

ASSP

Bidirectional Motor Driver

MB3763H

■ DESCRIPTION

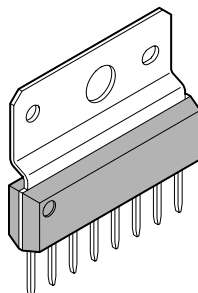
Fujitsu's MB3763H Motor Driver with forward/reverse control capability, is used in applications such as the front-loading mechanism in video cassette recorder or the auto-reverse tape deck, driven by a TTL signal. The MB3763H has 300 mA drive units and braking capability with TTL control. The MB3763H has wider power supply voltage range comparison with MB3763H. Suitable for 24V monitors for office automation equipments.

■ FEATURES

- Motor drive current: 300 mA maximum
- Wide power supply voltage range: 4 V to 28 V
- TTL-control capability
- Standby capability when input is off.
- Brake capability at motor stop mode.
- Built-in diode for surge absorption.
- Package: 8-pin plastic SIP package (Suffix: -PS)

■ PACKAGE

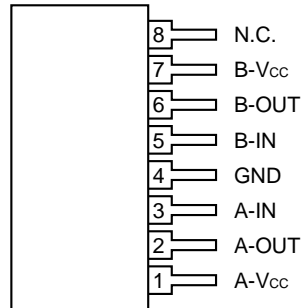
8-pin plastic SIP



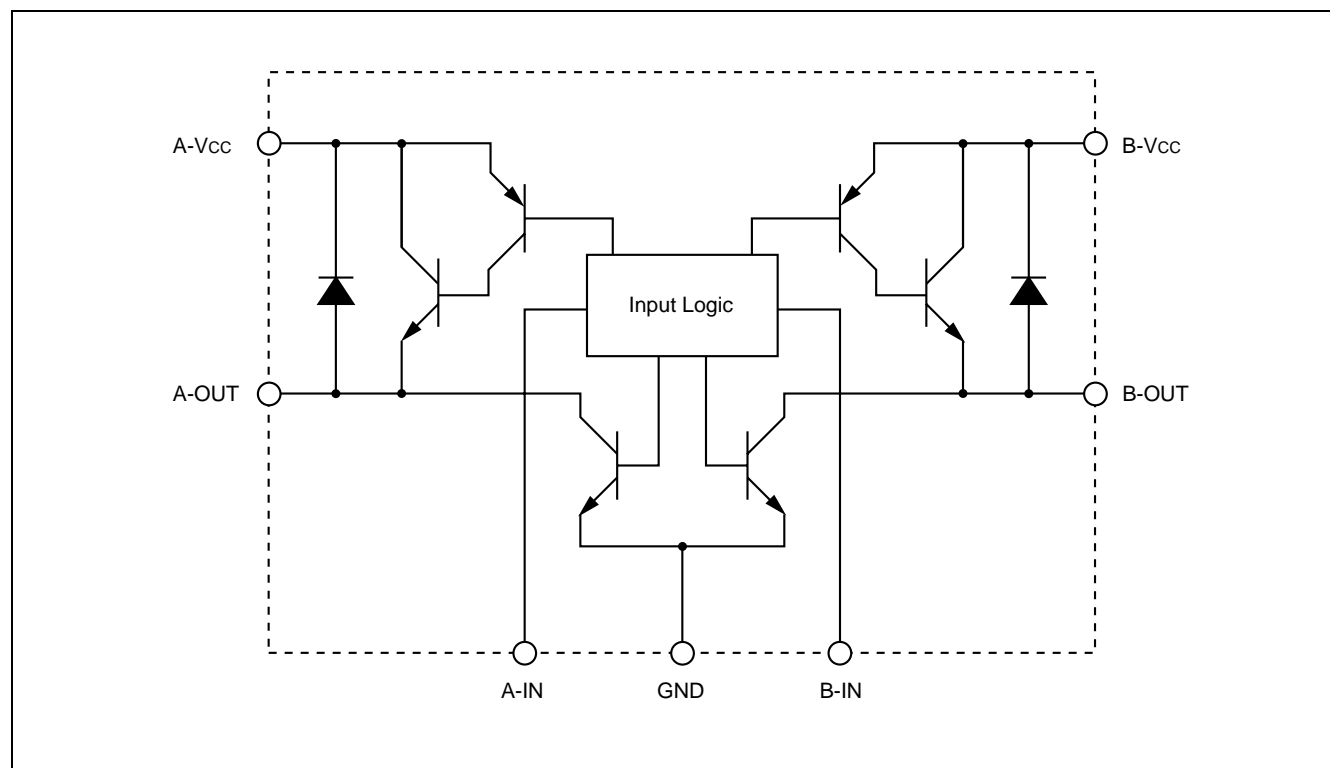
(SIP-8P-M01)

■ PIN ASSIGNMENT

(FRONT VIEW)



■ BLOCK DIAGRAM



■ ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Rating		Unit
		Min.	Max.	
Power supply voltage	V _{CC}	—	28	V
Output current	I _O	—	550* ¹	mA
Maximum output current	I _O MAX* ³	—	1.2	A
Power dissipation	P _D	—	2* ²	W
Operating temperature	T _{op}	−20	+75	°C
Storage temperature	T _{STG}	−55	+125	°C

Notes: *1 $t_{on} \leq 1$ s, Duty = 50%

*2 $T_a \leq 30^\circ\text{C}$

*3 $t \leq 5$ ms

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Value		Unit
		Min.	Max.	
Power supply voltage	V _{CC}	4	28	V
Output current	I _O	0	300 (500* ¹)	mA
Input high voltage	V _{IH} * ²	2.4	V _{CC} + 0.3	V
Input low voltage	V _{IL}	0	0.4	V

Notes: *1 $t_{on} \leq 1$ s, Duty = 50%

*2 When $V_{IH} \geq V_{CC}$, $I_{IH} \leq V_{CC} \times 0.2$ mA

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

■ ELECTRICAL CHARACTERISTICS

($V_{CC} = 24V$, $I_o = 300\text{ mA}$, $T_a = +25^\circ\text{C}$)

Parameter	Symbol	Condition	Value			Unit
			Min.	Typ.	Max.	
Standby supply current	I_{CC0}	$V_{CC} = 24\text{ V}$, $V_{IA} = V_{IB} = 0\text{ V}$	—	—	0.1	mA
Power supply current	I_{CC1}	$I_o = 0\text{ mA}$	—	12	27	mA
	I_{CC2}	$I_o = 300\text{ mA}$	—	15	—	mA
	I_{CC3}	$I_o = 0\text{ mA}$, $V_{IA} = V_{IB} = 2.4\text{ V}$	—	18	—	mA
Output high voltage	V_{OH}	—	22.8	23.1	—	V
Output low voltage	V_{OL}	—	—	0.2	0.5	V
Output saturation voltage	V_{SAT}	—	—	1.1	1.7	V
Input current	I_{IH}	$V_{IN} = 2.4\text{ V}$	—	250	400	μA
Input switching prohibition time	T_{OFF}	—	10	—	—	μs

■ FUNCTIONAL DESCRIPTIONS

FORWARD/REVERSE MODE (MODE B & C)

In this mode, the transistor pairs Q2-Q3 and Q1-Q4 work alternatively, changing the output current direction.

When the mode B is selected, Q2 and Q3 are active and Q1 and Q4 are inactive. Therefore A-OUT is at low level and B-OUT is at high level, with the current flowing from B-OUT to A-OUT through the motor. On the other hand, when the mode C is selected, the current flows in the reverse direction.

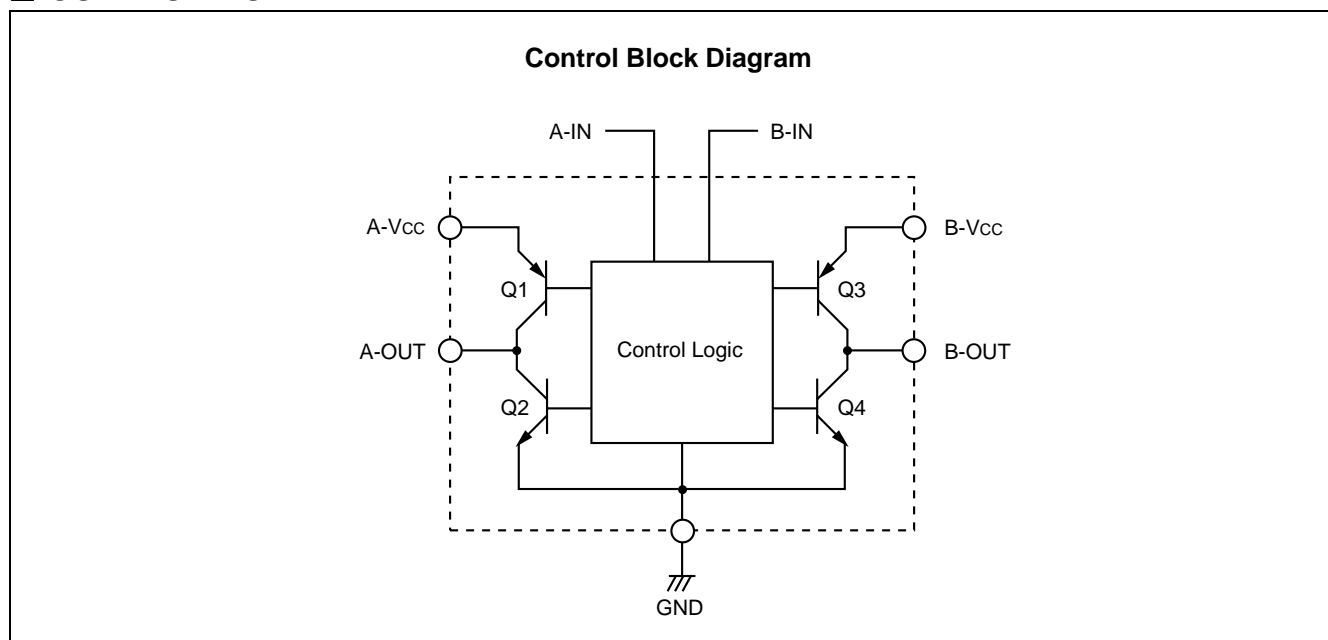
BRAKE/STOP MODE (MODE A)

When the mode A is selected, Q1 and Q3 are inactive and Q2 and Q4 are active. A-OUT and B-OUT are stuck at low-level; terminal of motor are shorted and the motor is forced to stop.

STANDBY MODE (MODE D)

In this mode, all transistors are inactive and the current through the motor does not flow. When the power supply voltage is applied to A-Vcc and B-Vcc, the supply current is still less than or equal to 0.1 mA.

■ CONTROL MODE

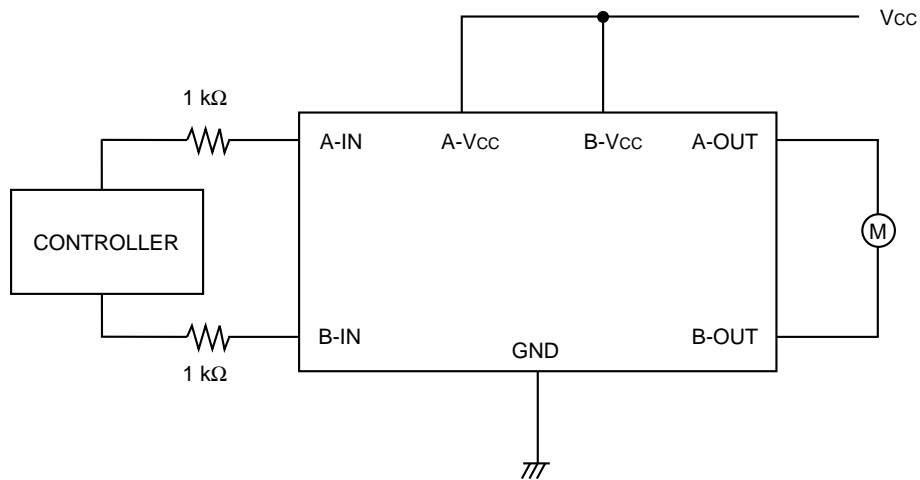


Mode	Input mode		Output mode		Operation
	A-IN	B-IN	A-OUT	B-OUT	
A	1	1	L	L	Short (Brake)
B	1	0	L	H	Forward
C	0	1	H	L	Reverse
D	0	0	—	—	Open (Standby)

Notes: 1: $\geq 2.4 \text{ V}$
0: $\leq 0.4 \text{ V}$

■ TYPICAL APPLICATION

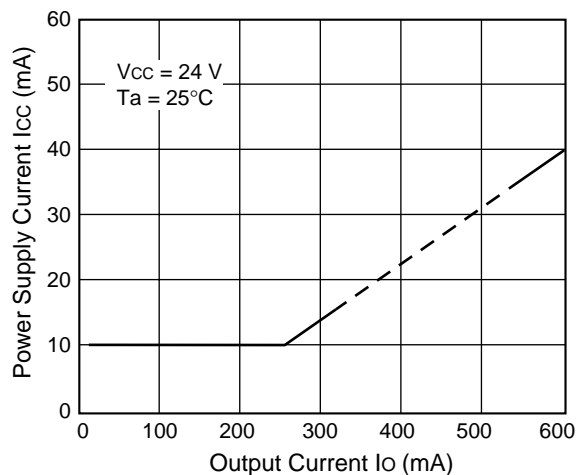
Typical Application Example



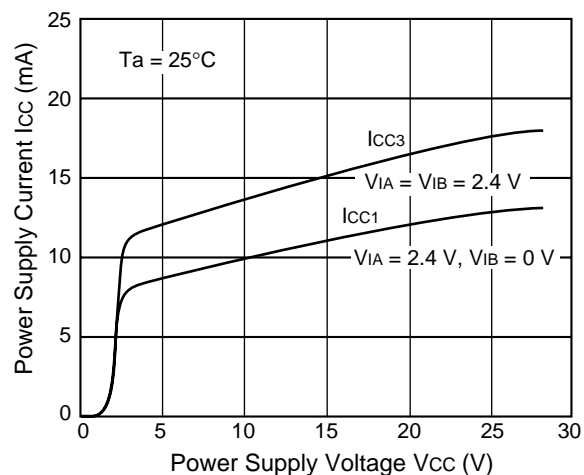
Note : In the case the control voltage is input when the power supply voltage is not applied because of the time lag between those two voltages, excess current flows into IC from the input terminals. In this case, please connect a resistor ($\geq 1 \text{ k}\Omega$) serially to input pin in order to prevent excess current flow.

■ TYPICAL PERFORMANCE CHARACTERISTICS

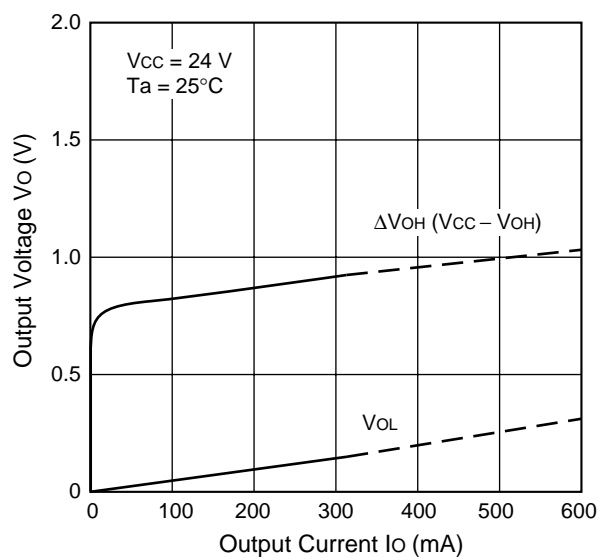
Output Current vs. Power Supply Current



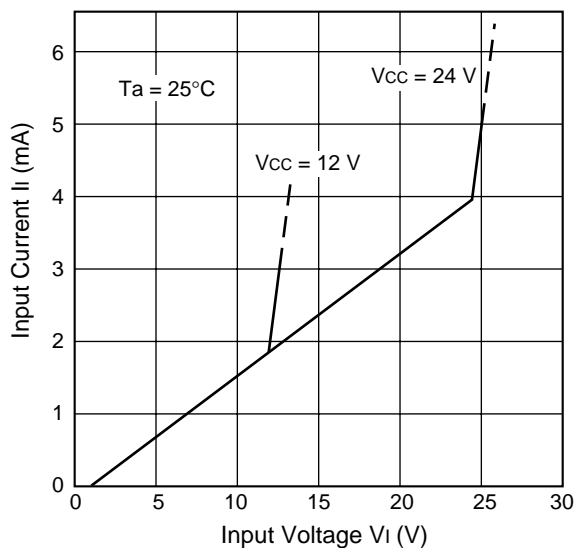
Power Supply Voltage vs. Power Supply Current



Output Current vs. Output Voltage

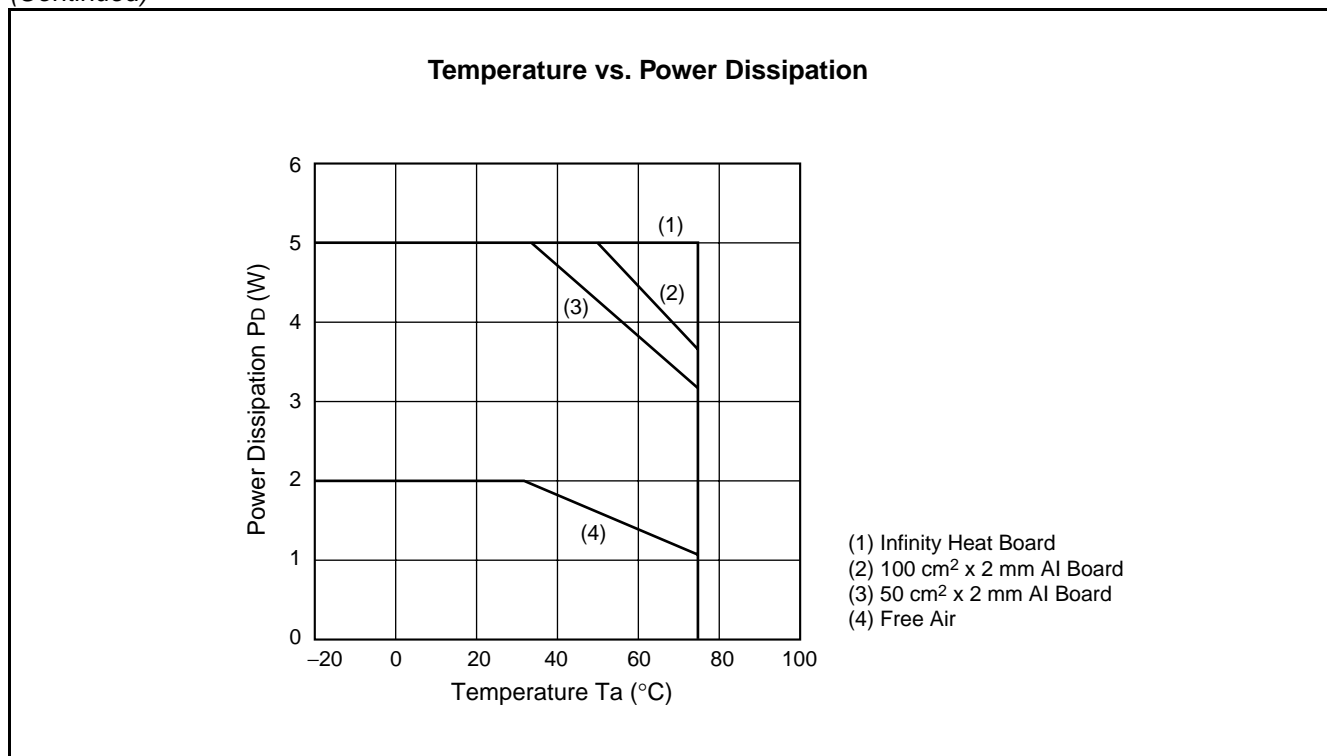


Input voltage vs. Input Current



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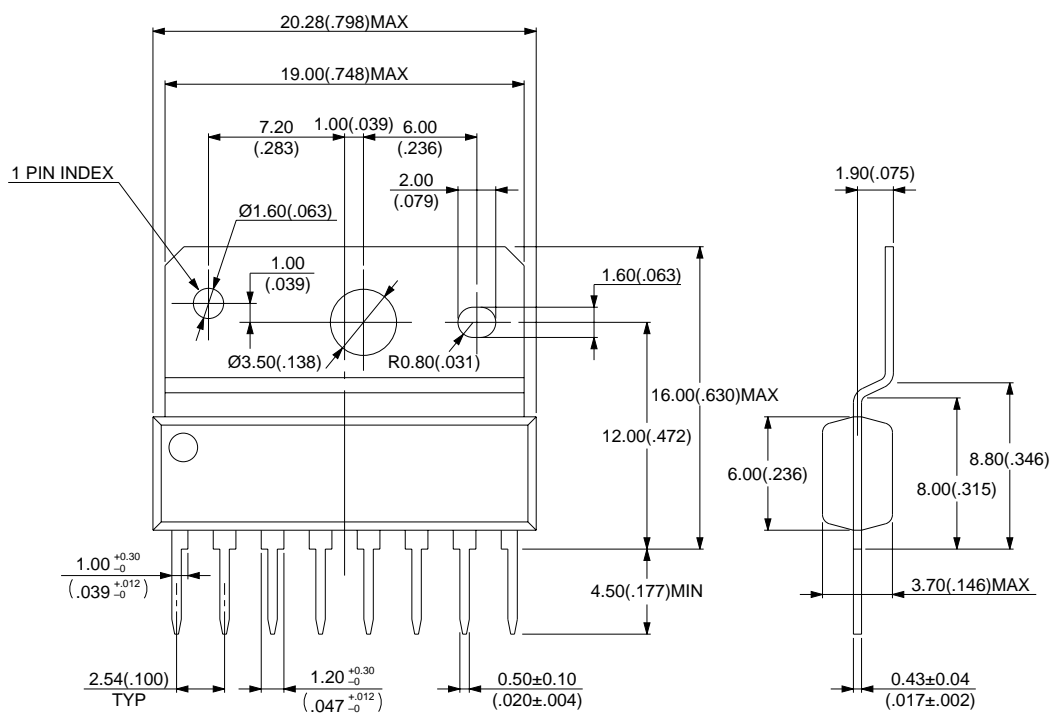


■ ORDERING INFORMATION

Part number	Package	Remarks
MB3763HPS	8-pin, plastic SIP (SIP-8P-M01)	

MB3763H

■ PACKAGE DIMENSION

8-pin plastic SIP
(SIP-8P-M01)

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Dimensions in mm (inches)

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