (pins counterclockwise), mating connector CON012-S

Please see encoder manual for detailed connection.

## ACCESSORIES

### Cable with mating connector M12 straight and angular - K4P (for analogue output potentiometer/ 10V/ 420A)

cable with straight connector:  
K4P2M-S-M12 2 m  
K4P5M-S-M12 5 m  
K4P10M-S-M12 10 m

cable with angular connector:  
K4P2M-SW-M12 2 m  
K4P5M-SW-M12 5 m  
K4P10M-SW-M12 10 m



### Mating connector M12 straight and angular for analogue output (field attachable connector)

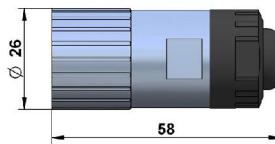
straight connector: D4-G-M12-S  
angular connector: D4-W-M12-S

protection class: IP67  
temperature range: -25...+90 °C  
mode of connection: screw terminals



### Mating connector M23 for digital output and SSI - CON012-S

M23, straight, female connector, 12-pin clockwise  
(fits to male, counterclockwise connector)  
metal housing

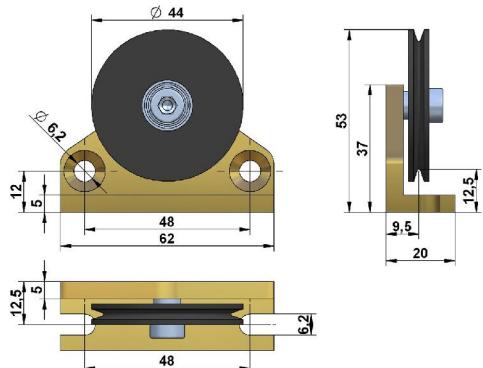
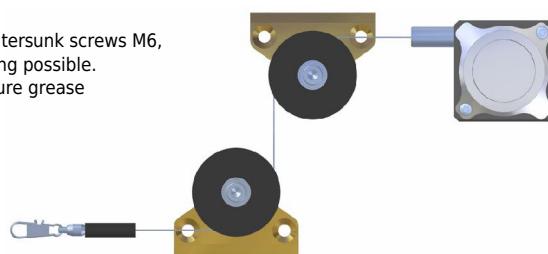


### Deflection pulley - UR2

By using the deflection pulley, the rope can be looped around to e. g. measure in places that are difficult to access or to protect the sensor from inclined traction on the rope.  
Several pulleys may be used.

material: anodised aluminium, POM  
mounting: by 2 hexagon socket or countersunk screws M6,  
vertical or horizontal mounting possible.  
Ball bearings with special low temperature grease  
and RS-sealing.

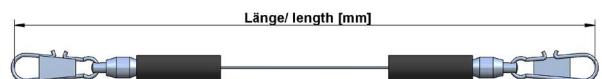
Temperature range: -40...+80 °C.



### Rope extension - SV

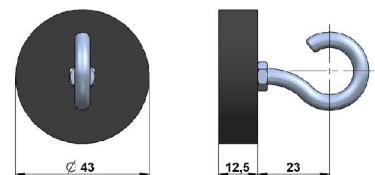
For bridging a greater distance from the measuring target to the sensor a rope extension can be applied. The rope clip must not be guided over the deflection pulley.

Please specify the length needed in your order.  
(example: rope extension of 250 mm = SV-250)



### Magnetic clamp - MGG1

Use the magnetic clamp to quickly attach the rope to metallic objects without any assembly time. A rubber coating provides gentle contact (e. g. on varnished surfaces) and prevents from slipping due to vibration.  
The magnet consists of a neodym core for an increased adhesive force of 260 N. The hook makes it easy to attach the rope clip (drill protection).



### Digital distance and speed measurement - PAX

Use PAX display to visualise the covered distance or the speed (tacho sensor) of the position transducer. It enables a transmission of the measurement data to the computer via interface. The comparator allows a good-bad-evaluation (limit values function).

inputs: incremental/ analogue, 2 independent counter, 1 tacho sensor  
analogue output: (0)4...20 mA, 0...10 V (plug in card)  
serial interfaces: RS485, RS232, DeviceNet (plug in card)  
Protection class (front panel): IP65  
display: 6 digits  
power supply: 11...36 VDC or 85...250 VAC



For further information please ask for the data sheet of the PAX display series.

## INSTALLATION

- Mount the sensor at the designated place by using the fixing holes **before** extracting the rope and **before** attaching the rope to the measuring target.
- Open the rope clip (not with set screw M4) after the sensor is fully mounted and extract the measuring rope. Hook the rope clip on the measuring object and close the bracket of the clip. For your safety put a screw driver through the clip to extract the rope.
- Check the track of the measuring target on **collision** with the sensor housing and on **exceeding** the specified measurement range. When installing the sensor make sure that the rubber stopper does not touch the rope outlet.
- Connect the electronics according to the sensor type. When laying the cables be careful not to under-run the minimal allowed bending radius of the cable (5 x cable diameter).
- The rope must be extracted from the sensor **vertically**. The maximum variation from the vertical is 3°. Avoid carefully extracting the rope at an inclination, since the durability of the instrument would shorten considerably. If it is not possible to keep the limit of 3°, a deflection pulley has to be used.
- The measuring range/ the **zero point** begins after approximately 2 mm extracted rope. The mechanical reserve at the end of the measuring range is about 20 mm.
- When mounting outdoors protect the sensor and the rope from ice-formation at temperatures below 0 °C.
- Lay the rope preferably in corners or guarded in guidings to prevent pollution or accidental touch.
- When operating the sensor, take care **not** to let the rope **snap back** by mistake or extract the rope **over** the specified **measurement range**, as this might destroy the sensor.
- **Maintenance:** These instruments are maintenance-free. If however, the rope is soiled due to adverse environmental conditions, it should be cleaned with a cloth drenched in resin-free machine oil.

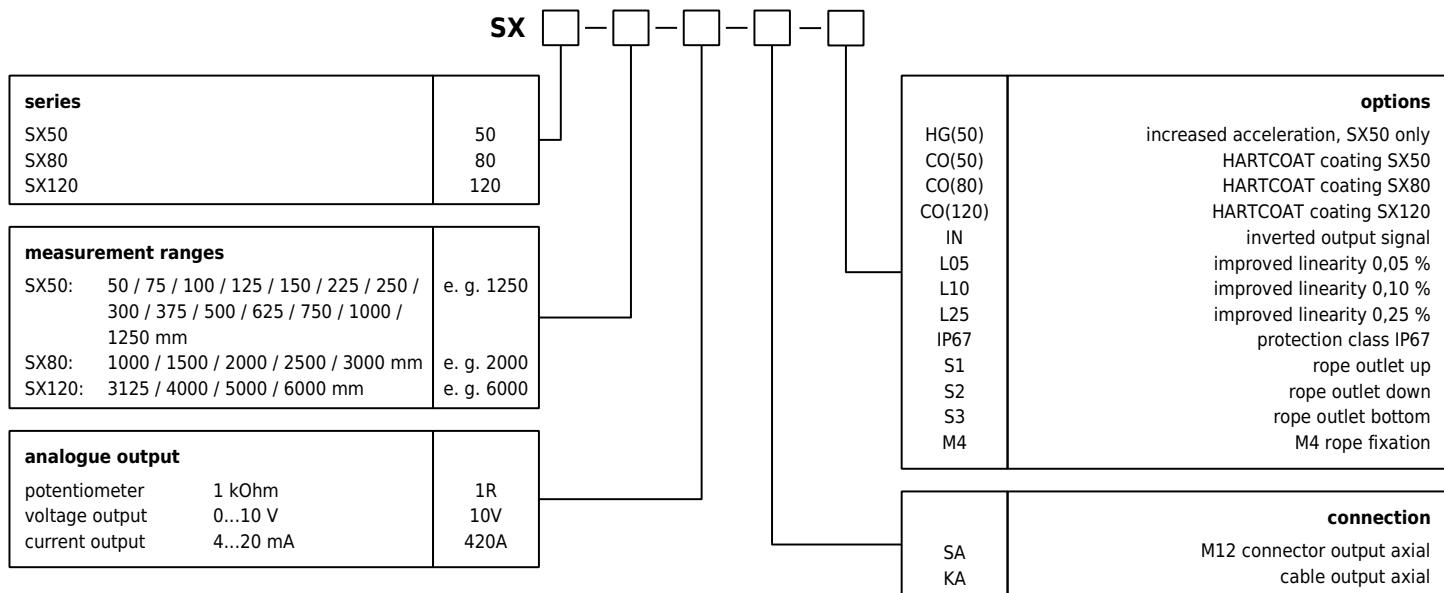


## WARNING NOTICES

- Don't let the rope snap back. If the rope is retracted freely, this may lead to injuries (whiplash effect) and the instrument may be damaged. Caution when unhooking and retracting the rope into the sensor.
- Never exceed the specified measurement range when extracting the rope!
- Don't try to open the instrument. The stored energy of the spring drive may lead to injuries when being mishandled.
- Don't touch the rope when operating the sensor.
- Avoid guiding the rope over edges or corners. Use a deflection pulley instead.
- Don't operate the sensor if the rope is buckled or damaged. A ripping of the rope may lead to injuries or damaging the sensor.



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