Interlaken MegaCore Function

User Guide

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UG-01092-1.0

Document last updated for Altera Complete Design Suite version: 10.1
Document publication date: December 2010

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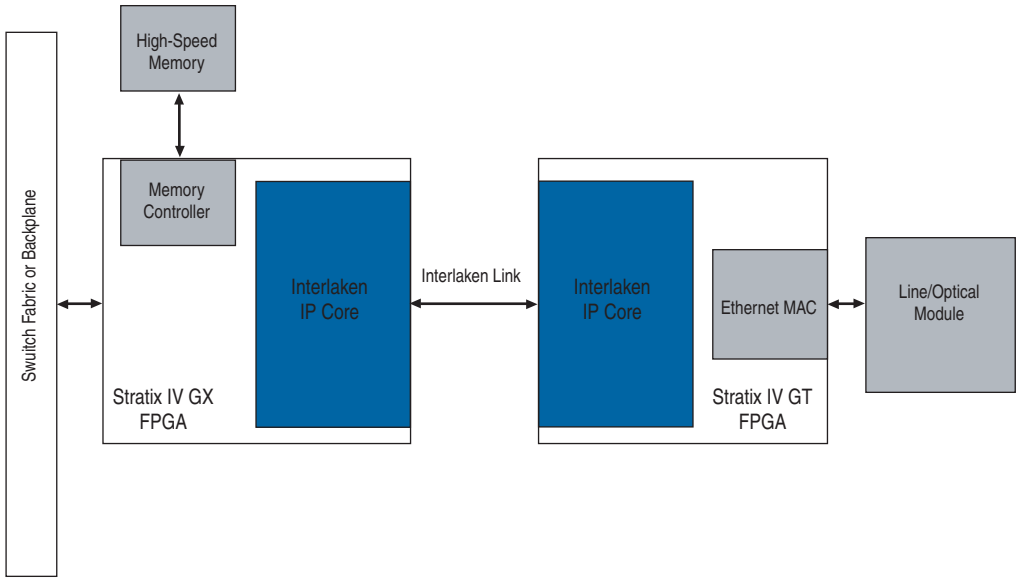
1. About This MegaCore Function

Interlaken is a high speed serial communication protocol for chip-to-chip packet transfers. The Altera® Interlaken MegaCore® function implements the *Interlaken Protocol Specification, Revision 1.2*. It supports specific combinations of number of lanes from 4 to 20, and lane rates from 3.125 to 10.3125 gigabits per second (Gbps), on Stratix IV GT devices, and lane rates from 3.125 to 6.375 Gbps on Stratix IV GX devices, providing raw bandwidth of 12.50 Gbps to 127.50 Gbps.

Interlaken provides low I/O count compared to earlier protocols, supporting scalability in both number of lanes and lane speed. Other key features include flow control, low overhead framing, and extensive integrity checking. The Interlaken MegaCore function incorporates a physical coding sublayer (PCS), a physical media attachment (PMA), and a media access control (MAC) block. The MegaCore function transmits and receives Avalon® Streaming (Avalon-ST) data on its FPGA fabric interface.

Figure 1–1 shows an example system implementation.

Figure 1–1. Typical Interlaken Application



Features

The Interlaken MegaCore function has the following features:

- Compliant with the *Interlaken Protocol Specification, Rev 1.2*
- Supports 4, 8, 10, 12, and 20 serial lanes in configurations that provide nominal bandwidths of 20 Gbps, 40 Gbps, and 100 Gbps
- Supports per-lane data rates of 3.125, 6.25, 6.375, and 10.3125 Gbps using Altera on-chip high-speed transceivers

- Supports fast simulation by allowing configuration without high-speed transceivers
- Supports up to 127.50 Gbps raw bandwidth
- Provides Avalon-ST interfaces on the transmit and receive datapaths
- Supports two logical channels in out-of-the-box configuration
- Supports in-band flow control with one calendar page
- Supports optional out-of-band flow control blocks for lane status, link status, and one calendar page

Table 1–1 lists the raw bandwidth enabled by the Interlaken MegaCore function in the supported combinations of lane rate and number of lanes.

Table 1–1. Enabled Raw Aggregate Bandwidth in Gbps

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	12.50	25.00	25.50	—
8	25.00	50.00	51.00	—
10	—	62.50	63.75	—
12	—	75.00	76.50	123.75
20	—	125.00	127.50	—

Device Family Support

Table 1–2 defines the device support levels for Altera IP cores.

Table 1–2. Altera IP Core Device Support Levels

FPGA Device Families	HardCopy Device Families
Preliminary support—The core is verified with preliminary timing models for this device family. The core meets all functional requirements, but might still be undergoing timing analysis for the device family. It can be used in production designs with caution.	**HardCopy Companion**—The core is verified with preliminary timing models for the HardCopy companion device. The core meets all functional requirements, but might still be undergoing timing analysis for the HardCopy device family. It can be used in production designs with caution.
Final support—The core is verified with final timing models for this device family. The core meets all functional and timing requirements for the device family and can be used in production designs.	**HardCopy Compilation**—The core is verified with final timing models for the HardCopy device family. The core meets all functional and timing requirements for the device family and can be used in production designs.

Table 1–3 shows the level of support offered by the Interlaken MegaCore function for each Altera device family.

Table 1–3. Device Family Support (Part 1 of 2)

Device Family	Support
Stratix® IV GT *(1)*	Final

Table 1–3. Device Family Support (Part 2 of 2)

Device Family	Support
Stratix IV GX	Final

Note to Table 1–3:

(1) Altera supports the 12-lane, 10-Gbps configuration in Stratix IV GT devices only.

MegaCore Verification

Before releasing a version of the Interlaken MegaCore function, Altera runs comprehensive regression tests in the current version of the Quartus® II software. These tests use standalone methods and the Qsys system integration tool to create the instance files. These files are tested in simulation and hardware to confirm functionality. Altera tests and verifies the Interlaken MegaCore function in hardware for different platforms and environments.

Constrained random techniques generate appropriate stimulus for the functional verification of the MegaCore function. Functional coverage metrics measure the quality of the random stimulus, and ensure that all important features are verified.

Performance and Resource Utilization

Table 1–4 lists the resources and expected performance for different Interlaken MegaCore function variations.

Table 1–4 shows results obtained using the Quartus II software v10.1 for the following devices:

- Stratix IV GT device EP4S100G5F45I1
- Stratix IV GX devices EP4SGX530NF45C2 and EP4SGX530KH40C2

Resource utilization is shown for variations that include the transceiver and do not include the out-of-band flow control block.

Table 1–4. Interlaken MegaCore Function FPGA Resource Utilization

Device	Parameters		Resource Utilization		
	Number of Lanes	Per-Lane Data Rate (Gbps)	Combinational ALUTs	Logic Registers	M9K Blocks
Stratix IV GX EP4SGX530NF45C2	4	6.25	12229	16774	52
	8	6.25	24825	31776	68
Stratix IV GX EP4SGX530KH40C2	10	6.25	29949	38033	96
	20	6.25	63033	77806	159
Stratix IV GT EP2S100G5F45I1	12	10.3125	50164	56948	84

For all Interlaken MegaCore function variations that target a Stratix IV GX device, Altera recommends that you target a C2 speed grade device. For all variations that target a Stratix IV GT device, Altera recommends you target an I1 speed grade device. In all cases, Altera recommends that you set the **Optimization Technique** in the Analysis & Synthesis Settings dialog box to **Speed**.

For information about how to apply the **Speed** setting, refer to volume 1 of the *Quartus II Handbook*.

Release Information

Table 1–5 provides information about this release of the Interlaken MegaCore function.

Table 1–5. Interlaken MegaCore Function Release Information

Item	Value	
Version	10.1	
Release Date	December 2010	
Vendor ID	6AF7	
License Ordering Codes and Product IDs		
License *(1)*	Ordering Code	Product ID
20G License	IP-INTLKN/20G/4L	00DA
40G License	IP-INTLKN/40G/8L	00D5
100G Licenses	IP-INTLKN/100G/20L	00D6
	IP-INTLKN/100G/12L	00D4

Note to Table 1–5:

(1) For information about the different licenses, refer to "Interlaken MegaCore Function Licenses" on page 1–5.

Altera verifies that the current version of the Quartus II software compiles the previous version of each MegaCore function. Any exceptions to this verification are reported in the *MegaCore IP Library Release Notes and Errata*. Altera does not verify compilation with MegaCore function versions older than the previous release.

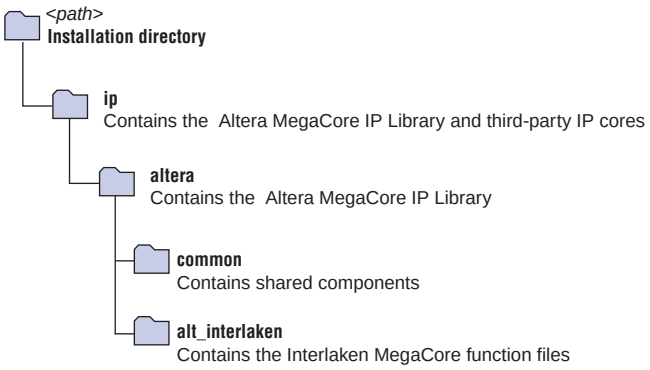
The Interlaken MegaCore function v10.1 is a new MegaCore function and has no previous version.

Installation and Licensing

The Interlaken MegaCore function is part of the MegaCore IP Library, which is distributed with the Quartus II software and downloadable from the Altera website, www.altera.com.

Figure 1–2 shows the directory structure after you install the Interlaken MegaCore function, where <*path*> is the installation directory. The default installation directory on Windows is **C:\altera**<*version number*>; on Linux it is **/opt/altera<***version number***>.**

Figure 1–2. Directory Structure



You can use Altera's free OpenCore evaluation feature to evaluate the MegaCore function in simulation before you purchase a license. You must purchase a license for the MegaCore function only when you are satisfied with its functionality, and you want to check performance in hardware and take your design to production.

After you purchase a license for the Interlaken MegaCore function, you can request a license file from the Altera website at **www.altera.com/licensing** and install it on your computer. When you request a license file, Altera emails you a **license.dat** file. If you do not have internet access, contact your local Altera representative.

Interlaken MegaCore Function Licenses

The Altera Interlaken MegaCore function is available to you through several different licenses, depending on the variation you wish to generate. Licensing is based primarily on aggregate bandwidth. Table 1–6 shows the license required to program a device with each supported variation.

Table 1–6. Interlaken MegaCore Function License Support

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	IP-INTLKN/20G/4L	IP-INTLKN/20G/4L	IP-INTLKN/20G/4L	—
8	IP-INTLKN/20G/4L	IP-INTLKN/40G/8L	IP-INTLKN/40G/8L	—
10	—	IP-INTLKN/40G/8L	IP-INTLKN/40G/8L	—
12	—	IP-INTLKN/40G/8L	IP-INTLKN/40G/8L	IP-INTLKN/100G/12L
20	—	IP-INTLKN/100G/20L	IP-INTLKN/100G/20L	—

After you acquire a license, you can compile and program your device with all the variations that require that license. However, to program a variation that requires a different license, you must acquire the additional license. You can generate, simulate, and compile all MegaCore function-supported variations without a license, because the Interlaken MegaCore function supports the Altera OpenCore evaluation feature.

OpenCore Evaluation

The Altera OpenCore evaluation feature allows you to generate RTL files and simulation models, to simulate, and to compile to validate timing, but requires that you acquire a license to generate a programming file with which to configure an FPGA. Therefore, without a license for the variation your design includes, you cannot create an SRAM Object File (**.sof**) or Programmer Object File (**.pof**) for programming a device with your design. With the free OpenCore evaluation feature, you can perform the following actions:

- Simulate the behavior of a megafunction (Altera MegaCore function or AMPP^{SM} megafunction) in your system using the Quartus II software and Altera-supported VHDL and Verilog HDL simulators.
- Verify the functionality of your design and evaluate its size and speed quickly and easily.



For more information about installation and licensing, refer to *Altera Software Installation and Licensing*.

Design Flows

You can customize the Interlaken MegaCore function to support a wide variety of applications. You can instantiate this MegaCore function using the MegaWizard Plug-in Manager or the Qsys system integration tool.

The MegaWizard Plug-in Manager flow offers the following advantages:

- Allows you to parameterize the MegaCore function to create a variation that you can instantiate manually in your design.

The Qsys flow offers the following advantages:

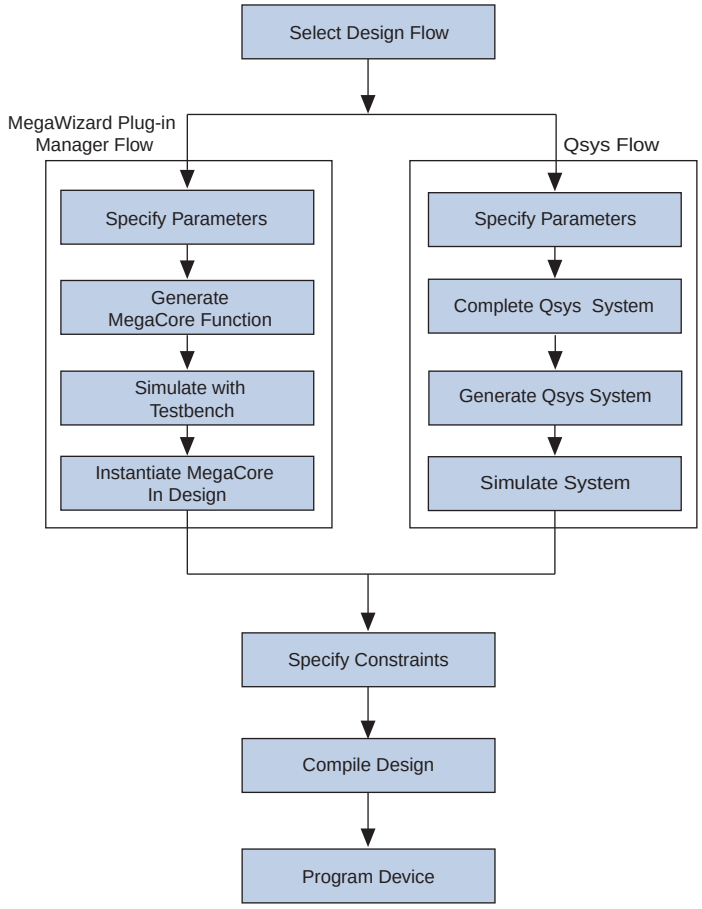
- Allows you to integrate other Altera-provided custom components such as DMA controllers, on-chip memories, and FIFOs in your design.
- Provides visualization of hierarchical designs.
- Allows customization of interconnect elements and pipelining.



Altera's Qsys system integration tool is now available as beta for evaluation in the Quartus II software subscription edition version 10.1. Altera does not recommend using the beta release of Qsys in the Quartus II software version 10.1 for designs that are close to completion and are meeting design requirements. Before using Qsys, review the *Quartus II Software Version 10.1 Release Notes* and *AN 632: SOPC Builder to Qsys Migration Guidelines* for known issues and limitations. To submit general feedback or technical support on the beta release of Qsys, submit a service request through **mysupport.altera.com**. Alternatively, to submit general feedback, click **Feedback** on the Quartus II software Help menu.

Figure 2–1 shows the stages for creating a system with the Interlaken MegaCore function and the Quartus II software. Each stage is described in detail in subsequent sections.

Figure 2–1. Interlaken MegaCore Function Design Flow



MegaWizard Plug-In Manager Design Flow

You can use the MegaWizard Plug-in Manager in the Quartus II software to parameterize a custom MegaCore function variation. The Interlaken parameter editor lets you interactively set parameter values and select optional ports. This flow is best for manual instantiation of a MegaCore function in your design.

Qsys Design Flow

The Qsys design flow enables you to integrate an Interlaken component in a Qsys system. The Qsys design flow allows you to connect component interfaces with the system interconnect, eliminating the requirement to design low-level interfaces and significantly reducing design time. When you add an Interlaken MegaCore function instance to your design, an Interlaken parameter editor guides you in selecting the properties of the Interlaken MegaCore function instance.

MegaWizard Plug-in Manager Design Flow

The MegaWizard Plug-in Manager flow allows you to customize the Interlaken MegaCore function, and manually integrate the function in your design.

Specifying Parameters and Generating the MegaCore Function

To specify Interlaken MegaCore function parameters using the MegaWizard Plug-in Manager, follow these steps:

1. Create a Quartus II project using the **New Project Wizard** available from the File menu. Ensure that you target a device family supported by the Interlaken MegaCore function.
2. Launch the **MegaWizard Plug-in Manager** from the Tools menu, and follow the prompts in the MegaWizard Plug-in Manager interface to create a custom megafunction variation.

   To select the Interlaken MegaCore function, click **Installed Plug-Ins** > **Interfaces > Interlaken > Interlaken v<*version*>**.

3. Specify the parameters in the Interlaken parameter editor. For details about these parameters, refer to Chapter 3, Parameter Settings.
4. Click **Finish** to generate the MegaCore function and supporting files.

   IEEE encrypted functional simulation models for the simulators listed in the *Simulating Altera Designs* chapter in volume 3 of the *Quartus II Handbook* are included in the supporting files. The models appear in a set directory hierarchy in the project directory. The functional simulation model is a cycle-accurate VHDL or Verilog HDL model produced by the Quartus II software.

   CAUTION: Use the simulation models only for simulation and not for synthesis or any other purposes. Using these models for synthesis creates a nonfunctional design.

5. If you generate the Interlaken MegaCore function instance in a Quartus II project, you are prompted to add the Quartus II IP File (**.qip**) to the current Quartus II project. You can also turn on **Automatically add Quartus II IP Files to all projects**.

   The **.qip** contains information about the generated IP core. In most cases, the **.qip** contains all of the necessary assignments and information required to process the MegaCore function or system in the Quartus II compiler. The MegaWizard Plug-in Manager generates a single **.qip** for each MegaCore function.
6. Click **Exit** to close the MegaWizard Plug-in Manager.

You can now integrate your custom MegaCore function variation in your design, simulate, and compile.

When you integrate your Interlaken MegaCore function variation in your design, note the following connection and assignment requirements and recommendations:

- If you turn off **Exclude transceiver** when you parameterize your Interlaken MegaCore function, you must ensure that you connect the calibration clock `cal_blk_clk` to a clock signal with the appropriate frequency range of 10–125 MHz. The `cal_blk_clk` ports on other components that use the same transceiver block must be connected to the same clock signal.
- If you turn off **Exclude transceiver** when you parameterize your Interlaken MegaCore function, you should set the RTL parameter `SIM_FAST_RESET` to 1 to improve your transceiver simulation time. In this version of the Interlaken MegaCore function, you must modify your RTL files to set the parameter. Add this parameter to the parameter list in your HSIO bank instances with the value 1'b1. The HSIO bank instances for the different variations are instantiations of the modules `alt_ntrlkn_hsio_bank_bpcs4`, `alt_ntrlkn_hsio_bank_10g`, `alt_ntrlkn_hsio_bank_bpcs_3g`, or `alt_ntrlkn_hsio_bank_pmad5`.

Simulating the Design

You can simulate your Interlaken MegaCore function variation using any of the vendor-specific IEEE encrypted functional simulation models which are generated in the new <*instance name*>_**sim** subdirectory of your project directory.

You cannot simulate the Interlaken MegaCore function in the ModelSim-AE simulator. ModelSim-AE is the simulation tool provided with the Quartus II software.

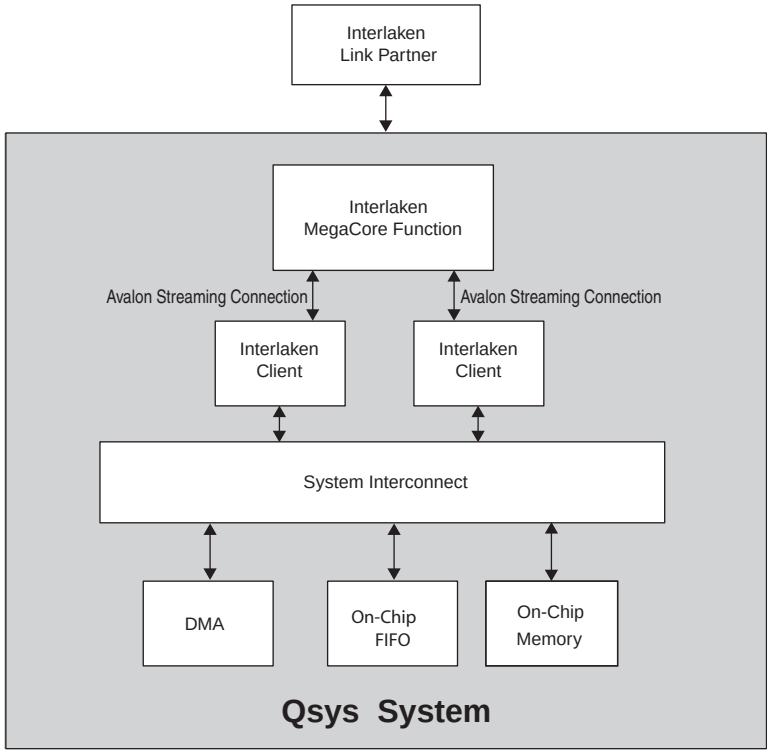
For Information About	Refer To
Quartus II software	See the Quartus II Help topics: "About the Quartus II Software" "About the MegaWizard Plug-In Manager"
MegaWizard Plug-in Manager	
Functional simulation models for Altera IP cores	*Simulating Altera Designs* chapter in volume 3 of the *Quartus II Handbook*

Qsys Design Flow

You can use Qsys to build a system that contains your customized Interlaken MegaCore function. You can easily add other components and quickly create a Qsys system. Qsys can automatically generate HDL files that include all of the specified components and interconnections. The HDL files are ready to be compiled by the Quartus II software to produce output files for programming an Altera device.

Figure 2–2 shows a block diagram of an example Qsys system.

Figure 2–2. Qsys System



For Information About	Refer To
System interconnect	*Qsys Interconnect* chapter in volume 1 of the *Quartus II Handbook* and the *Avalon Interface Specifications*
Qsys tool	*System Design with Qsys* section in volume 1 of the *Quartus II Handbook*
Quartus II software	Quartus II Help

Specifying Parameters

To specify Interlaken MegaCore function parameters using the Qsys flow, follow these steps:

1. Create a new Quartus II project using the **New Project Wizard** available from the File menu.
2. On the Tools menu, click **Qsys (Beta)**.
3. On the **System Contents** tab, expand **Interface Protocols** > **Interlaken** and double-click **Interlaken** to add it to your system. The Interlaken parameter editor appears.
4. Specify the parameters in the Interlaken parameter editor. For detailed explanations of these parameters, refer to Chapter 3, Parameter Settings.
5. Click **Finish** to complete the Interlaken MegaCore function and add it to the system.

Completing the Qsys System

To complete the Qsys system, follow these steps:

1. Add and parameterize any additional components.
2. Connect the components using the Connection panel on the **System Contents** tab.
3. If some signals are not displayed, click **Filters** to display the **Filters** dialog box. In the **Filter** list, click **All.**
4. Note the connection and assignment requirements listed in "Specifying Parameters and Generating the MegaCore Function" on page 2–3.
5. If you intend to simulate your Qsys system, on the **Generation** tab, turn on **Generate Verilog simulation model** to generate a functional simulation model in Verilog HDL.
6. Click **Generate** to generate the system. Qsys generates the system and produces a system **.qip** file, <*system name*>**.qip**, that contains the assignments and information required to process the IP cores and system in the Quartus II Compiler. The file is located in the **synthesis** subdirectory.
7. In the Quartus II software, click **Add/Remove Files in Project** and add the <*system name*>**.qip** file to the project.

Simulating the System

During system generation, Qsys optionally generates various IEEE encrypted functional simulation models for the Interlaken MegaCore function and functional simulation models for other components in the Qsys system. You can use these simulation models to simulate your system with your supported simulation tool.

In addition, you can simulate the static design example that is provided in Verilog HDL. The static design example is available for several Interlaken MegaCore function variations. Refer to Chapter 6, Qsys Design Examples.

The design examples are located in the **design_examples** subdirectory of the **alt_interlaken** installation directory. Each testbench provides some basic stimulus to the user interfaces of the Interlaken MegaCore function. You can use the example as a basis for your own system simulation.

For information about simulating Qsys systems, refer to the *System Design with Qsys* section in volume 1 of the *Quartus II Handbook*.

Specifying Constraints

Altera provides a Synopsys Design Constraints (**.sdc**) file that you must apply to ensure that the Interlaken MegaCore function meets design timing requirements. The script automatically constrains the system clocks and the reference clock based on the data rate you specify. If your design includes multiple instances of the Interlaken MegaCore function, you must edit the **.sdc** file to ensure that each instance name appears correctly in the file.

The Quartus II software v10.1 requires that you add the following additional constraints manually:

- Hard PLL Assignment Constraints
- I/O Standard Constraints
- 0PPM Settings

The following sections describe the constraints you must add manually.

Hard PLL Assignment Constraints

The **.sdc** script provided with the Quartus II software v10.1 requires that you add hard PLL assignment constraints to the Quartus Settings File (**.qsf**) before you compile your design. You can add these constraints directly to the **.qsf**, or you can use the Quartus II Assignment Editor.

You must add the following hard transceiver PLL assignments before compilation:

```
set_location_assignment IOBANK_<quad_location> -to <PLL_path>
```

where

- *<quad_location>* is any valid quad location on your device. It may be any of QLn or QRn, for n in {0,1,2,3}, depending on the device
- *<PLL_path>* is `"*|lt_ntrlkn_hsio_bank_*:alt_ilk_hsio_bank_<n>|*|tx_pll*0"` for any valid high-speed I/O (HSIO) bank number *<n>*

The valid HSIO bank numbers depend on the number of lanes in your Interlaken MegaCore function variation. Table 2–1 shows the valid HSIO bank numbers.

Table 2–1. Valid HSIO Bank Numbers Depending on Number of Lanes

Number of Lanes	Valid HSIO Bank Numbers			
	0	1	2	3
4	✓	—	—	—
8	✓	✓	—	—
10	✓	✓	—	—
12	✓	✓	✓	—
20	✓	✓	✓	✓

To add the constraint using the Assignment Editor, follow these steps:

1. Open your Quartus II project in the Quartus II software.
2. On the Processing menu, point to **Start** and click **Start Analysis & Elaboration**. The analysis and elaboration process might take several minutes to complete.
3. On the Assignments menu, click **Assignment Editor.**
4. Click **<<new>>** to edit a new assignment.
5. Double-click the new row in the **Assignment Name** column and select **Location**.
6. Double-click the new row in the **To** column.
7. Click the Node Finder icon. The **Node Finder** dialog box appears.

8. Ensure that **Filter** is set to **Design Entry (all names)**.
9. To fill the **Named** field, follow one of these steps:
   - If the number of lanes in your Interlaken MegaCore function is 10 or 20, in the **Named** field, type `*tx_pll_edge0`
   - If the number of lanes in your Interlaken MegaCore function is 4, 8, or 12, in the **Named** field, type `*tx_pll0`
10. Click **List**.
11. Highlight each node found and click the right-arrow icon to move it from the **Nodes Found** list to the **Selected Nodes** list.
12. Click **OK**. All the selected nodes appear in separate rows in the Assignment Editor, with **Assignment Name** set to **Location**.
13. For each new row, follow these steps:
    a. Double-click the new row in the **Value** column and click the Browse icon. A **Location** dialog box appears.
    b. For **Element**, select **I/O bank**.
    c. For Location, select **IOBANK_Q**<*m*> for your preferred value <*m*>.

       You must preserve the lane order in assigning IO banks, keeping in mind the requirement that 10- and 20-lane variations use five transceivers in each transceiver block, and the other variations use four transceivers in each transceiver block. Refer to "High-speed I/O Block" on page 4–21.
    d. Click **OK**. The value you selected appears in the **Value** column.

For more information about timing analyzers, refer to the Quartus II Help and the *Timing Analysis* section in volume 3 of the *Quartus II Handbook*.

I/O Standard Constraints

The Interlaken MegaCore function implements the transceivers with the programmable transmitter output buffer power (VCCH TX) set to 1.4 V. Therefore, the MegaCore function requires that you connect the Interlaken interface signals to pins that implement the 1.4-V PCML I/O standard. This setting increases the data rate range of the Interlaken interface. On a Stratix IV GX device, this requirement might not be implemented automatically. If your design includes high-speed transceivers, you should enforce this requirement manually. To enforce this requirement, after you generate the system, follow these steps:

1. In the Quartus II window, on the Assignments menu, click **Assignment Editor**.
2. For each `N`, follow these steps:
   a. In the **<<new>>** cell in the **To** column, type the top-level signal name for your Interlaken MegaCore function instance `rx_serial_dataN_export` signal.
   b. Double-click in the **Assignment Name** column and click **I/O Standard**.
   c. Double-click in the **Value** column and click **1.4-V PCML**.
3. Repeat step 2 for your Interlaken MegaCore function instance `tx_serial_dataN_export` signals.

0PPM Settings

The **.sdc** script provided with the Quartus II software v10.1 requires that you add 0PPM settings to the Quartus Settings File (**.qsf**) before you compile your design. You can add these settings directly to the **.qsf**, or you can use the Quartus II Assignment Editor.

You must add the following 0PPM settings before compilation:

```
set_instance_assignment -name GXB_0PPM_CORE_CLOCK ON \
                        -from *tx_serial_data* -to *tx_serial_data*

set_instance_assignment -name GXB_0PPM_CORE_CLOCK ON \
                        -from *rx_serial_data* -to *rx_serial_data*
```

To add the constraint using the Assignment Editor, follow these steps:

1. If you have not yet done so, open your Quartus II project in the Quartus II software.
2. If you have not yet done so, in the Processing menu, point to **Start** and click **Start Analysis & Elaboration**. The analysis and elaboration process might take several minutes to complete.
3. On the Assignments menu, click **Assignment Editor.**
4. Click **<<new>>** to edit a new assignment.
5. Double-click the new row in the **Assignment Name** column and select **GXB_0PPM_CORE_CLOCK**.
6. Double-click the new row in the **To** column.
7. Type `*tx_serial_data*`.
8. Double-click the new row in the **From** column.
9. Type `*tx_serial_data*`.
10. Double-click the new row in the **Value** column and select **On**.
11. Repeat steps 4 to 10, typing `*rx_serial_data*` instead of `*tx_serial_data*`.

Compiling the Full Design and Programming the FPGA

You can use the **Start Compilation** command on the Processing menu in the Quartus II software to compile your design.

The 10- and 20-lane Interlaken MegaCore function variations require fine tuning to achieve timing closure. Refer to Appendix C, Closing Timing on 10- and 20-lane Designs for a list of steps you can implement to improve timing.

After successfully compiling your design, program the targeted Altera device with the Programmer and verify the design in hardware. Programming the device requires that you have a license for your Interlaken MegaCore function variation. Refer to "Interlaken MegaCore Function Licenses" on page 1–5.



For Information About	Refer To
Compiling your design	*Quartus II Incremental Compilation for Hierarchical and Team-Based Design* chapter in volume 1 of the *Quartus II Handbook*
Programming the device	Device Programming section in volume 3 of the *Quartus II Handbook*

3. Parameter Settings

You customize the Interlaken MegaCore function by specifying parameters in the Interlaken parameter editor, which you access from the MegaWizard Plug-in Manager or from the Qsys tool in the Quartus II software.

This chapter describes the parameters and how they affect the behavior of the MegaCore function. To customize your Interlaken MegaCore function, you can modify parameters to specify the following properties:

- Operational mode
- Number of lanes
- Lane rate
- Meta frame length
- Whether the MegaCore function includes or excludes the transceiver
- Whether the MegaCore function enables out-of-band flow control

Operational Mode

The **Operational mode** parameter specifies whether the MegaCore function is configured to support simultaneous bidirectional communication. The operational mode with simultaneous bidirectional communication is called duplex mode. The current version of the MegaCore function supports only **Duplex** mode.

Number of Lanes

The **Number of lanes** parameter specifies the number of lanes available for Interlaken communication. Supported values are **4**, **8**, **10**, **12**, and **20**.

The Interlaken MegaCore function supports only certain combinations of number of lanes and lane rate. Table 3–1 shows the supported combinations.

Table 3–1. Supported Combinations of Number of Lanes and Lane Rate

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	✓	✓	✓	—
8	✓	✓	✓	—
10	—	✓	✓	—
12	—	✓	✓	✓
20	—	✓	✓	—

The Interlaken parameter editor does not enforce the license restrictions. If you specify a supported combination that your set of licenses does not allow, compilation does not generate a programming file.

For information about the lane number and lane rate combinations supported by the different Interlaken IP licenses, refer to "Installation and Licensing" on page 1–4.

Lane Rate

The **Lane rate** parameter specifies the data rate on each lane. All lanes have the same data rate.

The Interlaken MegaCore function supports only certain combinations of number of lanes and lane rate. Refer to Table 3–1. For information about the device support for different combinations, refer to Table 1–3 on page 1–2.



The Interlaken parameter editor does not enforce the license restrictions. If you specify a supported combination that your set of licenses does not allow, compilation does not generate a programming file.

For information about the lane number and lane rate combinations supported by the different Interlaken IP licenses, refer to "Installation and Licensing" on page 1–4.

Number of Words in Meta Frame

The **Meta frame length in words** parameter specifies the length of the meta frame, in 64-bit (8-byte) words. In the Interlaken specification, this parameter is called the MetaFrameLength parameter.

Smaller values for this parameter shorten the time to achieve lock. Larger values reduce overhead while transfering data, after lock is achieved. For information about achieving lock, refer to Appendix A, Initializing the Interlaken MegaCore Function.

Exclude Transceiver

Turn on the **Exclude transceiver** parameter to specify that your Interlaken MegaCore function does not include an HSIO block. By default, this parameter is turned off.

If this parameter is turned on, the Interlaken MegaCore function simulation model and the Interlaken MegaCore function generated RTL both exclude the transceivers.

This option is available to you for faster simulation. However, if you exclude the transceivers from your Interlaken MegaCore function, you must regenerate and compile with the parameter turned off to create your programming file.

Enable Out-of-band Flow Control

Turn on the **Enable out-of-band flow control** parameter to specify that your Interlaken MegaCore function includes out-of-band flow control functionality. By default, this parameter is not turned on.

Turning off out-of-band flow control decreases the resource utilization of your Interlaken MegaCore function, and excludes this optional specification feature.

For more information about the out-of-band flow control block, refer to "Out-of-band Flow Control Block" on page 4–23.

4. Functional Description

The Interlaken MegaCore function provides the functionality described in the *Interlaken Protocol Definition, Revision 1.2*, as well as arbitration between two incoming user-defined channels and regrouping received data to two outgoing user-defined channels. This chapter describes the individual interfaces and main blocks of the Interlaken MegaCore function and how data passes between them.

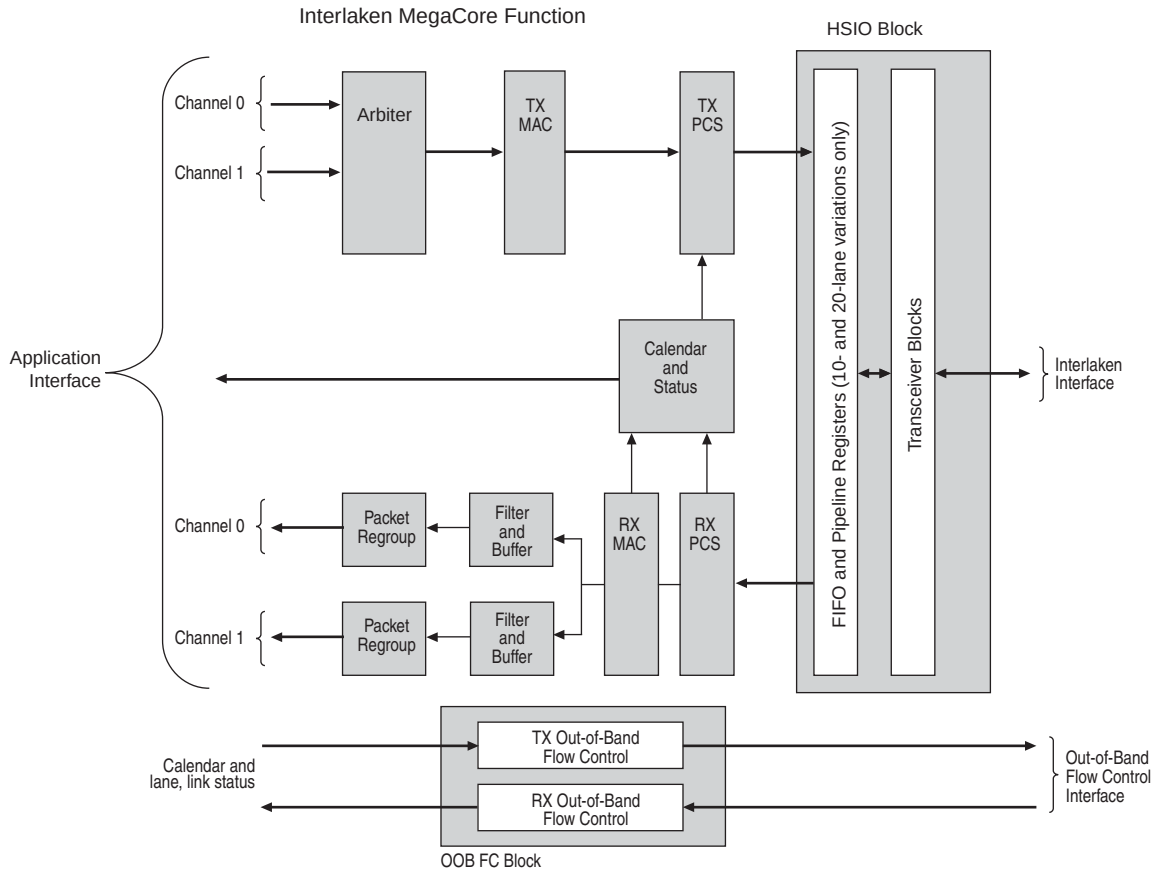
This chapter contains the following sections:

- "Architecture Overview"
- "Interfaces Overview"
- "Clocking and Reset Structure" on page 4–4
- "Transmit Path" on page 4–11
- "Receive Path" on page 4–17
- "Calendar and Status Block" on page 4–19
- "High-speed I/O Block" on page 4–21
- "Out-of-band Flow Control Block" on page 4–23

Architecture Overview

Figure 4–1 shows the main blocks of the Interlaken MegaCore function.

Figure 4–1. Interlaken MegaCore Function Block Diagram



The following sections describe the individual interfaces, clocks, and blocks.

Interfaces Overview

The Altera Interlaken MegaCore function supports the following interfaces:

- Interlaken Interface
- Application Interface
- Out-of-band Flow Control Interface

Interlaken Interface

The Interlaken interface complies with Revision 1.2 of the Interlaken Protocol Definition. It provides a high-speed transceiver interface to an Interlaken link.

Table 4–1 shows the Interlaken MegaCore function values for BurstMax and BurstShort. The MegaCore function does not support BurstMin.

Table 4–1. BurstMax and BurstShort Values

Datapath Width (Bits)	BurstMax (Bytes)	BurstShort (Bytes)
128	256	16
256	128	32
512	256	32

Note to Table 4–1:

(1) The BurstShort value for Interlaken MegaCore function variations with a 128-bit wide datapath increases link utilization while preventing multiple burst control words in the same clock cycle.

The Interlaken MegaCore function supports the following in-band flow control format for the RX and TX calendar bits:

- Bit 0: XON/XOFF bit for Channel 0
- Bit 1: XON/XOFF bit for Channel 1

The *Interlaken Protocol Definition, Revision 1.2* is available from the Interlaken Alliance website at www.interlakenalliance.com.

If you turn on the **Exclude transceiver** parameter to generate a faster simulation model, your functional simulation model's interface to and from the Interlaken link transceivers presents the data in slightly different format and exposes different clocks. For more information, refer to Appendix B, Excluding Transceivers for Faster Simulation

Application Interface

The application interface provides two channels of communication to and from the Interlaken link. Each channel in each direction is implemented as an Avalon-ST interface with one modification. The width of the Avalon-ST interfaces depends on the number of lanes in the Interlaken MegaCore function instance.

The Avalon-ST interface provides a standard, flexible, and modular protocol for data transfers from a source interface to a sink interface. The Avalon-ST interface protocol allows you to easily connect components to the Interlaken MegaCore function.

The application interface implements an Avalon-ST interface with a modification in how the empty signal is used and monitored. In the Avalon-ST interface, the empty signal is monitored only when end-of-packet is asserted. However, the application interface asserts and monitors this signal during other data-valid clock cycles as well. This modification allows the application to provide data in incomplete words, mirroring the same capability on the Interlaken link.

For more information about the application interface, refer to "Arbiter" on page 4–11 and "Packet Regrouper" on page 4–19.

For more information about the Avalon-ST interface, refer to *Avalon Interface Specifications*.

Out-of-band Flow Control Interface

The out-of-band (OOB) flow control interface conforms to the OOB requirements in Section 5.3.4.2, Out-of-Band Flow Control, of the *Interlaken Protocol Definition, Revision 1.2*. This interface is included in the Interlaken MegaCore function if you turn on the **Enable out-of-band flow control** parameter.

For more information, refer to "Out-of-band Flow Control Block" on page 4–23.

Clocking and Reset Structure

The Interlaken MegaCore function has a variable number of clock domains, depending on whether the MegaCore function includes or excludes transceivers, and on whether it includes or excludes the out-of-band flow control block.

In addition to the high-speed clock domains inside the Stratix IV GX transceivers, some of which also clock the PCS lanes, the Interlaken MegaCore function contains two MAC clock domains for the receive and transmit directions, four out-of-band flow control block clocks, and clocks for the Interlaken interface. For information about the clocks visible in your Interlaken IP core functional simulation model if you turn on **Exclude transceivers**, refer to Appendix B, Excluding Transceivers for Faster Simulation.

For recommended clock rates, refer to "Interlaken MegaCore Function Recommended Clock Rates" on page 4–8.

MegaCore Function MAC Clock Domains

The Interlaken MegaCore function MAC blocks have the following two clock domains:

- `rx_mac_c_clk`—Clocks the RX MAC block.
- `tx_mac_c_clk`—Clocks the TX MAC block.



Altera recommends that the same clock drive the `rx_mac_c_clk` and `tx_mac_c_clk` clocks.

Interlaken Interface Clocks

If you turn off **Exclude transceiver**, your Interlaken MegaCore function has the following four Interlaken interface clocks:

- `ref_clk`—Reference clock for the RX and TX transceiver PLLs.
- `cal_blk_clk`—Transceiver calibration-block clock.
- `rx_coreclkout`—Clocks the RX PCS block. This clock is derived from the physically central RX lane clock.
- `tx_coreclkout`—Clocks the TX PCS block. This clock is derived from the master TX clock from transceiver block 0. It drives all the transceiver block `clk_in` clocks, as well as the transmit lanes from the TX PCS block to the HSIO block.



For all Interlaken MegaCore variations except the 8-lane, 3.125-Gbps variation, Altera recommends that you drive the `rx_mac_c_clk` and `tx_mac_c_clk` clocks with the `tx_coreclkout` clock. Refer to "Interlaken MegaCore Function Recommended Clock Rates" on page 4–8.

For information about the Interlaken link facing clocks if you turn on **Exclude transceiver**, refer to Appendix B, Excluding Transceivers for Faster Simulation.

Out-of-band Flow Control Block Clocks

If you turn on **Enable out-of-band flow control**, your Interlaken MegaCore function has the following four additional clock domains:

- `rx_oob_in_fc_clk`—Clocks the incoming out-of-band flow control interface signals described in the Interlaken specification. This clock is received from an upstream TX out-of-band flow control block associated with the Interlaken link partner.
- `tx_oob_out_clk`—Clocks the outgoing out-of-band flow control interface signals described in the Interlaken specification. This clock is generated by the out-of-band flow control block and sent to a downstream RX out-of-band flow control block associated with the Interlaken link partner.
- `rx_oob_in_sys_clk`—Clocks the outgoing calendar and status information on the application side of the block. The frequency of this clock must be at least double the frequency of `rx_oob_in_fc_clk`.
- `tx_oob_in_double_fc`—Clocks the incoming calendar and status information on the application side of the block. The frequency of this clock must be double the frequency of `tx_oob_out_clk`.

Clock Diagrams for the Interlaken MegaCore Function

Figure 4–2 to Figure 4–6 show the clock diagrams for the Interlaken MegaCore function variations with the supported numbers of lanes. The figures show variations with transceivers. For figures that show variations without transceivers, refer to Appendix B, Excluding Transceivers for Faster Simulation.

The 10-lane and 20-lane variations use the transceivers in PMA Direct mode. These variations incorporate five lanes in a single transceiver block. The other variations use the transceivers in low latency PCS mode, incorporating four lanes in each transceiver block.

Figure 4–2 shows the clock diagram for a four-lane Interlaken MegaCore function.

Figure 4–2. Clock Diagram for 4-lane Interlaken MegaCore Function

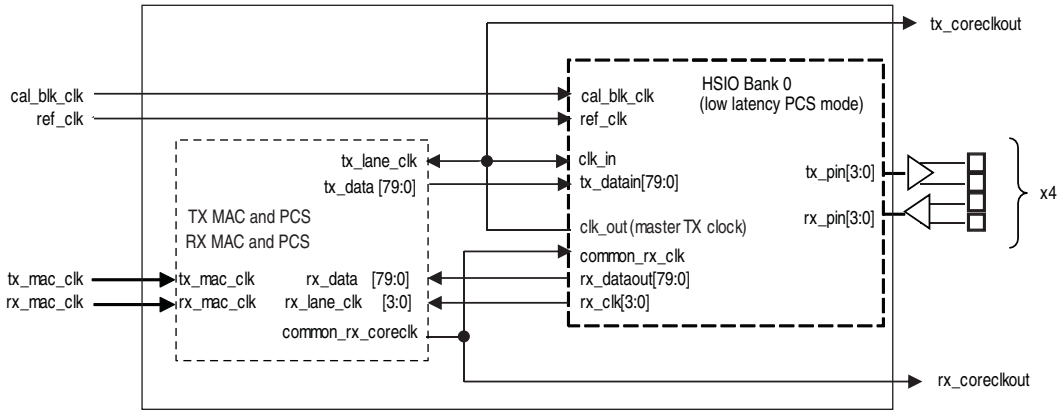


Figure 4–3 shows the clock diagram for an eight-lane Interlaken MegaCore function.

Figure 4–3. Clock Diagram for 8-lane Interlaken MegaCore Function

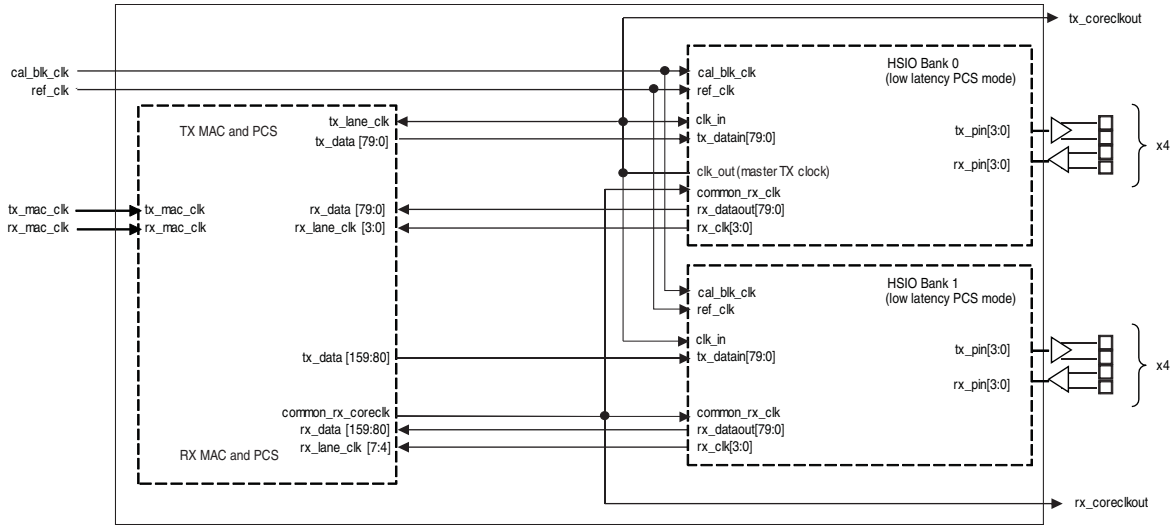


Figure 4–4 shows the clock diagram for a 10-lane Interlaken MegaCore function. This variation uses the transceivers in PMA Direct mode. For more information, refer to "High-speed I/O Block" on page 4–21.

Figure 4–4. Clock Diagram for 10-lane Interlaken MegaCore Function

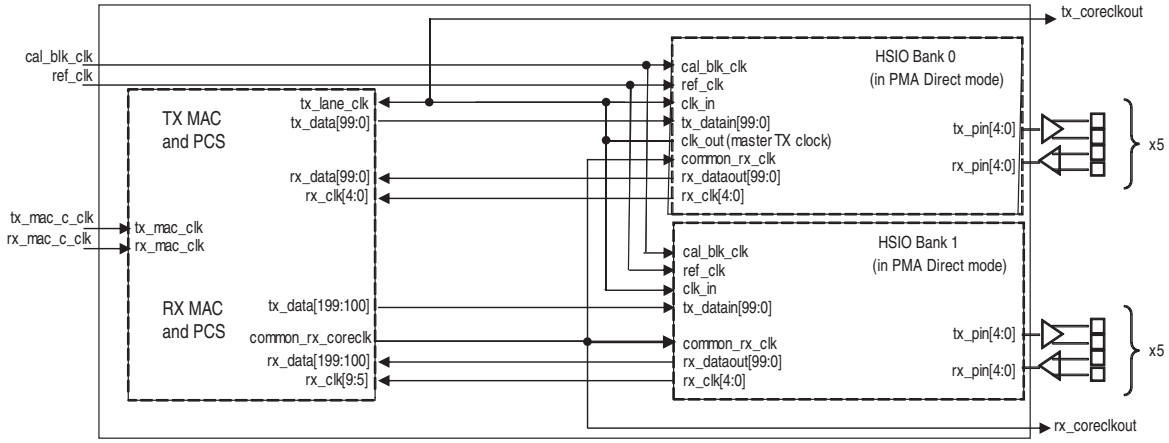


Figure 4–5 shows the clock diagram for a 12-lane, 6-Gbps variation. In this variation, the transceiver datapath width is 20. The clock diagram for a 12-lane, 10-Gbps variation is identical, except that the transceiver datapath width is 40.

Figure 4–5. Clock Diagram for 12-lane, 6-Gbps Interlaken MegaCore Function

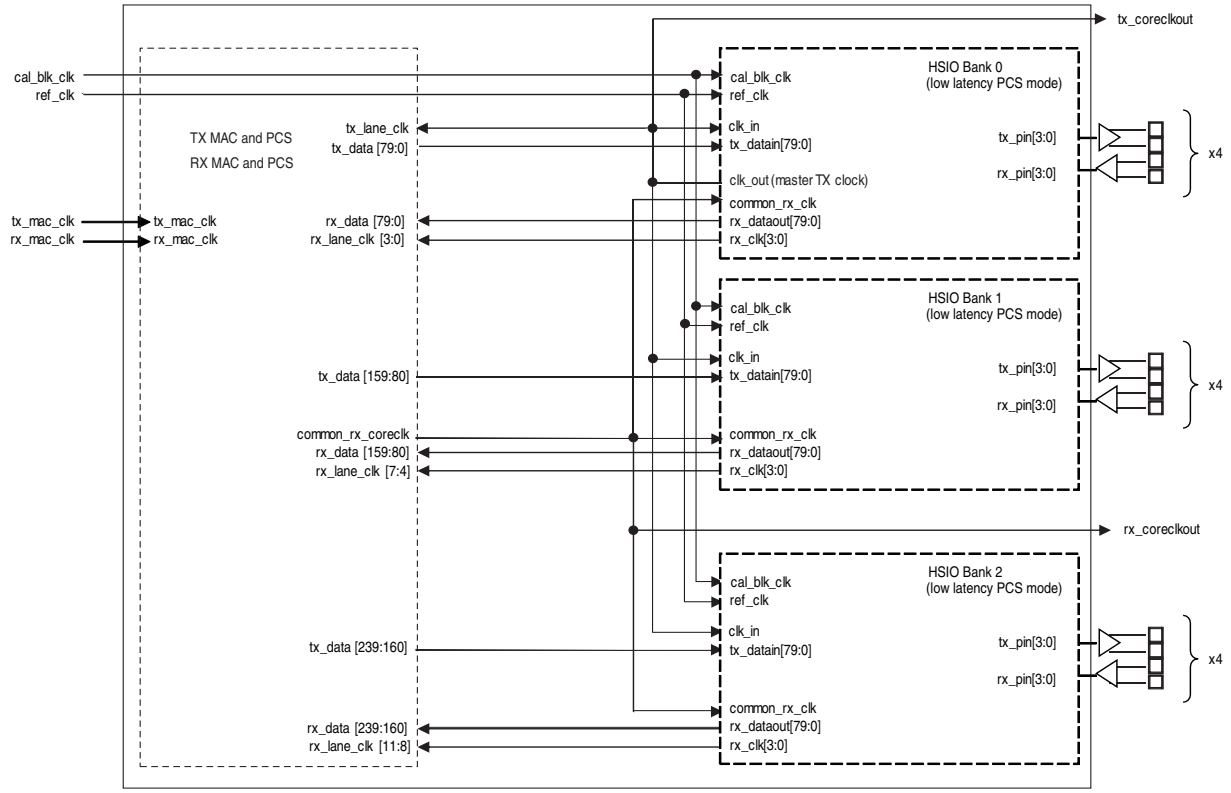
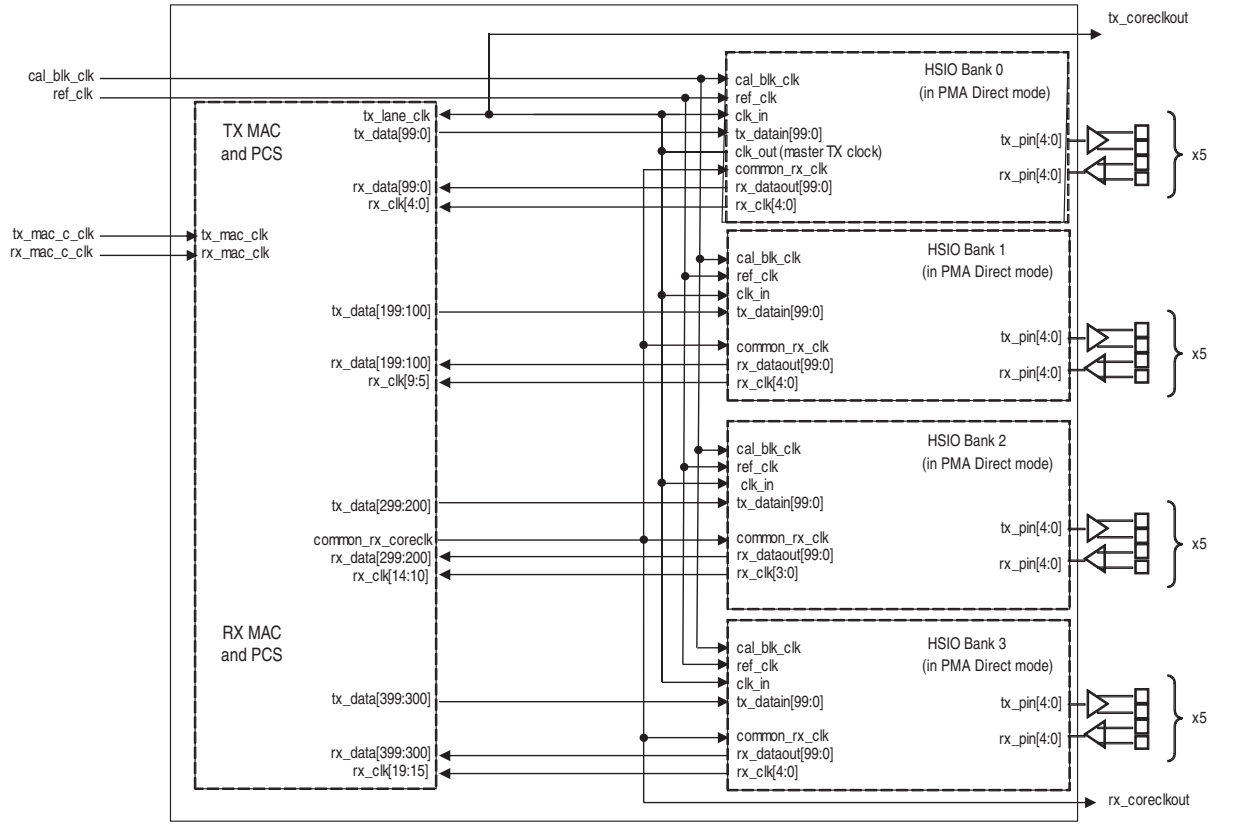


Figure 4–6 shows the clock diagram for a 20-lane Interlaken MegaCore function. This variation uses the transceivers in PMA Direct mode. For more information, refer to "High-speed I/O Block" on page 4–21.

Figure 4–6. Clock Diagram for 20-lane Interlaken MegaCore Function



Interlaken MegaCore Function Recommended Clock Rates

This section describes the recommended frequencies for the Interlaken MegaCore function clocks.

MAC Clock Verified Frequency

The Altera Interlaken MegaCore function supports the number of lanes and lane rate combinations shown in Table 3–1 on page 3–1. The verified MAC clock rates for each variation depend on the lane rate. Table 4–2 shows the MAC clock frequencies at which the Interlaken MegaCore function was verified. The MAC clocks are the `tx_mac_c_clk` and `rx_mac_c_clk` clocks.

Table 4–2. Verified MAC Block Frequencies in MHz (Part 1 of 2)

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	156.25	312.50	318.75	—
8	200.00	312.50	318.75	—

Table 4–2. Verified MAC Block Frequencies in MHz (Part 2 of 2)

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
10	—	312.50	318.75	—
12	—	312.50	318.75	257.81
20	—	312.50	318.75	—

The MAC block must run at an aggregate frequency greater than the PCS block frequency, to support the overhead of striping and destriping.

PCS Clock Frequencies

The lane rate determines the operating frequency of the TX and RX PCS blocks. For all variations except the 10.3125-Gbps variation, the PCS frequency is lane rate divided by 20. For the 10.3125-Gbps variation, because the transceiver datapath width is 40 rather than 20, the PCS frequency is lane rate divided by 40. The PCS clocks are `tx_coreclkout` and `rx_coreclkout`.

Table 4–3. MegaCore Function PCS Block Frequencies in MHz

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	156.25	312.50	318.75	—
8	156.25	312.50	318.75	—
10	—	312.50	318.75	—
12	—	312.50	318.75	257.81
20	—	312.50	318.75	—

For all variations except the 8-lane, 3.125-Gbps variation, Altera recommends that you drive the MAC clocks at the same frequency as the PCS clock. In the 8-lane, 3.125-Gbps variation, the recommended MAC frequency is faster than the PCS frequency.

Transceiver Reference Clock Recommended Frequency and Generation

The transceiver reference clock, `ref_clk`, is the incoming reference clock for the Stratix IV GX transceiver's PLL. To achieve the recommended PCS block operating frequency, `ref_clk` must have the following recommended frequency:

- For all variations except the 10.3125-Gbps variation, the recommended `ref_clk` frequency is lane rate divided by 20.
- For the 10.3125-Gbps variation, the recommended `ref_clk` frequency is 322.265625 MHz, to achieve the correct lane rate of 10.3125 Gbps.

For correct operation, you must ensure that `ref_clk` is generated by a GPLL on the device.

For more information about the transceiver reference clock, refer to the *ALTGX Transceiver Setup Guide* chapter in volume 3 of the *Stratix IV Device Handbook*. For information about high-speed transceiver blocks, refer to *volume 2* and *volume 3* of the *Stratix IV Device Handbook*.

Out-of-band Flow Control Block Recommended Clock Frequencies

The recommended frequency for the `rx_oob_in_fc_clk` and the `tx_oob_out_clk` clocks is 100 MHz, which is the maximum frequency allowed by the Interlaken specification.

The `rx_oob_in_sys_clk` frequency must be at least twice the `rx_oob_in_fc_clk` frequency, and the `tx_oob_in_double_fc_clk` frequency must be twice the `tx_oob_out_clk` frequency. In consequence, the recommended frequency for the `rx_oob_in_sys_clk` and `tx_oob_in_double_fc_clk` is 200 MHz.

Reset for Interlaken MegaCore Functions

The Interlaken MegaCore function has multiple independent reset signals. To reset the Interlaken MegaCore function completely, you must assert all the reset signals.

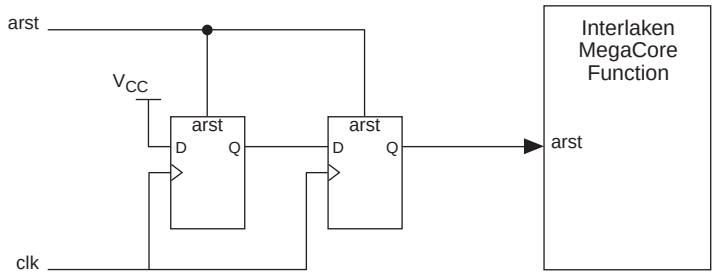
You can assert all reset signals asynchronously to any clock. However, each reset signal must be asserted for at least one full clock period of a specific clock, and be deasserted synchronously to the rising edge of that clock. For example, the RX MAC reset signal, `rx_mac_r_reset`, should be deasserted on the rising edge of `rx_mac_c_clk`. Table 4–4 shows the reset signals and their corresponding clock domains.

Table 4–4. Reset Signals and Corresponding Clock Domains

Reset Signal	Clock Domain	Description
`rx_mac_r_reset`	`rx_mac_c_clk`	Resets the MAC RX block.
`tx_mac_r_reset`	`tx_mac_c_clk`	Resets the MAC TX block.
`tx_lane_r_reset`	`tx_coreclkout` or `tx_lane_c_clk`	Resets the PCS TX block. Asserting this reset signal resets all the TX PCS internal registers, but does not reset the TX FIFO pointers (which are in the TX MAC). Instead, it clears the internal overflow bit, so the TX FIFO continues to empty, but deasserts the internal FIFO write enable. You must hold this reset signal asserted for 256 clock cycles to completely clear the TX FIFO.

You must implement logic to ensure the minimal hold time and synchronous deassertion of each reset input signal to the Interlaken MegaCore function. Figure 4–7 shows a circuit that ensures these conditions for one reset signal.

Figure 4–7. Circuit to Ensure Synchronous Deassertion of Asynchronous Reset Signal arst



In systems generated by Qsys, if you turn on **Global reset** on the **Project Settings** tab, these circuits are generated automatically. However, Altera recommends that you turn off **Global reset** in a Qsys system that includes an Interlaken MegaCore function, because the Qsys-generated reset sequence does not meet the reset sequence requirements for this MegaCore function.

For more information about the requirements for reset signals, refer to Chapter 5, Signals.

For information about the required reset sequence, refer to Appendix A, Initializing the Interlaken MegaCore Function.

Transmit Path

The Interlaken MegaCore function receives application data on two application channels. It combines the data from the two channels into a single data stream in which data is labeled with its source channel. The Interlaken TX MAC and PCS blocks format the data in protocol-compliant bursts and insert Idle words where required.

Arbiter

The channel arbiter arbitrates between the two incoming channels, channel 0 and channel 1, using a round-robin arbitration scheme. It implements an Avalon-ST interface in communication with the channel, with one important modification that involves the `tx_chX_datain_empty` signal.

Arbiter and Application Behavior

In the round-robin arbitration scheme, if data is available on both channels and the Interlaken IP core is not backpressuring either channel, the arbiter accepts data from the two channels on alternating cycles. The application can enforce full packet mode operation by forcing each channel to wait until the other channel completes sending a packet before it asserts its own valid signal. You can use the `tx_control_channel_enable[1:0]` bits to selectively disable a channel temporarily.

The channel width depends on the Interlaken MegaCore function variation. Both channels have the same width. Table 4–5 shows the channel width for each supported variation.

Table 4–5. Application Channel Width in Bits for Supported Variations

Lane Rate (Gbps) / Number of Lanes	3.125	6.25	6.375	10.3125
4	128	128	128	—
8	128	256	256	—
10	—	256	256	—
12	—	256	256	512
20	—	512	512	—

The application indicates to the arbiter that valid data is available on channel X by asserting the tx_chX_datain_valid signal. After the arbiter successfully receives the current data on tx_chX_datain_data, it asserts the tx_chX_datain_ready signal to indicate it is ready to receive new data. In effect, the tx_chX_datain_ready signal is an acknowledge signal rather than a data transfer initiation signal. Figure 4–8 shows an example of the required behavior.

Assertion of the tx_chX_datain_ready signal occurs after assertion of the valid signal. The ready signal indicates that the previous data has been processed and the application can safely proceed to provide the next data word on the channel. The application should not wait for the ready signal to be asserted before presenting the initial data to the tx_chX_datain_data bus and asserting the valid signal.

The channel deasserts its valid signal when it has no more valid data to present on tx_chX_datain_data. It must maintain the current data on the data bus while it asserts the valid signal, until the arbiter asserts the ready signal. This behavior is compliant with the Avalon-ST interface specification with ready latency 0.

For more information, refer to the *Avalon Interface Specifications*.

In addition to incoming data, the arbiter receives start-of-packet and end-of-packet indicators whose values apply to the data on tx_chX_datain_data in the current tx_mac_c_clk clock cycle, and an error indicator whose value is valid on the end-of-packet clock cycle and which refers to the current packet.

The empty vector tx_chX_datain_empty indicates the number of invalid bytes in the incoming data on tx_chX_datain_data in the current tx_mac_c_clk clock cycle. The valid data must be in the most significant bytes of the data bus. Use of the tx_chX_datain_empty signal on non end-of-packet cycles is a modification of the Avalon-ST interface protocol. This modification allows the application to provide the Interlaken MegaCore function with incomplete words of valid data, mirroring the same capability on the Interlaken link.

A two-bit signal, tx_control_channel_enable, allows the application to specify independently for each channel whether the arbiter should accept or ignore its data. The application can assert the tx_control_force_transmit signal to tell the arbiter to ignore the RX calendar value when accepting or ignoring input data from the application. These two signals provide input to an enable indicator for the channel.

The arbiter sends its interleaved stream of data to the TX MAC block. The information sent out every tx_mac_c_clk clock cycle includes the data, start-of-packet and end-of-packet indicators, and an indicator of the source channel for this data.

For more information about the arbiter signals, refer to "TX Application Interface Signals" on page 5–5.

Application Data Transfer Example

Figure 4–8 to Figure 4–11 show an example of a 1016-byte packet transfer on channel 0. For purposes of the example, assume that channel 1 is not in use (tx_ch1_datain_valid is not asserted) or is disabled (tx_control_channel_enable[1:0] has value 1). The tx_coreclkout clock signal drives the tx_mac_c_clk clock, which is shown in the waveforms. Figure 4–8 shows the beginning of the packet transfer on channel 0, illustrating the interaction between the tx_ch0_datain_valid and tx_ch0_datain_ready signal behavior at the beginning of a packet transfer. Figure 4–9 shows a point partway through the packet transfer, in which the application is utilizing the Interlaken link fully. The Interlaken MegaCore function backpressures the channel to prevent overflow. Figure 4–10 shows a different point partway through the packet transfer, at which the application deasserts the valid signal when it does not have data ready for the arbiter. This delay causes the

MegaCore function to insert idle symbols on the Interlaken link. Figure 4–11 shows the end of the 1016-byte packet on tx_ch0_datain_data, and the resulting non-zero value of tx_ch0_datain_empty. This example does not illustrate use of a non-zero empty signal partway through a packet transfer, although the arbiter does check the empty signal on every clock cycle in which valid data is transfered.

Figure 4–8. Beginning of 1016-Byte Packet Transfer on Channel 0

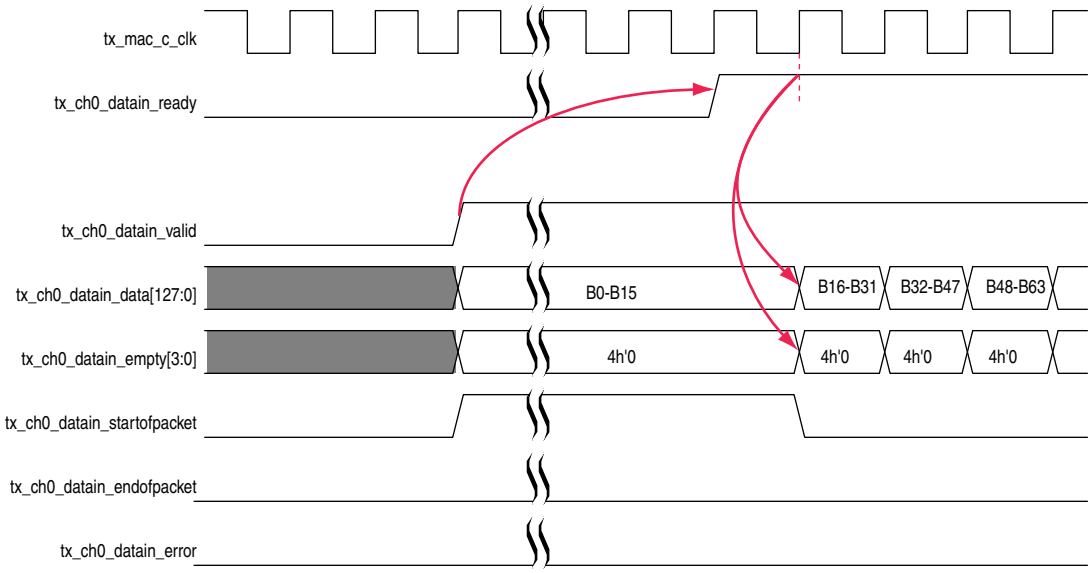


Figure 4–9 shows the application utilizing the Interlaken link fully. The Interlaken MegaCore function backpressures the application to prevent overflow, by deasserting the tx_ch0_datain_ready signal. When it is ready to accept data again, it reasserts the tx_ch0_datain_ready signal, and the channel can resume sending new data.

Figure 4–9. Full Link Utilization During 1016-Byte Packet Transfer on Channel 0

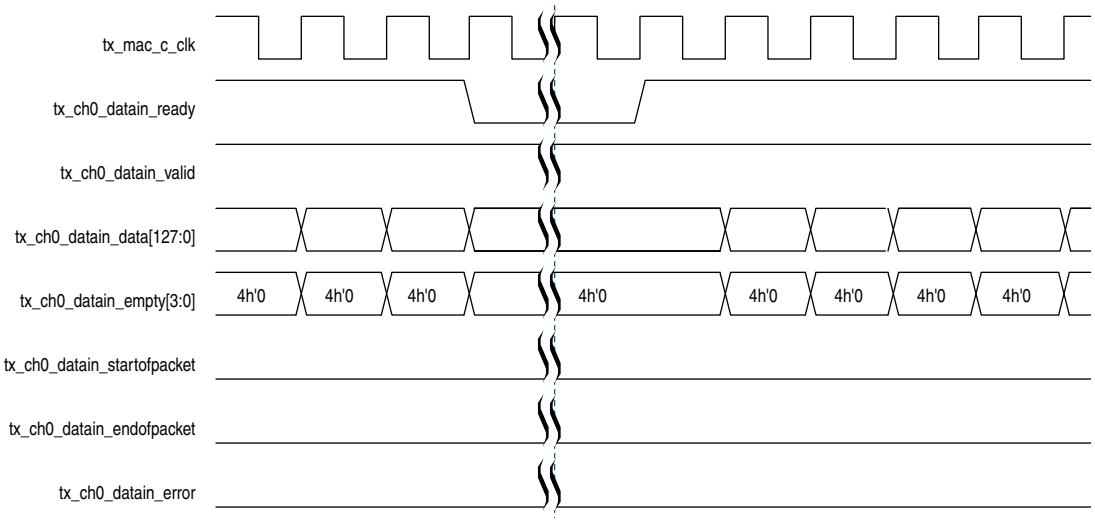


Figure 4–10 shows non-optimal utilization of the Interlaken link. In this case, the application deasserts its valid signal when it does not have data ready to transfer. As a result of this gap in incoming data, the Interlaken MegaCore function inserts Idle symbols on the Interlaken link. In this example, multiple Idle symbols are inserted as a result of the three cycles in which the application holds the valid signal low.

Figure 4–10. Non-optimal Link Utilization Caused During 1016-Byte Packet Transfer on Channel 0

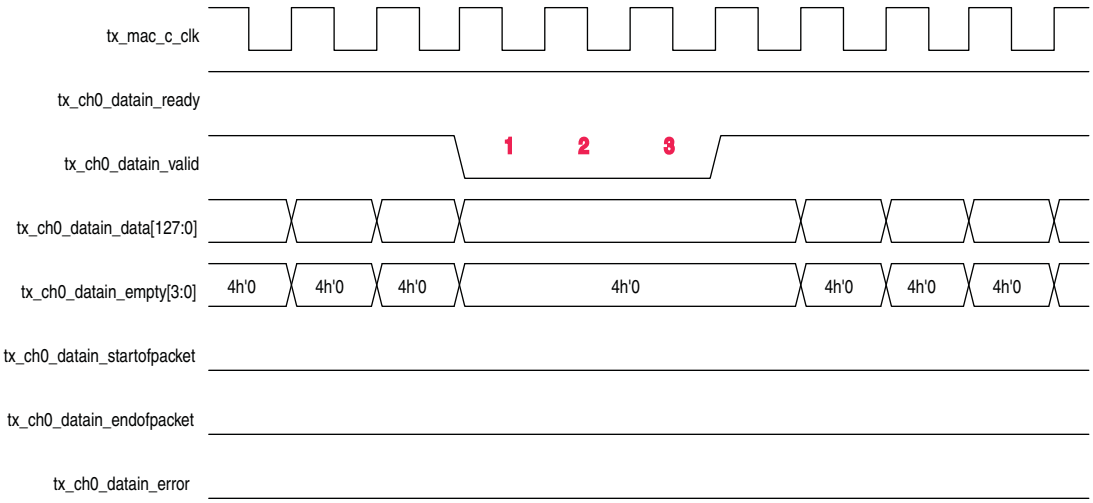
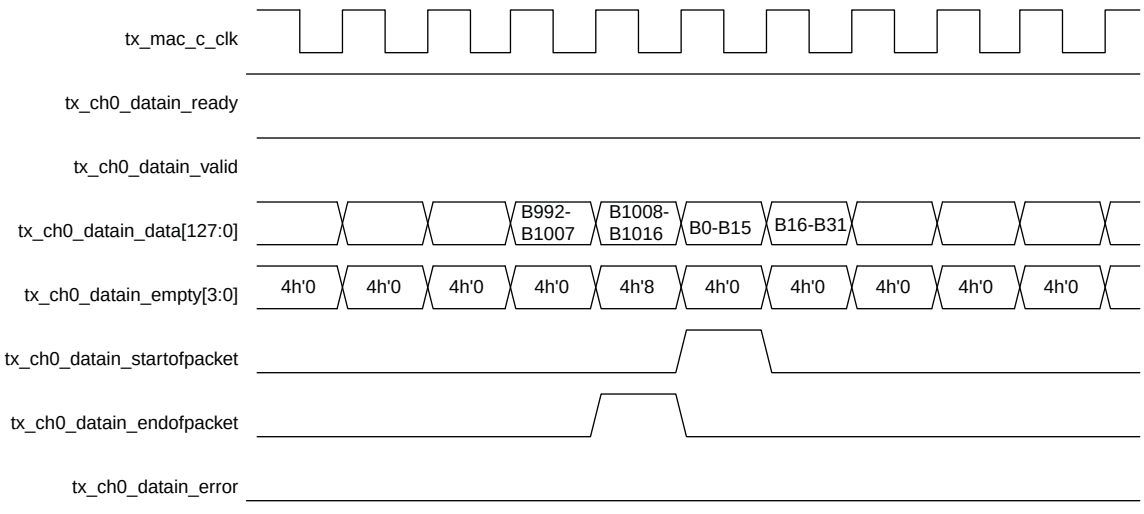


Figure 4–11 shows the end of the 1016-byte packet transfer, and the beginning of a new packet transfer. Because the 1016-byte packet transfer utilizes only 64 bits of the final 128-bit application data word on the channel, the `tx_ch0_datain_empty` signal has value eight to indicate that the least significant eight bytes in this word are invalid. Only the eight most significant bytes hold valid data.

Figure 4–11. End of 1016-Byte Packet Transfer and Beginning of New Packet Transfer on Channel 0



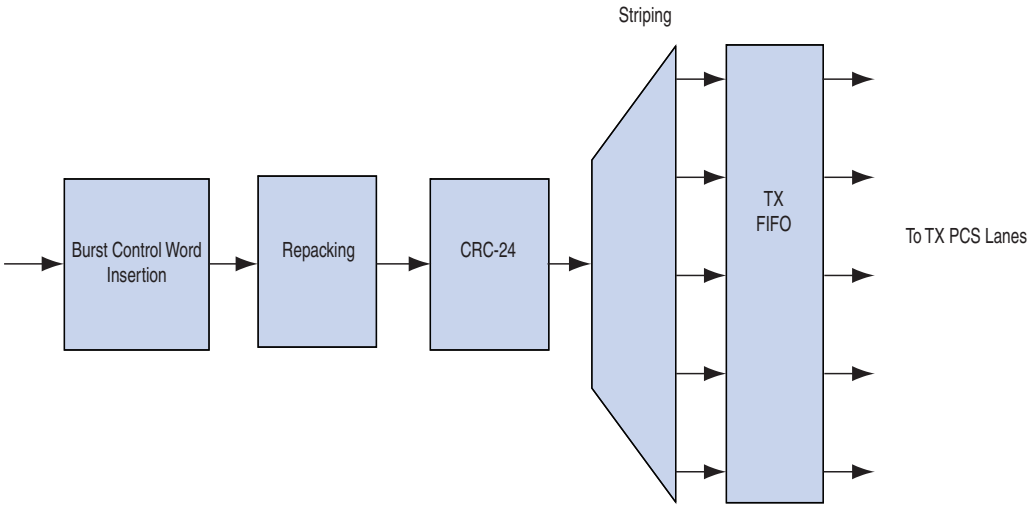
TX MAC

The Interlaken MegaCore function TX MAC performs the following functions:

- Inserts burst and idle control words in the incoming data stream.
- Repacks the data to ensure the maximum number of words is available on each valid clock cycle.
- Calculates and inserts CRC-24 bits in all burst and idle words.
- Inserts calendar data in all burst and idle words.
- Stripes the data across the PCS lanes.
- Buffers data between the application and the TX PCS block in the TX FIFO. The TX FIFO is used to recover bandwidth when the number of words delivered to the transmitter is less than the full width.

Figure 4–12 shows the flow through the Interlaken TX MAC block.

Figure 4–12. Data Flow Through Interlaken MegaCore Function TX MAC Block



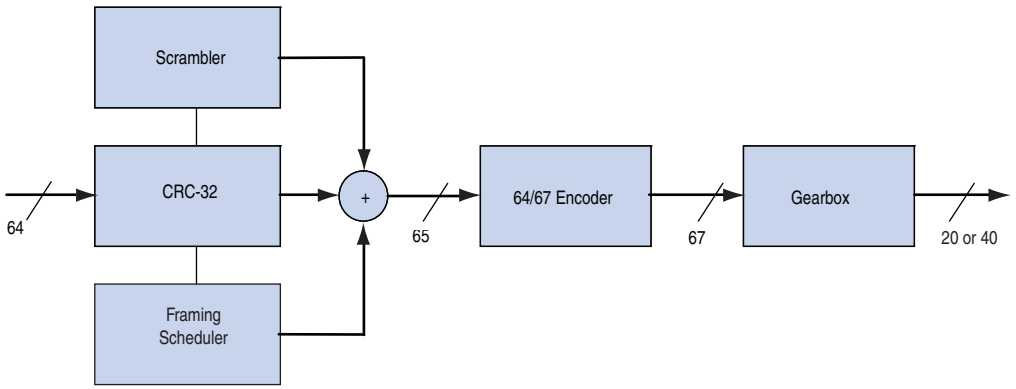
TX PCS

The Interlaken MegaCore function TX PCS block performs the following functions for each lane:

- Inserts the meta frame words in the incoming data stream.
- Calculates and inserts the CRC-32 bits in the meta frame diagnostic words.
- Scrambles the data according to the scrambler seed and the protocol-specified polynomial.
- Performs 64/67 encoding. The input to this function is 65 bits wide; the most significant bit is an Altera-defined control bit that indicates whether a word is a control word or a data word. The control bit has value 1 if the current word is a control word, and value 0 if the current word is a data word.
- Performs 67/20 gearboxing. For the 12-lane, 10-Gbps variation, performs 67/40 gearboxing.

Figure 4–13 shows the flow through the Interlaken TX PCS block.

Figure 4–13. Data Flow Through Interlaken MegaCore Function TX PCS Block



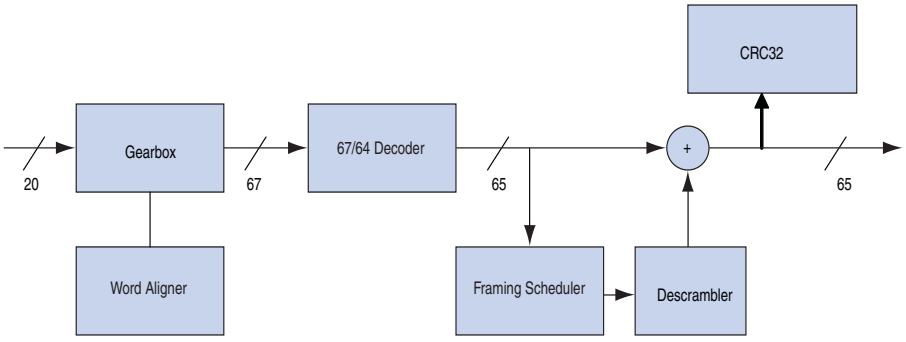
Receive Path

The Interlaken MegaCore function receives data on the Interlaken link and sends it through to the two application channels. The RX PCS and MAC blocks retrieve the data and calendar information from the incoming Interlaken link and send it out to two RX channel filtering blocks. The RX channel filtering blocks separate the data for the two channels, and the packet regroupers regroup each channel's data in the word format expected on the channels.

RX PCS

To retrieve the data, the PCS block reverses the gearboxing and 64/67 encoding, then descrambles the data, and validates the CRC-32 bits and the meta frame. The RX PCS block also sends lane status information to the calendar and status block. Figure 4–14 shows the flow through the RX PCS block. The width of the output from this block is 65 bits; the most significant bit is an Altera-defined control bit that indicates whether a word is a control word or a data word. The control bit has value 1 if the current word is a control word, and value 0 if the current word is a data word.

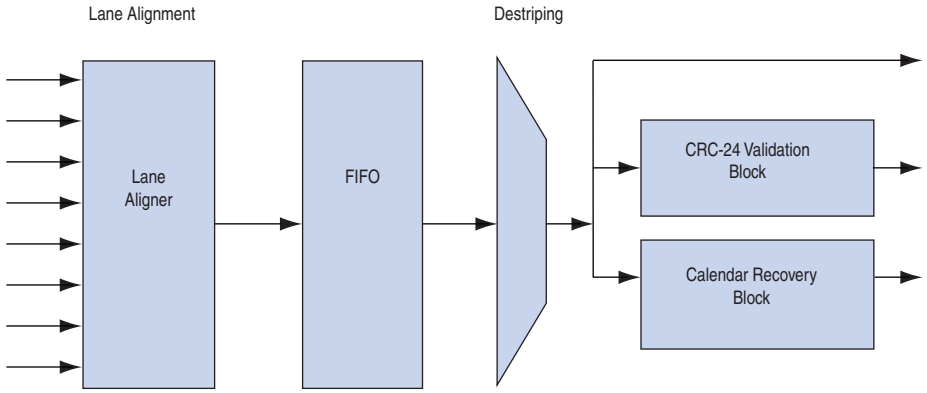
Figure 4–14. Data Flow Through Interlaken MegaCore Function RX PCS Block



RX MAC

To recover a packet or burst, the RX MAC takes data from each of the PCS lanes and reassembles the packet or burst. The RX MAC then validates the CRC-24 bits, and recovers the in-band flow control calendar bits. It sends the calendar bits to the calendar and status block, and sends the raw data it retrieves to the RX channel filtering blocks. Figure 4–15 shows the flow through the RX MAC block.

Figure 4–15. Data Flow Through Interlaken MegaCore Function RX MAC Block



Channel Filtering Blocks

Each channel filtering block identifies the data that targets the channel with which it is associated. It identifies the target channel of a burst from the burst control words. The channel filtering block passes that data through to a regrouper, filtering out the data that targets the other channel. As the channel filter filters the data, it rearranges each data sample so that the valid data and idle bytes for its associated channel are the most significant bytes.

The following example illustrates the function of the channel filtering blocks in a variation with a 256-bit channel width. Table 4–6 shows example four-word-wide raw data output from the RX MAC block. Each table cell represents a 64-bit word.

Table 4–6. Example Raw Data Output From RX MAC Block

t = 0	BC SOP ch0	Data 0	Data 1	Data 2
t = 1	Data 3	Data 4	BC EOP ch0, SOP ch1	Data 5
t = 2	Data 6	Data 7	Data 8	Data 9
t = 3	Data 10	Data 11	IDLE EOP ch1	—

Table 4–7 shows the resulting output stream from the RX channel 0 filter and Table 4–8 shows the resulting output stream from the RX channel 1 filter.

Table 4–7. Output Stream From RX Channel 0 Filter

t'= 0	BC SOP ch0	Data 0	Data 1	Data 2
t' = 1	Data 3	Data 4	BC EOP ch0	—
t' = 2	—	—	—	—
t' = 3	—	—	—	—

Table 4–8. Output Stream From RX Channel 1 Filter

t" = 0	—	—	—	—
t" = 1	BC SOP ch1	Data 5	—	—
t" = 2	Data 6	Data 7	Data 8	Data 9
t" = 3	Data 10	Data 11	IDLE EOP ch1	—

Packet Regrouper

The packet regrouper for each channel receives the filtered data and rearranges each channel data sample so that the valid bytes are the most significant bytes, removing all control words. The information is instead conveyed by using the `rx_chX_dataout_empty` vector to indicate the number of invalid bytes on the `rx_chX_dataout_data` bus in the current `rx_mac_c_clk` clock cycle. Any start-of-packet and end-of-packet information is likewise conveyed in separate signals, `rx_chX_dataout_startofpacket` and `rx_chX_dataout_endofpacket`, which are asserted during the clock cycle in which the appropriate condition holds.

The packet regrouper signals the application channel that it has data ready for transmission on the channel, by asserting the `rx_chX_dataout_valid` signal after it loads the data on the `rx_chX_dataout_data` bus. Refer to Table 4–5 on page 4–12 for the channel data bus width.

The packet regrouper implements an Avalon-ST interface with one important modification: the `rx_chX_dataout_empty` vector can indicate the number of invalid bytes on the `rx_chX_dataout_data` bus in any `rx_mac_c_clk` clock cycle in which it asserts the `rx_chX_dataout_valid` signal, not just in clock cycles in which it asserts `rx_chX_dataout_endofpacket`. This feature supports the transmission of data to the application interface in the arrangement that most closely reflects the format of this data on the Interlaken link.

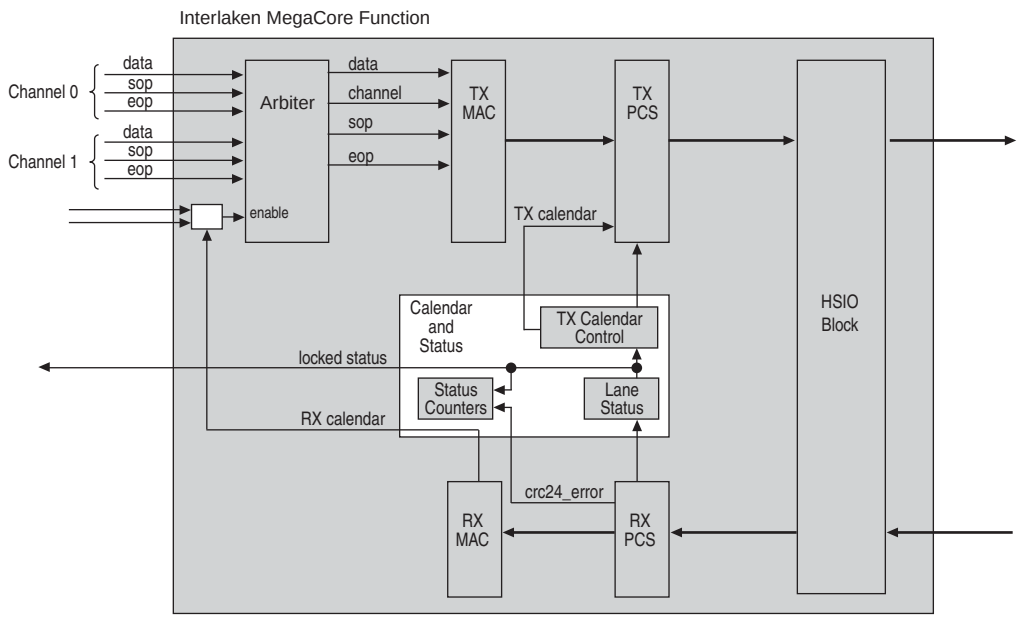
For more information about the RX channel interface signals, refer to "RX Application Interface Signals" on page 5–4.

Calendar and Status Block

The calendar and status block collects and disseminates in-band calendar information and lane and link status bits from the RX PCS to the TX path.

Figure 4–16 shows the calendar and status block and its sub-blocks.

Figure 4–16. Calendar and Status Block



The lane status block monitors the health of the Interlaken RX PCS lanes and delivers the status information to output status signals for use by the application. It also passes the lane status information to the TX calendar control block.

The Interlaken MegaCore function uses only two of the 16 available in-band calendar bits. Bit 0 is a XON/XOFF bit for channel 0, and bit 1 is a XON/XOFF bit for channel 1. To indicate to the Interlaken link partner that channel 0 or channel 1 cannot accept more data, the Interlaken MegaCore function sets TX calendar bit 0 or 1 to zero.

The TX calendar control block sets all the TX calendar bits to 1 at initialization — after the RX lanes and link are fully locked (in other words, the RX Operational state specified in the Interlaken specification is reached).

The calendar and status block sends the RX calendar bits to the enable logic for the arbiter. These bits contain the XON/XOFF status for the channels in the Interlaken link partner.

The status counters count the time and the number of CRC-24 errors encountered so far since the RX Operational state was achieved. The time counter increments every 318×10^6 `rx_mac_c_clk` cycles. The locked time appears on the `rx_status_locked_time` status signal bus.

For information about the individual output status signals, refer to Table 5–2 on page 5–2.

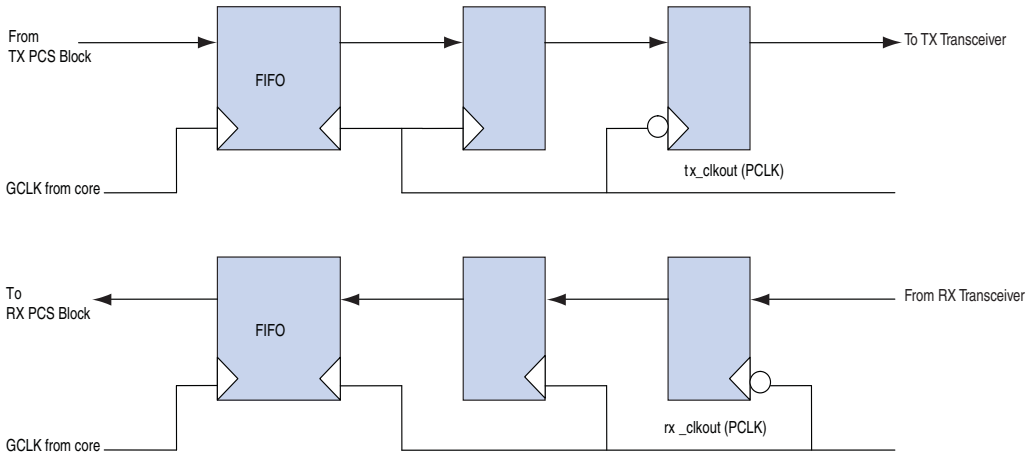
High-speed I/O Block

The high speed I/O (HSIO) block comprises multiple ALTGX megafunction blocks and an optional FIFO and pipeline registers block. The FIFO and pipeline registers block is instantiated only when the ALTGX megafunction operates in PMA Direct mode. The ALTGX megafunction is configured in PMA direct mode in 10- and 20-lane Interlaken MegaCore function variations, and in low latency PCS mode in the other variations.

FIFO and Pipeline Registers

Achieving timing closure can be difficult for the 10- and 20-lane Interlaken variations, which use the transceivers in PMA Direct mode. To resolve timing issues between the PMA Direct SERDES block in the transceiver and the Interlaken MegaCore function, the FIFO and pipeline registers block is instantiated for variations that use PMA Direct mode. The block includes a two-stage register pipeline and a clock-crossing FIFO. Figure 4–17 shows the receive and transmit paths through this block.

Figure 4–17. FIFO and Pipeline Registers Block

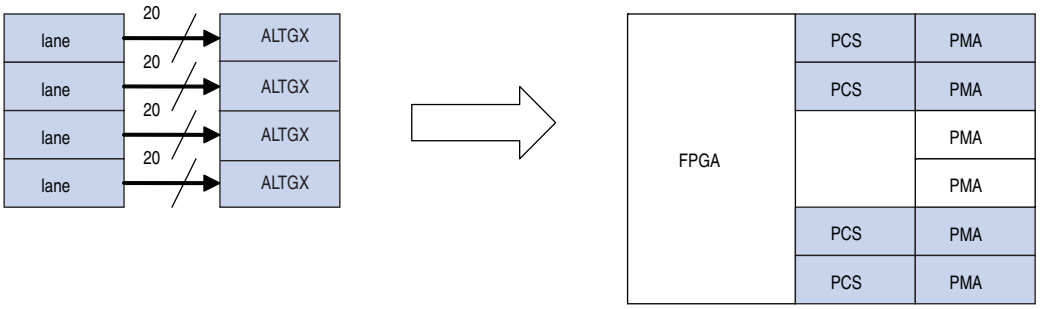


The pipelines are clocked by a global clock on the PCS side and a periphery clock on the transceiver side.

Transceivers

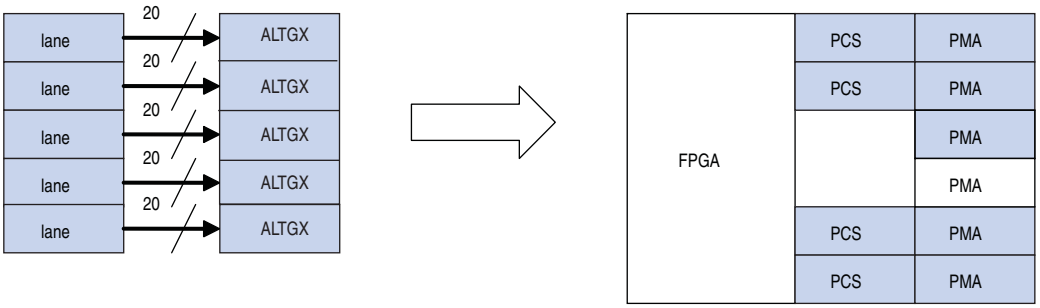
In 10- and 20-lane Interlaken MegaCore function variations, the transceivers are configured in PMA Direct mode. In all the other variations, the transceivers are configured in low latency PCS mode. Refer to the clock diagrams in "Clock Diagrams for the Interlaken MegaCore Function" on page 4–5 for information about how the transceiver bank clock and data lines are connected in the different variations. Figure 4–18 and Figure 4–19 show how the Interlaken MegaCore function uses the individual transceivers in each transceiver block, depending on the variation.

Figure 4–18. Transceiver Block Use in 4-, 8-, and 12-lane Variations



The 12-lane, 10.3125-Gbps variations use four PMAs in each of three transceiver blocks, with datapath width 40 bits rather than the 20 bits shown in Figure 4–18.

Figure 4–19. Transceiver Block Use in 10- and 20-lane Variations



A four-lane variation is configured with a single transceiver block, an eight-lane variation is configured with two transceiver blocks, and a 12-lane variation is configured with three transceiver blocks. These variations use four out of the six PMA blocks in each transceiver block. A 10-lane variation is configured with two transceiver blocks, and a 20-lane variation is configured with four transceiver blocks. These variations use five out of the six PMA blocks in each transceiver block. Because using five of the PMA blocks requires that one CMU channel be used, the transceivers are configured in PMA Direct mode. When only four of the PMA blocks are used, the transceivers are configured in low latency PCS mode.

Out-of-band Flow Control Block

Altera supports the optional inclusion of an out-of-band (OOB) flow control block in your Interlaken MegaCore function. If you turn on **Enable out-of-band flow control**, the block is configured in your MegaCore function. The block has an out-of-band flow control interface, as defined in Section 5.3.4.2 of the *Interlaken Protocol Definition, Revision 1.2*. You must connect the six signals in this interface to device pins.

On the application side, the OOB flow control block can receive link status, lane status, and calendar bits from the application, and transmit them on the TX OOB flow control interface to a downstream RX OOB flow control block associated with the Interlaken link partner. It can also transmit link status, lane status, and calendar bits to the application, after it receives them on the RX OOB flow control interface from an upstream TX OOB flow control block associated with the Interlaken link partner.

RX OOB Flow Control Block

The RX OOB flow control block can receive calendar bits from an upstream TX OOB flow control block associated with the Interlaken link partner, and transmit link status, lane status, and the original calendar bits to the application.

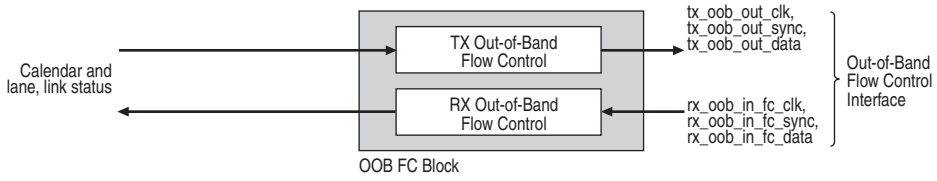
TX OOB Flow Control Block

The TX OOB flow control block can receive link status, lane status, and calendar bits from the application, and transmit them on the TX OOB flow control interface to a downstream RX OOB flow control block associated with the Interlaken link partner.

OOB Flow Control Block Signals

Figure 4–20 shows the OOB flow control block.

Figure 4–20. Out-of-band Flow Control Block



For clock constraints and comprehensive information about the signals of this block, refer to "Out-of-band Flow Control Interface Signals" on page 5–6.

5. Signals

This chapter describes the Interlaken MegaCore function signals.

Qsys allows you to export signals with different names or prefixes. Refer to the Qsys **System Contents** tab for the signals that support this capability, and to the Qsys **HDL Example** tab for the list of signals that are exported with predefined names. The default prefix for a newly exported signal is the MegaCore function instance name in the Qsys system. However, you can overwrite the name with which any signal is exported. After you export a signal, it is added in the **HDL Example** tab with the name you specify.

Interlaken Interface and External Transceiver Interface Signals

Table 5–1 through Table 5–3 list the pins related to the Interlaken interface of the Interlaken MegaCore function. If you turn off **Exclude transceivers**, your Interlaken MegaCore function includes high speed transceivers. Table 5–1 lists the Interlaken interface data signals in that case.

If you turn on **Exclude transceivers**, your Interlaken MegaCore function does not include high speed transceivers. In that case, the data for the Interlaken link appears on the external transceiver interface. Table B–1 on page B–3 lists the external transceiver interface signals.

Table 5–2 and Table 5–3 describe the Interlaken interface status signals. These signals are available whether or not you turn on **Exclude transceivers**.

Interlaken Interface Data and Clock Signals

Table 5–1 lists the Interlaken interface data and clock signals when you turn off **Exclude transceivers**.

Table 5–1. Interlaken Data Interface Signals (Part 1 of 2)

Signal	Direction	Description
`rx_serial_dataN_export [M:0]`	Input	Differential high speed serial input data to the transceiver. It is connected to the corresponding transmit data lines of the Interlaken link partner. N = 0 for 4-lane variations; N = {0,1} for 8- and 10-lane variations, N = {0,1,2} for 12-lane variations, and N = {0,1,2,3} for 20-lane variations. The width of the port is 4 (M=3) for 4-, 8-, and 12-lane variations, and 5 (M=4) for 10- and 20-lane variations.
`tx_serial_dataN_export [M:0]`	Input	Differential high speed serial output data from the transceiver. It is connected to the corresponding receive data lines of the Interlaken link partner. N = 0 for 4-lane variations; N = {0,1} for 8- and 10-lane variations, N = {0,1,2} for 12-lane variations, and N = {0,1,2,3} for 20-lane variations. The width of the port is 4 (M=3) for 4-, 8-, and 12-lane variations, and 5 (M=4) for 10- and 20-lane variations.
`ref_clk`	Input	Main transceiver reference clock. Refer to "Transceiver Reference Clock Recommended Frequency and Generation" on page 4–9.

Table 5–1. Interlaken Data Interface Signals (Part 2 of 2)

Signal	Direction	Description
cal_blk_clk	Input	Calibration clock for transceiver on-chip termination resistors. The Stratix IV GX transceiver on-chip termination resistors are calibrated by a single calibration block, which requires a calibration clock. The frequency range of cal_blk_clk is 10–125 MHz. For more information, refer to the *Stratix IV Transceiver Architecture* chapter in volume 2 of the *Stratix IV Device Handbook*.
tx_coreclkout	Output	Master TX clock from transceiver block 0. Clocks the transmit lanes of all transceiver blocks internally.
rx_coreclkout	Output	The physically central clock from among the rx_clk clocks output from the transceiver blocks. Drives the common_rx_clk input clock to all transceiver blocks internally. You can use this clock to drive the rx_mac_c_clk input clock.

Interlaken Interface Status Signals

Table 5–2 and Table 5–3 describe the Interlaken interface status signals. These signals are available whether or not you turn on **Exclude transceivers**.

Table 5–2. Interlaken RX Status Interface Signals *(Note 1)* (Part 1 of 2)

Signal	Direction	Description
rx_status_per_lane_word_lock [L:0]	Output	Indicates lane has locked onto the three-bit synchronization header. (Sixty-four consecutive legal sync patterns have been observed; 64B/67B Word Lock, in the Interlaken specification). This signal is deasserted when lane word lock is lost according to the Interlaken specification. Width is the number of lanes (L = num_lanes – 1).
rx_status_per_lane_sync_lock [L:0]	Output	Indicates lane has locked onto the meta frame boundary and recovered the scrambler seed from incoming traffic. (Rx LaneValid in the Interlaken specification). This signal is deasserted when sync lock is lost according to the Interlaken specification. Width is the number of lanes (L = num_lanes – 1).
rx_status_all_word_locked	Output	Indicates all lanes are word-locked.
rx_status_all_sync_locked	Output	Indicates all lanes are sync-locked.
rx_status_fully_locked	Output	Indicates the Interlaken receiver is fully locked. This signal is asserted when rx_status_all_word_locked is high, rx_status_all_sync_locked is high, and lane alignment is complete. (RX Operational, in Interlaken specification). The signal is deasserted when any of these three conditions no longer holds, according to the Interlaken specification.
rx_status_locked_time[15:0]	Output	Counter that tracks the time elapsed since rx_status_fully_locked is asserted. Increments once every 318×10^6 rx_mac_c_clk cycles.
rx_status_error_count[15:0]	Output	Counter that tracks the number of CRC-24 errors encountered.
rx_status_per_lane_crc32_errs [Q:0]	Output	Per-lane, 8-bit counters for tracking the number of CRC-32 errors encountered. Width is 8 × num_lanes. (Q = 8 × num_lanes – 1). Bits[7:0] track the CRC-32 errors on RX lane 0, bits [15:8] track the CRC-32 errors on RX lane 1, and so on.

Table 5–2. Interlaken RX Status Interface Signals *(Note 1)* (Part 2 of 2)

Signal	Direction	Description
rx_status_overflow	Output	Indicates that the RX MAC and channel filter blocks are unable to process data as fast as it arrives on the Interlaken link, and data is lost or corrupted. You can use the OOB flow control block to backpressure the Interlaken link partner.

Note to Table 5–2:

(1) All of the RX status signals are clocked by rx_mac_c_clk.

Table 5–3. Interlaken TX Status Interface Signals *(Note 1)*

Signal	Direction	Description
tx_status_hungry	Output	Indicates that the TX FIFO in the MAC TX block is close to underflow. By default, the Interlaken MegaCore function has TX underflow protection enabled, and the TX FIFO cannot actually underflow: in response to a near-underflow condition, the PCS TX block inserts IDLE words in the outgoing data stream (on tx_serial_dataN_export or tx_dataN_export). The application can monitor or ignore this signal. The signal warns the monitoring application that data density on the incoming channels is not ideal.
tx_status_overflow	Output	Indicates that the TX FIFO in the MAX TX block has overflowed. Data has been lost or corrupted.
tx_status_underflow	Output	Indicates that the TX FIFO in the MAC TX block has underflowed. By default, this condition cannot occur. The Interlaken MegaCore function has TX underflow protection enabled, and the TX FIFO cannot actually underflow: in response to a near-underflow condition, indicated by tx_status_hungry, the PCS TX block inserts IDLE words in the outgoing data stream (on tx_serial_dataN_export or tx_dataN_export).

Note to Table 5–3:

(1) All of the TX status signals are clocked by tx_mac_c_clk.

PCS Block Reset Signal

Table 5–4 describes the PCS TX block reset signal.

Table 5–4. Clock and Reset Interface signals

Signal	Direction	Description
tx_lane_r_reset	Input	Asynchronous reset for the Interlaken MegaCore function PCS TX block. Asserting this reset signal resets all the TX PCS internal registers, but does not reset the TX FIFO pointers (which are in the TX MAC). Instead, it clears the internal overflow bit, so the TX FIFO continues to empty, but deasserts the internal FIFO write enable. You must hold this reset signal asserted for 256 clock cycles to completely clear the TX FIFO. This reset signal can be asserted asynchronously, but must stay asserted at least one clock cycle and must be de-asserted synchronously with the clock with which it is associated (tx_coreclkout when transceivers are included in the MegaCore function, and tx_lane_c_clk when they are excluded for faster simulation). Refer to Figure 4–7 on page 4–11 for a circuit that shows how to enforce synchronous deassertion of tx_lane_r_reset.

Application Interface Signals

The application interface provides two channels through which the application receives data from and sends data to the Interlaken link. Table 5–5 through Table 5–8 describe the application interface signals.

RX Application Interface Signals

The RX application interface provides two channels through which the application receives data from the Interlaken link.

Table 5–5 and Table 5–6 describe the RX application interface signals.

Table 5–5. RX Application Clock and Reset Interface Signals

Signal	Direction	Description
rx_mac_c_clk	Input	Clocks the Interlaken MegaCore function MAC RX block and therefore, also, the RX application interface. For all MegaCore function variations except the 8-lane, 3.125-Gbps variations, Altera recommends that you drive this signal with the tx_coreclkout signal (in variations with transceivers), or that you drive this signal with the same clock that drives the tx_lane_c_clk signal (in variations without transceivers). For the 8-lane, 3.125-Gbps variations, the rx_mac_c_clk clock should be driven by a faster clock than the RX PCS clock, and Altera recommends that it be driven by the same clock that drives the tx_mac_c_clk. For recommended frequencies, refer to "Interlaken MegaCore Function Recommended Clock Rates" on page 4–8.
rx_mac_r_reset	Input	Asynchronous reset for the Interlaken MegaCore function MAC RX block. This reset signal can be asserted asynchronously, but must stay asserted at least one clock cycle and must be de-asserted synchronously with rx_mac_c_clk. Refer to Figure 4–7 on page 4–11 for a circuit that shows how to enforce synchronous deassertion of rx_mac_r_reset.

Table 5–6. RX Application Data Interface Signals *(Note 1)* (Part 1 of 2)

Signal	Direction	Description
rx_chX_dataout_data[W:0]	Output	Channel X data out. Streams the data received on the Interlaken interface out on channel X. Width is 128 bits for variations that require the 20G/4L license, 256 bits for variations that require the 40G/8L license, and 512 for variations that require one of the 100G licenses. For details, refer to Table 4–5 on page 4–12. (W = width – 1).
rx_chX_dataout_valid	Output	Indicates data out on the current channel (rx_chX_dataout_data) is valid in the current rx_mac_c_clk cycle.
rx_chX_dataout_startofpacket	Output	Indicates data out on the current channel in the current rx_mac_c_clk cycle includes a start-of-packet.
rx_chX_dataout_endofpacket	Output	Indicates data out on current channel in the current rx_mac_c_clk cycle includes an end-of-packet.
rx_chX_dataout_error	Output	Indicates an error occurred during transmission of the current packet on rx_chX_datain_data. This signal is valid only in an end-of-packet cycle.

Table 5–6. RX Application Data Interface Signals *(Note 1)* (Part 2 of 2)

Signal	Direction	Description
rx_chX_dataout_empty[T:0]	Output	Indicates the number of invalid bytes on the rx_chX_dataout_data bus in the current rx_mac_c_clk cycle, starting from the least significant byte. The value 1 indicates that bits [7:0] are invalid; the value 2 indicates bits [15:0] are invalid, and so on. Width is 4 bits for variations with a 128-bit wide channel (20G/4L license), 5 bits for variations with a 256-bit wide channel (40G/8L license), and 6 bits for variations with a 512-bit wide channel (either of the 100G licenses). For details, refer to Table 4–5 on page 4–12. (T = width – 1).

Note to Table 5–6:

(1) The Interlaken MegaCore function supports two channels on the application interface. The string "chX" in a signal name indicates two distinct signal names, one with "ch0" and one with "ch1", corresponding to the two channels, channel 0 and channel 1.

TX Application Interface Signals

The TX application interface provides two channels through which the application sends data to the Interlaken link.

Table 5–7 and Table 5–8 describe the TX application interface signals.

Table 5–7. TX Application Clock and Reset Interface Signals

Signal	Direction	Description
tx_mac_c_clk	Input	Clocks the Interlaken MegaCore function MAC TX block and therefore, also, the TX application interface. For all MegaCore function variations except the 8-lane, 3.125-Gbps variations, Altera recommends that you drive this signal with the tx_coreclkout signal (in variations with transceivers), or that you drive this signal with the same clock that drives the tx_lane_c_clk signal (in variations without transceivers). For the 8-lane, 3.125-Gbps variations, the tx_mac_c_clk clock should be driven by a faster clock than the TX PCS clock, and Altera recommends that it be driven by the same clock that drives the rx_mac_c_clk. For recommended frequencies, refer to "Interlaken MegaCore Function Recommended Clock Rates" on page 4–8.
tx_mac_r_reset	Input	Asynchronous reset for the Interlaken MegaCore function MAC TX block. This reset signal can be asserted asynchronously, but must stay asserted at least one clock cycle and must be de-asserted synchronously with tx_mac_c_clk. Refer to Figure 4–7 on page 4–11 for a circuit that shows how to enforce synchronous deassertion of tx_mac_r_reset.

Table 5–8. TX Application Interface SIgnals *(Note 1)* (Part 1 of 2)

Signal	Direction	Description
tx_chX_datain_data[W:0]	Input	Channel X data in. Streams in the channel X data to be transmitted on the Interlaken interface. Width is 128 bits for variations that require the 20G/4L license, 256 bits for variations that require the 40G/8L license, and 512 for variations that require one of the 100G licenses. For details, refer to Table 4–5 on page 4–12. (W = width – 1).
tx_chX_datain_valid	Input	Indicates data in on the current channel (tx_chX_datain_data) is valid in the current tx_mac_c_clk cycle.
tx_chX_datain_ready	Output	Acknowledge signal that indicates data has been received successfully and the application logic can proceed safely. This signal is the Avalon-ST protocol ready output flag. The input data stream for the current channel (tx_chX_datain_data) is backpressured until this signal is asserted.

Table 5–8. TX Application Interface SIgnals *(Note 1)* (Part 2 of 2)

Signal	Direction	Description
tx_chX_datain_startofpacket	Input	Indicates data in on the current channel in the current tx_mac_c_clk cycle includes a start-of-packet symbol.
tx_chX_datain_endofpacket	Input	Indicates data in on current channel in the current tx_mac_c_clk cycle includes an end-of-packet symbol.
tx_chX_datain_error	Input	Indicates an error occurred during transmission of the current packet on tx_chX_datain_data. This signal is valid only in an end-of-packet cycle.
tx_chX_datain_empty[T:0]	Input	Indicates the number of invalid bytes on the tx_chX_datain_data bus in the current tx_mac_c_clk cycle, starting from the least significant byte. The value 1 indicates that bits [7:0] are invalid; the value 2 indicates bits [15:0] are invalid, and so on. Width is 4 bits for variations with a 128-bit wide channel (20G/4L license), 5 bits for variations with a 256-bit wide channel (40G/8L license), and 6 bits for variations with a 512-bit wide channel (either of the 100G licenses). For details, refer to Table 4–5 on page 4–12. (T = width – 1).
tx_control_force_transmit	Input	RX calendar override. If this signal is asserted, the MegaCore function accepts data on tx_chX_datain_data (for every enabled channel) irrespective of the (in-band) RX calendar values.
tx_control_channel_enable [1:0]	Input	Channel enable vector. If the bit that corresponds to channel X (bit 0 for channel 0 and bit 1 for channel 1) is deasserted, the arbiter prevents the transfer of data on the corresponding channel, by not asserting the tx_chX_datain_ready signal for that channel in response to its tx_chX_datain_valid signal.

Note to Table 5–8:

(1) The Interlaken MegaCore function supports two channels on the application interface. The string "chX" in a signal name indicates two distinct signal names, one with "ch0" and one with "ch1", corresponding to the two channels, channel 0 and channel 1.

Out-of-band Flow Control Interface Signals

The OOB flow control interface is present only in Interlaken MegaCore function variations that include an OOB block. Table 5–9 and Table 5–11 describe the out-of-band flow control interface signals.

RX Out-of-band Flow Control Signals

The receive OOB flow control interface receives input flow-control clock, data, and sync signals and sends out calendar and status information. Table 5–9 describes the receive OOB flow control interface signals specified in the *Interlaken Protocol Definition, Revision 1.2*. Table 5–10 describes the signals on the application side of the RX OOB flow control block.

Table 5–9. RX Out-of-band Flow Control Interface Signals

Signal	Direction	Description
rx_oob_in_fc_clk *(1)*	Input	Input reference clock from an upstream OOB TX block. This signal clocks the rx_oob_in_fc_data and rx_oob_in_fc_sync signals. You must connect this signal to a device pin. Refer to "Out-of-band Flow Control Block Recommended Clock Frequencies" on page 4–10.
rx_oob_in_fc_data	Input	Input serial data pin from an upstream OOB TX block. You must connect this signal to a device pin.
rx_oob_in_fc_sync	Input	Input sync control pin from an upstream OOB TX block. You must connect this signal to a device pin.

Note to Table 5–9:

(1) The maximum rx_oob_in_clk frequency allowed by the Interlaken specification is 100 MHz. Altera recommends that you run the rx_oob_in_clk clock at 100 MHz.

Table 5–10. RX Out-of-band Flow Control Block Signals for Application Use

Signal	Direction	Description
rx_oob_in_sys_clk *(1)*	Input	Reference clock for capturing RX calendar, lane status, and link status. Frequency must be at least double the frequency of rx_oob_in_fc_clk.
rx_oob_in_sys_arst	Input	Asynchronous reset for the OOB RX block.
rx_oob_out_status_update	Output	Indicates a new value without CRC-4 errors is present on at least one of rx_oob_out_lane_status or rx_oob_out_link_status in the current rx_oob_in_sys_clk cycle. The value is ready to be read by the application logic.
rx_oob_out_lane_status[L:0]	Output	Lane status bits received from an upstream OOB TX block on rc_oob_in_fc_data. Width is the number of lanes (L = num_lanes – 1).
rx_oob_out_link_status	Output	Link status bit received from an upstream OOB TX block on rc_oob_in_fc_data.
rx_oob_out_status_error	Output	Indicates corrupt lane or link status. A new value is present on at least one of rx_oob_out_lane_status or rx_oob_out_link_status in the current rx_oob_in_sys_clk cycle, but the value has at least one CRC-4 error.
rx_oob_out_calendar[15:0]	Output	Calendar bits received from an upstream OOB TX block on rc_oob_in_fc_data.
rx_oob_out_calendar_update	Output	Indicates a new value without CRC-4 errors is present on rx_oob_out_calendar in the current rx_oob_in_sys_clk cycle. The value is ready to be read by the application logic.
rx_oob_out_calendar_error	Output	Indicates corrupt calendar bits. A new value is present on rx_oob_out_calendar in the current rx_oob_in_sys_clk cycle, but the value has at least one CRC-4 error.

Note to Table 5–10:

(1) Altera recommends that you run rx_oob_in_sys_clk at 200 MHz, to support the recommended (and maximum allowed) rx_oob_in_fc_clk frequency of 100 MHz.

TX Out-of-band Flow Control Interface Signals

The transmit OOB flow control interface receives calendar and status information, and transmits flow-control clock, data, and sync signals. Table 5–11 describes the transmit OOB flow control interface signals specified in the *Interlaken Protocol Definition, Revision 1.2*. Table 5–12 describes the signals on the application side of the TX OOB flow control block.

Table 5–11. TX Out-of-band Flow Control Interface Signals

Signal	Direction	Description
tx_oob_out_clk *(1)*	Output	Output reference clock for a downstream OOB RX block. This signal clocks the tx_oob_out_data and tx_oob_out_sync signals. You must connect this signal to a device pin. Refer to "Out-of-band Flow Control Block Recommended Clock Frequencies" on page 4–10.
tx_oob_out_data	Output	Output serial data pin for a downstream OOB RX block. You must connect this signal to a device pin.
tx_oob_out_sync	Output	Output sync control pin for a downstream OOB RX block. You must connect this signal to a device pin.

Note to Table 5–11:

(1) The maximum tx_oob_out_clk frequency allowed by the Interlaken specification is 100 MHz. Altera recommends that you run the tx_oob_out_clk clock at 100 MHz.

Table 5–12. TX Out-of-band Flow Control Block Signals for Application Use

Signal	Direction	Description
tx_oob_in_double_fc_clk *(1)*	Input	Reference clock for generating the flow control output clock tx_oob_out_clk. The frequency of the tx_oob_in_double_fc_clk clock must be double the intended frequency of tx_oob_out_clk.
tx_oob_in_double_fc_arst	Input	Asynchronous reset for the OOB TX block.
tx_oob_in_ena_status	Input	Enable transmission of the lane status and link status to the downstream OOB RX block. If this signal is asserted, the lane and link status information is transmitted on tx_oob_out_data. If this signal is not asserted, only the calendar information is transmitted on tx_oob_out_data.
tx_oob_in_lane_status[L:0]	Input	Lane status to be transmitted to a downstream OOB RX block if tx_oob_in_ena_status is asserted. Width is the number of lanes (L = num_lanes – 1).
tx_oob_in_link_status	Input	Link status to be transmitted to a downstream OOB RX block if tx_oob_in_ena_status is asserted.
tx_oob_in_calendar[15:0]	Input	Calendar status to be transmitted to a downstream OOB RX block.

Note to Table 5–12:

(1) Altera recommends that you run tx_oob_in_double_fc_clk at 200 MHz, to support the recommended (and maximum allowed) tx_oob_out_clk frequency of 100 MHz.

6. Qsys Design Examples

Design Examples Overview

The Interlaken MegaCore function includes four demonstration design examples. Each license allows you to program a device with one of the four design examples. Table 6–1 lists the design example available for each license. The design example names specify the Interlaken MegaCore function variations they test.

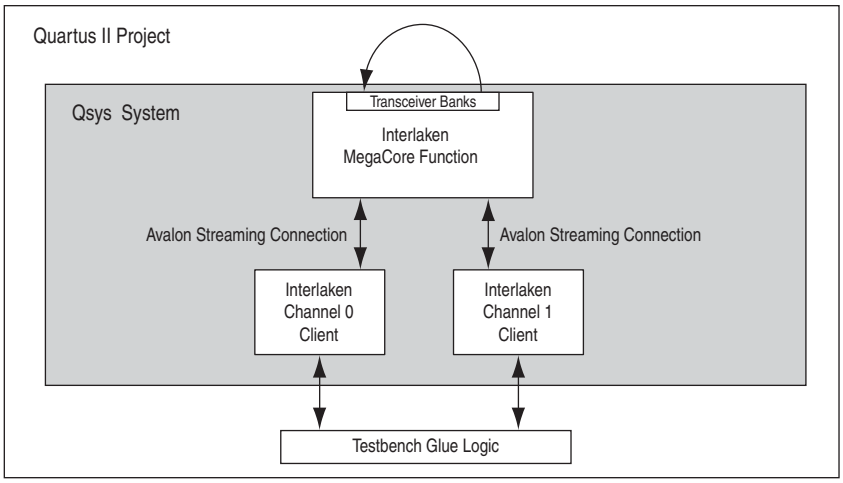
Table 6–1. Interlaken MegaCore Function Design Examples

License	Design Example
IP-INTLKN/20G/4L	alt_interlaken_4lane_3g
IP-INTLKN/40G/8L	alt_interlaken_8lane_6g
IP-INTLKN/100G/12L	alt_interlaken_12lane_10g
IP-INTLKN/100G/20L	alt_interlaken_20lane_6g

For information about acquiring the license required to program each design example variation on an Altera device, refer to "Installation and Licensing" on page 1–4.

Figure 6–1 shows a block diagram correct for each design example.

Figure 6–1. Qsys Interlaken Design Example



The design examples each demonstrate a system that combines an Interlaken MegaCore function with two channel clients that generate input to the application interface and check the resulting output. The Interlaken link transmit lines are connected to the receive lines, creating an external feedback loop. From the Qsys system provided with each design example, Qsys automatically generates Verilog HDL files that include all the required components and interconnections. Qsys also generates IEEE encrypted functional simulation models for the simulators listed in "Simulating the Design" on page 2–4. The Verilog HDL files that Qsys generates are ready to be compiled in the Quartus II software for programming an Altera device.

For more information about the interconnect fabric that Qsys generates, refer to the *Qsys Interconnect* chapter in volume 1 of the *Quartus II Handbook*. For more information about Qsys, refer to the *System Design with Qsys* section in volume 1 of the *Quartus II Handbook*.

The design example files are provided in the Interlaken IP core installation directory. You can use them as a basis for developing your own testbench for your Interlaken MegaCore function variation. Based on the example, you can create your own stimuli and verification criteria, using the Interlaken Sample Channel Client component available in the Qsys tool.

Interlaken Sample Channel Client Component

The design examples implement each channel client with an Interlaken Sample Channel Client component.

The Interlaken Sample Channel Client is a component in the Component Library in the Qsys system integration tool. The only parameter available in its parameter editor is **Width of datapath in bits**, which must match the datapath width of the Interlaken MegaCore function to which it connects. However, its instantiation relies on values being assigned to the additional parameters shown in Table 6–2.

Table 6–2. Interlaken Sample Channel Client Hidden Parameters

Parameter	Description	Default Value
WORDS	Number of 64-bit words in each data sample. (Not all bits need be valid). Value is one of 2, 4, or 8, depending on the DUT variation.	8
LOG_WORDS	Size of the internal register that holds the number of valid words in the current transmission in or out. Value is 2, 3, or 4, depending on the DUT variation, because holding a number from 0 to WORDS requires $\log_2$(WORDS) + 1 bits.	4
EMPTY_BITS	Size of the internal register that holds the number of empty bytes in transmissions in and out of the Interlaken Sample Channel Client. Value is 4, 5, or 6, depending on the DUT variation, because holding a number from 0 to 8, 0 to 16, or 0 to 64 requires 4, 5, or 6 bits.	6
BUFFER_WORDS	Number of 64-bit words in `TX_STRING` and `RX_STRING` vectors. Default value is WORDS × 2.	WORDS × 2
TX_STRING	String from which outgoing data samples are derived. Length is BUFFER_WORDS × 64.	
RX_STRING	String against which to check Interlaken RX incoming data samples after they pass through the channel interface.	

The Interlaken Sample Channel Client sends data samples on the channel to which it is connected in the RX application interface. Each data sample is some number of bits that fits in WORDS number of 64-bit (8-byte) words. These are the valid bits in the transmission. An internal register of size LOG_WORDS holds the number of 64-bit words with at least one valid bit in them, and an internal register of size EMPTY_BITS holds the number of bytes with no valid bits in them. The LOG_WORDS and EMPTY_BITS parameters can be derived from the value of WORDS, but are provided as separate parameters for legibility.

The Interlaken Sample Channel Client maintains a string (`TX_STRING`) from which it generates the data samples. It compares the returning data samples against another string of the same length (`RX_STRING`). In the design examples, the data passes through an Interlaken link external loopback path, and so the two strings are identical. However, the Interlaken Sample Channel Client component is useful in additional testing configurations. For example, you could create two instances of this component, connected to two Interlaken MegaCore function Interlaken link partners, to generate and check data samples at opposite ends of the link. In that case, you would define the `TX_STRING` in each to be identical to the `RX_STRING` in the other.

Design Example Simulation Sequence

The design example performs the following transactions:

- Activates the Interlaken Sample Channel Client on each of the two channels to send data samples to the RX application interface of the Interlaken MegaCore function. The channel client actions are described in "Interlaken Sample Channel Client Component".
- Confirms valid data is received by the sample channel client from the relevant channel of the RX application interface of the Interlaken MegaCore function.
- Keeps track of the count-stamp of the latest incoming data sample received, and checks that the current data sample count-stamp is equal to the previous stamp incremented by one.
- Monitors the output from each channel of the RX application interface of the Interlaken MegaCore function for CRC-24 and CRC-32 errors.

After the design example sends and receives 100 packets on each channel, with no CRC-24 or CRC-32 errors, it declares success and terminates.

Running a Design Example

The steps for running each design example are identical. Simply substitute the name of your preferred example from Table 6–1. For purposes of illustration, the steps in this chapter refer to the alt_interlaken_8lane_6g design example.

This section describes the following steps for running the alt_interlaken_8lane_6g design example:

1. Setting Up the Design Example
2. Creating the Quartus II Project and Generating the Qsys System
3. Simulating the System
4. Compiling and Programming the Device

Appendix C, Closing Timing on 10- and 20-lane Designs includes additional steps you must follow to ensure that the alt_interlaken_20lane_6g design example achieves timing closure on a Stratix IV GX FPGA.

Setting Up the Design Example

The design example files are located in the **design_examples** subdirectory of your Interlaken MegaCore function installation directory. Refer to "Installation and Licensing" and Figure 1–2 on page 1–5 for the location of the MegaCore function installation directory in your Altera installation.

To set up the alt_interlaken_8lane_6g design example, copy the **design_examples/alt_interlaken_8lane_6g** directory to your working directory. The new subdirectory, **alt_interlaken_8lane_6g**, is your design example working directory.

Creating the Quartus II Project and Generating the Qsys System

To create the Quartus II project for the design example, follow these steps:

1. On the Windows start menu, click **Programs > Altera > Quartus II** <*version*> **> Quartus II** <*version*> to run the Quartus II software.
2. On the View menu, point to **Utility Windows** and click **Tcl Console**.
3. In the Tcl Console, change directory to your new design example working directory, **alt_interlaken_8lane_6g**.
4. Type the following command:

   ```
   source setup_proj.tcl ↵
   ```

   The Tcl script creates a Quartus II project and adds some required assignments to the Quartus II Settings File (**.qsf**).
5. On the File menu, click **Open Project** and open the **alt_interlaken_8lane_6g.qpf** project.
6. On the File menu, click **Open** and open the **alt_interlaken_8lane_6g.qsys** file. The alt_interlaken_8lane_6g Qsys system opens in the Qsys tool.
7. In Qsys, on the **Generation** tab, turn on **Create Verilog simulation model** and **Create HDL design files for synthesis**.
8. Click **Generate**.

The Qsys system is generated and the project is ready to simulate in a supported simulator and to compile in the Quartus II software.

Simulating the System

Qsys generates vendor-specific IEEE encrypted functional simulation models for all the simulators listed in "Simulating the Design" on page 2–4. However the design examples includes a simulation script only for the ModelSim simulator. This section shows you how to simulate your system using that script with the currently supported ModelSim-SE simulator.

To simulate your system in the ModelSim simulation tool, follow these steps:

1. Start the ModelSim software.
2. Change directory to the testbench subdirectory of your design example working directory, **alt_interlaken_8lane_6g/testbench**.
3. Type the following command at the ModelSim command prompt:

   ```
   do run_simulation.do ↵
   ```

   The design example runs and displays a waveform showing the signals as the design example implements the sequence described in "Design Example Simulation Sequence" on page 6–3.

   The simulation run completes successfully with the following message:

   ```
   # Test complete
   # Received        100 packets on channel 0
   # Received        100 packets on channel 1
   # Simulation success...
   ```

4. When simulation finishes, on the File menu, click **Quit** to close the ModelSim software and return to the Quartus II software to compile your system.

Compiling and Programming the Device

The Qsys system files are now ready for compilation in the Quartus II software. If you have acquired a license for this design example variation, compilation generates an **.sof** for device programming. To compile your system design in the Quartus II software, follow these steps:

1. Open the Quartus II project you created in "Creating the Quartus II Project and Generating the Qsys System" on page 6–4.
2. On the Processing menu, click **Start Compilation** to compile your system.

After you compile the design example, you can program your target Altera device and verify the design in hardware using the appropriate Interlaken MegaCore function license.

The alt_interlaken_20lane_6g design example requires some additional steps to ensure it achieves timing closure. Refer to Appendix C, Closing Timing on 10- and 20-lane Designs for a list of steps you can implement to improve timing.

A. Initializing the Interlaken MegaCore Function

This appendix describes a basic initialization sequence for the Interlaken MegaCore function, provides some troubleshooting tips for the Interlaken link, and briefly describes the expected sequence of signal assertions during initialization.

Initialization Sequence

This section describes the most basic initialization sequence for an Interlaken system that contains two Interlaken MegaCore functions connected through their Interlaken interfaces.

To initialize the system, perform these steps:

1. Configure the devices with the two Interlaken MegaCore functions.
2. Perform the following reset sequence for each Interlaken MegaCore function:
   a. Assert the MAC resets (`rx_mac_r_reset` and `tx_mac_r_reset`) and the lane reset (`tx_lane_r_reset`).
   b. De-assert the `tx_lane_r_reset` reset signal.
   c. Wait 256 `tx_mac_c_clk` cycles.
   d. De-assert the `rx_mac_r_reset` and `tx_mac_r_reset` signals.

Following these steps, you should observe the behavior described in "Expected Behavior at Initialization".

Expected Behavior at Initialization

Following deassertion of the MAC reset signals, as your Interlaken MegaCore function initializes and establishes an Interlaken link with its link partner, you should observe the following changes on the output signals:

1. For each lane `i`, status signals change in the following order:
   a. `rx_status_per_lane_word_lock[i]` is asserted. This signal indicates the lane has locked onto the three-bit synchronization header, which occurs when 64 consecutive legal sync patterns have been observed. This state is 64B/67B Word Lock, shown in Figure 13 in the *Interlaken Protocol Definition, Revision 1.2*.
   b. `rx_status_per_lane_sync_lock[i]` is asserted. This signal indicates the lane has locked onto the meta frame boundary and recovered the scrambler seed from incoming traffic. This state is RX LaneValid, shown in Figure 8 in the *Interlaken Protocol Definition, Revision 1.2*.
2. After `rx_status_per_lane_word_lock[i]` is asserted for every lane `i` (every lane has achieved the 64B/67B Word Lock state), the `rx_status_all_word_locked` signal is asserted.
3. After `rx_status_per_lane_sync_lock[i]` is asserted for every lane `i` (every lane has achieved the RX LaneValid state), the `rx_status_all_sync_locked` signal is asserted.

4. After both rx_status_all_word_locked and rx_status_all_sync_locked are asserted, the rx_status_fully_locked signal is asserted. This signal indicates lane alignment and meta frame alignment are complete, and the Interlaken receiver is fully locked. This state is RX Operational, shown in Figure 9 in the *Interlaken Protocol Definition, Revision 1.2*.

   The rx_status_fully_locked signal is asserted four meta frames after the rx_status_all_word_locked and rx_status_all_sync_locked signals are asserted. All of the signals are expected to remain high after they are first asserted during initialization.

Now your Interlaken IP core is ready to start sending and receiving packets.



The TX status signals might toggle during initialization.Their values are not valid until after initialization completes, when the rx_status_fully_locked signal is asserted. By default, an internal parameter setting ensures that the TX FIFO never underflows, so the application can choose to monitor or to ignore the tx_status_hungry and tx_status_underflow signals. During initialization, the application should ignore all the TX status signals. Refer to Table 5–3 on page 5–3.

Troubleshooting an Interlaken Link

If your application cannot establish an Interlaken link, check for the following symptoms that indicate specific potential root causes:

- If the rx_status_per_lane_word_lock[i] signal is not asserted for some lane i, this lane has not achieved word lock. The RX lanes can establish word lock in the presence of very high bit error rates, so bit errors are unlikely to be the cause of the problem. Instead, focus on the consistency between your MegaCore function data rate and the different clock rates, and whether you have an extreme cabling error such as TX-RX reversal. For information about the recommended clock rates for different Interlaken data rates, refer to "Clocking and Reset Structure" on page 4–4.
- If the rx_status_per_lane_sync_lock[i] signal is not asserted for some lane i, this lane has not achieved meta frame lock or has not recovered the scrambler seed successfully. Meta frame lock requires a moderate quality connection to the transceiver. If the lane does not achieve the lock at all, check that the same meta frame length is specified for the two Interlaken link partners, and that the cables that connect to your board's transceiver pins meet the requirements of your board specification. If the lock is intermittent, recheck the physical connection of the link cables to the transceiver, and confirm that the analog settings of the transceiver remain at the default values for the Interlaken MegaCore function.
- If the value of rx_status_per_lane_crc32_errs is high for any lane, while rx_status_per_lane_sync_lock remains asserted, the lane is experiencing CRC-32 errors. Because the lane achieved meta frame lock, you can rule out gross physical connection issues. Instead, focus on analog signal integrity causes.

- If the lanes are locked and not generating CRC-32 errors, you can exchange traffic. If IDLE symbols pass, but regular traffic generates numerous CRC-24 errors, the lanes might be out of order. IDLE symbols are single word messages and therefore not subject to ordering issues. However, multi-word messages generate CRC-24 errors when the lanes are out of order. Due to manufacturing constraints, boards and adapters are often designed with scrambled lane order. Check that your physical connections take these lane order differences into account.

B. Excluding Transceivers for Faster Simulation

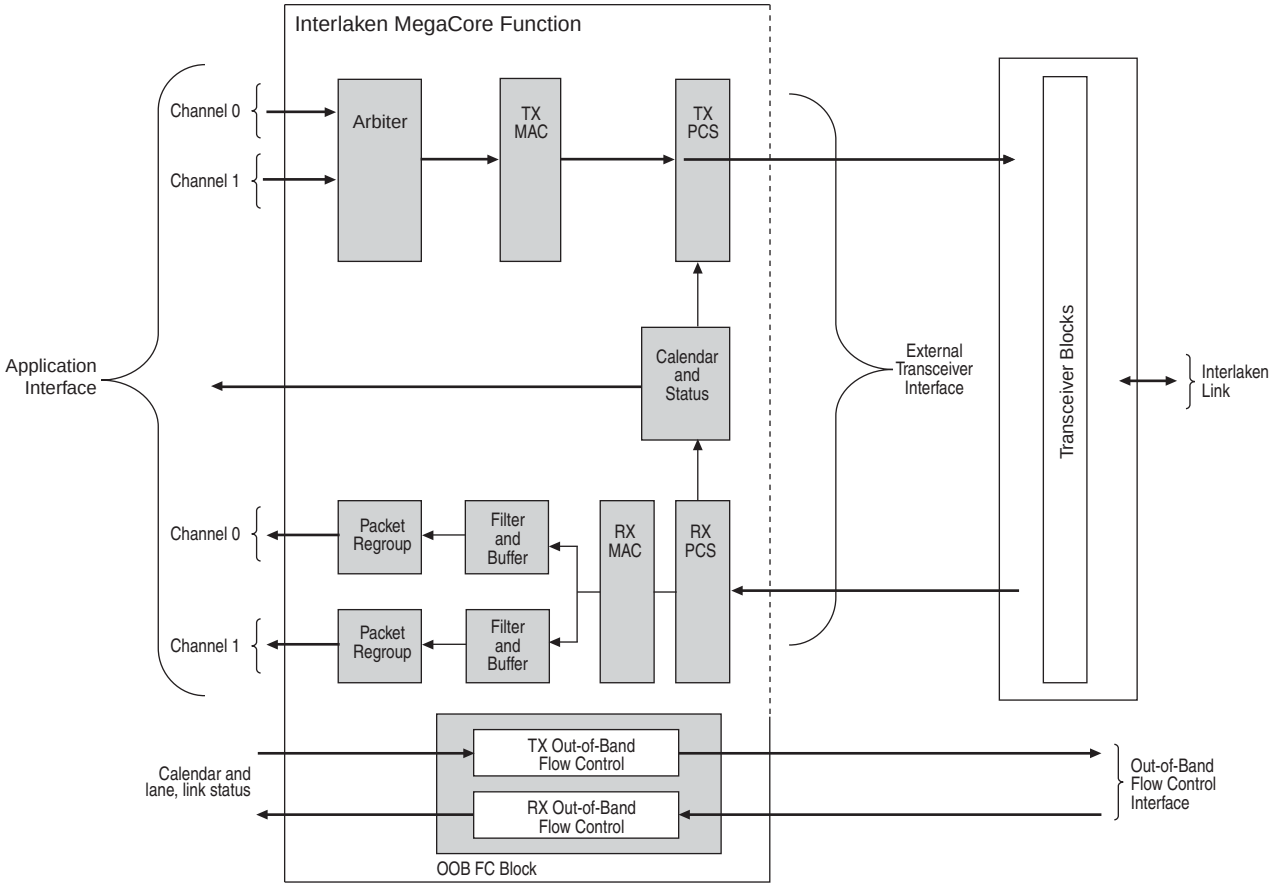
The external transceiver interface is the interface that connects the Interlaken MegaCore function to a transceiver if you turn on the **Exclude transceiver** parameter. You might choose to turn on this parameter to increase the simulation speed of your design. However, excluding the transceivers from the Interlaken MegaCore function removes them from the synthesizable RTL as well as from the functional simulation model. Therefore, you should expect to regenerate your Interlaken IP core with the transceivers after you verify your design in simulation.

The external transceiver interface provides parallel transmit and receive datapaths, plus the necessary clock signals to allow you to connect the Interlaken MegaCore functions to high-speed transceivers in your design.

An Interlaken MegaCore function that excludes transceivers can include or exclude the OOB flow control block.

Figure B–1 illustrates how the external transceiver interface is derived from the full Interlaken MegaCore function.

Figure B–1. Interlaken MegaCore Function Block Diagram Showing the External Transceiver Interface



This appendix describes the external transceiver interface.

External Transceiver Interface Clocks

If you turn on **Exclude transceivers**, your Interlaken MegaCore function exposes the interface to the transceivers. With this parameter setting, the Interlaken MegaCore function has the following external transceiver interface input clocks:

- `rx_lane_clkN_export[M:0]`—These (N × M) input clocks each clock a distinct Interlaken receive lane. The Interlaken MegaCore function derives an RX PCS block clock from these input clocks.

  The grouping of these clocks indicated by the use of N and M is based on the connections to transceivers when they are included: N is the number of transceiver blocks required for this variation (minus 1), and M is the number of lanes per transceiver block (minus 1). For the 10-lane and 20-lane variations, M is five. For the remaining variations, M is four. For an illustration of this numbering scheme, refer to "Clock Diagrams for the Interlaken MegaCore Function" on page 4–5.

- `tx_lane_c_clk`—Clocks the TX PCS block and the Interlaken transmit lanes.



For all Interlaken MegaCore variations except the 8-lane, 3.125-Gbps variation, Altera recommends that the same clock drive the `rx_mac_c_clk`, `tx_mac_c_clk`, and `tx_lane_c_clk` clocks.

Because the Interlaken MegaCore function does not include the high-speed transceivers in this case, the `ref_clk` and `cal_blk_clk` input clocks to the transceivers, which are input signals to the Interlaken MegaCore function if it includes transceivers, are not included in the MegaCore function that excludes transceivers.

Figure B–1 illustrates how you can derive the external transceiver interface signal and clock information by simply removing the HSIO banks from the corresponding variation with transceivers. Figure B–2 and Figure B–3 show the four-lane and eight-lane variations without transceivers.

Figure B–1. Clock Diagram for 4-lane Interlaken MegaCore Function with Transceivers

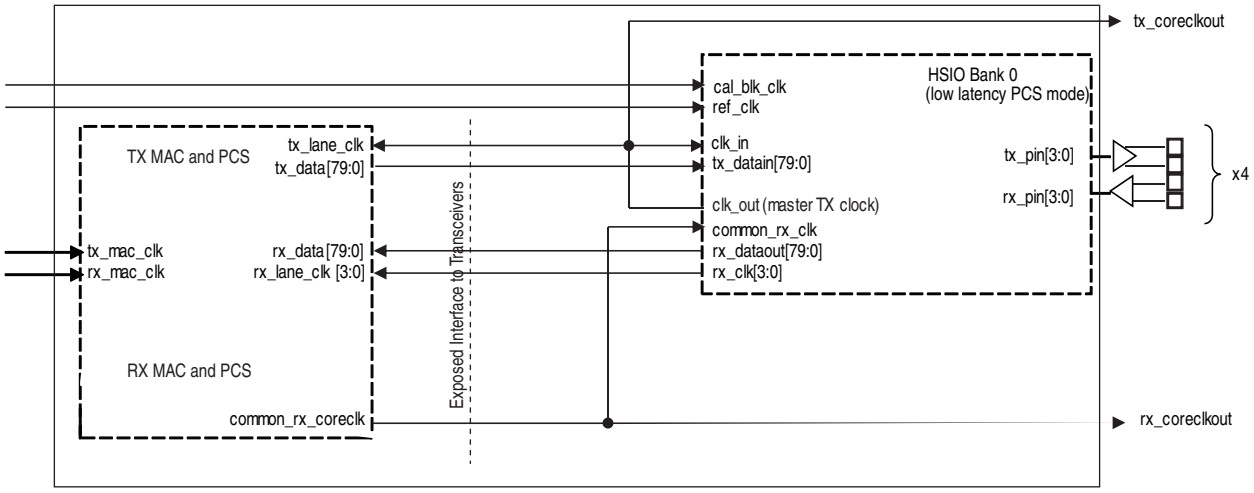


Figure B–2 shows the clock diagram for a four-lane variation that does not include transceivers.

Figure B–2. Clock Diagram for 4-lane Interlaken MegaCore Function Without Transceivers

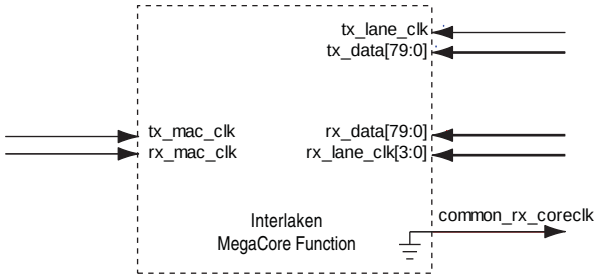
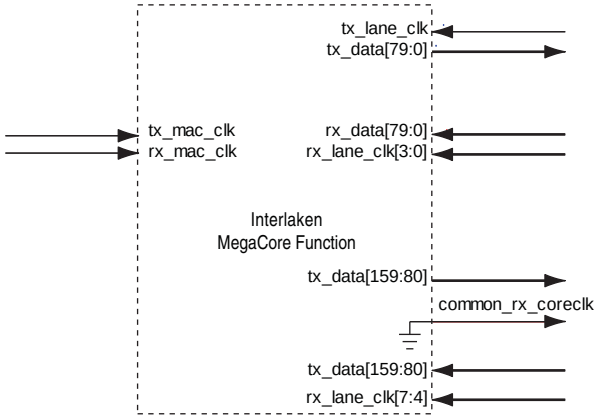


Figure B–3 shows the clock diagram for an eight-lane variation that does not include transceivers.

Figure B–3. Clock Diagram for 8-lane Interlaken MegaCore Function Without Transceivers



External Transceiver Interface Data and Clock Signals

If you turn on **Exclude transceivers**, your Interlaken MegaCore function does not include high speed transceivers. In that case, the data for the Interlaken link appears on the external transceiver interface. Table B–1 lists the external transceiver interface data and clock signals in Interlaken MegaCore function variations that do not include high speed transceivers.

Table B–1. External Transceiver Interface Signals (Part 1 of 2)

Signal	Direction	Description
`tx_dataN_export[S:0]`	Output	Parallel transmit data interface. Port width is transceiver datapath width times number of lanes. For the 12-lane, 10-Gbps variation, the transceiver datapath width is 40. For all the other variations, the transceiver datapath width is 20. (S = calculated port width – 1).
`rx_dataN_export[S:0]`	Input	Parallel receive data interface. Port width is transceiver datapath width times number of lanes. For the 12-lane, 10-Gbps variation, the transceiver datapath width is 40. For all the other variations, the transceiver datapath width is 20. (S = calculated port width – 1).

Table B–1. External Transceiver Interface Signals (Part 2 of 2)

Signal	Direction	Description
tx_lane_c_clk	Input	Clocks the Interlaken transmit lanes.
rx_lane_clkN_export[M:0]	Input	Clock inputs from external transceivers. N = 0 for 4-lane variations; N = {0,1} for 8- and 10-lane variations, N = {0,1,2} for 12-lane variations, and N = {0,1,2,3} for 20-lane variations. The width of the port is 4 (M=3) for 4-, 8-, and 12-lane variations, and 5 (M=4) for 10- and 20-lane variations.
common_rx_c_clk	Output	This signal is tied to 0 when the external transceiver interface is exposed.

C. Closing Timing on 10- and 20-lane Designs

I/O timing is critical for Interlaken MegaCore functions. Achieving timing closure for 10- and 20-lane Interlaken MegaCore function designs can be difficult, because these variations use the transceivers in Basic (PMA Direct) mode, in which the transceiver block PCS blocks are not utilized.

This appendix provides guidance to help achieve timing closure for your 20-lane Interlaken MegaCore function. You can adapt these steps for different locations and region sizes if you are having difficulty closing timing for your 10-lane Interlaken MegaCore function.

The steps described in this appendix use the LogicLock feature to lock the Interlaken MegaCore function on the left edge of the Stratix IV GX device and ensure that the various blocks are shaped so that all the transceiver assignments are on the same edge. After you use the LogicLock feature to lock the Interlaken IP core in a set location on the device, you compile your design and start working to close timing on the remaining failing paths identified by the TimeQuest Timing Analyzer.

To help close the timing gap for your 20-lane Interlaken MegaCore function, follow these steps before compiling your design:

1. In the Quartus II software, on the File menu, click **Open Project** and select your Quartus II project.
2. On the Processing menu, point to **Start** and click **Analysis & Synthesis**. Analysis and synthesis may take several minutes.
3. After Analysis and Synthesis completes, on the Assignments menu, click **LogicLock Regions Window**. The LogicLock Regions window opens.
4. To create LogicLock regions for the RX and TX paths, follow these steps:
    a. In the Compilation Hierarchy window, navigate to the top level of the Interlaken RX hierarchy, <*instance name*>**:irx**.
    b. Right-click the top level of the Interlaken RX hierarchy, select **LogicLock Region**, and click **Create New LogicLock Region**. The new LogicLock region appears in the LogicLock Regions window.
    c. Repeat steps a and b for the Interlaken TX hierarchy, <*instance name*>**:itx**.
5. To set the parameters of the new Interlaken RX hierarchy LogicLock region, follow these steps:
    a. In the LogicLock Regions window, right-click the new RX hierarchy LogicLock region row, and click **LogicLock Regions Properties**.
    b. On the **Size & Origin** tab, under **Size**, turn off **Auto** and set the **Width** to 55 and the **Height** to 64.
    c. Under **Origin**, turn off **Floating** and set **Location string** to `X7_Y64`.
    d. Click **Apply**.
    e. Click **OK**.

6. To set the parameters of the new Interlaken TX hierarchy LogicLock region, repeat step 5, with **Width** 58, **Height** 63, and **Origin** `X7_Y1`.
7. To create a LogicLock region for the clock-crossing FIFOs in the HSIO block, follow these steps:
   a. In the LogicLock Regions window, in the **Region Name** column, double-click **<<new>>** to create a new region.
   b. In the new row, in the **Region Name** column, type a name for your new region <*FIFO_LLR*>.
   c. Right-click the <*FIFO_LLR*> row, and click **LogicLock Regions Properties**.
   d. On the **General** tab, click **Add**. The **Add Node** dialog box appears.
   e. For **Node name**, type `*clock_crossing_fifo*`.
   f. Click **OK**.
   g. In the **LogicLock Regions Properties** dialog box, click **Apply**.
   h. On the **Size & Origin** tab, under **Size**, turn off **Auto** and set the **Width** to 3 and the **Height** to 129.
   i. Under **Origin**, turn off **Floating** and set **Location string** to `X3_Y1`.
   j. Click **Apply**.
   k. Click **OK**.
8. Repeat step 7 for a new region <*IGX_IF*> that includes the nodes that match `*launch*` or `*rx_capture*` or `*rx_dataout_to_fifo*`, with **Width** 5, **Height** 129, and **Origin** `X1_Y1`.
9. To force the transceivers to the left edge of the device, follow these steps:
   a. On the Assignments menu, click **Assignment Editor**.
   b. In the Assignment Editor, click **<<new>>**.
   c. In the new row, click the **Assignment Name** column and select **Location**.
   d. Double-click the **Value** column and click the Browse icon.
   e. In the **Location** dialog box, for **Element**, select **Edge**.
   f. For **Location**, select **EDGE_LEFT**.
   g. Click **OK**.
   h. Double-click the **To** column and click the Node Finder icon. The Node Finder appears.
   i. For **Named**, type `*serial*data*export*`.
   j. Click **List**.
   k. Click the double right arrow to move all the found nodes to the **Selected Nodes** list.
   l. Click **OK**.

10. To optimize the Fitter settings for the 10- or 20-lane Interlaken MegaCore function, follow these steps:
    a. On the Assignments menu, click **Settings**.
    b. In the **Settings** dialog box, under **Category**, click **Fitter Settings**.
    c. Turn on **Optimize hold timing** and select **All Paths**.
    d. Turn on **Optimize multi-corner timing**, select **Standard Fit**, and turn on **Limit to one fitting attempt**.
    e. Click **More Settings**.
    f. For **Name**, select **Placement Effort Multiplier**.
    g. For **Setting**, type `4.0`.
    h. Click **OK**.
    i. Click **Apply**.
    j. Click **OK**.
11. Perform the following iterative process:
    a. Compile your design.
    b. Turn off Global Signal to all `tx_launch` registers with failing paths. Depending on your paths, you might add a line similar to the following example assignment to your **.qsf** file:

```
set_instance_assignment -name GLOBAL_SIGNAL OFF \
            -from *transmit_pma0*clockout -to *tx_launch[*]
```

    c. Make PCLK assignments on remaining failing `tx_launch` registers. Depending on your paths, you might add a line similar to the following example assignment to your **.qsf** file:

```
set_instance_assignment -name GLOBAL_SIGNAL “PERIPHERY CLOCK”\
            -from *transmit_pma0*clockout -to *tx_prelaunch[*]
```

    d. Check the remaining failing paths, and force manual placement if needed.
    e. Repeat as needed.

For more information about LogicLock regions, refer to the *Quartus II Incremental Compilation for Hierarchical and Team-Based Design* chapter in volume 1 of the *Quartus II Handbook*.

For more information about the TimeQuest Timing Analyzer, refer to the Quartus II Help and the *Timing Analysis* section in volume 3 of the *Quartus II Handbook*.

D. Connecting to User-Defined Arbitration and Regrouping

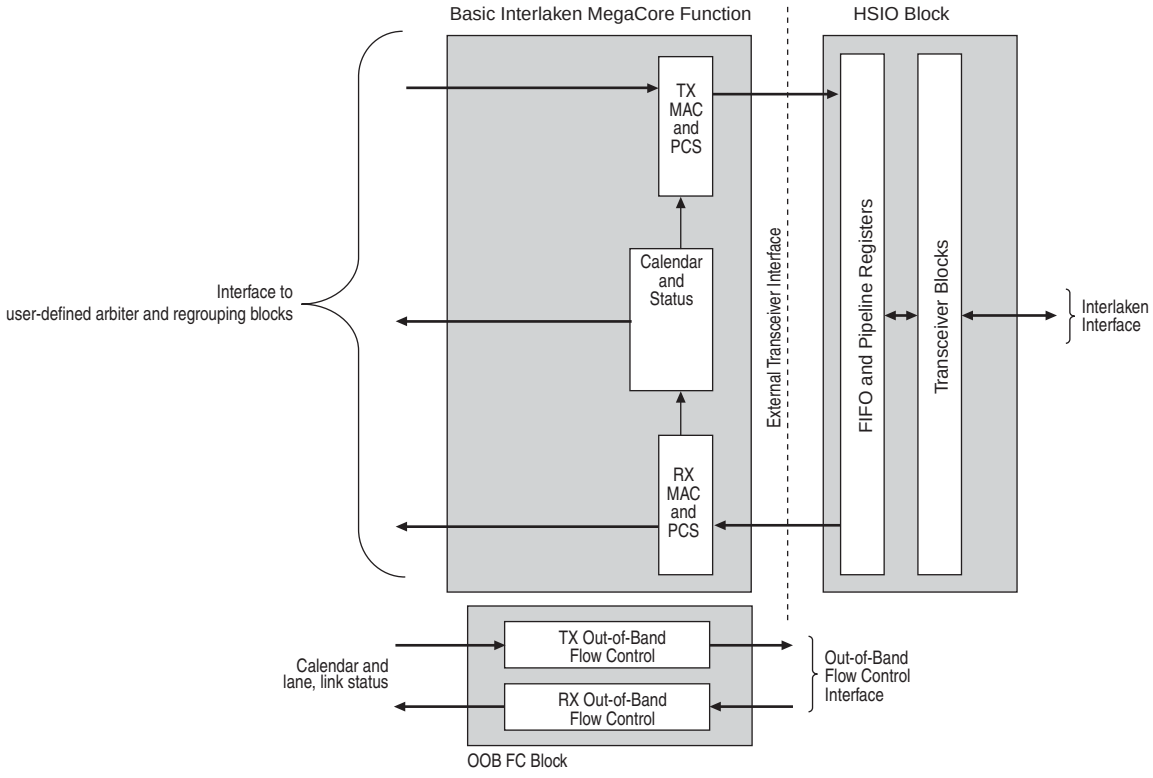
This appendix provides you the information you need to connect your own channel arbitration and regrouping implementation directly to the Interlaken MegaCore function, if you choose to incorporate your own implementation in your design.

Altera provides support to connect the Interlaken MegaCore function to two user-defined application channels. If you want to increase the number of application channels, up to 256 channels, you can connect your own arbitration and regrouping blocks directly to the main, internal parts of the Interlaken MegaCore function. This level of connection requires that you modify and remove source code from the Interlaken MegaCore function-generated HDL files.

Remaining Parts of the Interlaken MegaCore Function

Figure D–1 shows the parts of the Interlaken MegaCore function that remain after you remove the Altera-provided blocks that implement two-channel arbitration and regrouping. You connect your own implementation blocks to the remaining new interface. For a complete list of signals available in the new interface, refer to "Signals" on page D–2.

Figure D–1. Interlaken MegaCore Function with Arbiter and Regrouping Blocks Removed



Signals

Table D–1 and Table D–2 show the signals available to you on the new application interface to the Interlaken MegaCore function basic structure, after you make the modifications listed in "Required RTL Modifications" on page D–3. In addition to the signals listed in Table D–1 and Table D–2, the interface includes the status signals listed in Table 5–2 and Table 5–3 on page 5–3.

After you make the modifications, the signals listed in Table 5–6 on page 5–4 and Table 5–8 on page 5–5 are no longer available.

Table D–1. Application Interface RX Signals After RTL Changes

Signal	Direction	Description
rx_datwords[V:0]	Output	Output data to the application. Streams out the data received on the Interlaken interface. Width is 65 × INTERNAL_WORDS. (V = (65 × INTERNAL_WORDS) – 1). Width is 130 bits for variations with a 128-bit wide datapath (20G/4L license), 260 bits for variations with a 256-bit wide datapath (40G/8L license), and 520 bits for variations with a 512-bit wide datapath (either of the 100G licenses). Each 65 bits represents one 64-bit RX data word. The MSB of each 65-bit word is an Altera-defined control bit which indicates whether the current word is a data word or a control word, and the lower 64 bits are the data bits. The control bit has value 1 if the current word is a control word, and value 0 if the current word is a data word.
rx_datawords_valid	Output	Indicates that the data on rx_datwords is valid in the current rx_mac_c_clk cycle.

Table D–2. Application Interface TX Signals After RTL Changes (Part 1 of 2)

Signal	Direction	Description
tx_datwords[W:0]	Input	Input data from the application. Streams the data to be transmitted on the Interlaken interface. Width is 64 × INTERNAL_WORDS. (W = (64 × INTERNAL_WORDS) – 1). Width is the same as the datapath width in your Interlaken MegaCore variation: 128, 256, or 512. (W = datapath width – 1)..
tx_num_datwords_valid [U:0]	Input	Indicates the number of logical words in tx_datwords that are valid on the current tx_mac_c_clk clock cycle. The most significant words are assumed to be the valid words. Width is the number of bits required to represent the number of logical words, plus 1, to support representation of zero. Width is 2 bits for variations with a 128-bit wide channel (20G/4L license), 3 bits for variations with a 256-bit wide channel (40G/8L license), and 4 bits for variations with a 512-bit wide channel (either of the 100G licenses). (U = width – 1).
tx_chan[7:0]	Input	Channel number of the channel source for the value in tx_datwords on the current tx_mac_c_clk cycle. This signal can represent channel numbers 0–255, supporting as many as 256 channels, the maximum number allowed in the Interlaken specification.
tx_sop	Input	Indicates the current value on tx_datwords includes a start-of-packet.
tx_eopbits[3:0]	Input	This signal reflects the value for the EOP_Format field in bits [60:57] of the idle/burst control word format specified in Table 1 in the Interlaken specification. Refer to the specification for the definition and format of this signal.

Table D–2. Application Interface TX Signals After RTL Changes (Part 2 of 2)

Signal	Direction	Description
tx_valid	Input	Indicates data on tx_datawords is valid in the current tx_mac_c_clk cycle.
tx_ready	Output	Acknowledge signal that indicates data has been received successfully and the application logic can proceed safely. The input data stream tx_datwords is backpressured until this signal is asserted. As in the original application interface provided for the Interlaken MegaCore function, this signal is not asserted until after the application asserts the tx_valid signal.

Required RTL Modifications

To expose the interface shown in Figure D–1, you must remove several RTL modules from the design, and modify other modules to make visible at the top level some signals that were previously internal. "Signals" on page D–2 lists the signals that are visible on the new interface after the modifications.

This section has the following sections:

- RX Path Modifications
- TX Path Modifications

After you make the modifications described in each section, in the Quartus II software, on the Processing menu, highlight **Start** and click **Start Analysis & Synthesis**. The changes should not introduce any new warnings.

RX Path Modifications

The following sections describe the modifications you must make to the RX path to remove filtering and regrouping for the Altera-provided two-channel application interface:

- Editing alt_ntrlkn_<x>l_<y>g_xcvr_<n>lane.v
- Editing The Top-level File
- Editing The Top-level Simulation File

Editing alt_ntrlkn_<x>l_<y>g_xcvr_<n>lane.v

In the <*variant*>**/alt_ntrlkn_**<*x*>**l_**<y>**g_xcvr_**<*n*>**lane.v** file, you make modifications that remove the filtering and regrouping logic, delete old ports, create new ports, and rewire the new ports.

To remove the filtering and regrouping logic, follow these steps:

1. Delete both instances of the alt_ntrlkn_<*x*>l_<*y*>g_rx_channel_filter_<*num*> module and all of their associated defparam statements.
2. Delete both instances of the alt_ntrlkn_<*x*>l_<*y*>g_rx_packet_regroup_<*num*> module.

To remove old ports that are obsolete following removal of the filtering and regrouping logic, delete the following interface ports from the file:

- rx_chN_avl_data for N = {0,1}
- rx_chN_avl_sop for N = {0,1}
- rx_chN_avl_eop for N = {0,1}
- rx_chN_avl_valid for N = {0,1}
- rx_chN_avl_empty for N = {0,1}
- rx_chN_avl_error for N = {0,1}

To create new ports, add the following interface port declarations to the file:

- `output wire[65*INTERNAL_WORDS-1:0] rx_datwords`
- `output wire rx_datwords_valid`

To rewire the new ports, follow these steps:

1. Delete the declarations for the following wires, which are obsolete following removal of the filtering and regrouping logic:
   - rx_datwords_valid
   - rx_datwords
   - rx_num_chan0words_valid_i
   - rx_chan0words_i
   - rx_num_chan1words_valid_i
   - rx_chan1words_i
   - regroup_overflow

   The new ports are connected automatically after you delete these wires.
2. Replace the assignment statement

   ```
   assign rx_overflow = (|regroup_overflow) | rx_core_overflow;
   ```

   with the assignment statement

   ```
   assign rx_overflow = rx_core_overflow;
   ```

Editing The Top-level File

In the <*variant*>/<*variant*>_<*num*>**.v** file, you modify the Interlaken MegaCore function application interface, delete old ports, create new ports, and rewire the new ports.

To modify the Interlaken interface, you add and delete interface ports from the alt_ilk instance of the alt_ntrlkn_<*x*>l_<*y*>g_<*n*>lane module.

Add the following ports to the alt_ilk instance of the alt_ntrlkn_<*x*>l_<*y*>g_<*n*>lane module:

- rx_datwords
- rx_datwords_valid

Delete the following ports from the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module:

- `rx_chN_avl_data` for N = {0,1}
- `rx_chN_avl_sop` for N = {0,1}
- `rx_chN_avl_eop` for N = {0,1}
- `rx_chN_avl_valid` for N = {0,1}
- `rx_chN_avl_empty` for N = {0,1}
- `rx_chN_avl_error` for N = {0,1}

To remove old ports that are obsolete following removal of the filtering and regrouping logic, delete the following interface ports from the file:

- `rx_chN_dataout_data` for N = {0,1}
- `rx_chN_dataout_startofpacket` for N = {0,1}
- `rx_chN_dataout_endofpacket` for N = {0,1}
- `rx_chN_dataout_valid` for N = {0,1}
- `rx_chN_dataout_empty` for N = {0,1}
- `rx_chN_dataout_error` for N = {0,1}

To create new ports, add the following interface port declarations to the file:

- `output wire [<V>:0] rx_datwords`
- `output wire rx_datwords_valid`

For the full definition of `V`, refer to the description of the `rx_datwords` bus in Table D–1 on page D–2.

To rewire the new ports, connect each newly-created port in the file to the matching port in the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module.

Editing The Top-level Simulation File

In the <*variant*>**_sim/**<*variant*>**.v** file, you modify the Interlaken MegaCore function application interface, delete old ports, create new ports, and rewire the new ports.

Make the same modifications you made to the <*variant*>**/**<*variant*>_<*num*>**.v** file in the TX path "Editing The Top-level File" section, with the following modifications to the instructions:

- Replace the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module with the <*variant*>`_inst` instance of the <*variant*>_<*num*> module.

- Replace the list of ports you delete from the module instance with the following list:
  - rx_chN_dataout_data for N = {0,1}
  - rx_chN_dataout_startofpacket for N = {0,1}
  - rx_chN_dataout_endofpacket for N = {0,1}
  - rx_chN_dataout_valid for N = {0,1}
  - rx_chN_dataout_empty for N = {0,1}
  - rx_chN_dataout_error for N = {0,1}

TX Path Modifications

The following sections describe the modifications you must make to the TX path to remove the Altera-provided arbiter:

- Editing alt_ntrlkn_<x>l_<y>g_xcvr_<n>lane.v
- Editing The Top-level File
- Editing The Top-level Simulation File

Editing alt_ntrlkn_<x>l_<y>g_xcvr_<n>lane.v

In the <*variant*>**/alt_ntrlkn_**<*x*>**l_**<y>**g_xcvr_**<*n*>**lane.v** file, you make modifications that remove the arbitration logic, delete old ports, create new ports, and rewire the new ports.

To remove the arbitration logic, follow these steps:

1. Delete the alt_ntrlkn_<*x*>l_<*y*>g_2channel_arbiter module instance and all of its associated defparam statements.
2. Delete the localparam ARBITER_SKID statement and the entire if-else generate block that creates the alt_ntrlkn_<*x*>l_<*y*>g_ready_skid module instance.

To remove old ports that are obsolete following removal of the arbitration logic, delete the following interface ports from the file:

- tx_chN_avl_data for N = {0,1}
- tx_chN_avl_sop for N = {0,1}
- tx_chN_avl_eop for N = {0,1}
- tx_chN_avl_valid for N = {0,1}
- tx_chN_avl_empty for N = {0,1}
- tx_chN_avl_error for N = {0,1}
- tx_chN_avl_ready for N = {0,1}
- tx_force_transmit
- tx_channel_enable

To create new ports, add the following interface port declarations to the file:

- input wire [LOG_INTERNAL_WORDS-1:0] tx_num_datwords_valid

- `input wire [64*INTERNAL_WORDS-1:0] tx_datwords`
- `input wire [7:0] tx_chan`
- `input wire tx_sop`
- `input wire [3:0] tx_eopbits`
- `input wire tx_valid`
- `output wire tx_ready`

To rewire the new ports, delete the declarations for the following wires, which are obsolete following removal of the arbitration logic:

- `tx_num_datwords_valid`
- `tx_num_datwords_valid_a`
- `tx_datwords`
- `tx_datwords_a`
- `tx_chan`
- `tx_chan_a`
- `tx_sop`
- `tx_sop_a`
- `tx_eopbits`
- `tx_eopbits_a`
- `tx_ready`
- `tx_ready_a`
- `tx_valid`
- `tx_valid_a`
- `arb_enables`

The new ports are connected automatically after you delete these wires.

Editing The Top-level File

In the <*variant*>**/**<*variant*>_<*num*>**.v** file, you modify the Interlaken MegaCore function application interface, delete old ports, create new ports, and rewire the new ports.

To modify the Interlaken MegaCore application interface, you add and delete interface ports from the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module.

Add the following ports to the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module:

- `tx_num_datwords_valid`
- `tx_datwords`
- `tx_chan`
- `tx_sop`

- tx_eopbits
- tx_ready
- tx_valid

Delete the following ports from the alt_ilk instance of the alt_ntrlkn_<*x*>l_<*y*>g_<*n*>lane module:

- tx_chN_avl_data for N = {0,1}
- tx_chN_avl_sop for N = {0,1}
- tx_chN_avl_eop for N = {0,1}
- tx_chN_avl_valid for N = {0,1}
- tx_chN_avl_empty for N = {0,1}
- tx_chN_avl_error for N = {0,1}
- tx_chN_avl_ready for N = {0,1}
- tx_force_transmit
- tx_channel_enable

To remove old ports that are obsolete following removal of the arbitration logic, delete the following interface ports from the file:

- tx_chN_datain_data for N = {0,1}
- tx_chN_datain_startofpacket for N = {0,1}
- tx_chN_datain_endofpacket for N = {0,1}
- tx_chN_datain_valid for N = {0,1}
- tx_chN_datain_empty for N = {0,1}
- tx_chN_datain_error for N = {0,1}
- tx_chN_datain_ready for N = {0,1}
- tx_control_force_transmit
- tx_control_channel_enable

To create new ports, add the following interface port declarations to the file:

- input wire [<W>:0] tx_datwords
- input wire [<U>:0] tx_num_datwords_valid
- input wire [7:0] tx_chan
- input wire tx_sop
- input wire [3:0] tx_eopbits
- input wire tx_valid
- output wire tx_ready

where

- <W> is the datapath width minus 1, for datapath widths 128, 256, and 512, according to the Interlaken MegaCore function variation.

- <U> is 1 for datapath width 128, 2 for datapath width 256, and 3 for datapath width 512. For more infomation, refer to Table D–2 on page D–2.

To rewire the new ports, connect each newly-created port in the file to the matching port in the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module.

Editing The Top-level Simulation File

In the <*variant*>**_sim/**<*variant*>**.v** file, you modify the Interlaken MegaCore function application interface, delete old ports, create new ports, and rewire the new ports.

Make the same modifications you made to the <*variant*>**/**<*variant*>_<*num*>**.v** file in the TX path "Editing The Top-level File" section, with the following modifications to the instructions:

- Replace the `alt_ilk` instance of the `alt_ntrlkn_<x>l_<y>g_<n>lane` module with the <*variant*>`_inst` instance of the <*variant*>_<*num*> module.
- Replace the list of ports you delete from the module instance with the following list:
  - `tx_chN_datain_data` for N = {0,1}
  - `tx_chN_datain_sop` for N = {0,1}
  - `tx_chN_datain_eop` for N = {0,1}
  - `tx_chN_datain_valid` for N = {0,1}
  - `tx_chN_datain_empty` for N = {0,1}
  - `tx_chN_datain_error` for N = {0,1}
  - `tx_chN_datain_ready` for N = {0,1}
  - `tx_control_force_transmit`
  - `tx_control_channel_enable`

This chapter provides additional information about the document and Altera.

Document Revision History

The following table shows the revision history for this user guide.

Date	Version	Changes Made
December 2010	10.1	Initial release.

How to Contact Altera

To locate the most up-to-date information about Altera products, refer to the following table.

Contact *(1)*	Contact Method	Address
Technical support	Website	www.altera.com/support
Technical training	Website	www.altera.com/training
	Email	custrain@altera.com
Product literature	Website	www.altera.com/literature
Non-technical support (General)	Email	nacomp@altera.com
(Software Licensing)	Email	authorization@altera.com

Note to Table:

(1) You can also contact your local Altera sales office or sales representative.

Typographic Conventions

The following table shows the typographic conventions this document uses.

Visual Cue	Meaning
Bold Type with Initial Capital Letters	Indicate command names, dialog box titles, dialog box options, and other GUI labels. For example, **Save As** dialog box. For GUI elements, capitalization matches the GUI.
bold type	Indicates directory names, project names, disk drive names, file names, file name extensions, software utility names, and GUI labels. For example, **\qdesigns** directory, **D:** drive, and **chiptrip.gdf** file.
Italic Type with Initial Capital Letters	Indicate document titles. For example, *Stratix IV Design Guidelines*.
italic type	Indicates variables. For example, *n* + 1. Variable names are enclosed in angle brackets (< >). For example, *<file name>* and *<project name>***.pof** file.
Initial Capital Letters	Indicate keyboard keys and menu names. For example, the Delete key and the Options menu.

Visual Cue	Meaning
“Subheading Title”	Quotation marks indicate references to sections within a document and titles of Quartus II Help topics. For example, “Typographic Conventions.”
`Courier type`	Indicates signal, port, register, bit, block, and primitive names. For example, `data1`, `tdi`, and `input`. The suffix n denotes an active-low signal. For example, `resetn`. Indicates command line commands and anything that must be typed exactly as it appears. For example, `c:\qdesigns\tutorial\chiptrip.gdf`. Also indicates sections of an actual file, such as a Report File, references to parts of files (for example, the AHDL keyword `SUBDESIGN`), and logic function names (for example, `TRI`).
↵	An angled arrow instructs you to press the Enter key.
1., 2., 3., and a., b., c., and so on	Numbered steps indicate a list of items when the sequence of the items is important, such as the steps listed in a procedure.
■ ■ ■	Bullets indicate a list of items when the sequence of the items is not important.
	The hand points to information that requires special attention.
	A question mark directs you to a software help system with related information.
	The feet direct you to another document or website with related information.
	A caution calls attention to a condition or possible situation that can damage or destroy the product or your work.
	A warning calls attention to a condition or possible situation that can cause you injury.
	The envelope links to the Email Subscription Management Center page of the Altera website, where you can sign up to receive update notifications for Altera documents.