

# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

SLAS176B – DECEMBER 1997 – REVISED JULY 2002

- Four 10-Bit D/A Converters
- Programmable Settling Time of 3  $\mu$ s or 9  $\mu$ s Typ
- TMS320, (Q)SPI™, and Microwire™ Compatible Serial Interface
- Internal Power-On Reset
- Low Power Consumption:  
5.5 mW, Slow Mode – 5-V Supply  
3.3 mW, Slow Mode – 3-V Supply
- Reference Input Buffers
- Voltage Output Range . . . 2 $\times$  the Reference Input Voltage
- Monotonic Over Temperature
- Dual 2.7-V to 5.5-V Supply (Separate Digital and Analog Supplies)

- Hardware Power Down (10 nA)
- Software Power Down (10 nA)
- Simultaneous Update

### applications

- Battery Powered Test Instruments
- Digital Offset and Gain Adjustment
- Industrial Process Controls
- Machine and Motion Control Devices
- Communications
- Arbitrary Waveform Generation

### description

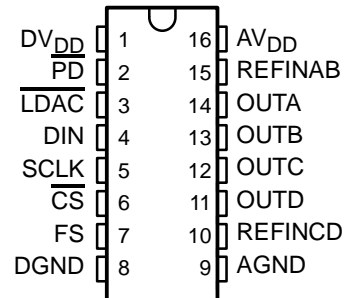
The TLV5604 is a quadruple 10-bit voltage output digital-to-analog converter (DAC) with a flexible 4-wire serial interface. The 4-wire serial interface allows glueless interface to TMS320, SPI, QSPI, and Microwire serial ports. The TLV5604 is programmed with a 16-bit serial word comprised of a DAC address, individual DAC control bits, and a 10-bit DAC value.

The device has provision for two supplies: one digital supply for the serial interface (via pins DV<sub>DD</sub> and DGND), and one for the DACs, reference buffers and output buffers (via pins AV<sub>DD</sub> and AGND). Each supply is independent of the other, and can be any value between 2.7 V and 5.5 V. The dual supplies allow a typical application where the DAC will be controlled via a microprocessor operating on a 3-V supply (also used on pins DV<sub>DD</sub> and DGND), with the DACs operating on a 5-V supply. Of course, the digital and analog supplies can be tied together.

The resistor string output voltage is buffered by a x2 gain rail-to-rail output buffer. The buffer features a Class AB output stage to improve stability and reduce settling time. A rail-to-rail output stage and a power-down mode makes it ideal for single voltage, battery based applications. The settling time of the DAC is programmable to allow the designer to optimize speed versus power dissipation. The settling time is chosen by the control bits within the 16-bit serial input string. A high-impedance buffer is integrated on the REFINAB and REFINCD terminals to reduce the need for a low source impedance drive to the terminal. REFINAB and REFINCD allow DACs A and B to have a different reference voltage than DACs C and D.

The device, implemented with a CMOS process, is available in 16-terminal SOIC and TSSOP packages. The TLV5604C is characterized for operation from 0°C to 70°C. The TLV5604I is characterized for operation from –40°C to 85°C.

D OR PW PACKAGE  
(TOP VIEW)



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# TLV5604

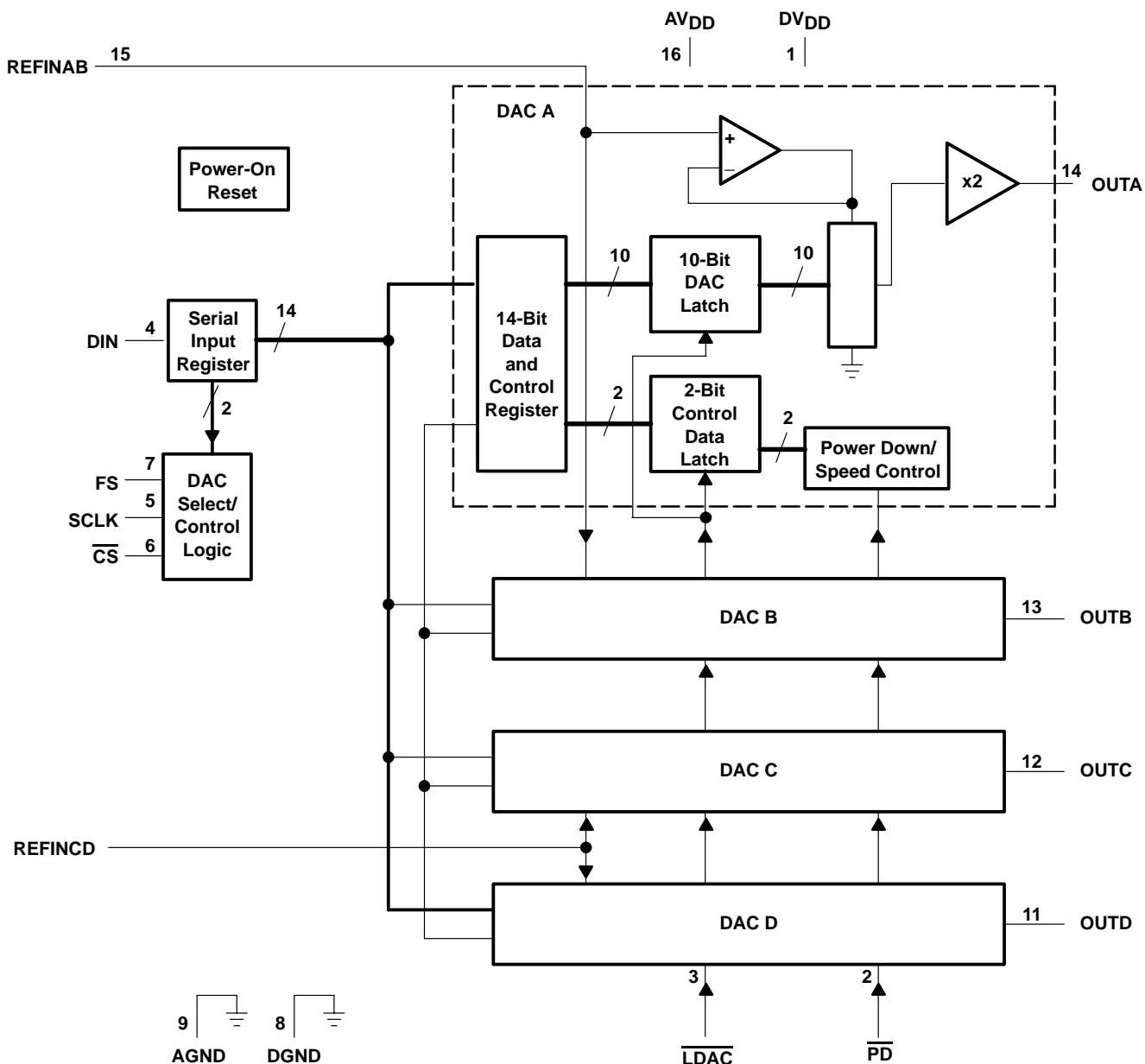
## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### AVAILABLE OPTIONS

T <sub>A</sub>	PACKAGE	
	SOIC (D)	TSSOP (PW)
0°C to 70°C	TLV5604CD	TLV5604CPW
–40°C to 85°C	TLV5604ID	TLV5604IPW

### functional block diagram



# TLV5604

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### Terminal Functions

TERMINAL NAME	NO.	I/O	DESCRIPTION
AGND	9		Analog ground
AV <sub>DD</sub>	16		Analog supply
$\overline{\text{CS}}$	6	I	Chip select. This terminal is active low.
DGND	8		Digital ground
DIN	4	I	Serial data input
DV <sub>DD</sub>	1		Digital supply
FS	7	I	Frame sync input. The falling edge of the frame sync pulse indicates the start of a serial data frame shifted out to the TLV5604.
$\overline{\text{PD}}$	2	I	Power-down pin. Powers down all DACs (overriding their individual power down settings), and all output stages. This terminal is active low.
$\overline{\text{LDAC}}$	3	I	Load DAC. When the $\overline{\text{LDAC}}$ signal is high, no DAC output updates occur when the input digital data is read into the serial interface. The DAC outputs are only updated when $\overline{\text{LDAC}}$ is low.
REFINAB	15	I	Voltage reference input for DACs A and B.
REFINCD	10	I	Voltage reference input for DACs C and D.
SCLK	5	I	Serial Clock input
OUTA	14	O	DAC A output
OUTB	13	O	DAC B output
OUTC	12	O	DAC C output
OUTD	11	O	DAC D output

### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)<sup>†</sup>

Supply voltage, (DV <sub>DD</sub> , AV <sub>DD</sub> to GND)	7 V
Supply voltage difference, (AV <sub>DD</sub> to DV <sub>DD</sub> )	–2.8 V to 2.8 V
Digital input voltage range	–0.3 V to DV <sub>DD</sub> + 0.3 V
Reference input voltage range	–0.3 V to AV <sub>DD</sub> + 0.3 V
Operating free-air temperature range, T <sub>A</sub> : TLV5604C	0°C to 70°C
TLV5604I	–40°C to 85°C
Storage temperature range, T <sub>stg</sub>	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

<sup>†</sup> Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.



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## recommended operating conditions

		MIN	NOM	MAX	UNIT
Supply voltage, $AV_{DD}$ , $DV_{DD}$	5-V supply	4.5	5	5.5	V
	3-V supply	2.7	3	3.3	
High-level digital input voltage, $V_{IH}$	$DV_{DD} = 2.7\text{ V}$	2			V
	$DV_{DD} = 5.5\text{ V}$	2.4			
Low-level digital input voltage, $V_{IL}$	$DV_{DD} = 2.7\text{ V}$			0.6	V
	$DV_{DD} = 5.5\text{ V}$			1	
Reference voltage, $V_{ref}$ to REFINAB, REFINCD terminal	5-V supply (see Note 1)	0	2.048	$AV_{DD}-1.5$	V
	3-V supply (see Note 1)	0	1.024	$AV_{DD}-1.5$	
Load resistance, $R_L$		2	10		k $\Omega$
Load capacitance, $C_L$				100	pF
Serial clock rate, SCLK				20	MHz
Operating free-air temperature	TLV5604C	0		70	$^{\circ}\text{C}$
	TLV5604I	-40		85	

NOTE 1: Voltages greater than  $AV_{DD}/2$  will cause output saturation for large DAC codes.

## electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

### static DAC specifications

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution		10			bits
Integral nonlinearity (INL), end point adjusted	See Note 2			$\pm 1$	LSB
Differential nonlinearity (DNL)	See Note 3		$\pm 0.1$	$\pm 1$	LSB
E <sub>ZS</sub> Zero scale error (offset error at zero scale)	See Note 4			$\pm 12$	mV
Zero scale error temperature coefficient	See Note 5		10		ppm/ $^{\circ}\text{C}$
E <sub>G</sub> Gain error	See Note 6			$\pm 0.6$	% of FS voltage
Gain error temperature coefficient	See Note 7		10		ppm/ $^{\circ}\text{C}$
PSRR Power supply rejection ratio	Zero scale gain	See Notes 8 and 9	-80		dB
	Gain		-80		

- NOTES: 2. The relative accuracy or integral nonlinearity (INL) sometimes referred to as linearity error, is the maximum deviation of the output from the line between zero and full scale excluding the effects of zero code and full-scale errors.
3. The differential nonlinearity (DNL) sometimes referred to as differential error, is the difference between the measured and ideal 1 LSB amplitude change of any two adjacent codes. Monotonic means the output voltage changes in the same direction (or remains constant) as a change in the digital input code.
4. Zero-scale error is the deviation from zero voltage output when the digital input code is zero.
5. Zero-scale-error temperature coefficient is given by:  $E_{ZS} \text{ TC} = [E_{ZS}(T_{\max}) - E_{ZS}(T_{\min})]/V_{\text{ref}} \times 10^6/(T_{\max} - T_{\min})$ .
6. Gain error is the deviation from the ideal output ( $2V_{\text{ref}} - 1\text{ LSB}$ ) with an output load of 10 k $\Omega$  excluding the effects of the zero-error.
7. Gain temperature coefficient is given by:  $E_G \text{ TC} = [E_G(T_{\max}) - E_G(T_{\min})]/V_{\text{ref}} \times 10^6/(T_{\max} - T_{\min})$ .
8. Zero-scale-error rejection ratio (E<sub>ZS</sub>-RR) is measured by varying the  $AV_{DD}$  from  $5 \pm 0.5\text{ V}$  and  $3 \pm 0.3\text{ V}$  dc, and measuring the proportion of this signal imposed on the zero-code output voltage.
9. Gain-error rejection ratio (E<sub>G</sub>-RR) is measured by varying the  $AV_{DD}$  from  $5 \pm 0.5\text{ V}$  and  $3 \pm 0.3\text{ V}$  dc and measuring the proportion of this signal imposed on the full-scale output voltage after subtracting the zero scale change.

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**electrical characteristics over recommended operating free-air temperature range  
(unless otherwise noted) (continued)**

**individual DAC output specifications**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_O$ Voltage output	$R_L = 10\text{ k}\Omega$	0	$AV_{DD}-0.4$		V
Output load regulation accuracy	$R_L = 2\text{ k}\Omega$ vs $10\text{ k}\Omega$		0.1	0.25	% of FS voltage

**reference input (REFINAB, REFINCD)**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_I$ Input voltage range	See Note 10	0	$AV_{DD}-1.5$		V
$R_I$ Input resistance			10		M $\Omega$
$C_I$ Input capacitance			5		pF
Reference feed through	REFIN = $1\text{ V}_{pp}$ at 1 kHz + 1.024 V dc (see Note 11)		-75		dB
Reference input bandwidth	REFIN = $0.2\text{ V}_{pp}$ + 1.024 V dc	Slow	0.5		MHz
		Fast	1		

NOTES: 10. Reference input voltages greater than  $V_{DD}/2$  will cause output saturation for large DAC codes.

11. Reference feedthrough is measured at the DAC output with an input code = 000 hex and a  $V_{ref}(\text{REFINAB or REFINCD})$  input = 1.024 Vdc + 1  $V_{pp}$  at 1 kHz.

**digital inputs ( $\overline{D0-D11}$ ,  $\overline{CS}$ ,  $\overline{WEB}$ ,  $\overline{LDAC}$ ,  $\overline{PD}$ )**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{IH}$ High-level digital input current	$V_I = DV_{DD}$			$\pm 1$	$\mu\text{A}$
$I_{IL}$ Low-level digital input current	$V_I = 0\text{ V}$			$\pm 1$	$\mu\text{A}$
$C_I$ Input capacitance			3		pF

**power supply**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{DD}$ Power supply current	5-V supply, No load, Clock running	Slow	1.4	2.2	mA
		Fast	3.5	5.5	
	3-V supply, No load, Clock running	Slow	1	1.5	mA
		Fast	3	4.5	
Power down supply current, See Figure 12			10		nA



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## electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (continued)

### analog output dynamic performance

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
SR	Output slew rate	C <sub>L</sub> = 100 pF, R <sub>L</sub> = 10 kΩ, V <sub>O</sub> = 10% to 90%, V <sub>ref</sub> = 2.048 V, 1024 V	Fast	5			V/μs
			Slow	1			V/μs
t <sub>s</sub>	Output settling time	To ± 0.5 LSB, C <sub>L</sub> = 100 pF, R <sub>L</sub> = 10 kΩ, See Notes 12 and 14	Fast	2.5	4		μs
			Slow	8.5	18		
t <sub>s(c)</sub>	Output settling time, code to code	To ± 0.5 LSB, C <sub>L</sub> = 100 pF, R <sub>L</sub> = 10 kΩ, See Note 13	Fast	1			μs
			Slow	2			
Glitch energy		Code transition from 7FF to 800		10			nV-sec
SNR	Signal-to-noise ratio	Sinewave generated by DAC, Reference voltage = 1.024 at 3 V and 2.048 at 5 V, f <sub>s</sub> = 400 KSPS, f <sub>OUT</sub> = 1.1 kHz sinewave, C <sub>L</sub> = 100 pF, R <sub>L</sub> = 10 kΩ, BW = 20 kHz		68			dB
S/(N+D)	Signal to noise + distortion			65			
THD	Total harmonic Distortion			−68			
SFDR	Spurious free dynamic range			70			

NOTES: 12. Settling time is the time for the output signal to remain within  $\pm 0.5\text{ LSB}$  of the final measured value for a digital input code change of 020 hex to 3FF hex or 3FF hex to 020 hex.

13. Settling time is the time for the output signal to remain within  $\pm 0.5\text{ LSB}$  of the final measured value for a digital input code change of one count, 1FF hex to 200 hex.

14. Limits are ensured by design and characterization, but are not production tested.

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**WITH POWER DOWN**

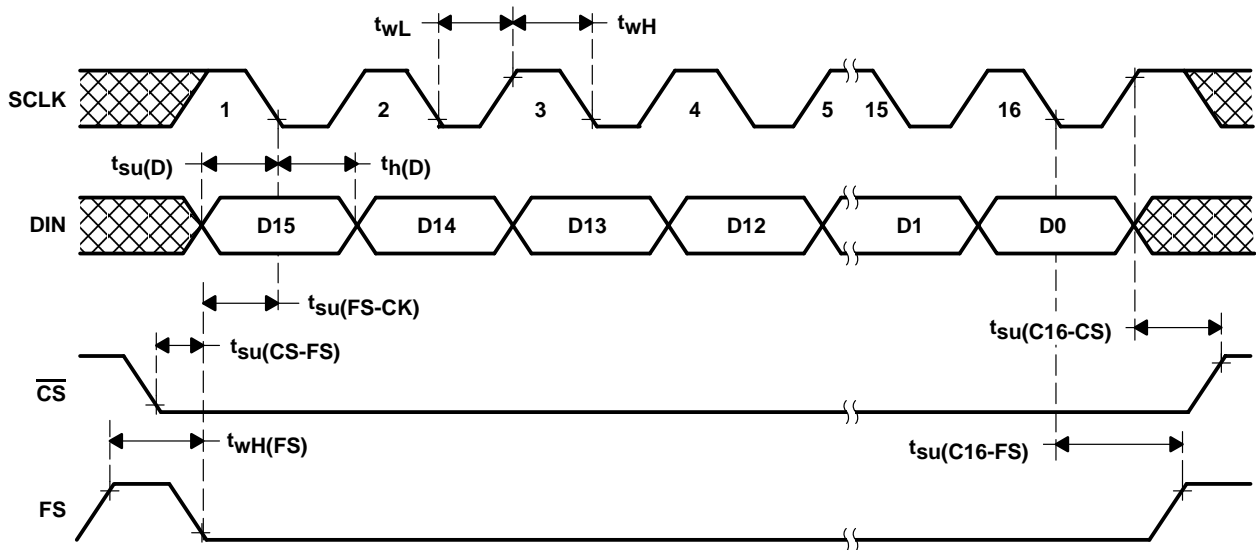
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**electrical characteristics over recommended operating free-air temperature range  
(unless otherwise noted) (continued)**

**digital input timing requirements**

	MIN	NOM	MAX	UNIT
$t_{su}(\overline{CS}-FS)$ Setup time, $\overline{CS}$ low before $FS\downarrow$	10			ns
$t_{su}(FS-CK)$ Setup time, FS low before first negative SCLK edge	8			ns
$t_{su}(C16-FS)$ Setup time, sixteenth negative SCLK edge after FS low on which bit D0 is sampled before rising edge of FS	10			ns
$t_{su}(C16-CS)$ Setup time. The first positive SCLK edge after D0 is sampled before $\overline{CS}$ rising edge. If FS is used instead of the SCLK positive edge to update the DAC, then the setup time is between the FS rising edge and $\overline{CS}$ rising edge.	10			ns
$t_{wH}$ Pulse duration, SCLK high	25			ns
$t_{wL}$ Pulse duration, SCLK low	25			ns
$t_{su}(D)$ Setup time, data ready before SCLK falling edge	8			ns
$t_h(D)$ Hold time, data held valid after SCLK falling edge	5			ns
$t_{wH}(FS)$ Pulse duration, FS high	20			ns

**PARAMETER MEASUREMENT INFORMATION**



**Figure 1. Timing Diagram**

## TYPICAL CHARACTERISTICS

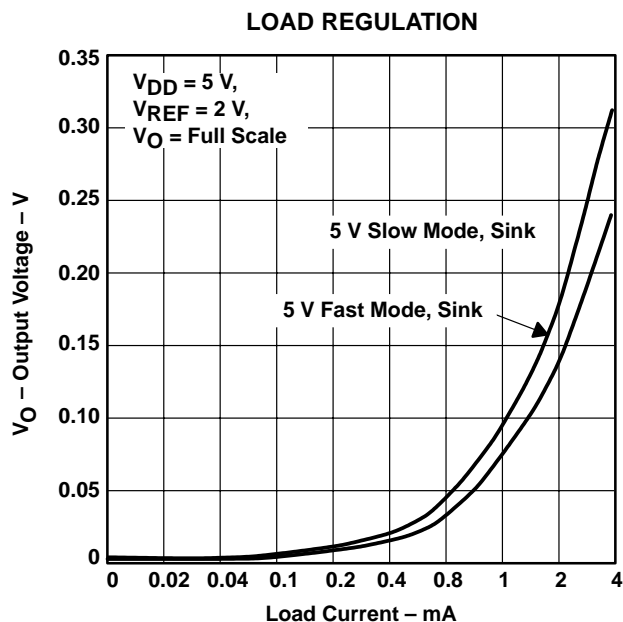


Figure 2

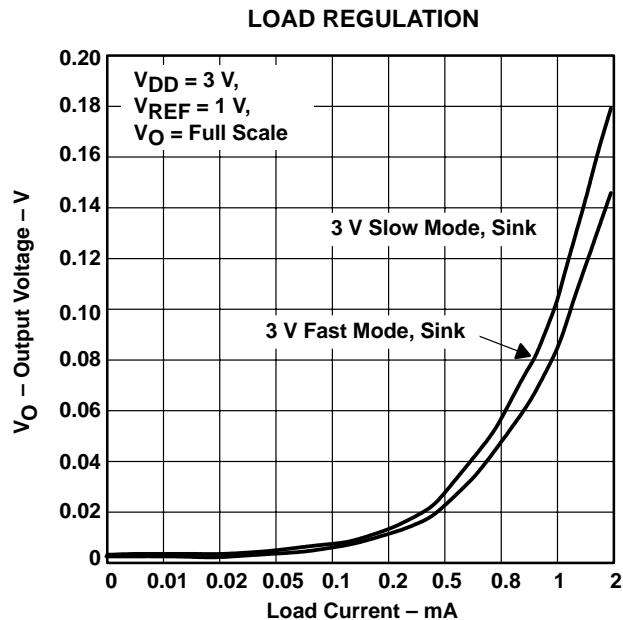


Figure 3

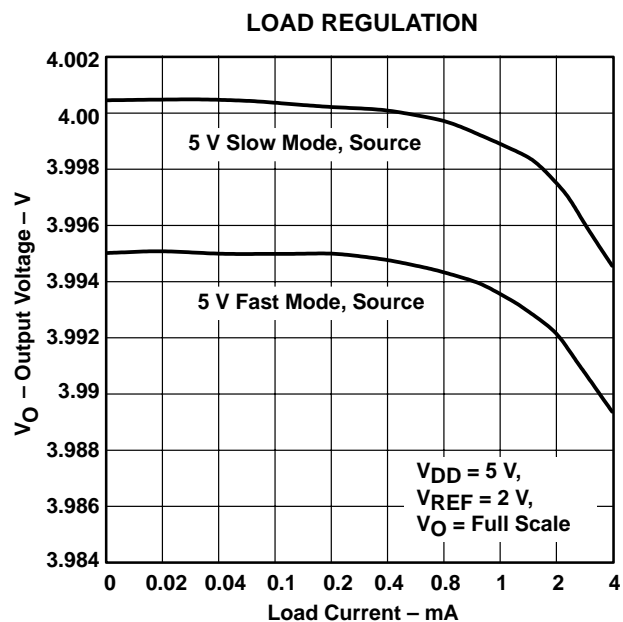


Figure 4

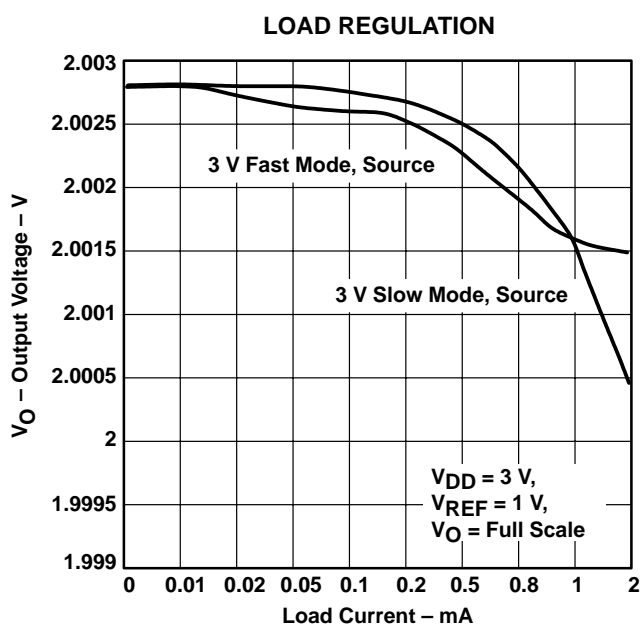


Figure 5



# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### TYPICAL CHARACTERISTICS

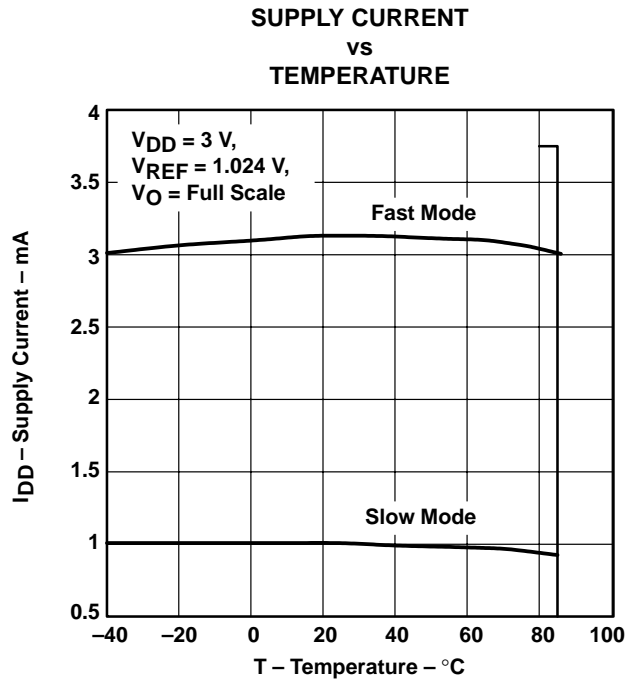


Figure 6

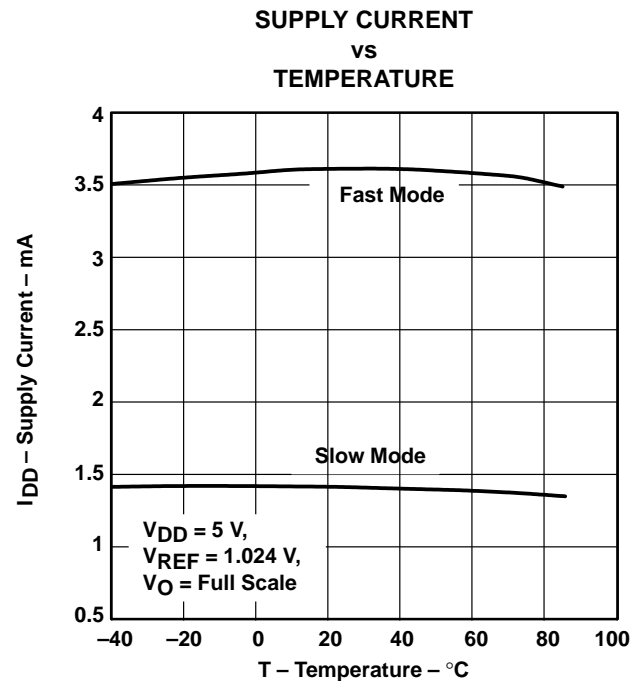


Figure 7

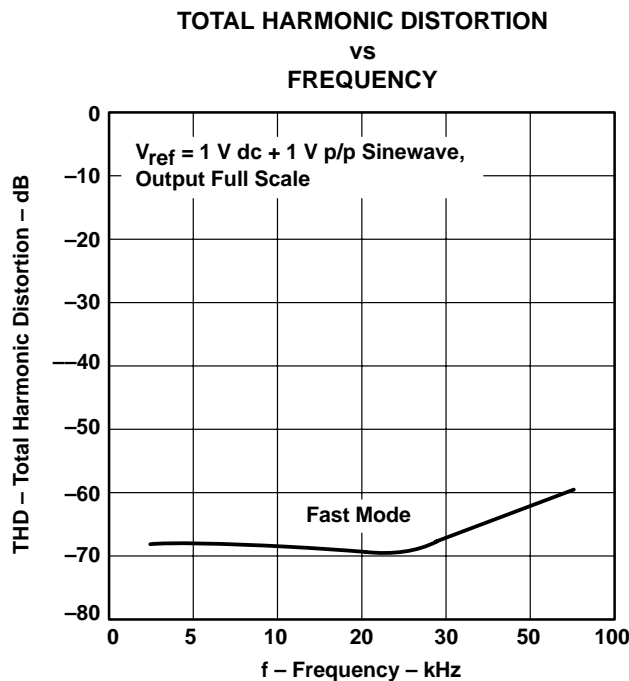


Figure 8

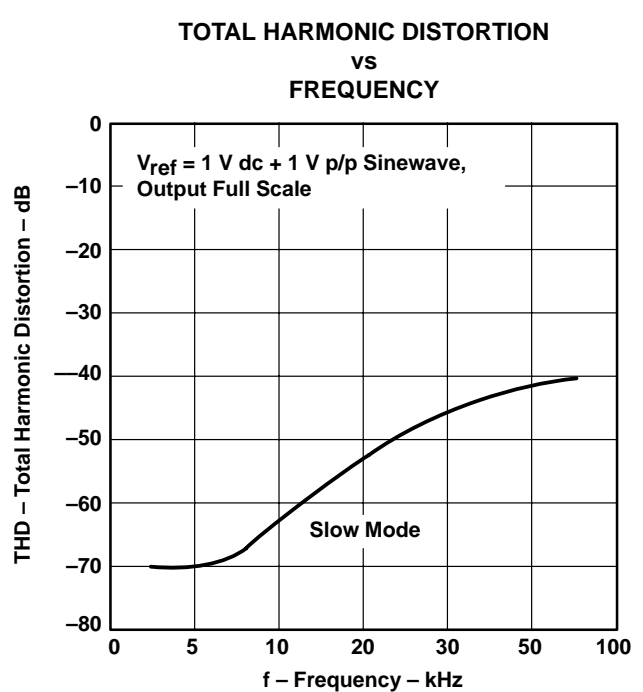


Figure 9

## TYPICAL CHARACTERISTICS

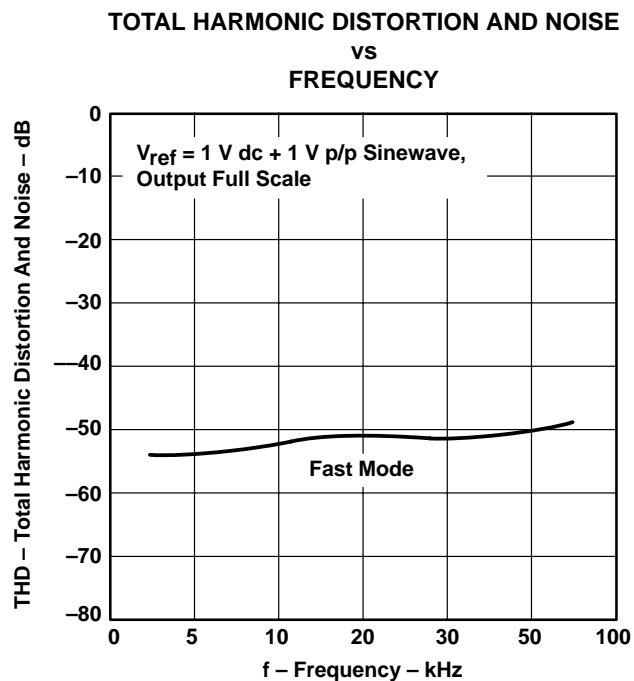


Figure 10

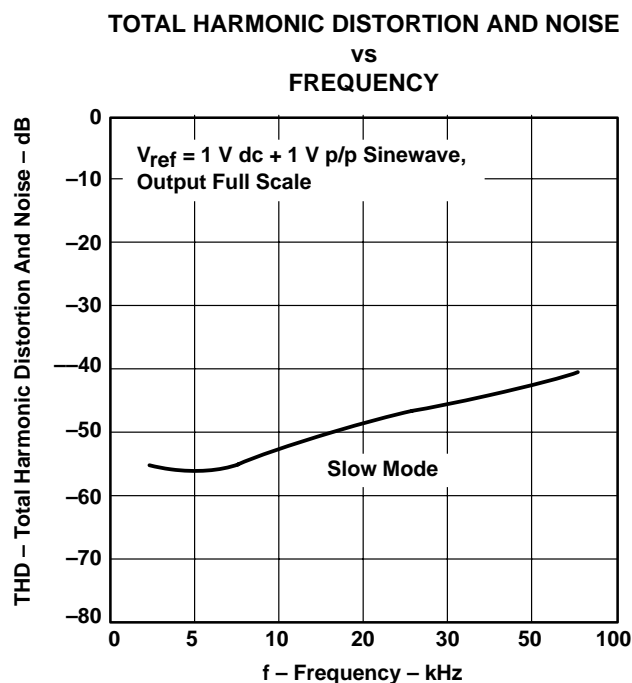


Figure 11

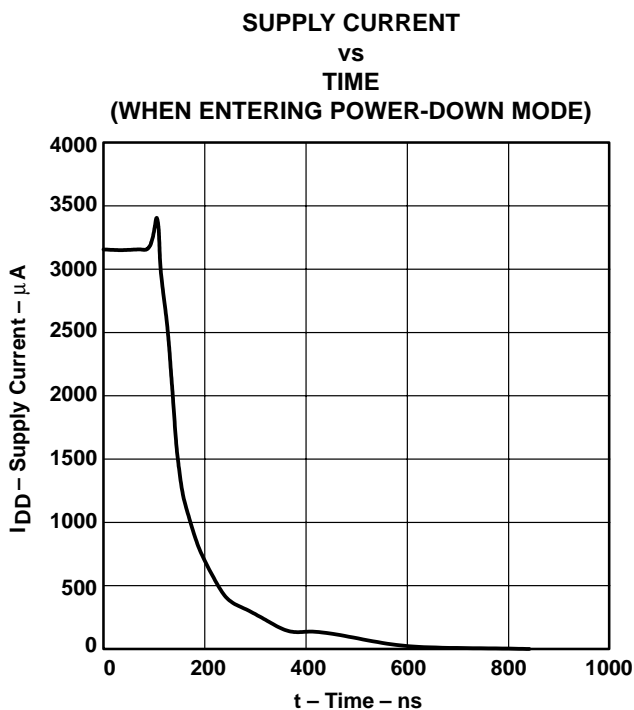


Figure 12

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**2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS  
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**TYPICAL CHARACTERISTICS**

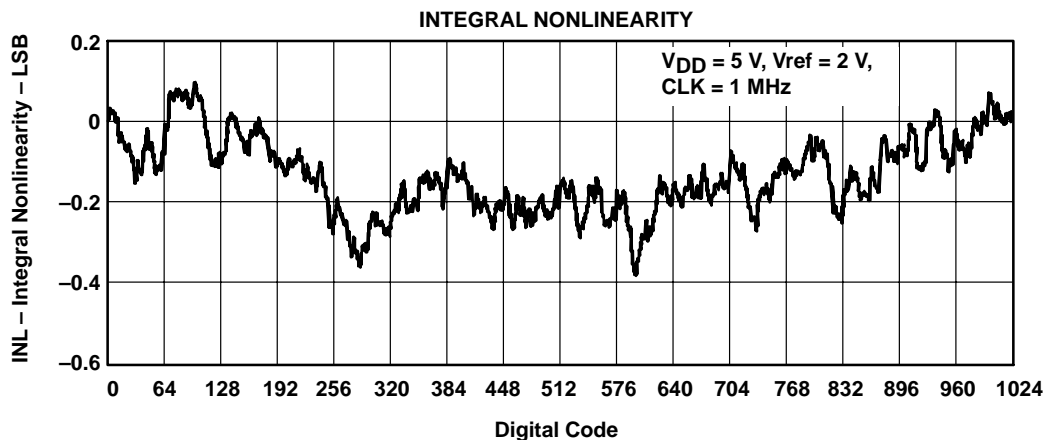


Figure 13

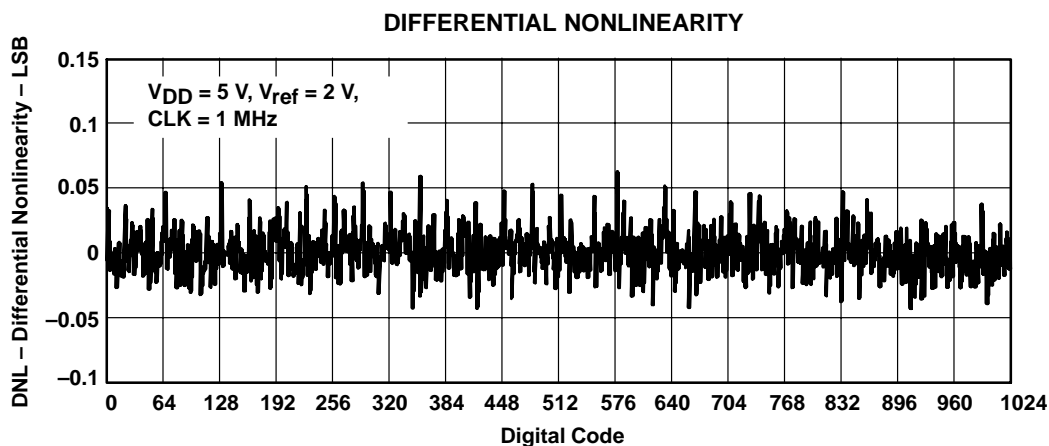


Figure 14

## APPLICATION INFORMATION

## general function

The TLV5604 is a 10-bit single supply DAC based on a resistor string architecture. The device consists of a serial interface, speed and power-down control logic, a reference input buffer, a resistor string, and a rail-to-rail output buffer.

The output voltage (full scale determined by external reference) is given by:

$$2 \text{ REF } \frac{\text{CODE}}{2^n} \text{ [V]}$$

Where REF is the reference voltage and CODE is the digital input value within the range of  $0_{10}$  to  $2^n-1$ , where  $n=10$  (bits). The 16-bit data word, consisting of control bits and the new DAC value, is illustrated in the *data format* section. A power-on reset initially resets the internal latches to a defined state (all bits zero).

## serial interface

Explanation of data transfer: First, the device has to be enabled with  $\overline{\text{CS}}$  set to low. Then, a falling edge of FS starts shifting the data bit-per-bit (starting with the MSB) to the internal register on the falling edges of SCLK. After 16 bits have been transferred or FS rises, the content of the shift register is moved to the DAC latch, which updates the voltage output to the new level.

The serial interface of the TLV5604 can be used in two basic modes:

- Four wire (with chip select)
- Three wire (without chip select)

Using chip select (four wire mode), it is possible to have more than one device connected to the serial port of the data source (DSP or microcontroller). The interface is compatible with the TMS320 family. Figure 15 shows an example with two TLV5604s connected directly to a TMS320 DSP.

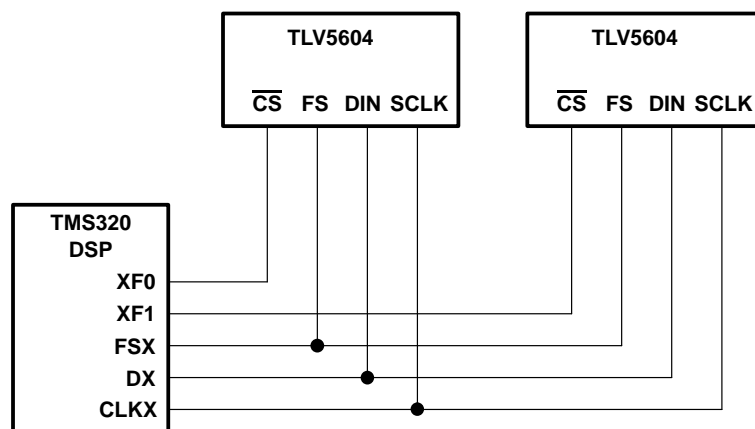
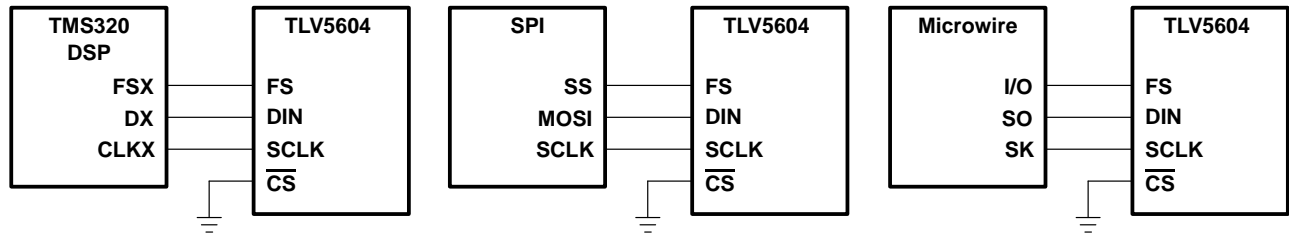


Figure 15. TMS320 Interface

## APPLICATION INFORMATION

### serial interface (continued)

If there is no need to have more than one device on the serial bus, then  $\overline{\text{CS}}$  can be tied low. Figure 16 shows an example of how to connect the TLV5604 to a TMS320, SPI, or Microwire port using only three pins.



**Figure 16. Three-Wire Interface**

Notes on SPI and Microwire: Before the controller starts the data transfer, the software has to generate a falling edge on the I/O pin connected to FS. If the word width is 8 bits (SPI and Microwire), two write operations must be performed to program the TLV5604. After the write operation(s), the DAC output is updated automatically on the next positive clock edge following the sixteenth falling clock edge.

### serial clock frequency and update rate

The maximum serial clock frequency is given by:

$$f_{\text{SCLKmax}} = \frac{1}{t_{\text{WH(min)}} + t_{\text{WL(min)}}} = 20 \text{ MHz}$$

The maximum update rate is:

$$f_{\text{UPDATEmax}} = \frac{1}{16 (t_{\text{WH(min)}} + t_{\text{WL(min)}})} = 1.25 \text{ MHz}$$

Note that the maximum update rate is a theoretical value for the serial interface since the settling time of the TLV5604 has to be considered also.

### data format

The 16-bit data word for the TLV5604 consists of two parts:

- Control bits (D15 . . . D12)
- New DAC value (D11 . . . D0)

D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
A1	A0	PWR	SPD	New DAC value (10 bits)										X	X

X: don't care

SPD: Speed control bit. 1 → fast mode 0 → slow mode

PWR: Power control bit. 1 → power down 0 → normal operation

## APPLICATION INFORMATION

In power down mode, all amplifiers within the TLV5604 are disabled. A particular DAC (A, B, C, D) of the TLV5604 is selected by A1 and A0 within the input word.

A1	A0	DAC
0	0	A
0	1	B
1	0	C
1	1	D

## TLV5604 interfaced to TMS320C203 DSP

## Hardware interfacing

Figure 17 shows an example of how to connect the TLV5604 to a TMS320C203 DSP. The serial port is configured in burst mode, with FSX generated by the TMS320C203 to provide the Frame Sync (FS) input to the TLV5604. Data is transmitted on the DX line, with the serial clock input on the CLKX line. The general-purpose input/output port bits IO0 and IO1 are used to generate the Chip Select ( $\overline{\text{CS}}$ ) and DAC Latch Update ( $\overline{\text{LDAC}}$ ) inputs to the TLV5604. The active low Power Down ( $\overline{\text{PD}}$ ) is pulled high all the time to ensure the DACs are enabled.

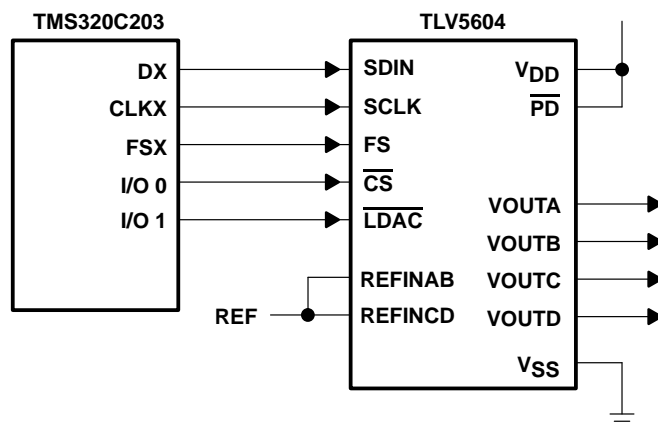


Figure 17. TLV5604 Interfaced with TMS320C203

## Software

The application example generates a differential in-phase (sine) signal between the VOUTA and VOUTB pins, and it is quadrature (cosine) signal as the differential signal between VOUTC and VOUTD.

The on-chip timer is used to generate interrupts at a fixed frequency. The related interrupt service routine pulses LDAC low to update all 4 DACs simultaneously, then fetches and writes the next sample to all 4 DACs. The samples are stored in a look-up table, which describes two full periods of a sine wave.

The synchronous serial port of the DSP is used in burst mode. In this mode, the processor generates an FS pulse preceding the MSB of every data word. If multiple, contiguous words are transmitted, a violation of the tsu(C16-FS) timing requirement will occur. To avoid this, the program waits until the transmission of the previous word has been completed.

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### APPLICATION INFORMATION

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;-----;
; Processor:  TMS320C203 running at 40 MHz;
; Description:
;
; This program generates a differential in-phase (sine) on (OUTA-OUTB) and it's
; quadrature (cosine) as a differential signal on (OUTC-OUTD).
;
; The DAC codes for the signal samples are stored as a table of 64 12-bit values,
; describing 2 periods of a sine function. A rolling pointer is used to address the
; table location in the first period of this waveform, from which the DAC A samples are
; read. The samples for the other 3 DACs are read at an offset to this rolling pointer:
; DAC      Function      Offset from rolling pointer;
; A        sine          0
; B        inverse sine   16
; C        cosine         8
; D        inverse cosine  24
;
; The on-chip timer is used to generate interrupts at a fixed rate. The interrupt
; service routine first pulses LDAC low to update all DACs simultaneously with the
; values which were written to them in the previous interrupt. Then all 4 DAC values are
; fetched and written out through the synchronous serial interface. Finally, the
; rolling pointer is incremented to address the next sample, ready for the next
; interrupt.
;
; © 1998, Texas Instruments Incorporated
;-----;
; -----I/O and memory mapped regs -----
; .include "regs.asm"
; -----jump vectors-----
; .ps      0h
; b        start
; b        int1
; b        int23
; b        timer_isr
;----- variables -----
temp      .equ    0060h
r_ptr     .equ    0061
iosr_stat .equ    0062h
DACA_ptr  .equ    0063h
DACB_ptr  .equ    0064h
DACC_ptr  .equ    0065h
DACD_ptr  .equ    0066h
;----- constants -----
; DAC control bits to be OR'ed onto data
; all fast mode
DACA_control .equ    01000h
DACB_control .equ    05000h
DACC_control .equ    09000h
DACD_control .equ    0d000h
;----- tables -----
; .ds      02000h
sinevals
; .word    00800h
; .word    0097Ch
; .word    00AE9h
; .word    00C3Ah
; .word    00D61h
; .word    00E53h
; .word    00F07h
; .word    00F76h
; .word    00F9Ch
; .word    00F76h
; .word    00F07h
; .word    00E53h
; .word    00D61h
; .word    00C3Ah

```



## APPLICATION INFORMATION

```

.word    00AE9h
.word    0097Ch
.word    00800h
.word    00684h
.word    00517h
.word    003C6h
.word    0029Fh
.word    001ADh
.word    000F9h
.word    0008Ah
.word    00064h
.word    0008Ah
.word    000F9h
.word    001ADh
.word    0029Fh
.word    003C6h
.word    00517h
.word    00684h
.word    00800h
.word    0097Ch
.word    00AE9h
.word    00C3Ah
.word    00D61h
.word    00E53h
.word    00F07h
.word    00F76h
.word    00F9Ch
.word    00F76h
.word    00F07h
.word    00E53h
.word    00D61h
.word    00C3Ah
.word    00AE9h
.word    0097Ch
.word    00800h
.word    00684h
.word    00517h
.word    003C6h
.word    0029Fh
.word    001ADh
.word    000F9h
.word    0008Ah
.word    00064h
.word    0008Ah
.word    000F9h
.word    001ADh
.word    0029Fh
.word    003C6h
.word    00517h
.word    00684h
;-----
; Main Program
;-----
        .ps    1000h
        .entry

start
;-----
; disable interrupts
;-----
        setc    INTM           ; disable maskable interrupts
        splk    #0ffffh, IFR   ; clear all interrupts
        splk    #0004h, IMR    ; timer interrupts unmasked

```



# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### APPLICATION INFORMATION

```

;-----
; set up the timer
; timer period set by values in PRD and TDDR
; period = (CLKOUT1 period) × (1+PRD) × (1+TDDR)
; examples for TMS320C203 with 40 MHz main clock
; Timer rate      TDDR      PRD
; 80 kHz          9         24 (18h)
; 50 kHz          9         39 (27h)
;-----

prd_val.equ      0018h
tcr_val.equ      0029h

    splk #0000h, temp    ; clear timer
    out  temp, TIM
    splk #prd_val, temp   ; set PRD
    out  temp, PRD
    splk #tcr_val, temp   ; set TDDR, and TRB=1 for auto-reload
    out  temp, TCR
;-----
; Configure IO0/1 as outputs to be :
; IO0 CS      - and set high
; IO1 LDAC     - and set high
;-----
    in   temp, ASPCR      ; configure as output
    lacl temp
    or   #0003h
    sac1 temp
    out  temp, ASPCR
    in   temp, IOSR       ; set them high
    lacl temp
    or   #0003h
    sac1 temp
    out  temp, IOSR
;-----
; set up serial port for
; SSPCR.TXM=1    Transmit mode - generate FSX
; SSPCR.MCM=1    Clock mode - internal clock source
; SSPCR.FSM=1    Burst mode
;-----
    splk #0000Eh, temp
    out  temp, SSPCR      ; reset transmitter
    splk #0002Eh, temp
    out  temp, SSPCR
;-----
; reset the rolling pointer
;-----
    lacl #000h      sac1 r_ptr
;-----
; enable interrupts
;-----
    clrc INTM
; enable maskable interrupts
;-----
; loop forever!
;-----
next    idle        ;wait for interrupt
        b          next
;-----
; all else fails stop here
;-----
done    b          done ;hang there

```



## APPLICATION INFORMATION

```

;-----
; Interrupt Service Routines
;-----
int1      ret      ; do nothing and return
int23     ret      ; do nothing and return
timer_isr:
    in      iosr_stat, IOSR ; store IOSR value into variable space
    lacl    iosr_stat      ; load acc with iosr status
    and     #0FFFDh        ; reset IO1 - LDAC low
    sac1    temp           ;
    out     temp, IOSR ;

    or      #0002h         ; set IO1 - LDAC high
    sac1    temp           ;
    out     temp, IOSR ;
    and     #0FFFEh        ; reset IO0 - CS low
    sac1    temp           ;
    out     temp, IOSR ;
    lacl    r_ptr          ; load rolling pointer to accumulator
    add     #sinevals      ; add pointer to table start
    sac1    DACa_ptr       ; to get a pointer for next DAC a sample
    add     #08h           ; add 8 to get to DAC C pointer
    sac1    DACc_ptr       ;
    add     #08h           ; add 8 to get to DAC B pointer
    sac1    DACb_ptr       ;
    add     #08h           ; add 8 to get to DAC D pointer
    sac1    DACd_ptr       ;
    mar     *,ar0          ; set ar0 as current AR

; DAC A
    lar     ar0, DACa_ptr ; ar0 points to DAC a sample
    lacl    *              ; get DAC a sample into accumulator
    or      #DACa_control ; OR in DAC A control bits
    sac1    temp           ;
    out     temp, SDTR     ; send data

;-----
; We must wait for transmission to complete before writing next word to the SDTR.
; TLV5604 interface does not allow the use of burst mode with the full packet rate, as
; we need a CLKX -ve edge to clock in last bit before FS goes high again, to allow SPI
; compatibility.
;-----

    rpt     #016h         ; wait long enough for this configuration
    nop                      ; of MCLK/CLKOUT1 rate

; DAC B
    lar     ar0, DACb_ptr ; ar0 points to DAC a sample
    lacl    *              ; get DAC a sample into accumulator
    or      #DACb_control ; OR in DAC B control bits
    sac1    temp           ;
    out     temp, SDTR     ; send data
    rpt     #016h         ; wait long enough for this configuration
    nop                      ; of MCLK/CLKOUT1 rate

```

TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### APPLICATION INFORMATION

```
    ; DAC C
    lar      ar0, DACc_ptr ; ar0 points to DAC a sample
    lacl     *              ; get DAC a sample into accumulator
    or       #DACc_control ; OR in DAC C control bits
    sac1     temp          ;
    out      temp, SDTR    ; send data
    rpt      #016h         ; wait long enough for this configuration
    nop      ; of MCLK/CLKOUT1 rate

    ; DAC D
    lar      ar0, DACd_ptr ; ar0 points to DAC a sample
    lacl     *              ; get DAC a sample into accumulator
    or       #DACd_control ; OR in DAC D control bits
    sac1     temp          ;
    out      temp, SDTR    ; send data
    lacl     r_ptr         ; load rolling pointer to accumulator
    add      #1h           ; increment rolling pointer
    and      #001Fh        ; count 0-31 then wrap back round
    sac1     r_ptr         ; store rolling pointer
    rpt      #016h         ; wait long enough for this configuration
    nop      ; of MCLK/CLKOUT1 rate
    ; now take CS high again
    lacl     iosr_stat     ; load acc with iosr status
    or       #0001h        ; set IO0 - CS high
    sac1     temp          ;
    out      temp, IOSR    ;
    clrc     intm          ; re-enable interrupts
    ret      ; return from interrupt
.end
```



# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### APPLICATION INFORMATION

#### TLV5604 interfaced to MCS<sup>®</sup>51 microcontroller

##### hardware interfacing

Figure 18 shows an example of how to connect the TLV5604 to an MCS<sup>®</sup>51 Microcontroller. The serial DAC input data and external control signals are sent via I/O Port 3 of the controller. The serial data is sent on the RxD line, with the serial clock output on the TxD line. Port 3 bits 3, 4, and 5 are configured as outputs to provide the DAC latch update ( $\overline{\text{LDAC}}$ ), chip select ( $\overline{\text{CS}}$ ) and frame sync (FS) signals for the TLV5604. The active low power down pin ( $\overline{\text{PD}}$ ) of the TLV5604 is pulled high to ensure that the DACs are enabled.

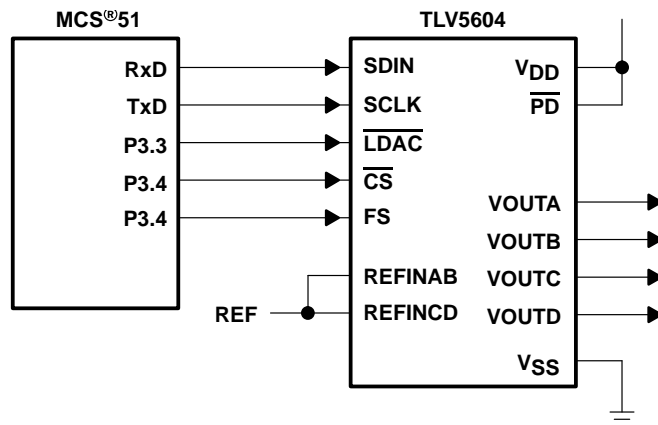


Figure 18. TLV5604 Interfaced with MCS<sup>®</sup>51

##### software

The example is the same as for the TMS320C203 in this datasheet, but adapted for a MCS<sup>®</sup>51 controller. It generates a differential in-phase (sine) signal between the VOUTA and VOUTB pins, and its quadrature (cosine) signal as the differential signal between VOUTC and VOUTD.

The on-chip timer is used to generate interrupts at a fixed frequency. The related interrupt service routine pulses  $\overline{\text{LDAC}}$  low to update all 4 DACs simultaneously, then fetches and writes the next sample to all 4 DACs. The samples are stored as a look-up table, which describes one full period of a sine wave.

The serial port of the controller is used in Mode 0, which transmits 8 bits of data on RxD, accompanied by a synchronous clock on TxD. Two writes concatenated together are required to write a complete word to the TLV5604. The  $\overline{\text{CS}}$  and FS signals are provided in the required fashion through control of IO port 3, which has bit addressable outputs.

MCS is a registered trademark of Intel Corporation.

# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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### APPLICATION INFORMATION

```

;-----
; Processor: 80C51
;
; Description:
;
; This program generates a differential in-phase (sine) on (OUTA-OUTB) and it's
; quadrature (cosine) as a differential signal on (OUTC-OUTD).
; © 1998, Texas Instruments Incorporated
;-----
NAME      GENIQ
MAIN      SEGMENT  CODE
ISR        SEGMENT  CODE
SINTBL     SEGMENT  CODE
VAR1       SEGMENT  DATA
STACK      SEGMENT  IDATA
;-----
; Code start at address 0, jump to start
;-----
                CSEG  AT 0
                LJMP  start      ; Execution starts at address 0 on power-up.
;-----
; Code in the timer0 interrupt vector
;-----
                CSEG  AT 0BH
                LJMP  timer0isr ; Jump vector for timer 0 interrupt is 000Bh
;-----
; Global variables need space allocated
;-----
                RSEG  VAR1
Temp_ptr:      DS      1
rolling_ptr:    DS      1
;-----
; Interrupt service routine for timer 0 interrupts
;-----
timer0isr:      RSEG  ISR
                PUSH  PSW
                PUSH  ACC

                CLR   INT1      ; pulse LDAC low
                SETB  INT1      ; to latch all 4 previous values at the same time
                                ; 1st thing done in timer isr => fixed period

                CLR   T0        ; set CS low
; The signal to be output on each DAC is a sine function.
; One cycle of a sine wave is held in a table @ sinevals as 32 samples of msb,
; lsb pairs (64 bytes). We have one pointer which rolls round this table,
; rolling_ptr, incrementing by 2 bytes (1 sample) on each interrupt (at the end of
; this routine).

; The DAC samples are read at an offset to this rolling pointer:
; DAC Function Offset from rolling_ptr
; A sine 0
; B inverse sine 32
; C cosine 16
; D inverse cosine 48
MOV  DPTR,#sinevals ; set DPTR to the start of the table of sine signal values
MOV  R7,rolling_ptr ; R7 holds the pointer into the sine table
MOV  A,R7           ; get DAC A msb
MOVC A,@A+DPTR      ; msb of DAC A is in the ACC
CLR  T1             ; transmit it - set FS low
MOV  SBUF,A         ; send it out the serial port
INC  R7             ; increment the pointer in R7
MOV  A,R7           ; to get the next byte from the table
MOVC A,@A+DPTR      ; which is the lsb of this sample, now in ACC

```



## APPLICATION INFORMATION

## A\_MSB\_TX:

```

JNB    TI,A_MSB_TX    ; wait for transmit to complete
CLR    TI              ; clear for new transmit
MOV    SBUF,A          ; and send out the lsb of DAC A

; DAC C next
; DAC C codes should be taken from 16 bytes (8 samples) further on in the sine table
; - this gives a cosine function
MOV    A,R7            ; pointer in R7
ADD    A,#0FH          ; add 15 - already done one INC
ANL    A,#03FH         ; wrap back round to 0 if > 64
MOV    R7,A            ; pointer back in R7

MOVC   A,@A+DPTR       ; get DAC C msb from the table
ORL    A,#01H          ; set control bits to DAC C address

```

## A\_LSB\_TX:

```

JNB    TI,A_LSB_TX    ; wait for DAC A lsb transmit to complete
SETB   T1              ; toggle FS
CLR    T1
CLR    TI              ; clear for new transmit
MOV    SBUF,A          ; and send out the msb of DAC C

INC     R7              ; increment the pointer in R7
MOV    A,R7            ; to get the next byte from the table
MOVC   A,@A+DPTR       ; which is the lsb of this sample, now in ACC

```

## C\_MSB\_TX:

```

JNB    TI,C_MSB_TX    ; wait for transmit to complete
CLR    TI              ; clear for new transmit
MOV    SBUF,A          ; and send out the lsb of DAC C

; DAC B next
; DAC B codes should be taken from 16 bytes (8 samples) further on
; in the sine table - this gives an inverted sine function
MOV    A,R7            ; pointer in R7
ADD    A,#0FH          ; add 15 - already done one INC
ANL    A,#03FH         ; wrap back round to 0 if > 64
MOV    R7,A            ; pointer back in R7

MOVC   A,@A+DPTR       ; get DAC B msb from the table
ORL    A,#02H          ; set control bits to DAC B address

```

## C\_LSB\_TX:

```

JNB    TI,C_LSB_TX    ; wait for DAC C lsb transmit to complete
SETB   T1              ; toggle FS
CLR    T1
CLR    TI              ; clear for new transmit
MOV    SBUF,A          ; and send out the msb of DAC B
; get DAC B LSB
INC     R7              ; increment the pointer in R7
MOV    A,R7            ; to get the next byte from the table
MOVC   A,@A+DPTR       ; which is the lsb of this sample, now in ACC

```

## B\_MSB\_TX:

```

JNB    TI,B_MSB_TX    ; wait for transmit to complete
CLR    TI              ; clear for new transmit
MOV    SBUF,A          ; and send out the lsb of DAC B

```

### APPLICATION INFORMATION

```

; DAC D next
; DAC D codes should be taken from 16 bytes (8 samples) further on in the sine table
; - this gives an inverted cosine function
MOV     A,R7                ; pointer in R7
ADD     A,#0FH              ; add 15 - already done one INC
ANL     A,#03FH             ; wrap back round to 0 if > 64
MOV     R7,A                ; pointer back in R7

MOVC    A,@A+DPTR           ; get DAC D msb from the table
ORL     A,#03H              ; set control bits to DAC D address

B_LSB_TX:
JNB     TI,B_LSB_TX         ; wait for DAC B lsb transmit to complete
SETB    T1                  ; toggle FS
CLR     T1
CLR     TI                  ; clear for new transmit
MOV     SBUF,A              ; and send out the msb of DAC D

INC     R7                  ; increment the pointer in R7
MOV     A,R7                ; to get the next byte from the table
MOVC    A,@A+DPTR           ; which is the lsb of this sample, now in ACC

D_MSB_TX:
JNB     TI,D_MSB_TX         ; wait for transmit to complete
CLR     TI                  ; clear for new transmit
MOV     SBUF,A              ; and send out the lsb of DAC D

; increment the rolling pointer to point to the next sample
; ready for the next interrupt
MOV     A,rolling_ptr
ADD     A,#02H              ; add 2 to the rolling pointer
ANL     A,#03FH             ; wrap back round to 0 if > 64
MOV     rolling_ptr,A       ; store in memory again

D_LSB_TX:
JNB TI,D_LSB_TX             ; wait for DAC D lsb transmit to complete
CLR     TI                  ; clear for next transmit

SETB    T1                  ; FS high
SETB    T0                  ; CS high
POP     ACC
POP     PSW

RETI

;-----
; Stack needs definition
;-----
RSEG    STACK
DS      10h                 ; 16 Byte Stack!

```

# 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

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## APPLICATION INFORMATION

```

;-----
; Main program code
;-----
        RSEG    MAIN
start:
        MOV     SP,#STACK-1      ; first set Stack Pointer

        CLR     A
        MOV     SCON,A           ; set serial port 0 to mode 0
        MOV     TMOD,#02H        ; set timer 0 to mode 2 - auto-reload
        MOV     TH0,#038H        ; set TH0 for 5 kHs interrupts

        SETB    INT1             ; set LDAC = 1
        SETB    T1               ; set FS = 1
        SETB    T0               ; set CS = 1

        SETB    ET0              ; enable timer 0 interrupts
        SETB    EA               ; enable all interrupts

        MOV     rolling_ptr,A    ; set rolling pointer to 0
        SETB    TR0              ; start timer 0

always:
        JMP     always           ; while(1) !
        RET

;-----
; Table of 32 sine wave samples used as DAC data
;-----
        RSEG    SINTBL
sinevals:
        DW      01000H
        DW      0903EH
        DW      05097H
        DW      0305CH
        DW      0B086H
        DW      070CAH
        DW      0F0E0H
        DW      0F06EH
        DW      0F039H
        DW      0F06EH
        DW      0F0E0H
        DW      070CAH
        DW      0B086H
        DW      0305CH
        DW      05097H
        DW      0903EH
        DW      01000H
        DW      06021H
        DW      0A0E8H
        DW      0C063H
        DW      040F9H
        DW      080B5H
        DW      0009FH
        DW      00051H
        DW      00026H
        DW      00051H
        DW      0009FH
        DW      080B5H
        DW      040F9H
        DW      0C063H
        DW      0A0E8H
        DW      06021H
END

```



# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

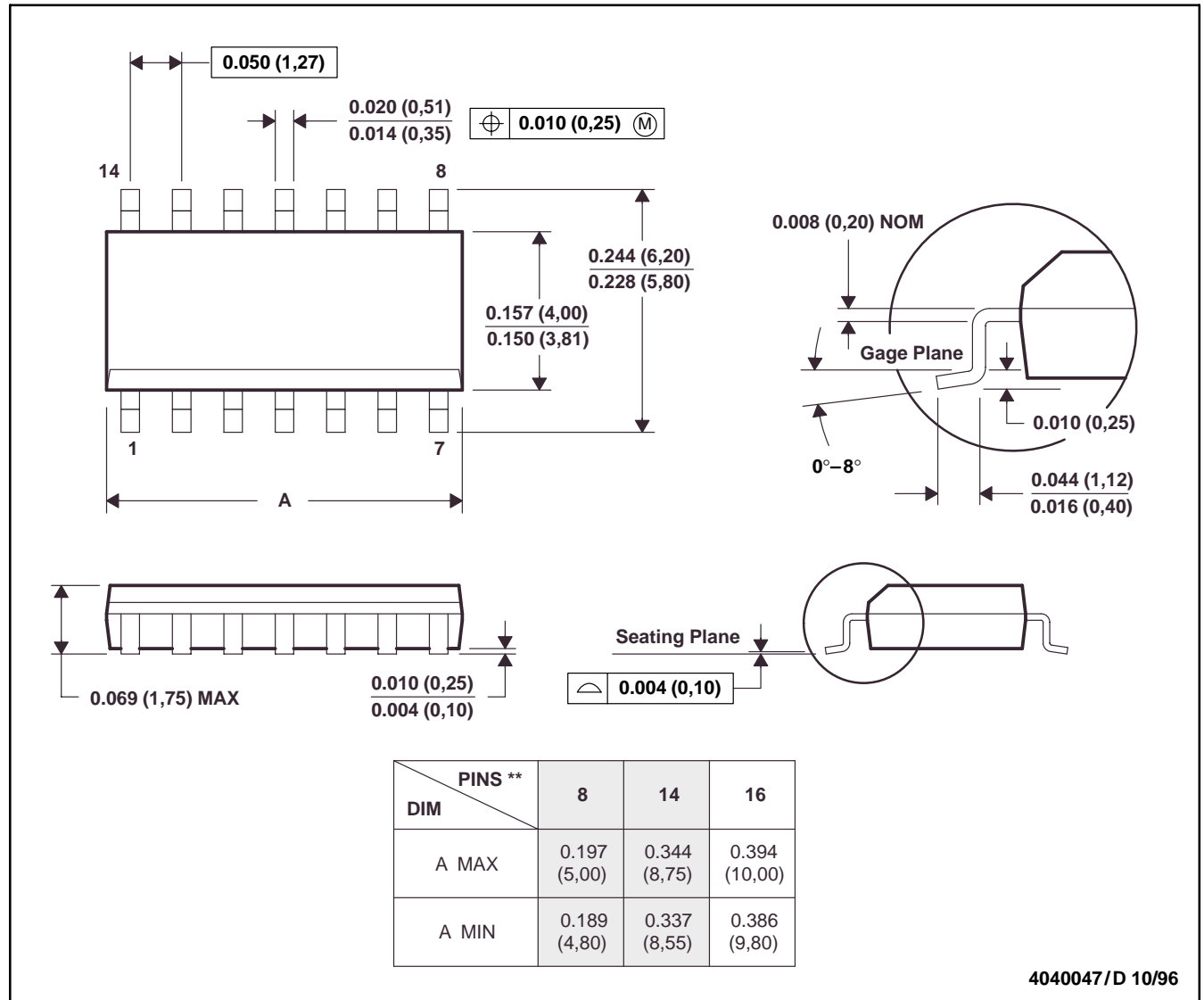
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### MECHANICAL DATA

D (R-PDSO-G\*\*)

PLASTIC SMALL-OUTLINE PACKAGE

14 PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).  
 B. This drawing is subject to change without notice.  
 C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).  
 D. Falls within JEDEC MS-012

# TLV5604

## 2.7-V TO 5.5-V 10-BIT 3- $\mu$ S QUADRUPLE DIGITAL-TO-ANALOG CONVERTERS WITH POWER DOWN

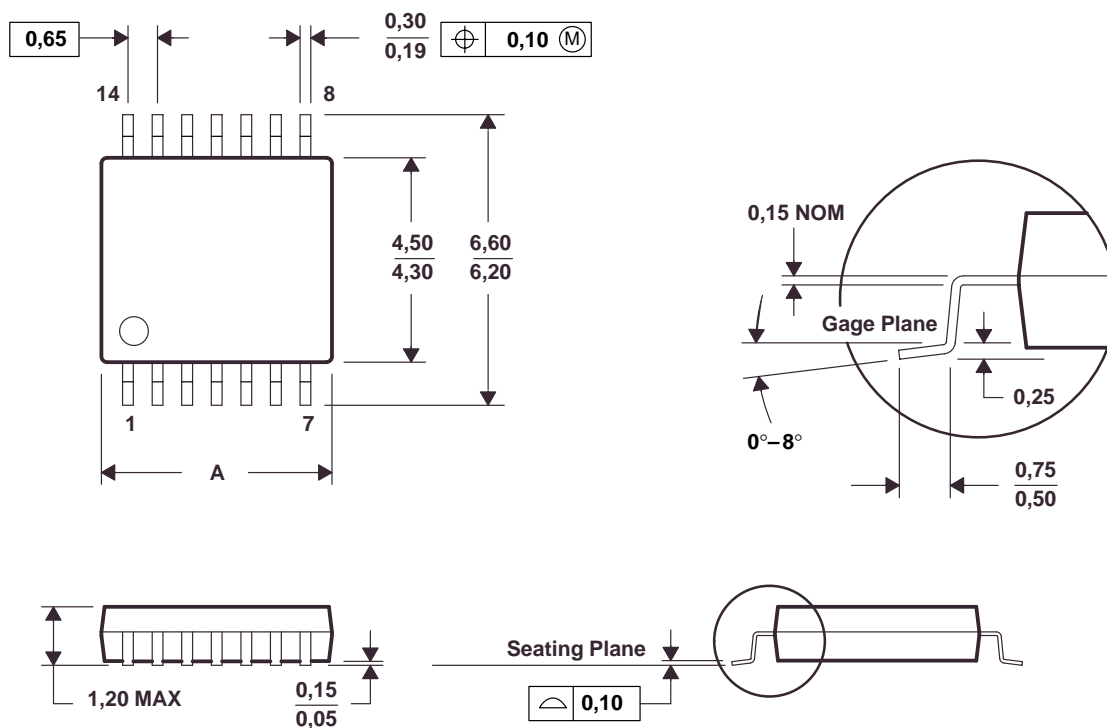
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### MECHANICAL DATA

PW (R-PDSO-G\*\*)

PLASTIC SMALL-OUTLINE PACKAGE

14 PIN SHOWN



DIM \ PINS **	8	14	16	20	24	28
A MAX	3,10	5,10	5,10	6,60	7,90	9,80
A MIN	2,90	4,90	4,90	6,40	7,70	9,60

4040064/E 08/96

- NOTES: A. All linear dimensions are in millimeters.  
B. This drawing is subject to change without notice.  
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.  
D. Falls within JEDEC MO-153

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Mailing Address:

Texas Instruments  
Post Office Box 655303  
Dallas, Texas 75265