IBM block storage CSI driver 1.5.0

User Guide



Note

Before using this document and the product it supports, read the information in "Notices" on page 27.

Edition notice

Publication number: SC27-9590-09. This publication applies to version 1.5.0 of IBM block storage CSI driver and to all subsequent releases and modifications until otherwise indicated in a newer publication.

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About this guide

This guide describes how to install, configure, and use the IBM block storage CSI driver.

Who should use this guide

This guide is intended for system administrators who are familiar with container-based application delivery, orchestration methods, and with the specific IBM storage system that is in use.

Conventions used in this guide

These notices are used in this guide to highlight key information.

Note: These notices provide important tips, guidance, or advice.

Important: These notices provide information or advice that might help you avoid inconvenient or difficult situations.



Attention: These notices indicate possible damage to programs, devices, or data. An attention notice appears before the instruction or situation in which damage can occur.

Related information and publications

For more information storage systems and orchestration platforms that are supported by IBM block storage CSI driver, see the following resources.

IBM resources

- IBM SAN Volume Controller on IBM Knowledge Center (ibm.com[®]/support/knowledgecenter/ STPVGU)
- IBM Spectrum Scale on IBM Knowledge Center (ibm.com/support/knowledgecenter/STXKQY)
- IBM FlashSystem[®] 5000, 5100, and Storwize[®] V5000E on IBM Knowledge Center (ibm.com/ support/knowledgecenter/STHGUJ)
- IBM FlashSystem 7200 and Storwize V7000 on IBM Knowledge Center (ibm.com/support/ knowledgecenter/ST3FR7)
- IBM Spectrum Virtualize as Software Only on IBM Knowledge Center (ibm.com/support/ knowledgecenter/STVLF4)
- IBM FlashSystem 9200 and 9100 on IBM Knowledge Center (ibm.com/support/knowledgecenter/ STSLR9)
- IBM FlashSystem A9000 on IBM Knowledge Center (ibm.com/support/knowledgecenter/STJKMM)
- IBM FlashSystem A9000R on IBM Knowledge Center (ibm.com/support/knowledgecenter/STJKN5)
- IBM DS8880 on IBM Knowledge Center (ibm.com/support/knowledgecenter/ST5GLJ)
- IBM DS8900 on IBM Knowledge Center (ibm.com/support/knowledgecenter/SSHGBU)
- IBM Spectrum[®] Access for IBM Cloud[®] Private Blueprint (ibm.com/downloads/cas/KK5PGD8E)

Used as the FlexVolume driver-based solution for OpenShift[®] 3.11, using <u>IBM Storage Enabler for</u> <u>Containers</u> (ibm.com/support/knowledgecenter/SSCKLT)

- IBM Storage for Red Hat[®] OpenShift Blueprint (http://www.redbooks.ibm.com/abstracts/ redp5565.html?Open)
- Using the IBM Block Storage CSI driver in a Red Hat OpenShift environment (http://www.redbooks.ibm.com/abstracts/redp5613.html?Open)

External resources

- Persistent volumes on Kubernetes (kubernetes.io/docs/concepts/storage/volumes)
- Kubernetes Documentation (kubernetes.io/docs/home/)
- Kubernetes Blog (kubernetes.io//blog)

Getting information, help, and service

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- #get-help_csi Slack channel
- IBM website (ibm.com)
- IBM Support Portal website (ibm.com/support/entry/portal/support? brandind=Hardware~System_Storage)
- IBM Directory of Worldwide Contacts website (ibm.com/planetwide)

Use the Directory of Worldwide Contacts to find the appropriate phone number for initiating voice call support. Select the Software option, when using voice response system.

When asked, provide your Internal Customer Number (ICN) and/or the serial number of the storage system that requires support. Your call will then be routed to the relevant support team, to whom you can provide the specifics of your problem.

IBM Publications Center

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Procedure

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- Send your comments by email to ibmdocs@us.ibm.com. Be sure to include the following information:
 - Exact publication title and version
 - Publication form number (for example, GA32-1234-00)
 - Page, table, or illustration numbers that you are commenting on
 - A detailed description of any information that should be changed

Chapter 1. Introduction

IBM block storage CSI driver is leveraged by Kubernetes persistent volumes (PVs) to dynamically provision for block storage used with stateful containers.

IBM block storage CSI driver is based on an open-source IBM project (<u>CSI driver</u>), included as a part of IBM storage orchestration for containers. IBM storage orchestration for containers enables enterprises to implement a modern container-driven hybrid multicloud environment that can reduce IT costs and enhance business agility, while continuing to derive value from existing systems.

By leveraging CSI (Container Storage Interface) drivers for IBM storage systems, Kubernetes persistent volumes (PVs) can be dynamically provisioned for block or file storage to be used with stateful containers, such as database applications (IBM Db2[®], MongoDB, PostgreSQL, etc) running in Red Hat OpenShift Container Platform and/or Kubernetes clusters. Storage provisioning can be fully automatized with additional support of cluster orchestration systems to automatically deploy, scale, and manage containerized applications.

IBM storage orchestration for containers includes the following driver types for storage provisioning:

- The IBM block storage CSI driver, for block storage (documented here).
- The IBM Spectrum Scale CSI driver, for file storage. For more information on Spectrum Scale and the Spectrum Scale CSI driver see the <u>IBM Spectrum Scale knowledge center website</u> (ibm.com/support/ knowledgecenter/STXKQY).

For details about volume provisioning with Kubernetes, refer to <u>Persistent volumes on Kubernetes</u> (kubernetes.io/docs/concepts/storage/volumes).

Note: For the user convenience, this guide might refer to IBM block storage CSI driver as CSI driver.



Figure 1. Integration of IBM block storage systems and CSI driver in a Kubernetes environment

Chapter 2. Installation

Download and install the IBM block storage CSI driver installation package your container platform (such as Kubernetes), as described in the following sections.

- "Compatibility and requirements" on page 3
- "Installing the operator and driver" on page 4
- "Upgrading the CSI driver" on page 7

For information about uninstallation, see "Uninstalling" on page 6.

Compatibility and requirements

For the complete and up-to-date information about the compatibility and requirements for using the IBM block storage CSI driver, refer to its latest release notes. The release notes detail supported operating system and container platform versions, as well as microcode versions of the supported storage systems. You can find the latest release notes on IBM block storage CSI driver Knowledge Center website (ibm.com/support/knowledgecenter/SSRQ8T).

Before you begin

Before beginning the installation of the CSI (Container Storage Interface) driver, be sure to verify that you comply with the following prerequisites.

For IBM Cloud Satellite users, see cloud.ibm.com/docs/satellite for full system requirements.

Important: When using Satellite, complete the following checks, configurations, and the installation process before assigning the hosts to your locations. In addition, **do not** create a Kubernetes cluster. This is done through Satellite.

• The CSI driver requires the following ports to be opened on the worker nodes OS firewall:

```
For all iSCSI users
Port 3260
FlashSystem A9000 and A9000R
```

Port 7778

IBM Spectrum Virtualize Family

includes IBM SAN Volume Controller and IBM FlashSystem family members built with IBM Spectrum Virtualize (FlashSystem 5010, 5030, 5100, 7200, 9100, 9200, 9200R) Port 22

DS8000[®] Family systems Port 8452

• Be sure that multipathing is installed and running.

About this task

Perform these steps for each worker node in Kubernetes cluster to prepare your environment for installing the CSI (Container Storage Interface) driver.

Procedure

- 1. For RHEL OS users: Ensure iSCSI connectivity. If using RHCOS or if the packages are already installed, skip this step and continue to step "2" on page 3.
- 2. Configure Linux[®] multipath devices on the host.

Important: Be sure to configure each worker with storage connectivity according to your storage system instructions. For more information, find your storage system documentation on <u>IBM Knowledge</u> Center (ibm.com/support/knowledgecenter).

a) Additional configuration steps for OpenShift Container Platform users (RHEL and RHCOS).

Other users can continue to step <u>"3" on page 4</u>.

Download and save the following yaml file:

curl https://raw.githubusercontent.com/IBM/ibm-block-csi-operator/master/deploy/99-ibmattach.yaml > 99-ibm-attach.yaml

This file can be used for both Fibre Channel and iSCSI configurations. To support iSCSI, uncomment the last two lines in the file.

Important: The 99-ibm-attach.yaml configuration file overrides any files that already exist on your system. Only use this file if the files mentioned are not already created.

If one or more have been created, edit this yaml file, as necessary.

Apply the yaml file.

oc apply -f 99-ibm-attach.yaml

3. If needed, enable support for volume snapshots (FlashCopy[®] function) on your Kubernetes cluster.

For more information and instructions, see the Kubernetes blog post, <u>Kubernetes 1.17 Feature:</u> <u>Kubernetes Volume Snapshot Moves to Beta</u> (kubernetes.io/blog/2019/12/09/kubernetes-1-17-feature-cis-volume-snapshot-beta/).

• Install both the Snapshot CRDs and the Common Snapshot Controller once per cluster.

The instructions and relevant yaml files to enable volume snapshots can be found at: <u>https://</u>github.com/kubernetes-csi/external-snapshotter#usage

- 4. Configure storage system connectivity.
 - a) Define the host of each Kubernetes node on the relevant storage systems with the valid WWPN (for Fibre Channel) or IQN (for iSCSI) of the node.
 - b) For Fibre Channel, configure the relevant zoning from the storage to the host.

Installing the operator and driver

Install the operator for IBM block storage CSI driver in order to deploy, install, and manage the CSI (Container Storage Interface) driver.

The CSI operator and driver can be downloaded in one of the following ways:

- Using the OpenShift web console.
- Using CLIs.
- Using the IBM Cloud Satellite web console. For more information, see cloud.ibm.com/docs/satellite.

Installing the driver using the OpenShift web console

When using the Red Hat OpenShift Container Platform, the operator for IBM block storage CSI driver can be installed directly from OpenShift web console, through the OperatorHub. Installing the CSI (Container Storage Interface) driver is part of the operator installation process.

Before you begin

About this task

The Red Hat OpenShift Container Platform uses the following **SecurityContextConstraints** for the following **serviceAccounts**:

Note: This data is for informational purposes only.

serviceAccount	SecurityContextConstraint
ibm-block-csi-operator	restricted
ibm-block-csi-controller-sa	anyuid
ibm-block-csi-node-sa	privileged

Procedure

- 1. From Red Hat OpenShift Container Platform **Home** > **Projects**, click **Create Project**. In the **Create Project** dialog box, enter a Project name (also referred to as *namespace*). Click **Create** to save.
- From Operators > OperatorHub. Select the namespace from Projects: <namespace>, defined in step <u>"1" on page 5</u>.
- 3. Search for IBM block storage CSI driver.
- 4. Select the **Operator for IBM block storage CSI driver** and click **Install**.
 - The Operator Installation form appears.
- 5. Set the **Installation Mode** to the project namespace selected previously, in step <u>"2" on page 5</u>, under **A specific namespace on the cluster**.
- 6. Set the Approval Strategy to either Automatic or Manual as per your preference.

Note: The general recommendation is to select **Automatic** option.

- 7. Click Install.
- 8. From **Operators** > **Installed Operators**, check the status of the Operator for IBM block storage CSI driver.

Wait until the **Status** is *Up to date* and then *Succeeded*.

Note: While waiting for the **Status** to change from *Up to date* to *Succeeded*, you can check the pod progress and readiness status from **Workloads** > **Pods**.

- 9. After the operator installation progress is complete, click the installed Operator for IBM block storage CSI driver.
- 10. Click Create Instance to create the IBM block storage CSI driver (IBMBlockCSI).

A yaml file opens in the web console. This file can be left as-is, or edited as needed.

- 11. Update the yaml file to include your user-defined namespace.
- 12. Click Create.

Wait until the **Status** is *Running*.

Installing the driver using CLIs

The operator for IBM block storage CSI driver can be installed directly from GitHub by using CLIs. Installing the CSI (Container Storage Interface) driver is part of the operator installation process.

Before you begin

Procedure

Use the following steps to install the operator and driver, using <u>GitHub</u> (github.com/IBM/ibm-block-csi-operator).

1. Download the manifest from GitHub.

```
curl https://raw.githubusercontent.com/IBM/ibm-block-csi-operator/v1.5.0/deploy/installer/
generated/ibm-block-csi-operator.yaml > ibm-block-csi-operator.yaml
```

2. **Optional:** Update the image fields in the ibm-block-csi-operator.yaml.

Note: Updating the namespace to a user-defined namespace might be necessary to ensure consistency and avoid trouble with operator installation.

- 3. Create a project namespace, using the kubectl create ns <namespace> command.
- 4. Install the operator, while using a user-defined namespace.

kubectl -n <namespace> apply -f ibm-block-csi-operator.yaml

5. Verify that the operator is running. (make sure that the Status is *Running*.)

- 6. Install the IBM block storage CSI driver by creating an IBMBlockCSI custom resource.
 - a) Download the manifest from GitHub.

```
curl https://raw.githubusercontent.com/IBM/ibm-block-csi-operator/v1.5.0/deploy/crds/
csi.ibm.com_v1_ibmblockcsi_cr.yaml > csi.ibm.com_v1_ibmblockcsi_cr.yaml
```

b) Optional: Update the image repository field, tag field, or both in the csi.ibm.com_v1_ibmblockcsi_cr.yaml.

Note: Updating the namespace to a user-defined namespace might be necessary in order to ensure consistency and avoid trouble with operator installation.

c) Install the csi.ibm.com_v1_ibmblockcsi_cr.yaml.

kubectl -n <namespace> apply -f csi.ibm.com_v1_ibmblockcsi_cr.yaml

Uninstalling

Use this information to uninstall the IBM CSI (Container Storage Interface) operator and driver.

Use one of the following procedures to uninstall the operator and driver:

- If using Red Hat OpenShift Container Platform, follow the instructions detailed in <u>"Uninstalling the</u> driver using the OpenShift web console" on page 6.
- If Red Hat OpenShift Container Platform is not being used, follow the instructions detailed in "Uninstalling the driver using CLIs" on page 7.

Uninstalling the driver using the OpenShift web console

Use this information to uninstall the IBM CSI (Container Storage Interface) operator and driver through the Red Hat OpenShift Container Platform web console.

About this task

Note: These instructions are for Red Hat OpenShift Container Platform users only. If you are not using the Red Hat OpenShift Container Platform, follow the instructions detailed in <u>"Uninstalling the driver using</u> CLIs" on page 7.

Procedure

Perform the following steps in order to uninstall the CSI driver and operator through Red Hat OpenShift Container Platform web console.

- 1. From the web console go to **Operators** > **Installed Operators**. Select the Project namespace, where installed, from **Projects:** <*namespace*>.
- 2. Select Operator for IBM block storage CSI driver.
- 3. Select IBM block storage CSI driver.

Operators > Installed Operators > Operator Details.

4. Click on the more menu for the ibm-block-csi driver and select Delete IBMBlock CSI.

Wait for the controller and node pods to terminate.

This deletes the CSI driver. Continue to step <u>"5" on page 7</u> to delete the operator for IBM block storage CSI driver.

5. From the **Installed Operators** page, click on the **more** menu for the **Operator for IBM block storage CSI driver** and select **Uninstall Operator**.

Uninstalling the driver using CLIs

Use this information to uninstall the IBM CSI (Container Storage Interface) operator and driver from a command line terminal.

About this task

Note: These instructions are for command-line terminal users only. If using the Red Hat OpenShift Container Platform, follow the instructions detailed in <u>"Uninstalling the driver using the OpenShift web</u> console" on page 6.

Procedure

Perform the following steps in order to uninstall the CSI driver and operator from a command line terminal.

1. Delete the IBMBlockCSI custom resource.

kubectl -n <namespace> delete -f csi.ibm.com_v1_ibmblockcsi_cr.yaml

2. Delete the operator.

kubectl -n <namespace> delete -f ibm-block-csi-operator.yaml

Upgrading the CSI driver

Use this information to upgrade the IBM block storage CSI driver.

When the **Approval Strategy** is set to **Automatic** within the OpenShift web console the CSI (Container Storage Interface) driver upgrades automatically when a new version is released. (See <u>"Installing the</u> driver using the OpenShift web console" on page 4.)

To check if your operator is running at the latest release level, from the OpenShift web console, browse to **Operators** > **Installed Operators**. Check the status of the Operator for IBM block storage CSI driver. Ensure that the **Upgrade Status** is *Up to date*.

To manually upgrade by using the OpenShift web console, see <u>"Upgrading the driver using the OpenShift</u> web console" on page 7.

To manually upgrade the CSI (Container Storage Interface) driver from a previous version by using CLI commands, perform step 1 and step 4 of the installation procedure for the latest version.

Upgrading the driver using the OpenShift web console

When using the Red Hat OpenShift Container Platform, the operator for IBM block storage CSI driver can be upgraded directly from OpenShift web console, through the OperatorHub.

Note: These instructions are for Red Hat OpenShift Container Platform users only. If you are not using the OpenShift Container Platform, follow the instructions detailed in <u>"Installing the driver using CLIs" on page</u> <u>5</u>.

When the Subscription **Approval** policy for the Operator for IBM block storage CSI driver is set to **Manual**, follow the procedure detailed in <u>"Manual upgrade with OpenShift" on page 8</u>.

Manual upgrade with OpenShift

When using the Red Hat OpenShift Container Platform, the CSI (Container Storage Interface) driver can be manually updated through the OpenShift web console.

Procedure

1. From Red Hat OpenShift Container Platform **Operators** > **Installed Operators** see the status of the **ibm-block-csi-operator**.

If the **Status** is *UpgradePending*, click on the operator.

2. From the **Subscription Overview** view, click on **1 requires approval**.

The **Review Manual Install Plan** notice appears.

- 3. Click on Preview Install Plan.
- 4. Review the manual install plan and click Approve.
- 5. From the **Subscription** tab, check the upgrade status and the installed version.
- 6. From Operators > Installed Operators > Operator for IBM block storage CSI driver, click Create Instance.
- 7. Check the **Subscriptions** > **Subscription Overview** tab see the Operator status. Wait for the **Upgrade Status** to be **Upgrading** and **1 requires approval** appears.
- 8. Click **1 requires approval**.

The Review Manual Install Plan notice appears.

- 9. Click on Preview Install Plan.
- 10. Review the manual install plan and click **Approve**.
- 11. From the **Subscription** tab, check the upgrade status and the installed version.
- 12. Check the **Overview** tab and that the **Controller Image Tab** and **Node Image Tag** are showing the most up-to-date version of the driver and the **Status** is *Running*.

Chapter 3. CSI driver configuration

Use this information to configure the IBM block storage CSI driver after installation.

Once the driver is installed and running (see <u>"Installing the operator and driver" on page 4</u>), in order to use the driver and run stateful applications using IBM block storage systems, the relevant yaml files must be created.

Multiple yaml files per type can be created (with different configurations), according to your storage needs.

- "Creating a Secret" on page 9
- "Creating a StorageClass" on page 10
- "Creating a PersistentVolumeClaim (PVC)" on page 11
- "Creating a StatefulSet" on page 13
- "Creating a VolumeSnapshotClass" on page 15
- "Creating a VolumeSnapshot" on page 16
- "Expanding a PersistentVolumeClaim (PVC)" on page 16
- "Advanced configuration" on page 17

Creating a Secret

Create an array secret YAML file in order to define the storage credentials (username and password) and address.

Important: When your storage system password is changed, be sure to also change the passwords in the corresponding secrets, particularly when LDAP is used on the storage systems.

Failing to do so causes mismatched passwords across the storage systems and the secrets, causing the user to be locked out of the storage systems.

Use one of the following procedures to create and apply the secret:

Creating an array secret file

1. Create the secret file, similar to the following demo-secret.yaml:

The **management_address** field can contain more than one address, with each value separated by a comma.

```
kind: Secret
apiVersion: v1
metadata:
    name: demo-secret
    namespace: default
type: Opaque
stringData:
    management_address: demo-management-address  # Array management addresses
    username: demo-username  # Array username
data:
    password: ZGVtby1wYXNzd29yZA==  # base64 array password
```

2. Apply the secret using the following command:

kubectl apply -f demo-secret.yaml

The secret/<NAME> created message is emitted.

Creating an array secret via command line

Note: This procedure is applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

Create the secret using the following command:

```
kubectl create secret generic <NAME> --from-literal=username=<USER> --from-
literal=password=<PASSWORD>
--from-literal=management_address=<ARRAY_MGMT> -n <namespace>
```

Creating a StorageClass

Create a storage class yaml file in order to define the storage system pool name, secret reference, **SpaceEfficiency**, and **fstype**.

Procedure

Use the following procedure to create and apply the storage classes.

Note: This procedure is applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

1. Create a storage class yaml file, similar to the following demo-storageclass.yaml.

Update the capabilities, pools, and array secrets, as needed.

Use the **SpaceEfficiency** parameters for each storage system, as defined in <u>Table 1 on page 10</u>. These values are not case-sensitive.

Table 1. SpaceEfficiency parameter definitions per storage system type		
Storage system type	SpaceEfficiency parameter options	
IBM FlashSystem A9000 and A9000R	Always includes deduplication and compression. No need to specify during configuration.	
IBM Spectrum Virtualize Family	 thick (default value) thin compressed deduplicated Note: If not specified, the default value is thick. 	
IBM DS8000 Family	 none (default value) thin Note: If not specified, the default value is none. 	

- The IBM DS8000 Family **pool** value is the pool ID and not the pool name as is used in other storage systems.
- The **pool** value should be a name of an existing pool on the storage system.
- The **allowVolumeExpansion** parameter is optional but is necessary for using volume expansion. The default value is *false*.

Note: Be sure to set the value to *true* to allow volume expansion.

- The **csi.storage.k8s.io/fstype** parameter is optional. The values that are allowed are *ext4* or *xfs*. The default value is *ext4*.
- The **volume_name_prefix** parameter is optional.

Note: For IBM DS8000 Family, the maximum prefix length is five characters. The maximum prefix length for other systems is 20 characters.

For storage systems using Spectrum Virtualize, the **CSI_** prefix is added as default if not specified by the user.

```
kind: StorageClass
apiVersion: storage.k8s.io/v1
metadata:
 name: demo-storageclass
provisioner: block.csi.ibm.com
parameters:
  SpaceEfficiency: deduplicated
                                  # Optional.
  pool: demo-pool
  csi.storage.k8s.io/provisioner-secret-name: demo-secret
  csi.storage.k8s.io/provisioner-secret-namespace: default
  csi.storage.k8s.io/controller-publish-secret-name: demo-secret
  csi.storage.k8s.io/controller-publish-secret-namespace: default
  csi.storage.k8s.io/controller-expand-secret-name: demo-secret
  csi.storage.k8s.io/controller-expand-secret-namespace: default
  csi.storage.k8s.io/fstype: xfs # Optional. Values ext4\xfs. The default is ext4.
volume_name_prefix: demoPVC
allowVolumeExpansion: true
                                    # Optional.
```

2. Apply the storage class.

kubectl apply -f demo-storageclass.yaml

The storageclass.storage.k8s.io/demo-storageclass created message is emitted.

Creating a PersistentVolumeClaim (PVC)

Create a PersistentVolumeClaim (PVC) yaml file for a persistent volume (PV).

The IBM block storage CSI driver supports using both file system and raw block volume types.

Important: If not defined, the default type is **Filesystem**. Be sure to define the type as **Block** if this configuration is preferred.

Note: The examples below create the PVC with a storage size 1 Gb. This can be changed, per customer needs.

Use the sections below for creating yaml files for PVCs with file system and raw block volume types. After each yaml file creation, use the **kubect1** apply command.

kubectl apply -f <filename>.yaml

The persistent volume claim / < filename > created message is emitted.

Use the following sections, according to your PVC needs:

- "Creating PVC for volume with file system" on page 12
- "Creating PVC for raw block volume" on page 12
- "Creating PVC from volume snapshot" on page 12
- "Creating a volume clone from an existing PVC" on page 13

Creating PVC for volume with file system

Create a PVC yaml file, similar to the following demo-pvc-file-system.yaml file, with the size of 1 Gb.

Note: volumeMode is an optional field. Filesystem is the default if the value is not added.

```
kind: PersistentVolumeClaim
apiVersion: v1
metadata:
    name: demo-pvc-file-system
    spec:
    volumeMode: Filesystem  # Optional. The default is Filesystem.
    accessModes:
    - ReadWriteOnce
    resources:
        requests:
        storage: 1Gi
        storageClassName: demo-storageclass
```

Creating PVC for raw block volume

Create a PVC yaml file, similar to the following demo-pvc-raw-block.yaml file, with the size of 1 Gb.

```
kind: PersistentVolumeClaim
apiVersion: v1
metadata:
   name: demo-pvc-raw-block
spec:
   volumeMode: Block
   accessModes:
        - ReadWriteOnce
   resources:
        requests:
        storage: 1Gi
   storageClassName: demo-storageclass
```

Creating PVC from volume snapshot

To create a PVC from an existing volume snapshot, create a PVC yaml file, similar to the following demopvc-from-snapshot.yaml file, with the size of 1 Gb.

```
kind: PersistentVolumeClaim
apiVersion: v1
metadata:
 name: demo-pvc-from-snapshot
spec:
 volumeMode: Filesystem
 accessModes:
  - ReadWriteOnce
 resources:
   requests:
     storage: 1Gi
  storageClassName: demo-storageclass
  dataSource:
   name: demo-snapshot
    kind: VolumeSnapshot
   apiGroup: snapshot.storage.k8s.io
```

Creating a volume clone from an existing PVC

Note: IBM FlashCopy function is referred to as the more generic volume snapshots and cloning within this documentation set. Not all supported products use the *FlashCopy function* terminology.

To create a volume clone from an existing PVC object, create a PVC yaml file, similar to the following demo-pvc-cloned-pvc.yaml file, with the size of 1 Gb.

```
kind: PersistentVolumeClaim
apiVersion: v1
metadata:
    name: demo-pvc-cloned-pvc
spec:
    volumeMode: Filesystem
    accessModes:
    - ReadWriteOnce
    resources:
        requests:
        storage: 1Gi
    storageClassName: demo-storageclass
    dataSource:
        name: demo-pvc-file-system
        kind: PersistentVolumeClaim
```

Creating a StatefulSet

Create a StatefulSet yaml file to manage stateful applications.

The IBM block storage CSI driver supports using both file system and raw block volume types.

StatefulSets can include volumes with file systems, raw block volume systems, or both.

Important: When defining the StatefulSet configuration, be sure to define volumes according to the PVC type.

Use the sections below for yaml creation of StatefulSets with file system, raw block volume, and mixed types. After each yaml file creation, use the **kubectl apply** command.

kubectl apply -f <filename>.yaml

The statefulset.apps/<filename> created message is emitted.

Creating a StatefulSet with file system volumes

Create a StatefulSet yaml file, similar to the following demo-statefulset-file-system.yaml file.

```
kind: StatefulSet
apiVersion: apps/v1
metadata:
 name: demo-statefulset-file-system
spec:
  selector:
    matchLabels:
      app: demo-statefulset
  serviceName: demo-statefulset
  replicas: 1
  template:
    metadata:
      labels:
         app: demo-statefulset
    spec:
       containers:
       - name: demo-container
         image: registry.access.redhat.com/ubi8/ubi:latest
command: [ "/bin/sh", "-c", "--" ]
args: [ "while true; do sleep 30; done;" ]
         volumeMounts:
           - name: demo-volume-file-system
             mountPath: "/data"
       volumes:
        - name: demo-volume-file-system
         persistentVolumeClaim:
           claimName: demo-pvc-file-system
```

Creating a StatefulSet with raw block volume

Create a StatefulSet yaml file, similar to the following demo-statefulset-raw-block.yaml file.

```
kind: StatefulSet
apiVersion: apps/v1
metadata:
  name: demo-statefulset-raw-block
spec:
  selector:
    matchLabels:
       app: demo-statefulset
  serviceName: demo-statefulset
  replicas: 1
  template:
    metadata:
       labels:
         app: demo-statefulset
     spec:
       containers:
        - name: demo-container
         image: registry.access.redhat.com/ubi8/ubi:latest
command: [ "/bin/sh", "-c", "--" ]
args: [ "while true; do sleep 30; done;" ]
          volumeDevices:
            - name: demo-volume-raw-block
devicePath: "/dev/block"
       volumes:
         name: demo-volume-raw-block
          persistentVolumeClaim:
            claimName: demo-pvc-raw-block
```

Creating a StatefulSet with both raw block and file system volumes

Create a StatefulSet yaml file, similar to the following demo-statefulset-combined.yaml file.

```
kind: StatefulSet
apiVersion: apps/v1
metadata:
 name: demo-statefulset-combined
spec:
  selector:
    matchLabels:
      app: demo-statefulset
  serviceName: demo-statefulset
  replicas: 1
  template:
    metadata:
      labels:
        app: demo-statefulset
    spec:
      containers:
       - name: demo-container
         image: registry.access.redhat.com/ubi8/ubi:latest
command: [ "/bin/sh", "-c", "--" ]
args: [ "while true; do sleep 30; done;" ]
         volumeMounts:
           - name: demo-volume-file-system
             mountPath: "/data"
         volumeDevices:
           - name: demo-volume-raw-block
             devicePath: "/dev/block"
      volumes:
       - name: demo-volume-file-system
         persistentVolumeClaim:
           claimName: demo-pvc-file-system
       - name: demo-volume-raw-block
         persistentVolumeClaim:
           claimName: demo-pvc-raw-block
```

Creating a VolumeSnapshotClass

Create a VolumeSnapshotClass YAML file to enable creation and deletion of volume snapshots.

Note:

- IBM FlashCopy function is referred to as the more generic volume snapshots and cloning within this documentation set. Not all supported products use the *FlashCopy function* terminology.
- For volume snapshot support, the minimum orchestration platform version requirements are Red Hat OpenShift 4.4 and Kubernetes 1.17.

In order to enable creation and deletion of volume snapshots for your storage system, create a VolumeSnapshotClass YAML file, similar to the following demo-snapshotclass.yaml.

When configuring the file, be sure to use the same array secret and array secret namespace as defined in "Creating a Secret" on page 9.

• The snapshot_name_prefix parameter is optional.

Note: For IBM DS8000 Family, the maximum prefix length is five characters. The maximum prefix length for other systems is 20 characters.

For storage systems using Spectrum Virtualize, the **CSI_** prefix is added as default if not specified by the user.

```
apiVersion: snapshot.storage.k8s.io/v1beta1
kind: VolumeSnapshotClass
metadata:
    name: demo-snapshotclass
driver: block.csi.ibm.com
deletionPolicy: Delete
parameters:
    csi.storage.k8s.io/snapshotter-secret-name: demo-secret
    csi.storage.k8s.io/snapshotter-secret-namespace: default
    snapshot_name_prefix: demoSnapshot  # Optional.
    pool: demo-pool  # Mandatory only for DS8000 Family.
```

After the YAML file is created, apply it by using the **kubectl apply** -f command.

kubectl apply -f <filename>.yaml

Creating a VolumeSnapshot

Create a VolumeSnapshot yaml file for a specific PersistentVolumeClaim (PVC).

Before you begin

VolumeSnapshotClass needs to be present before a VolumeSnapshot can be created. For more information, see "Creating a VolumeSnapshotClass" on page 15.

Note:

- IBM FlashCopy function is referred to as the more generic volume snapshots and cloning within this
 documentation set. Not all supported products use the FlashCopy function terminology.
- For volume snapshot support, the minimum orchestration platform version requirements are Red Hat OpenShift 4.4 and Kubernetes 1.17.

When creating volume snapshots, be sure to follow all of the snapshot configurations, found in "Compatibility and requirements" on page 3 before snapshot creation.

Procedure

1. Create a snapshot for a specific PersistentVolumeClaim (PVC) using the demo-snapshot.yaml.

For more information about PVC configuration, see <u>"Creating a PersistentVolumeClaim (PVC)" on page</u> <u>11</u>.

```
apiVersion: snapshot.storage.k8s.io/v1beta1
kind: VolumeSnapshot
metadata:
    name: demo-snapshot
spec:
    volumeSnapshotClassName: demo-snapshotclass
    source:
        persistentVolumeClaimName: demo-pvc-file-system
```

2. After the YAML file is created, apply it by using the **kubectl apply -f** command.

kubectl apply -f <filename>.yaml

3. Verify that the VolumeSnapshot was created.

Run the kubectl describe volumesnapshot command.

See the Status section of the output for the following:

- Bound Volume Snapshot Content Name: Indicates the volume is bound to the specified VolumeSnapshotContent.
- Creation Time: Indicates when the snapshot was created.
- Ready to Use: Indicates the volume snapshot is ready to use.
- **Restore Size:** Indicates the minimum volume size required when restoring (provisioning) a volume from this snapshot.

Expanding a PersistentVolumeClaim (PVC)

Use this information to expand existing volumes.

Important: Before expanding an existing volume, be sure that the relevant StorageClass yaml **allowVolumeExpansion** parameter is set to *true*. For more information, see <u>"Creating a StorageClass"</u> on page 10.

To expand an existing volume, open the relevant PersistentVolumeClaim (PVC) yaml file and increase the **storage** parameter value. For example, if the current **storage** value is set to *1Gi*, you can change it to *10Gi*, as needed. For more information about PVC configuration, see <u>"Creating a PersistentVolumeClaim</u> (PVC)" on page 11.

Be sure to use the **kubect1** apply command in order to apply your changes.

Advanced configuration

Use advanced configuration tasks to further customize the configuration of the IBM block storage CSI driver.

• "Importing an existing volume" on page 17

Importing an existing volume

Use this information to import volumes created externally from the IBM block storage CSI driver by using a persistent volume (PV) yaml file.

Before you begin

Before starting to import an existing volume, find the following information in the existing volume in order to include the information in the persistent volume (PV) yaml file:

- volumeHandle
- volumeAttributes (optional)

Including:

- pool_name: <Name of Pool where volume is located> (Listed as pool_id: for DS8000 Family systems.)
- storage_type: <SVC | A9K | DS8K>
- volume_name:<Volume name>
- array_address:<Array address>

To find the **volumeHandle**, use one of the following procedures:

• Through command line (for Spectrum Virtualize Family):

lsvdisk <volume name> | grep vdisk_UID

lsvdisk vol0 | grep vdisk_UID vdisk_UID 600507640082000B080000000004FF

• Through command line (for FlashSystem A9000 and A9000R):

vol_list_extended vol=<volume_name>

For example, for vol1:

A9000>> vol_list_extended vol=vol1 Name WWN Product Serial Number vol1 6001738CFC9035E800000000091F0C0 60035E800000000091F0C0

• Through the Spectrum Virtualize management GUI:

1. Select **Volumes** > **Volumes** from the side bar.

The Volumes page appears.

2. Browse to the volume that the port is on and right-click > Properties.

The Properties window appears. Use the UID number.

For more information about Spectrum Virtualize see IBM Spectrum Virtualize as Software Only on Knowledge Center (ibm.com/support/knowledgecenter/en/STVLF4) or your specific Spectrum Virtualize Family product page on Knowledge Center (ibm.com/support/knowledgecenter/).

- Through the IBM Hyper-Scale Manager user interface for FlashSystem A9000 and A90000R storage systems:
 - 1. Select **Pools and Volumes Views** > **Volumes** from the side bar.

The Volumes table is displayed.

2. Select the Volume.

The Volume Properties form appears.

3. Use the **ID** number.

For more information about the IBM Hyper-Scale Manager see <u>IBM Hyper-Scale Manager</u> on Knowledge Center (ibm.com/support/knowledgecenter/SSUMNQ).

About this task

Use this procedure to help build a PV yaml file for your volumes.

Note: These steps are setup for importing volumes from a Spectrum Virtualize Family system. Change parameters, as needed.

Procedure

1. Create a persistent volume (PV) yaml file.

Important: Be sure to include the **storageClassName** and **controllerPublishSecretRef** parameters or errors will occur.

2. Take the **volume_name** and other optional information (collected before the procedure) and insert it into the yaml file.

```
apiVersion: v1
kind: PersistentVolume
metadata:
  #annotations:
   #pv.kubernetes.io/provisioned-by: block.csi.ibm.com
 name: vol1-pv
spec:
  accessModes:
   ReadWriteOnce
  capacity:
    storage: 1Gi
  csi:
   controllerPublishSecretRef:
      name: demo-secret
      namespace: default
    driver: block.csi.ibm.com
    # volumeAttributes:
      # pool_name: ibmc-block-gold
      # storage_type: SVC
      # volume_name: vol1
      # array_address: baremetal10-cluster.xiv.ibm.com
    volumeHandle: SVC:600507640082000B0800000000004FF
  # persistentVolumeReclaimPolicy: Retain
  storageClassName: ibmc-block-gold
  # volumeMode: Filesystem
```

3. Create a PersistentVolumeClaim (PVC) yaml file.

Note:

- To include a specific 5 Gi PV, be sure to include the **storageClassName**.
- For more information about creating a PVC yaml file, see <u>"Creating a PersistentVolumeClaim (PVC)"</u> on page 11.

```
apiVersion: v1
kind: PersistentVolumeClaim
metadata:
   volume.beta.kubernetes.io/storage-provisioner: block.csi.ibm.com
   name: vol1-pvc
spec:
   accessModes:
    - ReadWriteOnce
   resources:
      requests:
      storage: 1Gi
   storageClassName: ibmc-block-gold
   volumeName: vol1-pv
```

4. Create a project namespace.

Using OpenShift web console

From Red Hat OpenShift Container Platform **Home** > **Projects**, click **Create Project**. In the **Create Project** dialog box, enter a Project name (also referred to as *namespace*).

Click Create to save.

Using command-line terminal

Note: This procedure is applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

Use the kubectl create ns <namespace> command to create a project namespace.

5. Create a StatefulSet.

For more information about creating a StatefulSet, see "Creating a StatefulSet" on page 13.

```
kind: StatefulSet
apiVersion: apps/v1
metadata:
  name: sanity-statefulset
spec:
  selector:
    matchLabels:
      app: sanity-statefulset
  serviceName: sanity-statefulset
  replicas: 1
  template:
    metadata:
       labels:
         app: sanity-statefulset
    spec:
       containers:
        - name: container1
         image: registry.access.redhat.com/ubi8/ubi:latest
command: [ "/bin/sh", "-c", "--" ]
args: [ "while true; do sleep 30; done;" ]
          volumeMounts:
            - name: vol1
mountPath: "/data"
       volumes:
       - name: vol1
          persistentVolumeClaim:
            claimName: vol1-pvc
```

Chapter 4. Using IBM block storage CSI driver

Use this information for further usage information for the CSI (Container Storage Interface) driver.

- "Sample configurations for running a stateful container" on page 21.
- "Recovering a pod volume attachment from a crashed Kubernetes node" on page 23.

Sample configurations for running a stateful container

You can use the CSI (Container Storage Interface) driver for running stateful containers with a storage volume provisioned from IBM block storage systems.

About this task

These examples illustrate a basic configuration required for running a stateful container with volumes provisioned on an IBM Spectrum Virtualize Family storage system.

While these examples specify the use of IBM Spectrum Virtualize products, the same configuration is used on all supported storage system types.

Note: The secret names given can be user specified. When giving secret names when managing different system storage types, be sure to give system type indicators to each name.

The following are examples of different types of secret names that can be given per storage type.

Storage system name	Secret name
IBM FlashSystem A9000 IBM FlashSystem A9000R	a9000-array1
IBM Spectrum Virtualize Family including IBM SAN Volume Controller and IBM FlashSystem family members built with IBM Spectrum Virtualize (FlashSystem 5010, 5030, 5100, 7200, 9100, 9200, 9200R)	storwize-array1
IBM DS8000 Family products	DS8000-array1

Note: This procedure is applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

Use this information to run a stateful container on StatefulSet volumes using either file systems or raw block volumes.

Procedure

- 1. Create an array secret, as described in "Creating a Secret" on page 9.
- 2. Create a storage class, as described in "Creating a StorageClass" on page 10.

Remember: The **SpaceEfficiency** values for Spectrum Virtualize Family are: thick, thin, compressed, or deduplicated. These values are not case specific.

For DS8000 Family systems, the default value is standard, but can be set to thin, if required. These values are not case specific. For more information, see "Creating a StorageClass" on page 10.

This parameter is not applicable for IBM FlashSystem A9000 and A9000R systems. These systems always include deduplication and compression.

3. Create a PVC with the size of 1 Gb, as described in <u>"Creating a PersistentVolumeClaim (PVC)" on page 11</u>.

- 4. Display the existing PVC and the created persistent volume (PV).
- 5. Create a StatefulSet, as described in <u>"Creating a StatefulSet" on page 13</u>.

Chapter 5. Troubleshooting

This section can help you detect and solve problems that you might encounter when using the IBM block storage CSI driver.

Log collection

Use the CSI (Container Storage Interface) driver logs for problem identification.

Note: These procedures are applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

To collect and display logs, related to the different components of IBM block storage CSI driver, use the following Kubernetes commands:

Log collection for CSI pods, daemonset, and StatefulSet

kubectl get all -n <namespace> -l csi

Log collection for IBM block storage CSI driver controller

kubectl log -f -n <namespace> ibm-block-csi-controller-0 -c ibm-block-csi-controller

Log collection for IBM block storage CSI driver node (per worker node or PODID)

kubectl log -f -n <namespace> ibm-block-csi-node-<PODID> -c ibm-block-csi-node

Log collection for Operator for IBM block storage CSI driver

kubectl log -f -n <namespace> ibm-block-csi-operator-<PODID> -c ibm-block-csi-operator

Detecting errors

Use this information to help pinpoint potential causes for stateful pod failure.

This is an overview of actions that you can take to pinpoint a potential cause for a stateful pod failure.

Note: This procedures is applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

1. Verify that the CSI driver is running. (Make sure the csi-controller pod status is *Running*).

\$> kubectl get all -n <namespace> -l csi

2. If pod/ibm-block-csi-controller-0 is not in a *Running* state, run the following command:

kubectl describe -n <namespace> pod/ibm-block-csi-controller-0

View the logs (see "Log collection" on page 23).

Recovering a pod volume attachment from a crashed Kubernetes node

This section details a manual operation required to revive Kubernetes pods that reside on a crashed node due to an existing Kubernetes limitation.

Identifying a crashed node

Note: These procedures are applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

When a worker node shuts down or crashes, all pods in a StatefulSet that reside on it become unavailable. In these scenarios, the node status is *NotReady*, and the pod status appears as *Terminating*.

For example:

```
$> kubectl get nodes
NAME STATUS ROLES AGE VERSION
k8s-master Ready master 6d <your k8s version>
k8s-node1 Ready <none> 6d <your k8s version>
k8s-node3 NotReady <none> 6d <your k8s version>
$> kubectl get pods --all-namespaces -o wide | grep default
default sanity-statefulset-0 1/1 Terminating 0 19m 10.244.2.37 k8s-node3
```

Recovering a crashed node



Attention: In order to avoid data loss, before continuing, verify that there are no pods connected to this volume.

Follow the following procedure to recover from a crashed node (see a full example at the end of the procedure):

1. Find for the **volumeattachment** of the created pod:

kubectl get volumeattachment

- 2. Copy the **volumeattachment** name.
- 3. Delete the volumeattachment:

kubectl delete volumeattachment <volumeattachment name>

4. Delete the pod:

kubectl delete pod <pod name> --grace-period=0 --force

5. Verify that the pod is now in a *Running* state and that the pod has moved to worker-node1.

For example:

```
$> kubectl get nodes
NAME STATUS ROLES AGE VERSION
k8s-master Ready master 6d <your k8s version>
k8s-node1 Ready <none> 6d <your k8s version>
k8s-node3 NotReady <none> 6d <your k8s version>
$> kubectl get pods --all-namespaces -o wide | grep default
default sanity-statefulset-0 1/1 Terminating 0 19m 10.244.2.37 k8s-node3
$> kubectl get volumeattachment
NAME AGE
csi-5944e1c742d25e7858a8e48311cdc6cc85218f1156dd6598d4cf824fb1412143 10m
$> kubectl delete volumeattachment
\texttt{csi-5944e1c742d25e7858a8e48311cdc6cc85218f1156dd6598d4cf824fb1412143}
volumeattachment.storage.k8s.io
"csi-5944e1c742d25e7858a8e48311cdc6cc85218f1156dd6598d4cf824fb1412143" deleted
$> kubectl delete pod sanity-statefulset-0 --grace-period=0 --force
warning: Immediate deletion does not wait for confirmation that the running resource has been
terminated. The resource may continue to run on the cluster indefinitely. pod "sanity-statefulset-0" deleted
$> kubectl get pods --all-namespaces -o wide | grep default
default sanity-statefulset-0 1/1 Running 0 26s 10.244.1.210 k8s-node1
```

Miscellaneous troubleshooting

Use this information to help pinpoint potential causes for stateful pod failure.

Note: These procedures are applicable for both Kubernetes and Red Hat OpenShift. For Red Hat OpenShift, replace kubectl with oc in all relevant commands.

- "General troubleshooting" on page 25
- "Error during pod creation" on page 25 (for volumes using StatefulSet only)

General troubleshooting

Use the following command for general troubleshooting:

```
kubectl get -n <namespace> csidriver,sa,clusterrole,clusterrolebinding,statefulset,pod,daemonset | grep
ibm-block-csi
```

Error during pod creation

Note: This troubleshooting procedure is relevant for volumes using file system types only (not for volumes using raw block volume types).

If the following error occurs during stateful application pod creation (the pod status is *ContainerCreating*):

```
-8e73-005056a49b44" : rpc error: code = Internal desc = 'fsck' found errors on device /dev/
dm-26 but could not correct them: fsck from util-linux 2.23.2
/dev/mapper/mpathym: One or more block group descriptor checksums are invalid. FIXED.
/dev/mapper/mpathym: Group descriptor 0 checksum is 0x00000, should be 0x3baa.
/dev/mapper/mpathym: UNEXPECTED INCONSISTENCY; RUN fsck MANUALLY.
(i.e., without -a or -p options)
```

1. Log in to the relevant worker node and run the **fsck** command to repair the filesystem manually.

fsck /dev/dm-<X>

The pod should come up immediately. If the pod is still in a *ContainerCreating* state, continue to the next step.

2. Run the # multipath -11 command to see if there are faulty multipath devices.

If there are faulty multipath devices:

- a. Restart multipath daemon, using the **systemctl restart multipathd** command.
- b. Rescan any iSCSI devices, using the **rescan-scsi-bus.sh** command.
- c. Restart the multipath daemon again, using the **systemctl restart multipathd** command.

The multipath devices should be running properly and the pod should come up immediately.

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Printed in USA

SC27-9590-09

