

1. Rotary Cam Switches

1.0. General

LEONARD rotary cam switches (formerly VOLLENBROICH) have been built as reliable and economical subassemblies for the industry automation since decades. Due to their robust and flawless operation the switches are indispensable for control of machines and installations, also in the decade of electronic data processing systems.

The beginning and the duration of a switching operation is surely controlled by progressively adjustable cam rings. Our rotary cam switches are used in the control technique as a reproducing tool, positioning tool, automation tool or as a numerator. They are suitable for operating on

- mill and steel works
- mining plant and machinery
- transportation plants
- transfer lines
- cranes and elevators
- presses
- punches
- welding machines
- assembly machines
- machine tools
- automobile industry
- etc.

LEONARD switchgears are rotary (cam) switches cased in housings made of cast aluminum, which contain mechanic and/or electronic switching elements. It is partially possible to couple our rotary cam switches with a second protective housing for a shaft encoder or another rotary cam switch, because the cam shaft (spindle) is brought out on both sides of the switch. In our whole range of products it is also possible to mount an encoder additional into the housing of the rotary cam switch.

LEONARD rotary cam switches can optionally be built with an integrated or a flange-mounted digital transmitter for rotary motion and can be connected to a monitoring unit (digital control). Especially our types GSW100, GSW100E and GSW100M are suitable for it and therefore they are excellent qualified for presses. You can take this and other equipment from our detailed technical data in this brochure.

As a driving unit for LEONARD rotary cam switches different spur or angular gearboxes from our accessories are available as well as rigid and adjustable couplings. The gearboxes can be delivered with maximum ratio of 1:10 or as a reduction gear with maximum ratio of 8000:1. In dependence of the type of the rotary cam switch the gear unit is integrated into the housing or is built for flange-mounting. In opposite to the integrated gear unit the flange-mounted one can be fitted secondary at any time. Please take all details from the chapter of each rotary cam switch or gearbox.

Function

With LEONARD rotary cam switches pulses could be connected precisely in dependence of a given motion. The beginning and the length (switching angle) of the pulse of each switching point is connected safely by two independent rings with 180°-cams (two cam rings = one cam disk set). The cam rings can be twisted against each other, so a maximum pulse length of 360° can be connected. The LEONARD rotary cam switches GSW100E use switch drums instead of cam disk sets. These switch drums have a unique construction and function. A detailed description about the mechanical construction and the adjustment of the cam disk sets and switch drums is given in the chapter of each type.

Each cam disk set respectively switch drum manipulate a mechanic or electronic switching element. The function depends on the type of the contact: A make-contact element (normally open - NO) closes a conducting path when the switch is actuated while a break-contact element (normally closed – NC) a conducting path opens

when the switch is actuated. A change-over contact element (CO) closes and opens alternating the conducting path when it is actuated.

The mechanic switching elements (miniature switches) have different switching mechanisms: either slow action contacts or snap action contacts, particularly with positive break according to VDE 0113. A slow action contact (touch contact) is a contact element in which the velocity of contact motion depends on the velocity of motion of the actuator while a snap action contact (spring contact) a contact element is in which the velocity of contact motion is substantially independent of the velocity of motion of the actuator.

The electronic switching elements (proximity switches) work in accordance with the principle of the electromagnetic induction. It is possible to fit electronic switching elements for direct current with a plus or minus switching operation (PNP, NPN) or to fit electronic switching elements for alternating voltage.

All technical data of the mechanic and electronic switching elements are shown in figure 1.0.1 and figure 1.0.4. A general view of our standard types of rotary cam limit switches is illustrated in figure 1.0.6. Our large variety of switches should enable you to find the right product for your application. Beyond it we have numerous different special executions. We will be glad to help you to solve your particular problem and find the right product for your application.

Construction

All LEONARD rotary cam switches have the common design as follows:

cam shaft (spindle):	ground according to DIN ISO 286 – tolerance h6 feather key according to DIN 6885 part 1 centre hole according to DIN 332-A, optional with thread
bearing:	deep groove ball bearings, maintenance free
housing colour:	RAL 6011 „green hammer finish“, optional seawaterproof
resistance of seals:	against oil and gasoline
protection:	IP65 according to EN 60529
fitting position:	any
cable entries:	M32 or M20 according to EN 50262, depending on the type of switch

LEONARD rotary cam switches differ in the built-in switching elements, the structural shape and the dimensions. They realize different precision and resolution of their represented pulse length. A general plan is shown in figure 1.0.6 while all details are described in the chapter of each type.

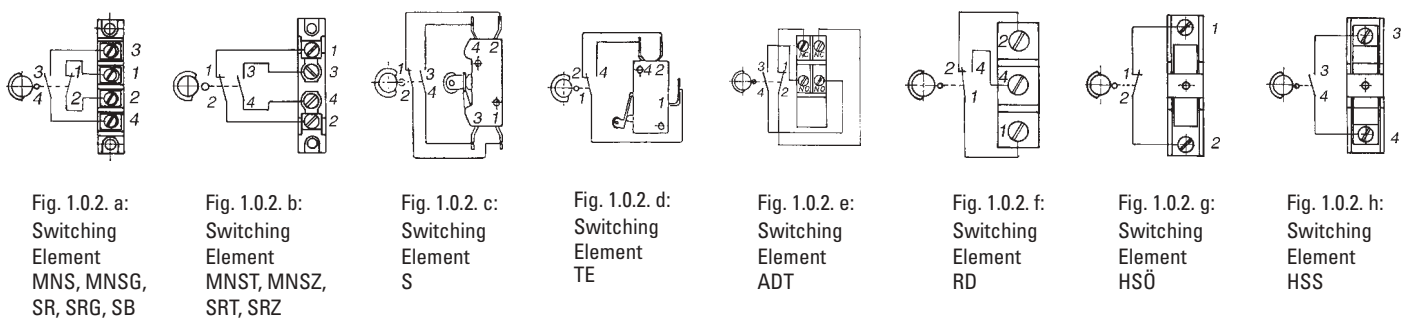
All LEONARD rotary cam switches are permitted for the ambient conditions as follows:

ambient temperature:	-25 to +70 °C (electronic switching elements) resp. -30 to +80 °C (mechanic switching elements)
storage temperature:	-30 to +75 °C (electronic switching elements) resp. -35 to +90 °C (mechanic switching elements)
vibration loading:	max. 1,5 mm amplitude at 55 Hz switching frequency
shock loading:	max. 30 g at 11 ms duration
shockproof limits:	max. 0,64 g at 24 Hz; max. 0,61 g at 120 Hz
frequency range:	0 - 2000 Hz
all-climate protection:	30 cycles according to DIN 50017, 2 cycles according to DIN 50018

Fig. 1.0.1: Technical Data of Mechanic Switching Elements

	MNS	MNSG	MNST	MNSZ	SÖ	SR	SRG	
type of contact NO = make-contact element (normally open) NC = break-contact element (normally closed) CO = change-over contact element	NO + NC	NO + NC	NO + NC	NO + NC	NC	NO + NC	NO + NC	
switching mechanism S = snap action mechanism (spring contact) T = slow action mechanism (touch contact)	S	S	T	S	T	S	S	
type of terminal S = screw connection K = screw connection with clamping saddles	K	K	K	K	K	K	K	
switching element with roller lever	no	no	no	no	no	yes	yes	
supply voltage	250 AC	24 DC	250 AC	250 AC	250 AC	250 AC	24 DC	
rated load current	6	0,1	10	10	6	6	0,1	
force separation	no	no	yes	yes	yes	no	no	
max. mechanical life	30 * 10 ⁶	30 * 10 ⁶	30 * 10 ⁶	30 * 10 ⁶	30 * 10 ⁶	30 * 10 ⁶	30 * 10 ⁶	
max. switching frequency	500	500	500	500	500	500	500	
max. radial switching hysteresis	5,5	5,5	5,5	1,0	5,5	5,5	5,5	
min. opening angle of cam rings	10	10	10	10	10	10	10	
min. switching angle for one switching actuation (switch on and off)	10,5	10,5	10,5	5,0	10,5	10,5	10,5	
repeating accuracy of switching actuation	± 0,03	± 0,03	± 0,03	± 0,03	± 0,03	± 0,03	± 0,03	
contact material	silver	gold-nickel	silver	silver	silver	silver	gold-nickel	
self-cleaning	yes	yes	yes	yes	yes	yes	yes	
material of housing	duro-plastic	duro-plastic	thermoplastic glass-fiber reinforced	Macrolon	duro-plastic	duro-plastic	duro-plastic	
weight	22	22	20	24	20	36	36	
wiring diagram	see fig. 1.0.2.a	see fig. 1.0.2.a	see fig. 1.0.2.b	see fig. 1.0.2.b		see fig. 1.0.2.a	see fig. 1.0.2.a	
terminal designation of the first three switching elements (according to EN 50013D)	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.c	see fig. 1.0.3.a	see fig. 1.0.3.a	

Fig. 1.0.2: Wiring Diagrams of Mechanic Switching Elements



	SRT	SRZ	S	SB	TE	ADT	RD	HSÖ	HSS	unit
	NO + NC	NO + NC	NO + NC	NO + NC	CO	NO + NC	CO	NC	NO	-
	S	S	S	S	S	S	S	T	T	-
	K	K	K	K	K	S	S	K	K	-
	yes	yes	yes	yes	yes	no	no	no	no	-
	250 AC	250 AC	250 AC	380 AC	250 AC	500 AC	500 AC	500 AC	500 AC	V
	6	10	6	10	10	10	15	25	25	A
	yes	yes	no	yes	yes	no	no	yes	no	-
	30 * 10 ⁶	30 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	10 * 10 ⁶	-
	500	500	150	300	150	300	300	200	200	min ⁻¹
	5,5	1,0	3	6,5	3	1,5	0,75	2	2	°
	10	10	10	10	10	7	6	10	10	°
	10,5	10,5	10	12	10	4,0	3,0	5,0	5,0	°
	± 0,03	± 0,03	± 0,1	± 0,1	± 0,1	± 0,03	± 0,03	± 0,05	± 0,05	°
	silver	silver	silver	silver	silver-nickel	silver	silver	silver-nickel	silver-nickel	-
	yes	yes	yes	yes	yes	yes	yes	no	no	
	thermoplastic glass-fiber reinforced	Macrolon	thermo- plastic	Macrolon	Macrolon	Phon	phenoli c resin	FS150- DIN7708	FS150- DIN7708	-
	36	40	12	30	15	41	37	53	53	10 ⁻³ kg
	see fig. 1.0.2.b	see fig. 1.0.2.b	see fig. 1.0.2.c	see fig. 1.0.2.a	see fig. 1.0.2.d	see fig. 1.0.2.e	see fig. 1.0.2.f	see fig. 1.0.2.g	see fig. 1.0.2.h	-
	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.a	see fig. 1.0.3.b	see fig. 1.0.3.a	see fig. 1.0.3.b	see fig. 1.0.3.c	see fig. 1.0.3.d	-

Fig. 1.0.3: Terminal Designation of the first three Switching Elements (according to EN 50013D)

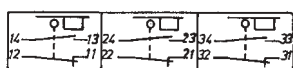


Fig. 1.0.3. a:
Switching Element MNS, MNSG,
MNST, MNSZ, SR, SRG, SRT,
SRZ, S, SB, ADT

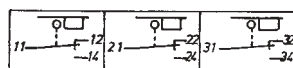


Fig. 1.0.3. b:
Switching Element RD, TE

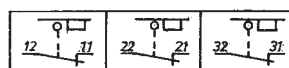


Fig. 1.0.3. c:
Switching Element SÖ, HSÖ

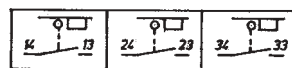


Fig. 1.0.3. d:
Switching Element HSS

Fig. 1.0.4: Technical Data of Electronic Switching Elements

	EGA1000.1	EGA400.5	EGA400.2	EGS200.1	
type of contact NO = make-contact element (normally open) NC = break-contact element (normally closed) CO = change-over contact element	NO + NC	NO + NC	NO + NC	NO	
switching operation	PNP	PNP	NPN	PNP	
type of terminal S = screw connection K = screw connection with clamping saddles	K	K	K	K	
LED	yes	yes	yes	yes	
supply voltage	10 - 30 DC	10 - 55 DC	10 - 30 DC	input: 10 - 30 DC output: 10 - 60 DC	
rated load current	1000	200	400	output: 250	
min. load resistor	-	-	-	-	
max. residual ripple	10	10	10	10	
max. residual current	10	10	10	10	
max. static current	-	-	-	-	
short circuit protection	no	yes	yes	no	
protection against inductive break peaks (overload protection)	yes	yes	yes	no	
protection against incorrect polarity of operating and interference voltage (reverse battery protection)	yes	yes	yes, load current	yes	
nominal switching distance	3	3	3	3	
max. switching frequency	500	500	500	2500	
max. radial switching hysteresis	15	15	15	10	
repeating accuracy of switching point	< 5	< 5	< 5	< 5	
min. aperture angle of cam disks	5	5	5	5	
impulse duplication	no	no	no	no	
pulse duration of 2. output (of each side of the impulse of the 1. output)	-	-	-	-	
min. module of toothed wheel	-	3	-	-	
material of housing	PA glass-fiber reinforced	PA glass-fiber reinforced	PA glass-fiber reinforced	PA glass-fiber reinforced	
weight	43	29	29	43	
wiring diagram	see fig. 1.0.5.a	see fig. 1.0.5.b	see fig. 1.0.5.c	see fig. 1.0.5.d	

Fig. 1.0.6: Standard Types of LEONARD Rotary Cam Switches

	GSW100	GSW100E	GSW100M	SWV100	GGSW100	
cam disks:						
cam rings made of metal, finished	x		x	x	x	
cam rings made of Hostaform						
switch drums made of plastic with steel foil		x		x		
diameter [mm]	100	100	100	100	100	
min. graduation of angular scale[°]	2	2	2	2	2	
mechanic switching elements:						
ADT						
HSÖ						
HSS						
MNS	x			x	x	
MNSG	x				x	
MNST	x				x	
RD	x		x	x	x	
S						
SR						
TE						
electronic switching elements:						
EGA400.5		x	x	x		
EGA400.2		x	x			
EWÖ25.1		x	x			
EWS25.1		x	x			
cam shaft:						
square shaft 22 mm	x	x	x	x	x	
square shaft 12 mm						
gear box:						
flange-mounted spur gear unit (slip-on gearbox)	x	x	x		x	
integrated spur gear unit				x		
integrated worm gear unit						
housing:						
gray cast iron					x	
cast aluminum	x	x	x	x		
cable entries:						
M20						
M32	x	x	x	x	x	

	EWÖ25.1	EWS25.1	EGS65.1	MG3-12G-01	MG4-12S-20	unit
	NC	NO	NO	NO	NO	-
	-	-	PNP	PNP	2 x NPN	-
	K	K	connector M8 x1	connector M12 x1	K	-
	yes	yes	yes	yes	yes (1. output)	-
	20 - 260 AC	20 - 260 AC	7 - 35 DC	10 - 30 DC	10 - 30 DC	V
	5 - 200	5 - 200	100	200	200	mA
	100	100	-	-	-	Ω
	-	-	10	10	10	%
	-	-	20	35	30	mA
	1,5	1,5	-	-	-	mA
	no	no	yes	yes	yes	-
	yes	yes	yes	yes	yes	-
	yes	yes	yes	yes	yes	-
	3	3	1	≤ 1	≤ 1	mm
	20	20	1500	10000	300	Hz
	15	15	15	-	-	%
	< 10	< 10	< 5	-	-	%
	10	10	5	-	-	°
	no	no	no	no	yes	-
	-	-	-	-	1	10^{-3} s
	-	-	3	1	1	-
	PA glass-fiber reinforced	PA glass-fiber reinforced	stainless steel	stainless steel	PA glass-fiber reinforced	-
	25	25	7	25	37	10^{-3} kg
	see fig. 1.0.5.e	see fig. 1.0.5.f	see fig. 1.0.5.g	see fig. 1.0.5.h	see fig. 1.0.5.i	-

Fig. 1.0.5:
Wiring Diagrams of Electronic Switching Elements

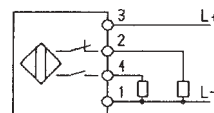


Fig. 1.0.5. a:
Switching Element
EGA1000.1

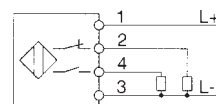


Fig. 1.0.5. b:
Switching Element
EGA400.5

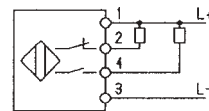


Fig. 1.0.5. c:
Switching Element
EGA400.2

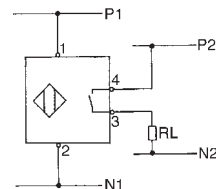


Fig. 1.0.5. d:
Switching Element
EGS200.1

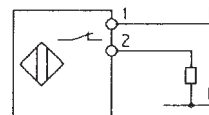


Fig. 1.0.5. e:
Switching Element
EWÖ25.1

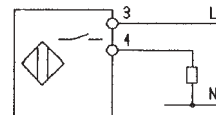


Fig. 1.0.5. f:
Switching Element
EWS25.1

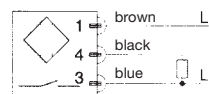


Fig. 1.0.5. g:
Switching Element
EGS65.1

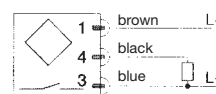


Fig. 1.0.5. h:
Switching Element
MG3-12G-01

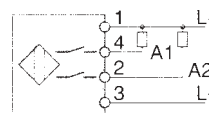


Fig. 1.0.5. i:
Switching Element
MG4-12S-20

	GGSW120	LNSE	LNSW	GSWF	GSWFK/u	KSW50
				x		
	x	x	x		x	x
	120	100	120	80	80	50
	5	2	5	10	10	10
		x				
			x			
	x		x	x		
	x		x	x		
	x	x	x	x		
					x	x
						x
	x	x	x	x	x	x
	x	x	x		x	x
				x		
	x					
		x	x	x	x	x
				x		
	x	x	x		x	x