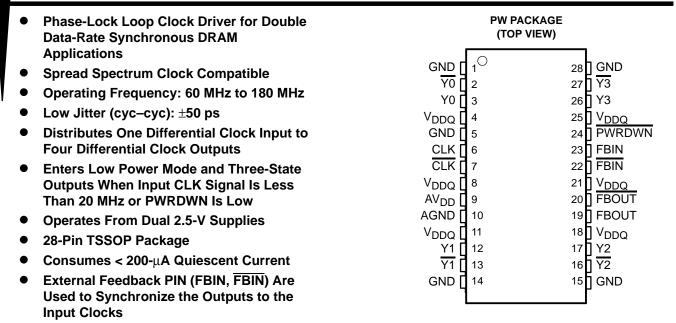
CDCV855, CDCV855I 2.5-V PHASE-LOCK LOOP CLOCK DRIVER

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description

The CDCV855 is a high-performance, low-skew, low-jitter zero delay buffer that distributes a differential clock input pair (CLK, $\overline{\text{CLK}}$) to four differential pairs of clock outputs (Y[0:3], $\overline{\text{Y[0:3]}}$) and one differential pair of feedback clock outputs (FBOUT, $\overline{\text{FBOUT}}$). When $\overline{\text{PWRDWN}}$ is high, the outputs switch in phase and frequency with CLK. When $\overline{\text{PWRDWN}}$ is low, all outputs are disabled to a high-impedance state (3-state), and the PLL is shut down (low-power mode). The device also enters this low-power mode when the input frequency falls below a suggested detection frequency that is below 20 MHz (typical 10 MHz). An input frequency detection circuit detects the low-frequency condition and after applying a >20-MHz input signal this detection circuit turns on the PLL again and enables the outputs.

When AV_{DD} is tied to GND, the PLL is turned off and bypassed for test purposes. The CDCV855 is also able to track spread spectrum clocking for reduced EMI.

Since the CDCV855 is based on PLL circuitry, it requires a stabilization time to achieve phase-lock of the PLL. This stabilization time is required following power up. The CDCV855 is characterized for both commercial and industrial temperature ranges.

AVAILABLE OPTIONS

T .	PACKAGED DEVICES
T _A	TSSOP (PW)
0°C to 70°C	CDCV855PW
-40°C to 85°C	CDCV855IPW



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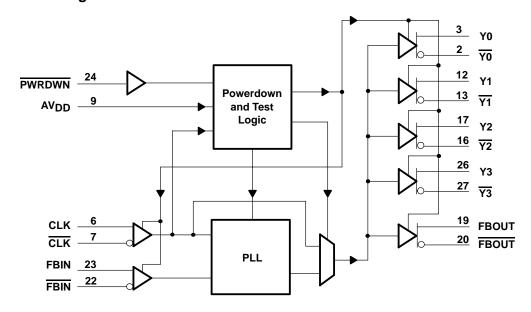


FUNCTION TABLE (Select Functions)

INPUTS					OUTPUTS			
AV _{DD}	PWRDWN	CLK	CLK	Y[0:3]	Y[0:3]	FBOUT	FBOUT	
GND	Н	L	Н	L	Н	L	Н	Bypassed/Off
GND	Н	Н	L	Н	L	Н	L	Bypassed/Off
X	L	L	Н	Z	Z	Z	Z	Off
X	L	Н	L	Z	Z	Z	Z	Off
2.5 V (nom)	Н	L	Н	L	Н	L	Н	On
2.5 V (nom)	Н	Н	L	Н	L	Н	L	On
2.5 V (nom)	Х	<20 MHz†	<20 MHz [†]	Z	Z	Z	Z	Off

[†] Typically 10 MHz

functional block diagram



Terminal Functions

TER	TERMINAL			
NAME	NO.	1/0	DESCRIPTION	
AGND	10		Ground for 2.5-V analog supply	
AV_{DD}	9		2.5-V analog supply	
CLK, CLK	6, 7	I	Differential clock input	
FBIN, FBIN	23, 22	I	Feedback differential clock input	
FBOUT, FBOUT	19, 20	0	Feedback differential clock output	
GND	1, 5, 14, 15, 28		Ground	
PWRDWN	24	ı	Control input to turn device in the power-down mode	
V_{DDQ}	4, 8, 11, 18, 21, 25		2.5-V supply	
Y[0:3]	3, 12, 17, 26	0	Buffered output copies of input clock, CLK	
<u>Y[0:3]</u>	2, 13, 16, 27	0	Buffered output copies of input clock, CLK	



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absolute maximum ratings over operating free-air temperature (unless otherwise noted)†

Supply voltage range, V _{DDQ} , AV _{DD}	
Input voltage range, V _I (see Notes 1 and 2)	$-0.5 \text{ V to V}_{DDQ} + 0.5 \text{ V}$
Output voltage range, VO (see Notes 1 and 2)	0.5 V to V _{DDQ} + 0.5 V
Input clamp current, I_{IK} ($V_I < 0$ or $V_I > V_{DDQ}$)	±50 mA
Output clamp current, I _{OK} (V _O < 0 or V _O > V _{DDO})	±50 mA
Continuous output current, I _O (V _O = 0 to V _{DDQ})	±50 mA
Continuous current to GND or V _{DDQ}	±100 mA
Package thermal impedance, θ _{JA} (see Note 3): PW package	105.8°C/W
Storage temperature range T _{stq}	–65°C to 150°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. The input and output negative voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

- 2. This value is limited to 3.6 V maximum.
- 3. The package thermal impedance is calculated in accordance with JESD 51.

recommended operating conditions (see Note 4)

		MIN	TYP	MAX	UNIT
Supply voltage, V _{DDQ} , AV _{DD}		2.3		2.7	V
Law law Band on tank	CLK, CLK, FBIN, FBIN			V _{DDQ} /2 – 0.18	
ow-level input voltage, V _{IL} igh-level input voltage, V _{IH} C input signal voltage (see Note 5) ifferential input signal voltage, V _{ID} (see Note 6) utput differential cross-voltage, V _{O(X)} (see Note 7 put differential pair cross-voltage, V _{I(X)} (see Note	PWRDWN	-0.3		0.7	V
I Pale Javed Secretaria Name A	CLK, CLK, FBIN, FBIN	V _{DDQ} /2 + 0.18			
High-level input voltage, VIH	PWRDWN	1.7		V _{DDQ} + 0.3	V
DC input signal voltage (see Note 5)		-0.3		V_{DDQ}	V
Differential input signal voltage, V _{ID} (see Note 6)	CLK, FBIN	0.36		V _{DDQ} + 0.6	V
Output differential cross-voltage, $V_{O(X)}$ (see Note 7)		V _{DDQ} /2 - 0.2	V _{DDQ} /2	V _{DDQ} /2 + 0.2	V
Input differential pair cross-voltage, $V_{I(X)}$ (see Note 7	7)	V _{DDQ} /2 - 0.2		$V_{DDQ}/2 + 0.2$	V
High-level output current, IOH				-12	mA
Low-level output current, IOL			12	mA	
Input slew rate, SR (see Figure 7)		1		4	V/ns
On senting from air to sent one T	Commercial	0		85	00
Operating free-air temperature, T _A	Industrial	-40		85	°C

NOTES: 4. Unused inputs must be held high or low to prevent them from floating.

- 5. DC input signal voltage specifies the allowable dc execution of differential input.
- 6. Differential input signal voltage specifies the differential voltage |VTR VCP| required for switching, where VTR is the true input level and VCP is the complementary input level.
- 7. Differential cross-point voltage is expected to track variations of V_{DDQ} and is the voltage at which the differential signals must be crossing.



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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST C	ONDITIONS	MIN	TYP†	MAX	UNIT	
VIK	Input voltage	All inputs	$V_{DDQ} = 2.3 V,$	I _I = -18 mA			-1.2	V
.,			V_{DDQ} = min to max, I_{OH} = -1 mA		V _{DDQ} - 0.1			
VOH	High-level output	voltage	V _{DDQ} = 2.3 V,	I _{OH} = -12 mA	1.7			V
.,			V _{DDQ} = min to max	c, I _{OL} = 1 mA			0.1	V
V_{OL}	Low-level output	voitage	$V_{DDQ} = 2.3 V,$	I _{OL} = 12 mA			0.6	V
ЮН	High-level output	current	$V_{DDQ} = 2.3 V$,	V _O = 1 V	-18	-32		mA
loL	Low-level output	current	$V_{DDQ} = 2.3 V$,	V _O = 1.2 V	26	35		mA
VOD	Output voltage sv	ving	Differential entents	and the marks at a disciplin	1.1		V _{DDQ} – 0.4	
VOX	Output differentia cross-voltage‡	I	Differential outputs are terminated with 120 Ω		V _{DDQ} /2 – 0.2	V _{DDQ} /2	V _{DDQ} /2 + 0.2	V
lį	Input current		$V_{DDQ} = 2.7 V,$	V _I = 0 V to 2.7 V			±10	μА
loz	High-impedance- current	state output	V _{DDQ} = 2.7 V,	$V_O = V_{DDQ}$ or GND			±10	μΑ
I _{DD(PD)}	Power-down curr V _{DDQ} + AV _{DD}	ent on	CLK and $\overline{\text{CLK}} = 0 \text{ N}$ Σ of IDD and AIDD	IHz; PWRDWN = Low;		100	200	μΑ
		.,	Differential outputs are terminated with 120 Ω / CL = 14 pF			150	180	
lDD	DD Dynamic current o		Differential outputs are terminated with 120 Ω / CL = 0 pF	f _O = 167 MHz		130	160	mA
AI_{DD}	Supply current or	n AV _{DD}	f _O = 167 MHz			8	10	mA
Cl	Input capacitance)	V _{DDQ} = 2.5 V	$V_I = V_{DDQ}$ or GND	2	2.5	3	pF
СО	Output capacitan	се	V _{DDQ} = 2.5 V	$V_O = V_{DDQ}$ or GND	2.5	3	3.5	pF

[†] All typical values are at respective nominal VDDQ.

timing requirements over recommended ranges of supply voltage and operating free-air temperature

	PARAMETER	MIN	MAX	UNIT
fCLK	Operating clock frequency	60	180	MHz
	Input clock duty cycle	40%	60%	
	Stabilization time (PLL mode)		10	μs
	Stabilization time (Bypass mode)§		30	ns

[§] Recovery time required when the device goes from power-down mode into bypass mode (test mode with AV_{DD} at GND).



[‡] Differential cross-point voltage is expected to track variation of VDDQ and is the voltage at which the differential signals must be crossing.

Time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal. For phase lock to be obtained, a fixed-frequency, fixed-phase reference signal must be present at CLK. Until phase lock is obtained, the specifications for propagation delay, skew, and jitter parameters given in the switching characteristics table are not applicable. This parameter does not apply for input modulation under SSC application.

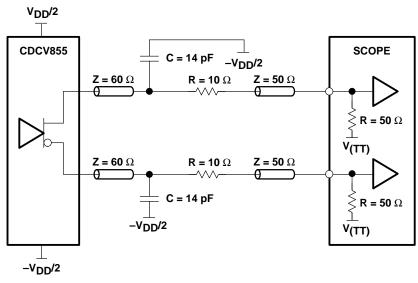
switching characteristics

	PARAMETER	TES	T CONDITIONS	MIN	TYP [†] MAX	UNIT
tPLH [‡]	Low-to-high level propagation delay time	Test mod	Test mode/CLK to any output		4.5	ns
[‡]	High-to-low level propagation delay time	Test mode/CLK to any output			4.5	ns
	W. (1 N O T)	66 MHz		-55	55	ps
^t jit(per) [§]	Jitter (period), See Figure 5	100/133/	167/180 MHz	-35	35	ps
. 8	W. ()	66 MHz		-60	60	
t _{jit(cc)} §	Jitter (cycle-to-cycle), See Figure 2	100/133/	100/133/167/180 MHz		50	ps
		66 MHz		-130	130	
^t jit(hper) [§]	Half-period jitter, See Figure 6	100 MHz		-90	90	ps
, , ,			133/167/180 MHz		75	·
	0	Load = 120Ω / 14 pF		1	2	V/ns
^t slr(o)	Output clock slew rate, See Figure 7	Load = 12	20Ω / 4 pF	1	3	V/ns
	Dynamic phase offset (this includes jitter),	SSC off	66 MHz	-180	180	ps
			100/133 MHz	-130	130	
. 8			167/180 MHz	-90	90	
^t d(Ø) [§]	See Figure 3(b)		66 MHz	-230	230	
		SSC on	100/133 MHz	-170	170	
			167/180 MHz	-100	100	
	0	66 MHz	66 MHz		150	
^t (Ø)	Static phase offset, See Figure 3(a)		100/133/167/180 MHz		100	ps
tsk _(O) ¶	Output skew, See Figure 4				50	ps
tr, tf	Output rise and fall times (20% – 80%)	Load: 120) Ω/14 pF	650	900	ps

[†] All typical values are at a respective nominal V_{DDQ}. ‡ Refers to transition of noninverting output

[§] This parameter is assured by design but can not be 100% production tested. ¶ All differential output pins are terminated with 120 Ω /14 pF.

PARAMETER MEASUREMENT INFORMATION



NOTE: $V_{(TT)} = GND$

Figure 1. Output Load Test Circuit

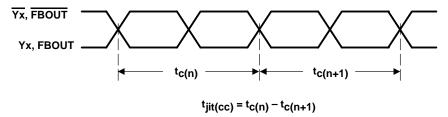
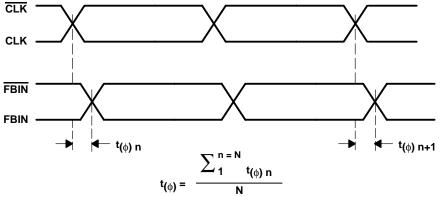


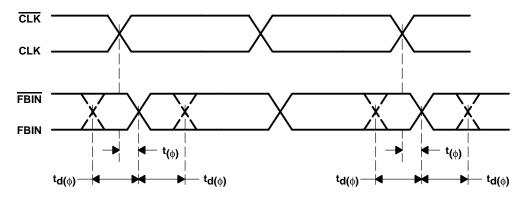
Figure 2. Cycle-to-Cycle Jitter

PARAMETER MEASUREMENT INFORMATION



(N is a Large Number of Samples)

(a) Static Phase Offset



(b) Dynamic Phase Offset

Figure 3. Phase Offset

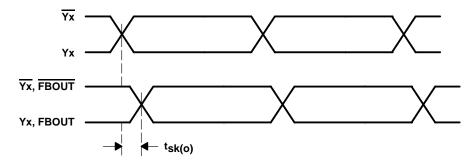


Figure 4. Output Skew

PARAMETER MEASUREMENT INFORMATION

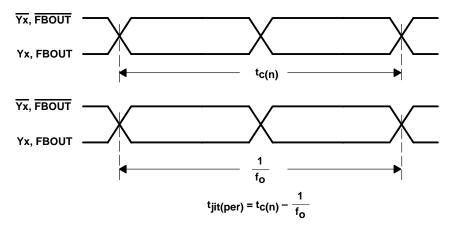


Figure 5. Period Jitter

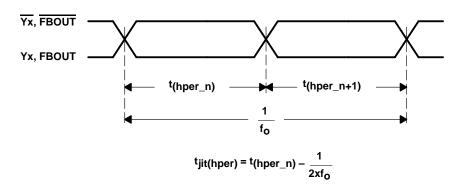


Figure 6. Half-Period Jitter

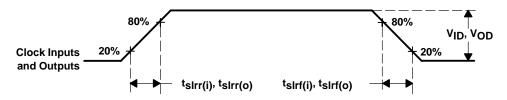


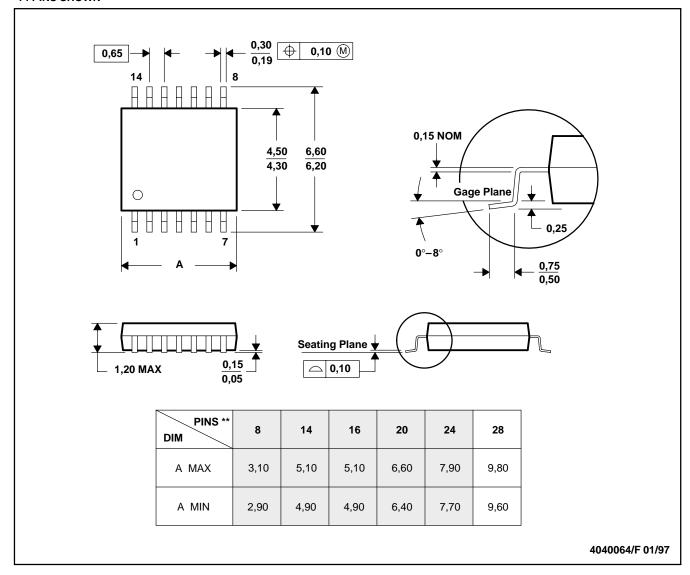
Figure 7. Input and Output Slew Rates

MECHANICAL DATA

PW (R-PDSO-G**)

14 PINS SHOWN

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.

D. Falls within JEDEC MO-153

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