

SN74GTLP1612

18-BIT LVTTTL-TO-GTL+ ADJUSTABLE-EDGE-RATE UNIVERSAL BUS TRANSCEIVER

SCES287 – OCTOBER 1999

- **UBT™ (Universal Bus Transceiver)**
Combines D-Type Latches and D-Type Flip-Flops for Operation in Transparent, Latched, Clocked, or Clock-Enabled Mode
- **Bidirectional Interface Between GTL+ Signal Levels and LVTTTL Logic Levels**
- **Equivalent to '16601 Function**
- **LVTTTL Interfaces Are 5-V Tolerant**
- **High-Drive GTL+ Outputs (100 mA)**
- **LVTTTL Outputs (–24 mA/24 mA)**
- **Variable Edge-Rate Control (ERC) Input**
Selects GTL+ Rise and Fall Times for Optimal Data-Transfer Rate and Signal Integrity
- **I_{off}, Power-Up 3-State, and BIAS V_{CC} Support Live Insertion**
- **Bus Hold on A-Port Data Inputs**
- **Distributed V_{CC} and GND-Pin Configuration Minimizes High-Speed Switching Noise**
- **Packaged in Plastic Thin Shrink Small-Outline Package**

description

The SN74GTLP1612 is a high-drive 18-bit universal bus transceiver (UBT) that provides LVTTTL-to-GTL+ and GTL+-to-LVTTTL signal-level translation. It allows for transparent, latched, clocked, or clock-enabled modes of data transfer identical to the '16601 function. The device provides a high-speed interface between cards operating at LVTTTL logic levels and a backplane operating at GTL+ signal levels. High-speed (about two times faster than standard TTL or LVTTTL) backplane operation is a direct result of GTLP's reduced output swing (<1 V), reduced input threshold levels, improved differential input, and output edge control (OEC™). Improved GTLP OEC circuits minimize bus settling time and have been designed and tested using several backplane models. The high drive is suitable for driving double-terminated low-impedance backplanes using incident-wave switching.

DGG PACKAGE
(TOP VIEW)

| | | | |
|-----------------|----|----|----------------------|
| OEAB | 1 | 64 | CEAB |
| LEAB | 2 | 63 | CLKAB |
| A1 | 3 | 62 | B1 |
| A2 | 4 | 61 | B2 |
| GND | 5 | 60 | GND |
| A3 | 6 | 59 | B3 |
| V _{CC} | 7 | 58 | BIAS V _{CC} |
| A4 | 8 | 57 | B4 |
| A5 | 9 | 56 | B5 |
| GND | 10 | 55 | GND |
| A6 | 11 | 54 | B6 |
| A7 | 12 | 53 | B7 |
| A8 | 13 | 52 | B8 |
| GND | 14 | 51 | GND |
| A9 | 15 | 50 | B9 |
| V _{CC} | 16 | 49 | V _{CC} |
| A10 | 17 | 48 | B10 |
| GND | 18 | 47 | GND |
| A11 | 19 | 46 | B11 |
| A12 | 20 | 45 | B12 |
| GND | 21 | 44 | GND |
| A13 | 22 | 43 | B13 |
| A14 | 23 | 42 | B14 |
| GND | 24 | 41 | GND |
| A15 | 25 | 40 | B15 |
| V _{CC} | 26 | 39 | V _{REF} |
| A16 | 27 | 38 | B16 |
| ERC | 28 | 37 | GND |
| A17 | 29 | 36 | B17 |
| A18 | 30 | 35 | B18 |
| OEBA | 31 | 34 | CLKBA |
| LEBA | 32 | 33 | CEBA |

PRODUCT PREVIEW



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description (continued)

GTL+ is the Texas Instruments derivative of the Gunning transceiver logic (GTL) JEDEC standard JESD 8-3. The AC specification of the SN74GTLPH1612 is given only at the preferred higher noise margin GTL+, but the user has the flexibility of using this device at either GTL ($V_{TT} = 1.2\text{ V}$ and $V_{REF} = 0.8\text{ V}$) or GTL+ ($V_{TT} = 1.5\text{ V}$ and $V_{REF} = 1\text{ V}$) signal levels.

Normally, the B port operates at GTL or GTL+ levels, while the A-port and control inputs are compatible with LVTTL logic levels and are 5-V tolerant. V_{REF} is the reference input voltage for the B port.

This device is fully specified for live-insertion applications using I_{off} , power-up 3-state, and BIAS V_{CC} . The I_{off} circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down. The power-up 3-state circuitry places the outputs in the high-impedance state during power up and power down, which prevents driver conflict. The BIAS V_{CC} circuitry precharges and preconditions the B-port input/output connections, preventing disturbance of active data on the backplane during card insertion or removal, and permits true live-insertion capability.

High-drive GTLP backplane interface devices feature adjustable edge-rate control (\overline{ERC}). Changing the \overline{ERC} input voltage between GND and V_{CC} adjusts the B-port output rise and fall times. This allows the designer to optimize system data-transfer rate and signal integrity to the backplane load.

Active bus-hold circuitry is provided to hold unused or undriven LVTTL inputs at a valid logic state. Use of pullup or pulldown resistors with the bus-hold circuitry is not recommended.

When V_{CC} is between 0 and 1.5 V, the device is in the high-impedance state during power up or power down. However, to ensure the high-impedance state above 1.5 V, the output-enable (\overline{OE}) input should be tied to V_{CC} through a pullup resistor; the minimum value of the resistor is determined by the current-sinking capability of the driver.

The SN74GTLPH1612 is characterized for operation from -40°C to 85°C .

functional description

The SN74GTLPH1612 is a high-drive (100 mA) 36-bit UBT containing D-type latches and D-type flip-flops for data-path operation in transparent, latched, clocked, or clock-enabled modes and can replace any of the functions shown in Table 1.

Table 1. SN74GTLPH1612 UBT Replacement Functions

| FUNCTION | 8 BIT | 9 BIT | 10 BIT | 16 BIT | 18 BIT |
|--|------------------|-------|--------|------------------------|----------------|
| Transceiver | '245, '623, '645 | '863 | '861 | '16245, '16623 | '16863 |
| Buffer/Driver | '241, '244, '541 | | '827 | '16241, '16244, '16541 | '16825 |
| Latched transceiver | '543 | | | '16543 | '16472 |
| Latch | '373, '573 | '843 | '841 | '16373 | '16843 |
| Registered transceiver | '646, '652 | | | '16646, '16652 | '16474 |
| Flip-flop | '374, '574 | | '821 | '16374 | |
| Standard UBT | | | | | '16500, '16501 |
| Universal bus driver | | | | | '16835 |
| Registered transceiver with CLK enable | '2952 | | | '16470, '16952 | |
| Flip-flop with CLK enable | '377 | '823 | | | '16823 |
| Standard UBT with CLK enable | | | | | '16600, '16601 |
| SN74GTLPH1612 UBT replaces all above functions | | | | | |

functional description (continued)

Data flow in each direction is controlled by output-enable (\overline{OEAB} and \overline{OEBA}), latch-enable (LEAB and LEBA), and clock (CLKAB and CLKBA) inputs. The clock can be controlled by clock-enable (\overline{CEAB} and \overline{CEBA}) inputs. \overline{OEAB} and \overline{OEBA} control the 18 bits of data for the A-to-B and B-to-A directions, respectively.

For A-to-B data flow, the devices operate in the transparent mode when LEAB is high. When LEAB is low, the A data is latched if \overline{CEAB} is low and CLKAB is held at a high or low logic level. If LEAB is low, the A data is stored in the latch/flip-flop on the low-to-high transition of CLKAB if \overline{CEAB} also is low. When \overline{OEAB} is low, the outputs are active. When \overline{OEAB} is high, the outputs are in the high-impedance state.

Data flow for B to A is similar to that for A to B, buses \overline{OEBA} , LEBA, CLKBA, and \overline{CEBA} .

Function Tables

OUTPUT ENABLE†

| INPUTS | | | | | OUTPUT B | MODE |
|-------------------|-------------------|------|-------|---|----------------|---------------------------|
| \overline{CEAB} | \overline{OEAB} | LEAB | CLKAB | A | | |
| X | H | X | X | X | Z | Isolation |
| L | L | L | H | X | B_0^\ddagger | Latched storage of A data |
| L | L | L | L | X | B_0^\S | |
| X | L | H | X | L | L | Transparent |
| X | L | H | X | H | H | |
| L | L | L | ↑ | L | L | Clocked storage of A data |
| L | L | L | ↑ | H | H | |
| H | L | L | X | X | B_0^\S | Clock inhibit |

† A-to-B data flow is shown: B-to-A data flow is similar but uses \overline{OEBA} , LEBA, CLKBA, and \overline{CEBA} .

‡ Output level before the indicated steady-state input conditions were established, provided that CLKAB was high before LEAB went low

§ Output level before the indicated steady-state input conditions were established

B-PORT EDGE-RATE CONTROL (\overline{ERC})

| INPUT \overline{ERC} | | OUTPUT B-PORT EDGE RATE |
|------------------------|--------------------|-------------------------------|
| LOGIC LEVEL | NOMINAL VOLTAGE | |
| L | GND | Slow |
| H | V_{CC} | Fast |

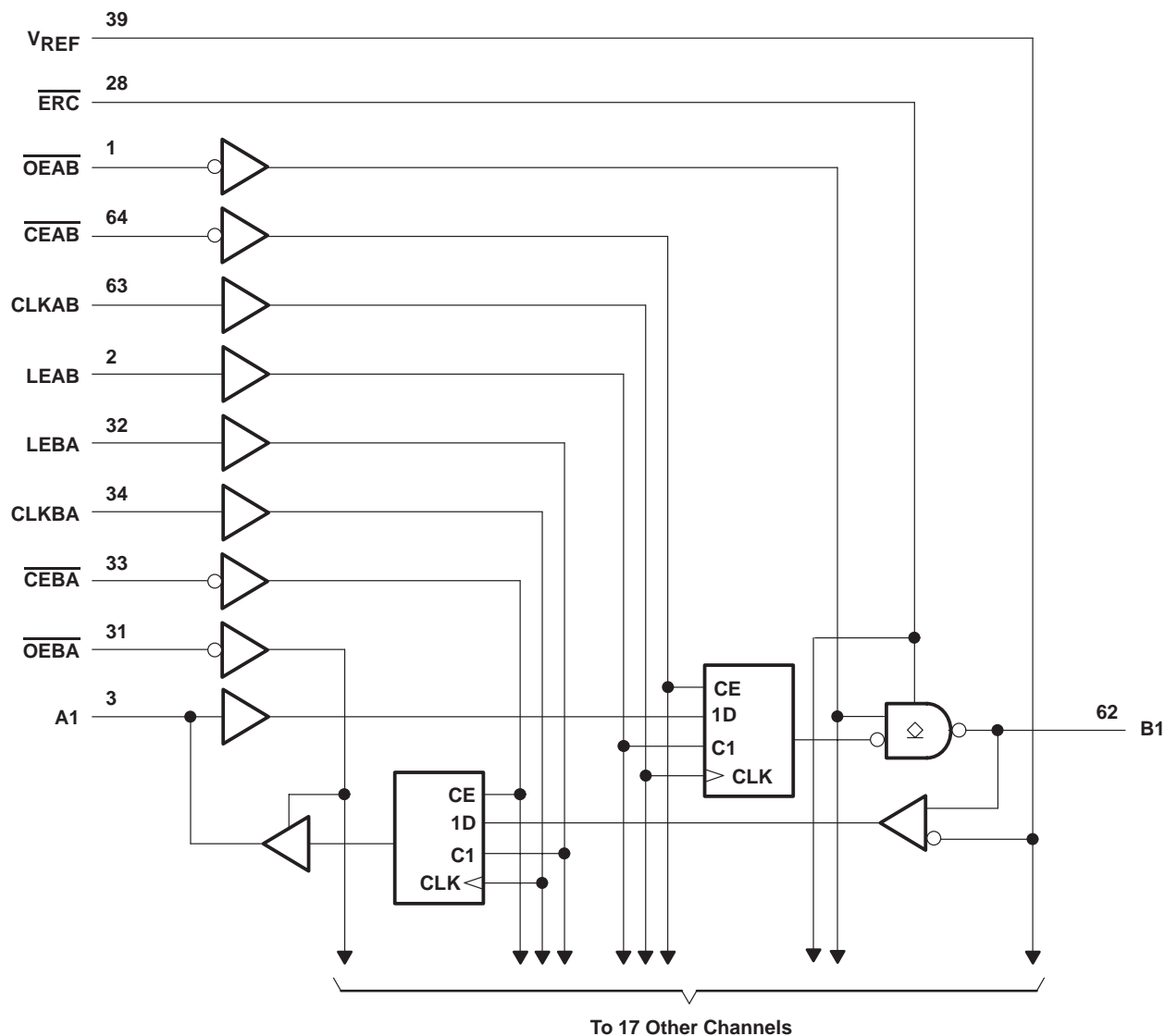
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logic diagram (positive logic)



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absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

| | |
|---|----------------------------|
| Supply voltage range, V_{CC} and BIAS V_{CC} | –0.5 V to 4.6 V |
| Input voltage range, V_I (see Note 1): A-port and control inputs | –0.5 V to 7 V |
| B port, \overline{ERC} , and V_{REF} | –0.5 V to 4.6 V |
| Voltage range applied to any output in the high-impedance or power-off state, V_O | |
| (see Note 1): A port | –0.5 V to 7 V |
| B port | –0.5 V to 4.6 V |
| Voltage range applied to any output in the high or low state, V_O | |
| (see Note 1): A port | –0.5 V to $V_{CC} + 0.5$ V |
| B port | –0.5 V to 4.6 V |
| Current into any output in the low state, I_O : A port | 48 mA |
| B port | 200 mA |
| Current into any A-port output in the high state, I_O (see Note 2) | 48 mA |
| Continuous current through each V_{CC} or GND | ± 100 mA |
| Input clamp current, I_{IK} ($V_I < 0$) | –50 mA |
| Output clamp current, I_{OK} ($V_O < 0$) | –50 mA |
| Package thermal impedance, θ_{JA} (see Note 3) | 55°C/W |
| Storage temperature range, T_{stg} | –65°C to 150°C |

† Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

- NOTES: 1. The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.
2. This current flows only when the output is in the high state and $V_O > V_{CC}$.
3. The package thermal impedance is calculated in accordance with JESD 51.

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recommended operating conditions (see Notes 4 through 6)

| | | | MIN | NOM | MAX | UNIT |
|---|--------------------------------|-----------------------|------------------------|-----------------|------|------|
| V _{CC} , BIAS V _{CC} | Supply voltage | | 3.15 | 3.3 | 3.45 | V |
| V _{TT} | Termination voltage | GTL | 1.14 | 1.2 | 1.26 | V |
| | | GTL+ | 1.35 | 1.5 | 1.65 | |
| V _{REF} | Supply voltage | GTL | 0.74 | 0.8 | 0.87 | V |
| | | GTL+ | 0.87 | 1 | 1.1 | |
| V _I | Input voltage | B port | V _{TT} | | | V |
| | | Except B port | V _{CC} | | | |
| V _{IH} | High-level input voltage | B port | V _{REF} +0.05 | | | V |
| | | ERC | V _{CC} −0.6 | V _{CC} | | |
| | | Except B port and ERC | 2 | | | |
| V _{IL} | Low-level input voltage | B port | V _{REF} −0.05 | | | V |
| | | ERC | GND | | | |
| | | Except B port and ERC | 0.8 | | | |
| I _{IK} | Input clamp current | | −18 | | | mA |
| I _{OH} | High-level output current | A port | −24 | | | mA |
| I _{OL} | Low-level output current | A port | 24 | | | mA |
| | | B port | 100 | | | |
| T _A | Operating free-air temperature | | −40 | 85 | | °C |

- NOTES: 4. All unused control and B-port inputs of the device must be held at V_{CC} or GND to ensure proper device operation. Refer to the TI application report, *Implications of Slow or Floating CMOS Inputs*, literature number SCBA004.
5. Normal connection sequence is GND first, BIAS $V_{CC}=3.3$ V second, and $V_{CC}=3.3$ V, I/O, control inputs, V_{TT} and V_{REF} (any order) last. However, if the B-port I/O precharge is not required, the acceptable connection sequence is GND first and $V_{CC}=3.3$ V, BIAS $V_{CC}=3.3$ V, I/O, control inputs, V_{TT} and V_{REF} (any order) last. When V_{CC} is connected, the BIAS V_{CC} circuitry is disabled.
6. V_{TT} and R_{TT} can be adjusted to accommodate backplane impedances as long as they do not exceed the DC absolute I_{OL} ratings. Similarly, V_{REF} can be adjusted to optimize noise margins, but normally is $2/3 V_{TT}$.

electrical characteristics over recommended operating free-air temperature range for GTL+ (unless otherwise noted)

| PARAMETER | | TEST CONDITIONS | | MIN | TYP† | MAX | UNIT |
|---------------------|---------------------------|--|--|---------------------------------------|------|------|------|
| V _{IK} | | V _{CC} = 3.15 V, I _I = −18 mA | | | | −1.2 | V |
| V _{OH} | A port | V _{CC} = 3.15 V to 3.45 V, I _{OH} = −100 μA | | V _{CC} −0.2 | | | V |
| | | V _{CC} = 3.15 V | | I _{OH} = −12 mA | | 2.4 | |
| | | | | I _{OH} = −24 mA | | 2 | |
| V _{OL} | A port | V _{CC} = 3.15 V to 3.45 V, I _{OL} = 100 μA | | | | 0.2 | V |
| | | V _{CC} = 3.15 V | | I _{OL} = 12 mA | | 0.4 | |
| | | | | I _{OL} = 24 mA | | 0.5 | |
| | B port | V _{CC} = 3.15 V | | I _{OL} = 10 mA | | 0.2 | |
| | | | | I _{OL} = 64 mA | | 0.4 | |
| | | | | I _{OL} = 100 mA | | 0.55 | |
| I _I ‡ | B port | V _{CC} = 3.45 V, V _I = 0 to 1.5 V | | | | ±10 | μA |
| | A-port and control inputs | V _{CC} = 3.45 V | | V _I = 0 or V _{CC} | | ±10 | |
| | | | | V _I = 5.5 V | | ±20 | |
| I _{BHL} § | A port | V _{CC} = 3.15 V, V _I = 0.8 V | | 75 | | | μA |
| I _{BHH} ¶ | A port | V _{CC} = 3.15 V, V _I = 2 V | | −75 | | | μA |
| I _{BHLO} # | A port | V _{CC} = 3.45 V, V _I = 0 to V _{CC} | | | | 500 | μA |
| I _{BHHO} | A port | V _{CC} = 3.45 V, V _I = 0 to V _{CC} | | | | −500 | μA |
| I _{CC} | A or B port | V _{CC} = 3.45 V, I _O = 0, V _I (A-port or control input) = V _{CC} or GND | | Outputs high | | 80 | mA |
| | | V _I (B port) = V _{TT} or GND | | Outputs low | | 80 | |
| | | | | Outputs disabled | | 80 | |
| ΔI _{CC} ☆ | | V _{CC} = 3.45 V, One A-port or control input at V _{CC} − 0.6 V, Other A-port or control inputs at V _{CC} or GND | | | | 1 | mA |
| C _i | Control inputs | V _I = 3.15 V or 0 | | | | | pF |
| C _{io} | A port | V _O = 3.15 V or 0 | | | | | pF |
| | B port | V _O = 1.5 V or 0 | | | | | |

† All typical values are at $V_{CC} = 3.3\text{ V}$, $T_A = 25^\circ\text{C}$.

‡ For I/O ports, the parameter I_I includes the off-state output leakage current.

§ The bus-hold circuit can sink at least the minimum low sustaining current at V_{ILmax} . I_{BHL} should be measured after lowering V_{IN} to GND and then raising it to V_{ILmax} .

¶ The bus-hold circuit can source at least the minimum high sustaining current at V_{IHmin} . I_{BHH} should be measured after raising V_{IN} to V_{CC} and then lowering it to V_{IHmin} .

An external driver must source at least I_{BHLO} to switch this node from low to high.

|| An external driver must sink at least I_{BHHO} to switch this node from high to low.

☆ This is the increase in supply current for each input that is at the specified TTL voltage level rather than V_{CC} or GND.

live-insertion specifications for A port over recommended operating free-air temperature range

| PARAMETER | TEST CONDITIONS | | | MIN | MAX | UNIT |
|------------|--|---------------------------------------|--|-----|-----------|---------------|
| I_{off} | $V_{CC} = 0$, | BIAS $V_{CC} = 0$, | V_I or $V_O = 0\text{ to } 5.5\text{ V}$ | | 100 | μA |
| I_{OZPU} | $V_{CC} = 0\text{ to } 1.5\text{ V}$, | $V_O = 0.5\text{ V to } 3\text{ V}$, | $\overline{OE} = 0$ | | ± 100 | μA |
| I_{OZPD} | $V_{CC} = 1.5\text{ V to } 0$, | $V_O = 0.5\text{ V to } 3\text{ V}$, | $\overline{OE} = 0$ | | ± 100 | μA |

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live-insertion specifications for B port over recommended operating free-air temperature range

| PARAMETER | TEST CONDITIONS | | | MIN | MAX | UNIT |
|---------------------------|-----------------------------|---|-----------------------------|-----------|------|---------|
| I_{off} | $V_{CC} = 0$, | BIAS $V_{CC} = 0$, | V_I or $V_O = 0$ to 1.5 V | 100 | | μA |
| I_{OZPU} | $V_{CC} = 0$ to 1.5 V, | $V_O = 0.5$ V to 1.5 V, | $\overline{OE} = 0$ | ± 100 | | μA |
| I_{OZPD} | $V_{CC} = 1.5$ V to 0, | $V_O = 0.5$ V to 1.5 V, | $\overline{OE} = 0$ | ± 100 | | μA |
| I_{CC} (BIAS V_{CC}) | $V_{CC} = 0$ to 3.15 V | BIAS $V_{CC} = 3.15$ V to 3.45 V, V_O (B port) = 0 to 1.5 V | | 5 | | mA |
| | $V_{CC} = 3.15$ V to 3.45 V | | | 10 | | μA |
| V_O | $V_{CC} = 0$, | BIAS $V_{CC} = 3.3$ V | | 0.95 | 1.05 | V |
| I_O | $V_{CC} = 0$, | BIAS $V_{CC} = 3.15$ V to 3.45 V, V_O (B port) = 0.6 V | | –1 | | μA |

timing requirements over recommended ranges of supply voltage and operating free-air temperature, $V_{TT} = 1.5$ V and $V_{REF} = 1$ V for GTL+ (normal mode) (unless otherwise noted)

| | | | MIN | MAX | UNIT |
|-------------|-----------------|---|-----|-----|------|
| f_{clock} | Clock frequency | | | | MHz |
| t_w | Pulse duration | LEAB or LEBA high | | | ns |
| | | CLKAB or CLKBA high or low | | | |
| t_{su} | Setup time | A before CLKAB \uparrow | | | ns |
| | | B before CLKBA \uparrow | | | |
| | | A before LEAB \downarrow , CLK = don't care | | | |
| | | B before LEBA \downarrow , CLK = don't care | | | |
| | | \overline{CEAB} before CLKAB \uparrow | | | |
| | | \overline{CEBA} before CLKBA \uparrow | | | |
| t_h | Hold time | A after CLKAB \uparrow | | | ns |
| | | B after CLKBA \uparrow | | | |
| | | A after LEAB \downarrow , CLK = don't care | | | |
| | | B after LEBA \downarrow , CLK = don't care | | | |
| | | \overline{CEAB} after CLKAB \uparrow | | | |
| | | \overline{CEBA} after CLKBA \uparrow | | | |

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switching characteristics over recommended ranges of supply voltage and operating free-air temperature, $V_{TT} = 1.5\text{ V}$ and $V_{REF} = 1\text{ V}$ for GTL+ (normal mode) (see Figure 1)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | EDGE RATE† | MIN | TYP‡ | MAX | UNIT |
|------------------|--|----------------|------------|-----|------|-----|------|
| f _{max} | | | | | | | MHz |
| t _{pd} | A | B | Slow | | | | ns |
| | | | Fast | | | | |
| | LEAB | B | Slow | | | | |
| | | | Fast | | | | |
| | CLKAB | B | Slow | | | | |
| | | | Fast | | | | |
| t _{en} | $\overline{\text{OEAB}}$ | B | Slow | | | ns | |
| t _{dis} | | | | | | | |
| t _{en} | $\overline{\text{OEAB}}$ | B | Fast | | | ns | |
| t _{dis} | | | | | | | |
| t _r | Rise time, B outputs (0.6 V to 1.3 V) | | Slow | | | ns | |
| | | | Fast | | | | |
| t _f | Fall time, B outputs (1.3 V to 0.6 V) | | Slow | | | ns | |
| | | | Fast | | | | |
| t _{pd} | B | A | | | | ns | |
| | LEBA | | | | | | |
| | CLKBA | | | | | | |
| t _{en} | $\overline{\text{OEBA}}$ | A | | | | ns | |
| t _{dis} | | | | | | | |

† Slow ($\overline{ERC} = GND$) and Fast ($\overline{ERC} = V_{CC}$)

‡ All typical values are at $V_{CC} = 3.3\text{ V}$, $T_A = 25^\circ\text{C}$.

PRODUCT PREVIEW



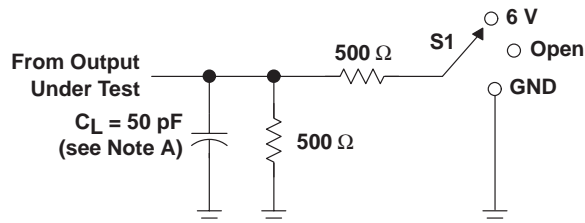
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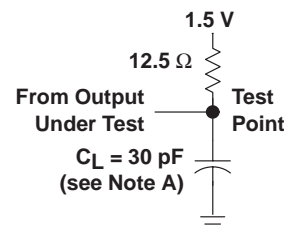
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PARAMETER MEASUREMENT INFORMATION

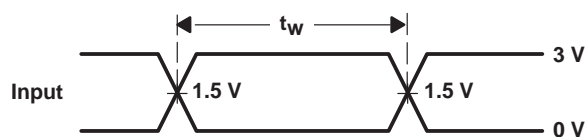


LOAD CIRCUIT FOR A OUTPUTS

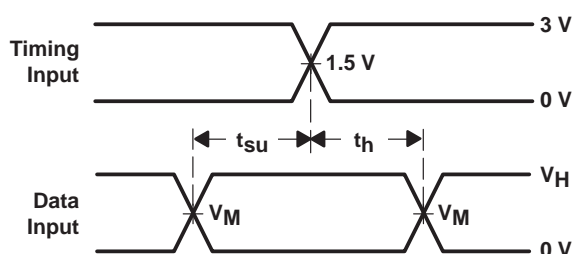
| TEST | S1 |
|-------------------|------|
| t_{PLH}/t_{PHL} | Open |
| t_{PLZ}/t_{PZL} | 6 V |
| t_{PHZ}/t_{PZH} | GND |



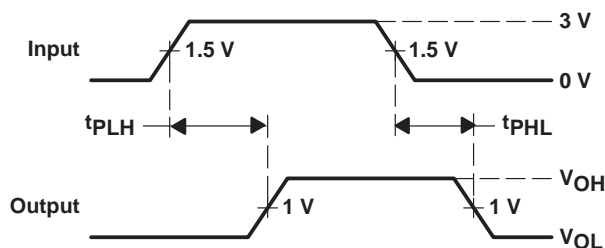
LOAD CIRCUIT FOR B OUTPUTS



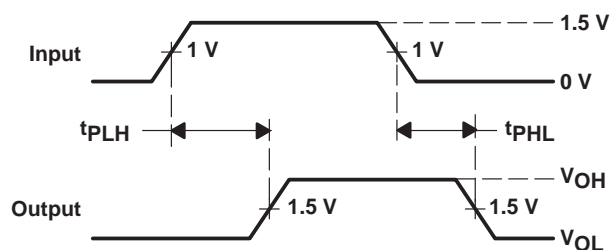
VOLTAGE WAVEFORMS
PULSE DURATION



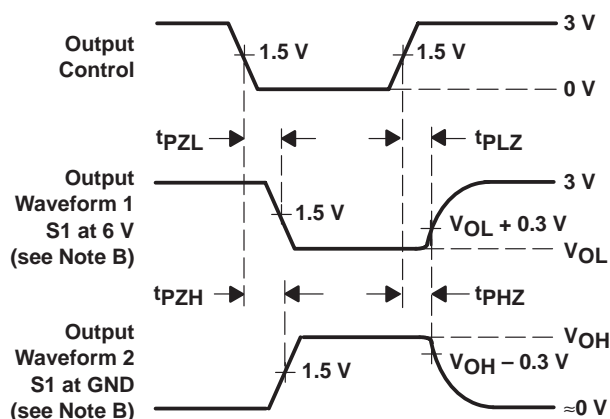
VOLTAGE WAVEFORMS
SETUP AND HOLD TIMES
($V_M = 1.5 \text{ V}$ for A port and 1 V for B port)
($V_H = 3 \text{ V}$ for A port and 1.5 V for B port)



VOLTAGE WAVEFORMS
PROPAGATION DELAY TIMES
(A port to B port)



VOLTAGE WAVEFORMS
PROPAGATION DELAY TIMES
(B port to A port)



VOLTAGE WAVEFORMS
ENABLE AND DISABLE TIMES
(A port)

- NOTES:
- C_L includes probe and jig capacitance.
 - Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
 - All input pulses are supplied by generators having the following characteristics: $PRR \leq 10 \text{ MHz}$, $Z_O = 50 \Omega$, slew rate $\leq 1 \text{ V/ns}$.
 - The outputs are measured one at a time with one transition per measurement.

Figure 1. Load Circuits and Voltage Waveforms

DISTRIBUTED-LOAD BACKPLANE SWITCHING CHARACTERISTICS

This data sheet is specified for and tested to the lump load shown in Figure 1. However, the designer probably uses this GTLP device in a distributed load like that shown in Figure 2, in which actual B-port backplane switching characteristics are different. Therefore, the device is modeled as shown in Figure 3, which very closely matches the results obtained using Figure 2. Switching characteristics based on Figure 3 more closely match actual backplane design requirements.

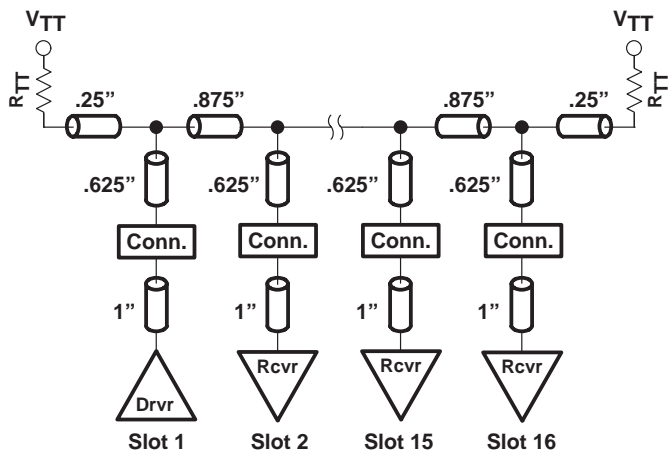


Figure 2. Test Backplane Model

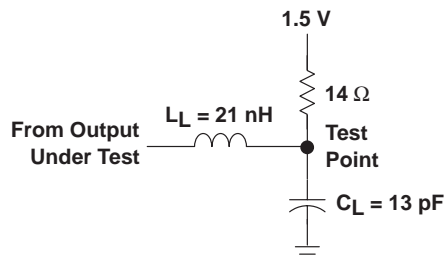


Figure 3. Distributed-Load Circuit for B Outputs

switching characteristics over recommended ranges of supply voltage and operating free-air temperature, $V_{TT} = 1.5 \text{ V}$ and $V_{REF} = 1 \text{ V}$ for GTL+ (see Figure 3)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | EDGE RATE† | MIN | TYP‡ | MAX | UNIT |
|------------------|--|----------------|------------|-----|------|-----|------|
| f _{max} | | | | | | | MHz |
| t _{pd} | A | B | Slow | | | | ns |
| | | | Fast | | | | |
| | LEAB | B | Slow | | | | |
| | | | Fast | | | | |
| | CLK | B | Slow | | | | |
| | | | Fast | | | | |
| t _{en} | $\overline{\text{OEAB}}$ | B | Slow | | | ns | |
| t _{dis} | | | | | | | |
| t _{en} | $\overline{\text{OEAB}}$ | B | Fast | | | ns | |
| t _{dis} | | | | | | | |
| t _r | Rise time, B outputs (0.6 V to 1.3 V) | | Slow | | | ns | |
| | | | Fast | | | | |
| t _f | Fall time, B outputs (1.3 V to 0.6 V) | | Slow | | | ns | |
| | | | Fast | | | | |

† Slow ($\overline{ERC} = GND$) and Fast ($\overline{ERC} = V_{CC}$)

‡ All typical values are at $V_{CC} = 3.3 \text{ V}$, $T_A = 25^\circ\text{C}$.

PRODUCT PREVIEW

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