### CDC2516供应商

### CDC2516 3.3-V PHASE-LOCK LOOP CLOCK DRIVER

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<ul> <li>Phase-Lock Loop Clock Distribution for Synchronous DRAM Applications</li> </ul>	DGG PACKAGE (TOP VIEW)		
<ul> <li>Distributes One Clock Input to Four Banks of Four Outputs</li> </ul>	V <sub>CC</sub> [		8 V <sub>CC</sub>
<ul> <li>Separate Output Enable for Each Output Bank</li> </ul>	1Y0 [ 1Y1 [	3 4	.7    4Y0 .6    4Y1
<ul> <li>External Feedback Pin (FBIN) Is Used to Synchronize the Outputs to the Clock Input</li> </ul>	GND [ GND [ 1Y2 [	5 4	5 GND 4 GND
On-Chip Series-Damping Resistors	1Y3 [	7 4	3 4Y2 2 4Y3
<ul> <li>No External RC Network Required</li> <li>Operates at 3.3-V V<sub>CC</sub></li> </ul>	V <sub>CC</sub> [ 1G [	9 4	1 0 V <sub>CC</sub> 0 4 G
<ul> <li>Packaged in Plastic 48-Pin Thin Shrink Small-Outline Package</li> </ul>	GND [ AV <sub>CC</sub> [	11 3	9 GND 8 AV <sub>CC</sub>
description	CLK [ AGND [	13 3	
The CDC2516 is a high-performance, low-skew,	AGND [ GND [	15 3	5 FBOUT
low-jitter, phase-lock loop (PLL) clock driver. It uses a PLL to precisely align, in both frequency and phase, the feedback output (FBOUT) to the	2G [ V <sub>CC</sub> [ 2Y0 [	17 3	3 3G 2 V <sub>CC</sub> 1 3Y0
clock (CLK) input signal. It is specifically designed	2Y1 [	19 3	0 3Y1
for use with synchronous DRAMs. The CDC2516 operates at 3.3-V $V_{CC}$ and provides integrated	GND [ GND [	21 2	9 GND 8 GND
series-damping resistors that make it ideal for driving point-to-point loads.	2Y2 [ 2Y3 [	23 2	7   3Y2 6   3Y3
Four banks of four outputs provide 16 low-skew,	V <sub>CC</sub> [	24 2	5 V <sub>CC</sub>

Four banks of four outputs provide 16 low-skew, low-jitter copies of the input clock. Output signal duty cycles are adjusted to 50 percent, independent of the duty cycle at the input clock. Each bank of outputs can be enabled or disabled separately via the 1G, 2G, 3G, and 4G control inputs. When the G inputs are high, the outputs switch in phase and frequency with CLK; when the G inputs are low, the outputs are disabled to the logic-low state.

Unlike many products containing PLLs, the CDC2516 does not require external RC networks. The loop filter for the PLL is included on-chip, minimizing component count, board space, and cost.

Because it is based on PLL circuitry, the CDC2516 requires a stabilization time to achieve phase lock of the feedback signal to the reference signal. This stabilization time is required following power up and application of a fixed-frequency, fixed-phase signal at CLK, as well as following any changes to the PLL reference or feedback signals. The PLL may be bypassed for test purposes by strapping AV<sub>CC</sub> to ground.

The CDC2516 is characterized for operation from 0°C to 70°C.



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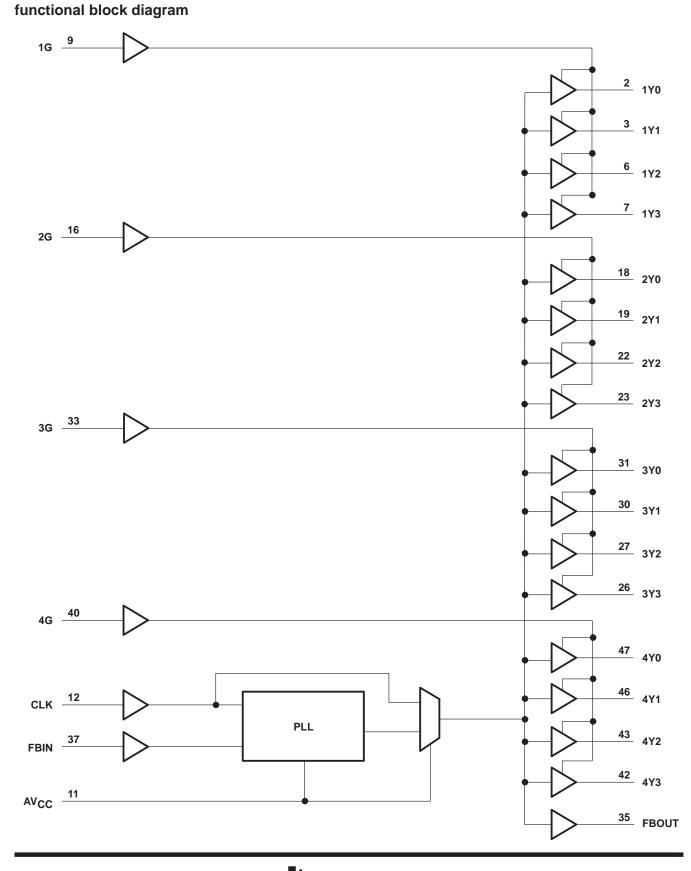
				FUNCTIO	ON TABI	.E			
	INPUTS				OUTPUTS				
1G	2G	3G	4G	CLK	1Y (0:3)	2Y (0:3)	3Y (0:3)	4Y (0:3)	FBOUT
Х	Х	Х	Х	L	L	L	L	L	L
L	L	L	L	Н	L	L	L	L	Н
L	L	L	Н	Н	L	L	L	Н	Н
L	L	Н	L	Н	L	L	Н	L	Н
L	L	Н	Н	Н	L	L	Н	Н	Н
L	Н	L	L	Н	L	Н	L	L	Н
L	Н	L	Н	Н	L	Н	L	Н	Н
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н	L	Н	L	Н	Н	L	Н	L	Н
н	L	Н	Н	Н	н	L	Н	Н	Н
н	Н	L	L	Н	н	Н	L	L	Н
н	Н	L	Н	Н	н	Н	L	Н	Н
н	Н	Н	L	Н	н	Н	Н	L	Н
н	Н	Н	Н	Н	Н	Н	Н	Н	Н

#### **AVAILABLE OPTIONS**

	PACKAGE				
TA	SMALL OUTLINE (DGG)				
0°C to 70°C	CDC2516DGGR				



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#### **Terminal Functions**

TE	RMINAL	TVDE	DECODIDATION
NAME	NO.	TYPE	DESCRIPTION
CLK	12	I	Clock input. CLK provides the clock signal to be distributed by the CDC2516 clock driver. CLK is used to provide the reference signal to the integrated PLL that generates the clock output signals. CLK must have a fixed frequency and fixed phase for the PLL to obtain phase lock. Once the circuit is powered up and a valid CLK signal is applied, a stabilization time is required for the PLL to phase lock the feedback signal to its reference signal.
FBIN	37	I	Feedback input. FBIN provides the feedback signal to the internal PLL. FBIN must be hard-wired to FBOUT to complete the PLL. The integrated PLL synchronizes CLK and FBIN so that there is nominally zero phase error between CLK and FBIN.
1G	9	I	Output bank enable. 1G is the output enable for outputs $1Y(0:3)$ . When 1G is low, outputs $1Y(0:3)$ are disabled to a logic-low state. When 1G is high, all outputs $1Y(0:3)$ are enabled and switch at the same frequency as CLK.
2G	16	I	Output bank enable. 2G is the output enable for outputs $2Y(0:3)$ . When 2G is low, outputs $2Y(0:3)$ are disabled to a logic-low state. When 2G is high, all outputs $2Y(0:3)$ are enabled and switch at the same frequency as CLK.
3G	33	I	Output bank enable. 3G is the output enable for outputs 3Y(0:3). When 3G is low, outputs 3Y(0:3) are disabled to a logic-low state. When 3G is high, all outputs 3Y(0:3) are enabled and switch at the same frequency as CLK.
4G	40	I	Output bank enable. 4G is the output enable for outputs $4Y(0:3)$ . When 4G is low, outputs $4Y(0:3)$ are disabled to a logic-low state. When 4G is high, all outputs $4Y(0:3)$ are enabled and switch at the same frequency as CLK.
FBOUT	35	ο	Feedback output. FBOUT is dedicated for external feedback. It switches at the same frequency as CLK. When externally wired to FBIN, FBOUT completes the feedback loop of the PLL. FBOUT has an integrated $25$ - $\Omega$ series-damping resistor.
1Y(0:3)	2, 3, 6, 7	ο	Clock outputs. These outputs provide low-skew copies of CLK. Outputs $1Y(0:3)$ are enabled via 1G. These outputs can be disabled to a logic-low state by deasserting the 1G control input. Each output has an integrated 25- $\Omega$ series-damping resistor.
2Y(0:3)	18, 19, 22, 26	ο	Clock outputs. These outputs provide low-skew copies of CLK. Outputs 2Y(0:3) are enabled via 2G. These outputs can be disabled to a logic-low state by deasserting the 2G control input. Each output has an integrated 25- $\Omega$ series-damping resistor.
3Y(0:3)	31, 30, 27, 26	ο	Clock outputs. These outputs provide low-skew copies of CLK. Outputs $3Y(0:3)$ are enabled via 3G. These outputs can be disabled to a logic-low state by deasserting the 3G control input. Each output has an integrated 25- $\Omega$ series-damping resistor.
4Y(0:3)	47, 46, 43, 42	ο	Clock outputs. These outputs provide low-skew copies of CLK. Outputs 4Y(0:3) are enabled via 4G. These outputs can be disabled to a logic-low state by deasserting the 4G control input. Each output has an integrated 25- $\Omega$ series-damping resistor.
AVCC	11, 38	Power	Analog power supply. AV <sub>CC</sub> provides the power reference for the analog circuitry. In addition, AV <sub>CC</sub> can be used to bypass the PLL for test purposes. When AV <sub>CC</sub> is strapped to ground, the PLL is bypassed and CLK is buffered directly to the device outputs.
AGND	13, 14, 36	Ground	Analog ground. AGND provides the ground reference for the analog circuitry.
VCC	1, 8, 17, 24, 25, 32, 41, 48	Power	Power supply
GND	4, 5, 10, 15, 20, 21, 28, 29, 34, 39, 44, 45	Ground	Ground



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#### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)<sup>†</sup>

Supply voltage range, V <sub>CC</sub> Input voltage range, V <sub>I</sub> (see Note 1) Voltage range applied to any output in the high	
or low state, $V_O$ (see Notes 1 and 2)	–0.5 V to Vcc + 0.5 V
Input clamp current, $I_{IK}$ ( $V_I < 0$ )	
Output clamp current, $I_{OK}$ ( $V_O$ < 0 or $V_O$ > $V_{CC}$ )	
Continuous output current, $I_O (V_O = 0 \text{ to } V_{CC})$	±50 mA
Continuous current through each V <sub>CC</sub> or GND	±100 mA
Maximum power dissipation at $T_A = 55^{\circ}C$ (in still air) (see Note 3)	0.85 W
Storage temperature range, T <sub>stg</sub>	–65°C to 150°C

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

2. This value is limited to 4.6 V maximum.

3. The maximum package power dissipation is calculated using a junction temperature of 150°C and a board trace length of 750 mils. For more information, refer to the *Package Thermal Considerations* application note in the *ABT Advanced BiCMOS Technology Data Book*, literature number SCBD002.

#### recommended operating conditions (see Note 4)

		MIN	MAX	UNIT
Vcc	Supply voltage	3	3.6	V
VIH	High-level input voltage	2		V
VIL	Low-level input voltage		0.8	V
VI	Input voltage	0	VCC	V
ЮН	High-level output current		-12	mA
IOL	Low-level output current		12	mA
Т <sub>А</sub>	Operating free-air temperature	0	70	°C
		0	10	

NOTE 4: Unused inputs must be held high or low to prevent them from floating.

# electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST C	ONDITIONS	V <sub>CC</sub>	MIN	TYP‡	MAX	UNIT
VIK	Ij = -18 mA		3 V			-1.2	V
	I <sub>OH</sub> = -100 μA		MIN to MAX	V <sub>CC</sub> -0.2			
VOH	I <sub>OH</sub> = -12 mA		3 V	2.4			V
	$I_{OH} = -6 \text{ mA}$		3 V	2.1			
	I <sub>OL</sub> = 100 μA		MIN to MAX			0.2	
VOL	I <sub>OL</sub> = 12 mA		3 V			0.8	V
	I <sub>OL</sub> = 6 mA		3 V			0.55	
Ц	$V_I = V_{CC}$ or GND		3.6 V			±5	μA
ICC§	$V_I = V_{CC}$ or GND	$I_{O} = 0$ , Outputs: low or high	3.6 V			20	μA
ΔICC	One input at V <sub>CC</sub> – 0.6 V,	Other inputs at $V_{CC}$ or GND	3.3 V to 3.6 V			500	μA
Ci	$V_I = V_{CC}$ or GND		3.3 V		4		pF
Co	$V_{O} = V_{CC}$ or GND		3.3 V		6		pF

<sup>‡</sup> For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions.

For I<sub>CC</sub> of AV<sub>CC</sub>, see Figure 5. For dynamic digital I<sub>CC</sub>, see Figure 6.



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# timing requirements over recommended ranges of supply voltage and operating free-air temperature

		MIN	MAX	UNIT
fclock	Clock frequency	25	125	MHz
	Input clock duty cycle	40%	60%	
	Stabilization time <sup>†</sup>		1	ms

<sup>†</sup> Time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal. For phase lock to be obtained, a fixed-frequency, fixed-phase reference signal must be present at CLK. Until phase lock is obtained, the specifications for propagation delay, skew, and jitter parameters given in the switching characteristics table are not applicable.

# switching characteristics over recommended ranges of supply voltage and operating free-air temperature, $C_L = 30 \text{ pF}$ (see Note 5 and Figures 1 and 2)<sup>‡</sup>

PARAMETER	FROM (INPUT)	TO (OUTPUT)	V <sub>CC</sub> = 3.3 V ± 0.165 V			V <sub>CC</sub> = 3.3 V ± 0.3 V			UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	
<sup>t</sup> phase error reference (see Figure 3)	66 MHz < CLKIN↑ < 100 MHz	FBIN↑					-0.70.18		ns
<sup>t</sup> phase error, – jitter, (see Note 6)	CLKIN↑ = 100 MHz	FBIN↑	-360		50		-170		ps
t <sub>sk(o)</sub> §	Any Y or FBOUT	Any Y or FBOUT						200	ps
Jitter(pk-pk)	F(clkin > 66 MHz)	Any Y or FBOUT				-100		100	ps
Duty avala	F(clkin ≤ 66 MHz)	Any Y or FBOUT				45%		55%	
Duty cycle	F(clkin > 66 MHz)	Any Y or FBOUT				43%		55%	
tr		Any Y or FBOUT		1.3	1.9	0.7		2.1	ns
tf		Any Y or FBOUT		1.7	2.5	1.2		2.5	ns

<sup>‡</sup>These parameters are not production tested.

 $\$  The t<sub>sk(0)</sub> specification is only valid for equal loading of all outputs.

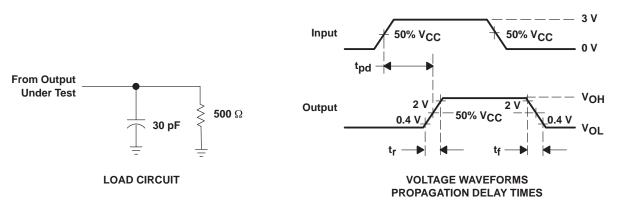
NOTES: 5. The specifications for parameters in this table are applicable only after any appropriate stabilization time has elapsed.

6. Phase error does not include jitter. The total phase error is -460 ps to 150 ps for the 5% V<sub>CC</sub> range.



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#### PARAMETER MEASUREMENT INFORMATION



NOTES: A. CL includes probe and jig capacitance.

- B. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  100 MHz, Z<sub>O</sub> = 50  $\Omega$ , t<sub>r</sub>  $\leq$  1.2 ns, t<sub>f</sub>  $\leq$  1.2 ns.
- C. The outputs are measured one at a time with one transition per measurement.

#### Figure 1. Load Circuit and Voltage Waveforms



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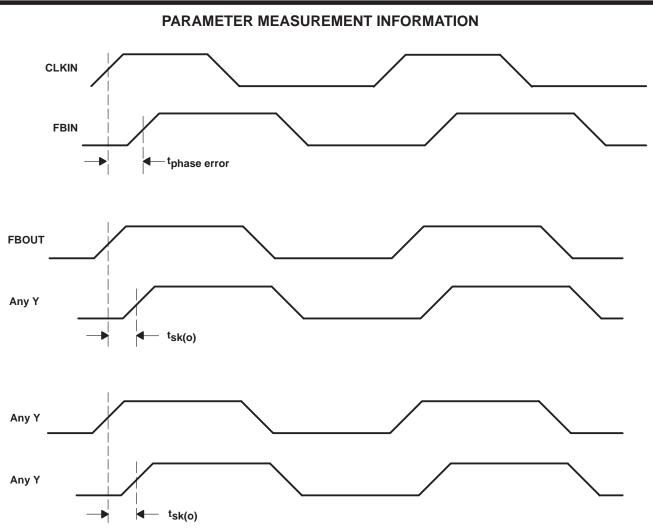
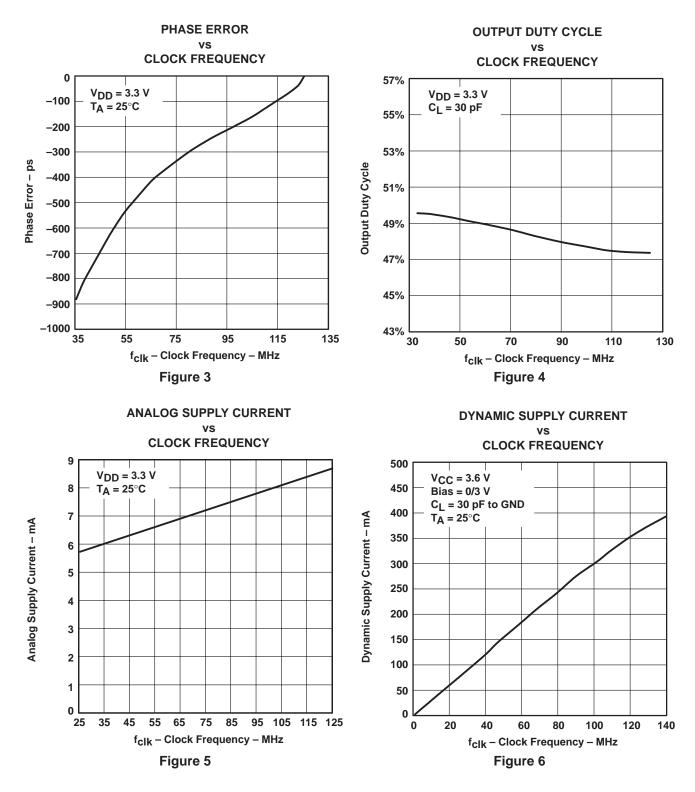


Figure 2. Phase Error and Skew Calculations



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#### **TYPICAL CHARACTERISTICS**



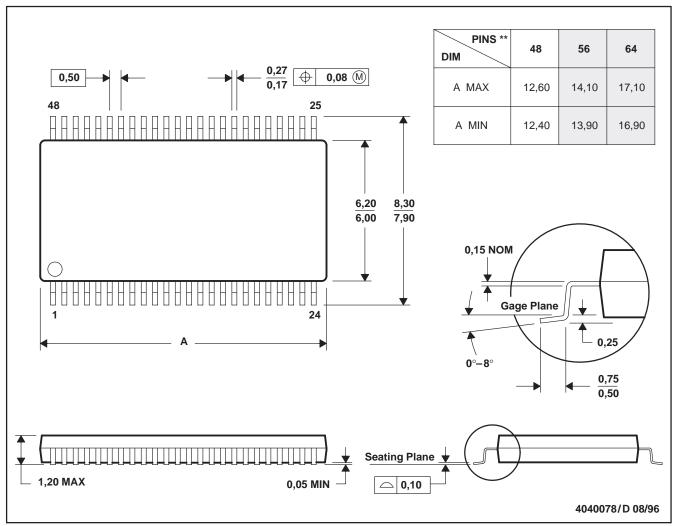
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#### **MECHANICAL INFORMATION**

#### DGG (R-PDSO-G\*\*)

#### PLASTIC SMALL-OUTLINE PACKAGE

#### **48 PIN SHOWN**



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MO-153



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