## Agilent

## E4980A Precision LCR Meter 20 Hz to 2 MHz

Data Sheet


## Definitions

All specifications apply to the conditions of a 0 to $55^{\circ} \mathrm{C}$ temperature range, unless otherwise stated, and 30 minutes after the instrument has been turned on.

Specifications (spec.): Warranted performance. Specifications include guardbands to account for the expected statistical performance distribution, measurement uncertainties, and changes in performance due to environmental conditions.

Supplemental information is provided as information that is useful in operating the instrument, but is not covered by the product warranty. This information is classified as either typical or nominal.

Typical (typ.): Expected performance of an average unit without taking guardbands into account.

Nominal (nom.): A general descriptive term that does not imply a level of performance.

## How to Use Tables

When measurement conditions fall under multiple categories in a table, apply the best value.
For example, basic accuracy Ab is $0.10 \%$ under the following conditions;

| Measurement time mode | SHORT |
| :--- | :--- |
| Test frequency | 125 Hz |
| Test signal voltage | 0.3 Vrms |

## Basic Specifications <br> Measurement functions

## Measurement parameters

- Cp-D, Cp-Q, Cp-G, Cp-Rp
- Cs-D,Cs-Q, Cs-Rs
- Lp-D,Lp-Q,Lp-G,Lp-Rp,Lp-Rdc ${ }^{1}$
- Ls-D, Ls-Q, Ls-Rs, Ls-Rdc ${ }^{1}$
- R-X
- Z-Өd, Z-өr
- G-B
- $\mathrm{Y}-\theta \mathrm{d}, \mathrm{Y}-\theta \mathrm{r}$
- Vdc-Idc ${ }^{1}$


## Definitions

Cp Capacitance value measured with parallel-equivalent circuit model
Cs Capacitance value measured with series-equivalent circuit model
Lp Inductance value measured with parallel-equivalent circuit model
Ls Inductance value measured with series-equivalent circuit model
D Dissipation factor
0 Quality factor (inverse of D)
G Equivalent parallel conductance measured with parallel-equivalent circuit model
Rp Equivalent parallel resistance measured with parallel-equivalent circuit model
Rs Equivalent series resistance measured with series-equivalent circuit model
Rdc Direct-current resistance
R Resistance
X Reactance
Z Impedance
Y Admittance
$\theta \mathbf{d}$ Phase angle of impedance/admittance (degree)
$\theta \mathbf{r} \quad$ Phase angle of impedance/admittance (radian)
B Susceptance
Vdc Direct-current voltage
Idc Direct-current electricity
Deviation measurement function: Deviation from reference value and percentage of deviation from reference value can be output as the result.

Equivalent circuits for measurement: Parallel, Series
Impedance range selection: Auto (auto range mode), manual (hold range mode)
Trigger mode: Internal trigger (INT), manual trigger (MAN), external trigger (EXT), GPIB trigger (BUS)

[^0]Table 1. Trigger delay time

| Range | $0 \mathrm{~s}-999 \mathrm{~s}$ |
| :--- | :--- |
| Resolution | $100 \mu \mathrm{~s}(0 \mathrm{~s}-100 \mathrm{~s})$ |
|  | $1 \mathrm{~ms}(100 \mathrm{~s}-999 \mathrm{~s})$ |

Table 2. Step delay time

| Range | $0 \mathrm{~s}-999 \mathrm{~s}$ |
| :--- | :--- |
| Resolution | $100 \mu \mathrm{~s}(0 \mathrm{~s}-100 \mathrm{~s})$ |
|  | $1 \mathrm{~ms}(100 \mathrm{~s}-999 \mathrm{~s})$ |

Measurement terminal: Four-terminal pair
Test cable length: $0 \mathrm{~m}, 1 \mathrm{~m}, 2 \mathrm{~m}, 4 \mathrm{~m}$
Measurement time modes: Short mode, medium mode, long mode.

## Table 3. Averaging

| Range | $1-256$ measurements |
| :--- | :--- |
| Resolution | 1 |

## Test signal

Table 4. Test frequencies

| Test frequencies | $20 \mathrm{~Hz}-2 \mathrm{MHz}$ |
| :--- | :--- |
| Resolution | $0.01 \mathrm{~Hz}(20 \mathrm{~Hz}-99.99 \mathrm{~Hz})$ |
|  | $0.1 \mathrm{~Hz}(100 \mathrm{~Hz}-999.9 \mathrm{~Hz})$ |
|  | $1 \mathrm{~Hz}(1 \mathrm{kHz}-9.999 \mathrm{kHz})$ |
|  | $10 \mathrm{~Hz}(10 \mathrm{kHz}-99.99 \mathrm{kHz})$ |
|  | $100 \mathrm{~Hz}(100 \mathrm{kHz}-999.9 \mathrm{kHz})$ |
|  | $1 \mathrm{kHz}(1 \mathrm{MHz}-2 \mathrm{MHz})$ |
| Measurement accuracy | $\pm 0.01 \%$ |

## Table 5. Test signal modes

| Normal | Program selected voltage or current at the measurement <br> terminals when they are opened or short-circuited, respectively. |
| :--- | :--- |
| Constant | Maintains selected voltage or current at the device under test <br>  |

## Signal level

Table 6. Test signal voltage

| Range |  | 0 Vrms - 2.0 Vrms |
| :---: | :---: | :---: |
| Resolution |  | $100 \mu \mathrm{Vrms}$ (0 Vrms - 0.2 Vrms ) |
|  |  | $200 \mu \mathrm{Vrms}$ (0.2 Vrms - 0.5 Vrms ) |
|  |  | $500 \mu \mathrm{Vrms}$ (0.5 Vrms - 1 Vrms) |
|  |  | 1 mVrms (1 Vrms - 2 Vrms) |
| Accuracy | Normal | $\pm(10 \%+1 \mathrm{mVrms})$ Test frequency $\leq 1 \mathrm{MHz}$ : spec. |
|  |  | Test frequency > 1 MHz : typ. |
|  | Constant ${ }^{1}$ | $\pm(6 \%+1 \mathrm{mVrms})$ Test frequency $\leq 1 \mathrm{MHz}$ : spec. |
|  |  | Test frequency > 1 MHz : typ. |

Table 7. Test signal current

| Range |  | 0 Arms - 20 mArms |
| :---: | :---: | :---: |
| Resolution |  | $1 \mu \mathrm{Arms} \mathrm{(0} \mathrm{Arms} \mathrm{-} 2 \mathrm{mArms}$ ) |
|  |  | $2 \mu$ Arms ( $2 \mathrm{mArms}-5 \mathrm{mArms}$ ) |
|  |  | $5 \mu \mathrm{Arms} \mathrm{( } 5 \mathrm{mArms}-10 \mathrm{mArms}$ ) |
|  |  | $10 \mu \mathrm{Arms} \mathrm{( } 10 \mathrm{mArms}$ - 20 mArms ) |
| Accuracy | Normal | $\pm(10 \%+10 \mu \mathrm{Arms})$ Test frequency $\leq 1 \mathrm{MHz}$ : spec. |
|  |  | Test frequency > 1 MHz : typ. |
|  | Constant ${ }^{1}$ | $\pm(6 \%+10 \mu \mathrm{Arms})$ Test frequency < = 1 MHz : spec. |
|  |  | Test frequency > 1 MHz : typ. |

Output impedance: $100 \Omega$ (nominal)

## Test signal level monitor function

- Test signal voltage and test signal current can be monitored.
- Level monitor accuracy:

Table 8. Test signal voltage monitor accuracy (Vac)

| Test signal voltage ${ }^{\mathbf{2}}$ | Test frequency | Specification |
| :--- | :--- | :--- |
| $\mathbf{5} \mathbf{~ m V r m s ~}-\mathbf{2}$ Vrms | $\leq 1 \mathrm{MHz}$ | $\pm(3 \%$ of reading value $+0.5 \mathrm{mVrms})$ |
|  | $>1 \mathrm{MHz}$ | $\pm(6 \%$ of reading value $+1 \mathrm{mVrms})$ |

Table 9. Test signal current monitor accuracy (lac)

| Test signal current ${ }^{2}$ | Test frequency | Specification |
| :--- | :--- | :--- |
| $\mathbf{5 0} \boldsymbol{\mu}$ Arms $\mathbf{- 2 0} \mathbf{~ m A r m s ~}$ | $\leq 1 \mathrm{MHz}$ | $\pm(3 \%$ of reading value $+5 \mu \mathrm{Arms})$ |
|  | $>1 \mathrm{MHz}$ | $\pm(6 \%$ of reading value $+10 \mu \mathrm{Arms})$ |

1. When auto level control function is on.
2. This is not an output value but rather a displayed test signal level.

## Measurement display ranges

Table 10 shows the range of measured value that can be displayed on the screen.
Table 10. Allowable display ranges for measured values

| Parameter | Measurement display range |
| :--- | :--- |
| Cs, Cp | $\pm 1.000000$ aF to 999.9999 EF |
| Ls, Lp | $\pm 1.000000$ aH to 999.9999 EH |
| D | $\pm 0.000001$ to 9.999999 |
| Q | $\pm 0.01$ to 99999.99 |
| R, Rs, Rp, | $\pm 1.000000 \mathrm{a} \Omega$ to $999.9999 \mathrm{E} \Omega$ |
| $\mathrm{X}, \mathrm{Z}, \mathrm{Rdc}$ | $\pm 1.000000$ aS to 999.9999 ES |
| $\mathrm{G}, \mathrm{B}, \mathrm{Y}$ | $\pm 1.000000$ aV to 999.9999 EV |
| Vdc | $\pm 1.000000$ aA to 999.9999 EA |
| Idc | $\pm 1.000000$ arad to 3.141593 rad |
| $\theta \mathrm{r}$ | $\pm 0.0001$ deg to 180.0000 deg |
| $\theta \mathrm{d}$ | $\pm 0.0001 \%$ to $999.9999 \%$ |
| $\Delta \%$ |  |

a: $1 \times 10^{-18}, \mathrm{E}: 1 \times 10^{18}$

## Absolute measurement accuracy

The following equations are used to calculate absolute accuracy.
Absolute accuracy Aa of $|Z|,|Y|, L, C, R, X, G, B(L, C, X$, and $B$ accuracies apply when $\mathrm{Dx} \leq 0.1, \mathrm{R}$ and G accuracies apply when $\mathbf{0 x} \leq 0.1$ )

Equation 1. $\quad A a=A e+$ Acal

| Aa | Absolute accuracy (\% of reading value) |
| :--- | :--- |
| Ae | Relative accuracy (\% of reading value) |
| Acal | Calibration accuracy (\%) |
| where G accuracy is applied only to G-B measurements. |  |

D accuracy (when $\mathrm{Dx} \leq 0.1$ )
Equation 2. De $+\theta c a l$

| Dx | Measured $D$ value |
| :--- | :--- |
| De | Relative accuracy of $D$ |
| $\theta$ cal | Calibration accuracy of $\theta$ (radian) |

$\mathbf{0}$ accuracy (When $\mathbf{0 x} \times \mathbf{D a}<\mathbf{1}$ )
Equation 3. $\pm \frac{\left(0 x^{2} \times D a\right)}{(1 \mp O x \times D a)}$

| $0 x$ Measured 0 value <br> Da Absolute accuracy of $D$ |  |
| :--- | :--- |
| $\theta$ accuracy |  |
| Equation 4. | $\theta e+\theta c a l$ |
| $\theta e$ | Relative accuracy of $\theta$ (degree) |
| $\theta$ cal | Calibration accuracy of $\theta$ (degree) |

## G accuracy (when $\mathbf{D x} \leq 0.1$ )

$$
\begin{array}{ll}
\text { Equation 5. } & B x+D a \quad(S) \\
B x=2 \pi f C x=\frac{1}{2 \pi f L x}
\end{array}
$$

| Dx | Measured D value |
| :--- | :--- |
| Bx | Measured B value (S) |
| Da | Absolute accuracy of D |
| f | Test frequency (Hz) |
| Cx | Measured C value (F) |
| Lx | Measured L value (H) |

where the accuracy of G is applied to Cp -G measurements.

## Absolute accuracy of $\operatorname{Rp}$ (when $\mathrm{Dx} \leq 0.1$ )

| Equation 6. | $\pm \frac{R p x \times D a}{D x \mp D a}$ |
| :--- | :--- |
| Rpx | Measured Rp value $(\Omega)$ |
| Dx | Measured D value |
| Da | Absolute accuracy of $D$ |

## Absolute accuracy of Rs (when $\mathrm{Dx} \leq 0.1$ )

| Equation 7. | $X x \times D a \quad(\Omega)$ |
| :--- | :--- |
| $X x=\frac{1}{2 \pi f C x}=2 \pi f L x$ |  |


| Dx | Measured D value |
| :--- | :--- |
| Xx | Measured X value ( $\Omega$ ) |
| Da | Absolute accuracy of D |
| f | Test frequency (Hz) |
| Cx | Measured C value (F) |
| Lx | Measured L value (H) |

## Relative accuracy

Relative accuracy includes stability, temperature coefficient, linearity, repeatability, and calibration interpolation error. Relative accuracy is specified when all of the following conditions are satisfied:

- Warm-up time: 30 minutes
- Test cable length: $0 \mathrm{~m}, 1 \mathrm{~m}, 2 \mathrm{~m}$, or 4 m (Agilent 16047A/B/D/E)
- A "Signal Source Overload" warning does not appear.

When the test signal current exceeds a value in table 11 below, a "Signal Source Overload" warning appears.

Table 11.

| Test signal voltage | Test frequency | Condition ${ }^{1}$ |
| :--- | :--- | :--- |
| $\leq 2$ Vrms | - | - |
| $>2$ Vrms | $\leq 1 \mathrm{MHz}$ | the smaller value of either 110 mA or |
|  |  | $>130 \mathrm{~mA}-0.0015 \times \mathrm{Vac} \times(\mathrm{Fm} / 1 \mathrm{MHz}) \times\left(\mathrm{L} \_\right.$cable +0.5$)$ |
|  |  | $70 \mathrm{~mA}-0.0015 \times \mathrm{Vac} \times(\mathrm{Fm} / 1 \mathrm{MHz}) \times\left(\mathrm{L} \_\right.$cable +0.5$)$ |
|  |  |  |
| Vac $[\mathrm{V}]$ | Test signal voltage |  |
| Fm [Hz] | Test frequency |  |
| L_cable $[\mathrm{m}]$ | Cable length |  |

- OPEN and SHORT corrections have been performed.
- Bias current isolation: Off
- The DC bias current does not exceed a set value within each range of the DC bias current
- The optimum impedance range is selected by matching the impedance of DUT to the effective measuring range.
- Under an AC magnetic field, the following equation is applied to the measurement accuracy.
Ax(1+Bx(2+0.5/Vs))
Where
A: Absolute accuracy
B: Magnetic flux density [Gauss]
Vs: Test signal voltage level [Volts]


## $|Z|,|Y|, L, C, R, X, G$, and $B$ accuracy ( $L, C, X$, and $B$ accuracies apply when $D x \leq 0.1, R$ and $G$ accuracies apply $\mathbf{O x} \leq 0.1$ )

Relative accuracy Ae is given as:
Equation 8. $\quad A e=[A b+Z s /|Z m| \times 100+Y o \times|Z m| \times 100] \times K t$
Zm Impedance of DUT
Ab Basic accuracy
Zs Short offset
Yo Open offset
Kt Temperature coefficient

## D accuracy

D accuracy De is given as

- when $\mathrm{Dx} \leq 0.1$

Equation 9. $D e= \pm A e / 100$
Dx Measured D value
Ae Relative accuracies of $|Z|,|Y|, L, C, R, X, G$, and $B$

1. When the calculation result is a negative value, 0 A is applied.

## $\mathbf{0}$ accuracy (when $\mathbf{0} \times \mathrm{De}<\mathbf{1}$ )

0 accuracy 0 e is given as:
Equation 10. $\quad 0 e= \pm \frac{\left(Q x^{2} \times D e\right)}{(1 \mp Q x \times D e)}$
Qx Measured 0 value
De Relative D accuracy

## $\theta$ accuracy

$\theta$ accuracy $\theta \mathrm{e}$ is given as:
Equation 11. $\quad \theta e=\frac{180 \times A e}{\pi \times 100} \quad$ (deg)
Ae Relative accuracies of $|Z|,|Y|, L, C, R, X, G$, and $B$

## G accuracy (when $\mathbf{D x} \leq 0.1$ )

G accuracy Ge is given as:

Equation 12. $\quad$| $G e$ | $=B x \times D e \quad$ (S) |
| ---: | :--- |
| $B x$ | $=2 \pi f C x=\frac{1}{2 \pi f L x}$ |

| Ge | Relative $G$ accuracy |
| :--- | :--- |
| Dx | Measured D value |
| Bx | Measured B value |
| De | Relative D accuracy |
| f | Test frequency |
| Cx | Measured C value (F) |
| Lx | Measured L value (H) |

## Rp accuracy (when $\mathbf{D x} \leq 0.1$ )

Rp accuracy Rpe is given as:

$$
\text { Equation 13. } \quad R p e= \pm \frac{R p x \times D e}{D x \mp D e}
$$

| Rpe | Relative Rp accuracy |
| :--- | :--- |
| Rpx | Measured Rp value $(\Omega)$ |
| Dx | Measured D value |
| De | Relative D accuracy |

## Rs accuracy (when $\mathbf{D x} \leq 0.1$ )

Rs accuracy Rse is given as:
Equation 14. Rse $=X x \times D e \quad(\Omega)$
$X x=\frac{1}{2 \pi f C x}=2 \pi f L x$

| Rse | Relative Rs accuracy |
| :--- | :--- |
| Dx | Measured $D$ value |
| Xx | Measured $X$ value $(\Omega)$ |
| De | Relative $D$ accuracy |
| $f$ | Test frequency (Hz) |
| Cx | Measured C value (F) |
| Lx | Measured L value (H) |

## Example of C-D accuracy calculation

## Measurement conditions

Test Frequency: 1 kHz
Measured C value: 100 nF
Test signal voltage: 1 Vrms
Measurement time mode: Medium
Measurement temperature: $23^{\circ} \mathrm{C}$
$\mathrm{Ab}=0.05 \%$
$|Z m|=1 /\left(2 \pi \times 1 \times 10^{3} \times 100 \times 10^{-9}\right)=1590 \Omega$
$\mathrm{Zs}=0.6 \mathrm{~m} \Omega \times(1+0.400 / 1) \times(1+\sqrt{(1000 / 1000)}=1.68 \mathrm{~m} \Omega$
Yo $=0.5 \mathrm{nS} \times(1+0.100 / 1) \times(1+\sqrt{(100 / 1000})=0.72 \mathrm{nS}$
$C$ accuracy: $\mathrm{Ae}=[0.05+1.68 \mathrm{~m} / 1590 \times 100+0.72 \mathrm{n} \times 1590 \times 100] \times 1=0.05 \%$
D accuracy: $\mathrm{De}=0.05 / 100=0.0005$

## Basic accuracy

Basic accuracy Ab is given below.
Table 12. Measurement time mode $=$ SHORT

|  | Test signal voltage |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Test <br> frequency [Hz] | $\mathbf{5} \mathbf{~ m V r m s ~ - ~}$ | $\mathbf{5 0} \mathbf{~ m V r m s}$ | $\mathbf{0 . 3}$ Vrms - | $\mathbf{0 . 3}$ Vrms - | $\mathbf{1}$ Vrms - |
| $20-125$ | $(0.6 \%) \times$ | $\mathbf{1 0}$ Vrms - |  |  |  |
|  | $(50 \mathrm{mVrms} / \mathrm{Vs})$ |  | $0.60 \%$ | $\mathbf{1 0}$ Vrms | $\mathbf{2 0}$ Vrms |
| $125-1 \mathrm{M}$ | $(0.2 \%) \times$ | $0.20 \%$ | $0.10 \%$ | $0.30 \%$ |  |
|  | $(50 \mathrm{mVrms} / \mathrm{Vs})$ |  | $0.15 \%$ | $0.15 \%$ |  |
| $1 \mathrm{M}-2 \mathrm{M}$ | $(0.4 \%) \times$ | $0.40 \%$ | $0.20 \%$ | $0.30 \%$ | $0.30 \%$ |
|  | $(50 \mathrm{mVrms} / \mathrm{Vs})$ |  |  |  |  |

Table 13. Measurement time mode = MED, LONG

| Test frequency [Hz] | Test signal voltage |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5 mVrms 50 mVrms | 50 mVrms 0.3 Vrms | $\begin{aligned} & \hline \text { 0.3 Vrms - } \\ & 1 \text { Vrms } \end{aligned}$ | 1 Vrms 10 Vrms | $\begin{aligned} & 10 \text { Vrms - } \\ & 20 \text { Vrms } \end{aligned}$ |
| 20-125 | $\begin{aligned} & \hline(0.25 \%) \times \\ & (30 \mathrm{mVrms} / \mathrm{Vs}) \end{aligned}$ | 0.25\% | 0.10\% | 0.15\% | 0.15\% |
| 125-1 M | $\begin{aligned} & \hline(0.1 \%) \times \\ & (30 \mathrm{mVrms} / \mathrm{Vs}) \end{aligned}$ | 0.10\% | 0.05\% | 0.10\% | 0.15\% |
| 1 M - 2 M | $\begin{array}{\|l} \hline(0.2 \%) \times \\ (30 \mathrm{mVrms} / \mathrm{Vs}) \end{array}$ | 0.20\% | 0.10\% | 0.20\% | 0.30\% |

Vs [Vrms] Test signal voltage

## Effect by impedance of DUT

Table 14. For impedance of DUT below $30 \Omega$, the following value is added.

| Test <br> frequency $[\mathrm{Hz}]$ | Impedance of DUT |  |
| :--- | :--- | :--- |
|  | $\mathbf{1 . 0 8} \Omega \leq\|Z \mathbf{Z x}\|<\mathbf{3 0} \Omega$ | $\|\mathrm{Zx}\|<\mathbf{1 . 0 8} \Omega$ |
| $20-1 \mathrm{M}$ | $0.05 \%$ | $0.10 \%$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | $0.10 \%$ | $0.20 \%$ |

Table 15. For impedance of DUT over $9.2 \mathrm{k} \Omega$, the following value is added.

| est <br> frequency $[\mathrm{Hz}]$ | Impedance of DUT |  |
| :--- | :--- | :--- |
|  | $\mathbf{9 . 2} \mathbf{~} \Omega<\|\mathbf{Z x}\| \leq \mathbf{9 2} \mathbf{k} \Omega$ | $\mathbf{9 2} \mathbf{~} \Omega<\|\mathbf{Z x}\|$ |
| $10 \mathrm{k}-100 \mathrm{k}$ | $0 \%$ | $0.05 \%$ |
| $100 \mathrm{k}-1 \mathrm{M}$ | $0.05 \%$ | $0.05 \%$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | $0.10 \%$ | $0.10 \%$ |

Effect of cable extension
When the cable is extended, the following element is added per one meter.
$0.015 \% \times(\mathrm{Fm} / 1 \mathrm{MHz})^{2} \times\left(\mathrm{L} \_ \text {cable }\right)^{2}$
Fm [Hz] Test Frequency
L_cable [m] Cable length

## Short offset Zs

Table 16. Impedance of DUT $>1.08 \Omega$

| Test <br> frequency $[\mathrm{Hz}]$ | Measurement time mode |  |
| :--- | :--- | :--- |
|  | SHORT | MED, LONG |
| $20-2 \mathrm{M}$ | $2.5 \mathrm{~m} \Omega \times(1+0.400 / \mathrm{Vs}) \times$ | $0.6 \mathrm{~m} \Omega \times(1+0.400 / \mathrm{Vs}) \times$ |
|  | $(1+\sqrt{(1000 / \mathrm{Fm})})$ | $(1+\sqrt{(1000 / \mathrm{Fm})})$ |

Table 17. Impedance of DUT $\leq 1.08 \Omega$

| Test <br> frequency $[\mathrm{Hz}]$ | Measurement time mode |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
|  | SHORT | MED, LONG |  |  |  |
| $20-2 \mathrm{M}$ | $1 \mathrm{~m} \Omega \times(1+1 / \mathrm{Vs}) \times$ | $0.2 \mathrm{~m} \Omega \times(1+1 / \mathrm{Vs}) \times$ |  |  |  |
|  | $(1+\sqrt{(1000 / \mathrm{Fm}))})$ |  |  |  |  |
| Vs $[\mathrm{Vrms}]$ |  |  |  | Test signal voltage <br> $\mathrm{Fm}[\mathrm{Hz}]$ | Test frequency |

## Effect of cable extension (Short offset)

Table 18. When the cable is extended, the following value is added to $\mathbf{Z s}$ (independent of the measurement time mode).

| Test <br> frequency $[\mathrm{Hz}]$ | Cable length |  |  |  |
| :--- | :--- | :---: | :--- | :--- |
|  | $\mathbf{0} \mathbf{m}$ | $\mathbf{1} \mathbf{m}$ | $\mathbf{2} \mathbf{m}$ | $\mathbf{4} \mathbf{m}$ |
| $20-1 \mathrm{M}$ | 0 | $0.25 \mathrm{~m} \Omega$ | $0.5 \mathrm{~m} \Omega$ | $1 \mathrm{~m} \Omega$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | 0 | $1 \mathrm{~m} \Omega$ | $2 \mathrm{~m} \Omega$ | $4 \mathrm{~m} \Omega$ |

## Open offset Yo

Table 19. Test signal voltage $\leq \mathbf{2 . 0}$ Vrms

| Test <br> frequency [Hz] | Measurement time mode |  |
| :--- | :--- | :--- |
|  | SHORT | MED, LONG |
| $20-100 \mathrm{k}$ | $2 \mathrm{nS} \times(1+0.100 / \mathrm{Vs}) \times$ | $0.5 \mathrm{nS} \times(1+0.100 / \mathrm{Vs}) \times$ |
|  | $(1+\sqrt{(100 / \mathrm{Fm})})$ | $(1+\sqrt{(100 / \mathrm{Fm})})$ |
| $100 \mathrm{k}-1 \mathrm{M}$ | $20 \mathrm{nS} \times(1+0.100 / \mathrm{Vs})$ | $5 \mathrm{nS} \times(1+0.100 / \mathrm{Vs})$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | $40 \mathrm{nS} \times(1+0.100 / \mathrm{Vs})$ | $10 \mathrm{nS} \times(1+0.100 / \mathrm{Vs})$ |

Table 20. Test signal voltage > 2.0 Vrms

| Test <br> frequency $[\mathrm{Hz}]$ | Measurement time mode |  |
| :--- | :--- | :--- |
|  | SHORT | MED, LONG |
| $100 \mathrm{kS}-1 \mathrm{M}$ | $(1+\sqrt{(100 / \mathrm{Fm})})$ | $0.5 \mathrm{nS} \times(1+2 / \mathrm{Vs}) \times$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | $20 \mathrm{nS} \times(1+2 / \mathrm{Vs})$ | $(1+\sqrt{(100 / \mathrm{Fm})})$ |


| $\mathrm{Vs}[\mathrm{Vrms}]$ | Test signal voltage |
| :--- | :--- |
| $\mathrm{Fm}[\mathrm{Hz}]$ | Test frequency |

Effect of cable length
Table 21. When the cable is extended, multiply Yo by the following factor.

| Test |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| frequency [Hz] | Cable length |  |  |  |
|  | $\mathbf{0 m}$ | $\mathbf{1 m}$ | $\mathbf{2 m}$ | $\mathbf{4 m}$ |
| $100-100 \mathrm{k}$ | 1 | $1+5 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+10 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+20 \times \mathrm{Fm} / 1 \mathrm{MHz}$ |
| $100 \mathrm{k}-1 \mathrm{M}$ | 1 | $1+0.5 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+1 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+2 \times \mathrm{Fm} / 1 \mathrm{MHz}$ |
| $1 \mathrm{M}-2 \mathrm{M}$ | 1 | $1+1 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+2 \times \mathrm{Fm} / 1 \mathrm{MHz}$ | $1+4 \times \mathrm{Fm} / 1 \mathrm{MHz}$ |

Fm [Hz] Test frequency

## Temperature factor Kt

Table 22. The temperature factor Kt is given below.

| Temperature $\left[{ }^{\circ} \mathbf{C}\right]$ | $\mathbf{K t}$ |
| :--- | :--- |
| $0-18$ | 4 |
| $18-28$ | 1 |
| $28-55$ | 4 |

## Calibration accuracy Acal

Calibration accuracy Acal is given below.
For impedance of DUT on the boundary line, apply the smaller value.
Table 23. Impedance range $=0.1,1,10 \Omega$

|  | Test frequency [ Hz ] |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 20-1k | 1k-10 k | 10 k-100 k | 100 k - 300 k | $300 \mathrm{k}-1 \mathrm{M}$ | 1 M - 2 M |
| \|Z| [\%] | 0.03 | 0.05 | 0.05 | $\begin{aligned} & 0.05+ \\ & 5 \times 10^{-5} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.05+ \\ & 5 \times 10^{-5} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.1+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ |
| $\overline{\theta \text { [radian] }}$ | $1 \times 10^{-4}$ | $2 \times 10^{-4}$ | $3 \times 10^{-4}$ | $\begin{aligned} & 3 \times 10^{-4}+ \\ & 2 \times 10^{-7} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 3 \times 10^{-4}+ \\ & 2 \times 10^{-7} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 6 \times 10^{-4}+ \\ & 4 \times 10^{-7} \mathrm{Fm} \end{aligned}$ |

Table 24. Impedance range $=100 \Omega$

|  | Test frequency [Hz] |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 20-1k | 1 k-10k | 10k-100 k | 100 k - 300 k | 300 k-1 M | 1 M - 2 M |
| \|Z| [\%] | 0.03 | 0.05 | 0.05 | $\begin{aligned} & 0.05+ \\ & 5 \times 10^{-5} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.05+ \\ & 5 \times 10^{-5} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.1+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ |
| $\theta$ [radian] | $1 \times 10^{-4}$ | $2 \times 10^{-4}$ | $3 \times 10^{-4}$ | $3 \times 10^{-4}$ | $3 \times 10^{-4}$ | $6 \times 10^{-4}$ |

Table 25. Impedance range $=300,1 \mathrm{k} \Omega$

|  | Test frequency $[\mathbf{H z}]$ |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | $\mathbf{2 0 - 1} \mathbf{- 1}$ | $\mathbf{1 k - 1 0} \mathbf{~}$ | $\mathbf{1 0} \mathbf{k - 1 0 0} \mathbf{k}$ | $\mathbf{1 0 0} \mathbf{k - 3 0 0} \mathbf{k}$ | $\mathbf{3 0 0} \mathbf{k - 1} \mathbf{~ M}$ | $\mathbf{1} \mathbf{~ M} \mathbf{- 2 ~ M}$ |
| $\|Z\|[\%]$ | 0.03 | 0.03 | 0.05 | 0.05 | 0.05 | 0.1 |
| $\theta[$ radian $]$ | $1 \times 10^{-4}$ | $1 \times 10^{-4}$ | $3 \times 10^{-4}$ | $3 \times 10^{-4}$ | $3 \times 10^{-4}$ | $6 \times 10^{-4}$ |

Table 26. Impedance range $=\mathbf{3 k}, 10 \mathrm{k} \Omega$

|  | Test frequency [ Hz ] |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 20-1k | 1 k-10 k | $10 \mathrm{k}-100 \mathrm{k}$ | 100 k-300 k | 300 k - 1 M | 1 M - 2 M |
| \|Z| [\%] | $\begin{aligned} & 0.03+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.03+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.03+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.03+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.03+ \\ & 1 \times 10^{-4} \mathrm{Fm} \end{aligned}$ | $\begin{aligned} & 0.06+ \\ & 2 \times 10^{-4} \mathrm{Fm} \end{aligned}$ |
| $\bar{\theta}$ [radian] | $\begin{aligned} & 100+ \\ & 2.5 \mathrm{Fm}) \times 10^{-6} \end{aligned}$ | $\left\|\begin{array}{l\|} (100+ \\ 2.5 \mathrm{Fm}) \times 10^{-6} \end{array}\right\|$ | $\begin{aligned} & (100+ \\ & 2.5 \mathrm{Fm}) \times 10^{-6} \end{aligned}$ | $\left\|\begin{array}{\|l\|} \hline 100+ \\ 2.5 \mathrm{Fm}) \times 10^{-6} \end{array}\right\|$ | $\begin{array}{\|l\|} \hline(100+ \\ 2.5 \mathrm{Fm}) \times 10^{-6} \end{array}$ | $\begin{aligned} & (200+ \\ & 5 \mathrm{Fm}) \times 10^{-6} \end{aligned}$ |

Table 27. Impedance range $=\mathbf{3 0} \mathbf{k}, 100 \mathbf{k} \Omega$

|  | Test frequency [Hz] |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | $\mathbf{2 0 - 1} \mathbf{- 1}$ | $\mathbf{1 k - 1 0} \mathbf{k}$ | $\mathbf{1 0} \mathbf{k - 1 0 0} \mathbf{k}$ | $\mathbf{1 0 0} \mathbf{k - 3 0 0} \mathbf{~}$ | $\mathbf{3 0 0} \mathbf{k - 1 ~ M}$ | $\mathbf{1} \mathbf{~ M - 2 ~ M}$ |
| $\|Z\|[\%]$ | $0.03+$ | $0.03+$ | $0.03+$ | $0.03+$ | $0.03+$ | $0.06+$ |
|  | $1 \times 10^{-3} \mathrm{Fm}$ | $1 \times 10^{-3} \mathrm{Fm}$ | $1 \times 10^{-3} \mathrm{Fm}$ | $1 \times 10^{-3} \mathrm{Fm}$ | $1 \times 10^{-4} \mathrm{Fm}$ | $2 \times 10^{-4} \mathrm{Fm}$ |
| $\theta[$ radian] | $(100+$ | $(100+$ | $(100+$ | $(100+$ | $(100+$ | $(200+$ |
|  | $20 \mathrm{Fm}) \times 10^{-6}$ | $20 \mathrm{Fm}) \times 10^{-6}$ | $20 \mathrm{Fm}) \times 10^{-6}$ | $20 \mathrm{Fm}) \times 10^{-6}$ | $2.5 \mathrm{Fm}) \times 10^{-6}$ | $5 \mathrm{Fm}) \times 10^{-6}$ |

Fm[kHz] Test frequency


Figure 1. Impedance measurement accuracy (Test signal voltage $=1 \mathrm{Vrms}$, cable length=0 m, measurement time mode $=$ MED)

## Note

A parameter selected for one of the two parameters cannot be selected for the other parameter. It is not possible to set up a combination of test signal voltage and test signal current or one of test signal voltage of DC bias signal and test signal current of DC bias.

The secondary parameter can be set only with SCPI commands.

## Compensation function

Table 28. The E4980A provides three types of compensation functions: OPEN compensation, SHORT compensation, and LOAD compensation.

| Type of compensation | Description |
| :--- | :--- |
| OPEN compensation | Compensates errors caused by the stray admittance (C, G) <br> of the test fixture. |
| SHORT compensation | Compensates errors caused by the residual impedance (L, R) <br> of the test fixture. |
| LOAD compensation | Compensates errors between the actual measured value <br> and a known standard value under the measurement conditions <br> desired by the user. |

## List sweep

Points: There is a maximum of 201 points.
First sweep parameter (primary parameter): Test frequency, test signal voltage, test signal current, test signal voltage of DC bias signal, test signal current of DC bias signal, DC source voltage.

Second sweep parameter (secondary parameter): None, impedance range, test frequency, test signal voltage, test signal current, test signal voltage of DC bias signal, test signal current of DC bias signal, DC source voltage

## Trigger mode

Sequential mode: When the E4980A is triggered once, the device is measured at all sweep points. /EOM/INDEX is output only once.

Step mode: The sweep point is incremented each time the E4980A is triggered. /EOM/INDEX is output at each point, but the result of the comparator function of the list sweep is available only after the last /EOM is output.

## Note

The following USB memory can be used. Complies with USB 1.1; mass storage class, FAT16/FAT32 format; maximum consumption current is below 500 mA .

Recommended USB memory: 64MB USB Flash memory (Agilent PN 1818-8989).

Use the recommended USB memory device exclusively for the E4980A, otherwise, previously saved data may be cleared. If you use a USB memory other than the recommended device, data may not be saved or recalled normally.

Agilent Technologies will NOT be responsible for data loss in the USB memory caused by using the E4980A.

Comparator function of list sweep: The comparator function enables setting one pair of lower and upper limits for each measurement point.

You can select from: Judge with the first sweep parameter/Judge with the second parameter/Not used for each pair of limits.

Time stamp function: In the sequential mode, it is possible to record the measurement starting time at each measurement point by defining the time when FW detects a trigger as 0 and obtain it later with the SCPI command.

## Comparator function

Bin sort: The primary parameter can be sorted into 9 BINs, OUT_OF_BINS, AUX_BIN, and LOW_C_REJECT. The secondary parameter can be sorted into HIGH, IN, and LOW. The sequential mode and tolerance mode can be selected as the sorting mode.

Limit setup: Absolute value, deviation value, and \% deviation value can be used for setup.

BIN count: Countable from 0 to 999999.

## DC bias signal

Table 29. Test signal voltage

| Range | 0 V to +2 V |
| :--- | :--- |
| Resolution | $0 \mathrm{~V} / 1.5 \mathrm{~V} / 2 \mathrm{~V}$ only |
| Accuracy | $0.1 \%+2 \mathrm{mV}\left(23{ }^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}\right)$ |
|  | $(0.1 \%+2 \mathrm{mV}) \times 4$ |
|  | $\left(0\right.$ to $18^{\circ} \mathrm{C}$ or 28 to $\left.55^{\circ} \mathrm{C}\right)$ |

Output impedance: $100 \Omega$ (nominal)

## Measurement assistance functions

Data buffer function: Up to 201 measurement results can be read out in a batch.

## Save/Recall function:

- Up to 10 setup conditions can be written to/read from the built-in non-volatile memory.
- Up to 10 setup conditions can be written to/read from the USB memory.
- Auto recall function can be performed when the setting conditions are written to Register 10 of the USB memory.

Key lock function: The front panel keys can be locked.
GPIB: 24-pin D-Sub (Type D-24), female; complies with IEEE488.1, 2 and SCPI.
USB host port: Universal serial bus jack, type-A (4 contact positions, contact 1 is on your left), female (for connection to USB memory only).
USB interface port: Universal serial bus jack, type mini-B (4 contact positions); complies with USBTMC-USB488 and USB 2.0; female; for connection to the external controller.

USBTMC: Abbreviation for USB Test \& Measurement Class
LAN: 10/100 BaseT Ethernet, 8 pins (two speed options)
LXI Compliance: Class C (only applies to units with firmware revision A.02.00 or later)

## Options

## Note <br> Option xxx is described as E4980A-xxx in the order information

The following options are available for the E4980A LCR Meter.

## Option 001 (Power and DC bias enhancement)

Increases test signal voltage and adds the variable DC bias voltage function.

## Measurement parameters

The following parameters can be used.

- Lp-Rdc
- Ls-Rdc
- Vdc-Idc
where
Rdc Direct-current resistance (DCR)
Vdc Direct-current voltage
Idc Direct-current electricity


## Test signal

## Signal level

Table 30. Test signal voltage

| Range |  | 0 Vrms to 20 Vrms (test frequency $\leq 1 \mathrm{MHz}$ ) |
| :---: | :---: | :---: |
|  |  | 0 Vrms to 15 Vrms (test frequency $>1 \mathrm{MHz}$ ) |
| Resolution |  | $100 \mu \mathrm{Vrms}$ ( 0 Vrms - 0.2 Vrms ) |
|  |  | $200 \mu \mathrm{Vrms}$ (0.2 Vrms - 0.5 Vrms ) |
|  |  | $500 \mu \mathrm{Vrms}$ (0.5 Vrms - 1 Vrms) |
|  |  | 1 mVrms (1 Vrms - 2 Vrms) |
|  |  | 2 mVrms (2Vrms - 5 Vrms) |
|  |  | 5 mVrms (5Vrms - 10 Vrms ) |
|  |  | 10 mVrms (10 Vrms - 20 Vrms ) |
| Setup accuracy | normal | $\begin{aligned} & \pm(10 \%+1 \mathrm{mVrms}) \text { (test signal voltage } \leq 2 \mathrm{Vrms} \text { ) } \\ & \text { (test frequency } \leq 1 \mathrm{MHz}: \text { spec., test frequency }>1 \mathrm{MHz}: \text { typ.) } \end{aligned}$ |
|  |  | $\pm(10 \%+10 \mathrm{mVrms})$ (Test frequency $\leq 300 \mathrm{kHz}$, test signal voltage $>2 \mathrm{Vrms}$ ) (spec.) |
|  |  | ```\pm(15% + 20 mVrms) (test frequency > 300 kHz, test signal voltage > 2 Vrms) (test frequency }\leq1\textrm{MHz}: spec. test frequency > 1 MHz : typ.)``` |
|  | Constant ${ }^{1}$ | $\begin{aligned} & \pm(6 \%+1 \mathrm{mVrms}) \text { (test signal voltage } \leq 2 \mathrm{Vrms} \text { ) } \\ & \text { (test frequency } \leq 1 \mathrm{MHz} \text { : spec. , test frequency }>1 \mathrm{MHz} \text { : typ.) } \end{aligned}$ |
|  |  | $\begin{aligned} & \pm(6 \%+10 \mathrm{mVrms})(\text { test frequency } \leq 300 \mathrm{kHz} \\ & \text { test signal voltage }>2 \mathrm{Vrms}) \text { (spec.) } \end{aligned}$ |
|  |  | ```\pm(12% + 20 mVrms) (test frequency > 300 kHz, test signal voltage > 2 Vrms) (test frequency }\leq1\textrm{MHz}: spec. test frequency > 1 MHz : typ.)``` |

Table 31. Test signal current

| Range |  | 0 Arms - 100 mArms |
| :---: | :---: | :---: |
| Resolution |  | $1 \mu$ Arms (0 Arms - 2 mArms ) |
|  |  | $2 \mu \mathrm{Arms}$ ( $2 \mathrm{mArms}-5 \mathrm{mArms}$ ) |
|  |  | $5 \mu \mathrm{Arms}$ ( $5 \mathrm{mArms}-10 \mathrm{mArms}$ ) |
|  |  | $10 \mu \mathrm{Arms} \mathrm{( } 10 \mathrm{mArms}-20 \mathrm{mArms}$ ) |
|  |  | $20 \mu \mathrm{Arms} \mathrm{( } 20 \mathrm{mArms}$ - 50 mArms ) |
|  |  | $50 \mu \mathrm{Arms}$ ( 50 mArms - 100 mArms ) |
| Setup accuracy | normal | $\pm(10 \%+10 \mu \mathrm{Arms})$ (test signal voltage $\leq 20 \mathrm{mArms}$ ) <br> (test frequency $\leq 1 \mathrm{MHz}$ : spec., test frequency $>1 \mathrm{MHz}$ : typ.) |
|  |  | $\pm(10 \%+100 \mu \mathrm{Arms})$ (test frequency $\leq 300 \mathrm{kHz}$, test signal current > 20 mArms ) (spec.) |
|  |  | ```\pm(15% + 200 \muArms) (test frequency > 300 kHz, test signal voltage > 20 mArms) (test frequency }\leq1\textrm{MHz}: spec. test frequency > 1 MHz : typ.)``` |
|  | Constant ${ }^{1}$ | $\begin{aligned} & \pm(6 \%+10 \mu \mathrm{Arms}) \text { (test signal voltage } \leq 20 \mathrm{mArms} \text { ) } \\ & \text { (test frequency } \leq 1 \mathrm{MHz}: \text { spec. , test frequency }>1 \mathrm{MHz}: \text { typ.) } \end{aligned}$ |
|  |  | $\pm(6 \%+100 \mu \mathrm{Arms})$ (test frequency $\leq 300 \mathrm{kHz}$, test signal voltage $>20 \mathrm{mArms}$ ) (spec.) |
|  |  | ```\pm(12% + 200 \muArms) (test frequency > 300 kHz, test signal voltage > 20 mArms) (test frequency \leq 1 MHz : spec., test frequency > 1 MHz : typ.)``` |

## Test signal level monitor function

- Test signal voltage and test signal current can be monitored.
- Level monitor accuracy:

Table 32. Test signal voltage monitor accuracy (Vac)

| Test signal voltage $^{2}$ | Test frequency | Specification |
| :--- | :--- | :--- |
| 5 mVrms to 2 Vrms | $\leq 1 \mathrm{MHz}$ | $\pm(3 \%$ of reading value $+0.5 \mathrm{mVrms})$ |
|  | $>1 \mathrm{MHz}$ | $\pm(6 \%$ of reading value $+1 \mathrm{mVrms})$ |
| $>2 \mathrm{Vrms}$ | $\leq 300 \mathrm{kHz}$ | $\pm(3 \%$ of reading value $+5 \mathrm{mVrms})$ |
|  | $>300 \mathrm{kHz}$ | $\pm(6 \% \text { of reading value }+10 \mathrm{mVrms})^{3}$ |

Table 33. Test signal current monitor accuracy (lac)

| Test signal current ${ }^{2}$ | Test frequency | Specification |
| :--- | :--- | :--- |
| $50 \mu \mathrm{Arms}$ to 20 mArms | $\leq 1 \mathrm{MHz}$ | $\pm(3 \%$ of reading value $+5 \mu \mathrm{Arms})$ |
|  | $>1 \mathrm{MHz}$ | $\pm(6 \%$ of reading value $+10 \mu \mathrm{Arms})$ |
| $>20 \mathrm{mArms}$ | $\leq 300 \mathrm{kHz}$ | $\pm(3 \%$ of reading value $+50 \mu \mathrm{Arms})$ |
|  | $>300 \mathrm{kHz}$ | $\pm(6 \%$ of reading value $+100 \mu \mathrm{Arms})$ |

[^1]
## DC bias signal

Table 34. Test signal voltage

| Range |  | -40 V to +40 V |
| :---: | :---: | :---: |
| Resolution |  | Setup resolution: $100 \mu \mathrm{~V}$, effective |
|  |  | resolution: $330 \mu \mathrm{~V} \pm(0 \mathrm{~V}-5 \mathrm{~V})$ |
|  |  | $1 \mathrm{mV} \pm(5 \mathrm{~V}-10 \mathrm{~V})$ |
|  |  | $2 \mathrm{mV} \pm(10 \mathrm{~V}-20 \mathrm{~V})$ |
|  |  | $5 \mathrm{mV} \pm(20 \mathrm{~V}-40 \mathrm{~V})$ |
| Accuracy | test signal voltage $\leq 2 \mathrm{Vrms}$ | $0.1 \%+2 \mathrm{mV}\left(23{ }^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}\right)$ |
|  |  | $(0.1 \%+2 \mathrm{mV}) \times 4$ |
|  |  | (0 to $18{ }^{\circ} \mathrm{C}$ or 28 to $55^{\circ} \mathrm{C}$ ) |
|  | test signal voltage > 2 Vrms | 0.1 \% + $4 \mathrm{mV}\left(23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}\right)$ |
|  |  | $(0.1 \%+4 \mathrm{mV}) \times 4$ |
|  |  | (0 to $18{ }^{\circ} \mathrm{C}$ or 28 to $55^{\circ} \mathrm{C}$ ) |

Table 35. Test signal current

| Range | $-100 \mathrm{~mA}-100 \mathrm{~mA}$ |
| :--- | :--- |
| Resolution | Setup resolution: $1 \mu \mathrm{~A}$, effective |
|  | resolution: $3.3 \mu \mathrm{~A} \pm(0 \mathrm{~A}-50 \mathrm{~mA})$ |
|  | $10 \mu \mathrm{~A} \pm(50 \mathrm{~mA}-100 \mathrm{~mA})$ |

## DC bias voltage level monitor Vdc

( $0.5 \%$ of reading value +60 mV ) $\times \mathrm{Kt}$
When using Vdc-Idc measurement: (spec.)
When using level monitor: (typ.)
Kt Temperature coefficient

## DC bias current level monitor Idc

(A [\%] of the measurement value $+\mathrm{B}[\mathrm{A}]) \times \mathrm{Kt}$
When using Vdc-Idc measurement: (spec.)
When using level monitor: (typ.)
A [\%] When the measurement time mode is SHORT: 2\% When the measurement time mode is MED or LONG: $1 \%$
$B[A]$ given below
Kt Temperature coefficient
When the measurement mode is SHORT, double the following value.

Table 36. Test signal voltage $\leq 0.2$ Vrms (measurement time mode $=$ MED, LONG)

| DC bias <br> current range | $<\mathbf{5}$ |  |  |  |  |
| :--- | :---: | :--- | :--- | :--- | :--- |
|  | $<\mathbf{1 0 0}$ | $\mathbf{1 0 0}$ | $\mathbf{3 0 0 , 1} \mathbf{k}$ | $\mathbf{3 k}, \mathbf{1 0} \mathbf{k}$ | $\mathbf{3 0 k}, \mathbf{1 0 0} \mathbf{k}$ |
| $20 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA | 45 nA |
| $200 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA | 300 nA |
| 2 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ |
| 20 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ |
| 100 mA | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ |

Table 37. 0.2 Vrms < test signal voltage $\leq 2$ Vrms
(measurement time mode = MED, LONG)

| DC bias <br> current range | $<\mathbf{y y y y y}$ |  |  |  |  |
| :--- | :---: | :--- | :--- | :--- | :--- |
|  | $<\mathbf{1 0 0}$ | $\mathbf{1 0 0}, \mathbf{3 0 0}$ | $\mathbf{1 k}, \mathbf{3 k}$ | $\mathbf{1 0 k}, \mathbf{3 0} \mathbf{k}$ | $\mathbf{1 0 0} \mathbf{k}$ |
| $20 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA | 45 nA |
| $200 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA | 300 nA |
| 2 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ |
| 20 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ |
| 100 mA | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ |

Table 38. Test signal voltage $\mathbf{>} \mathbf{2}$ Vrms (measurement time mode $=$ MED, LONG)

| DC bias current range | Impedance range [ $\Omega$ ] |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\leq 300$ | $1 \mathrm{k}, 3 \mathrm{k}$ | 10k, 30 k | 100 k |
| $20 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA |
| $200 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | 300 nA |
| 2 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ | $3 \mu \mathrm{~A}$ |
| 20 mA | $150 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ | $30 \mu \mathrm{~A}$ |
| 100 mA | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ | $150 \mu \mathrm{~A}$ |

Table 39. Input impedance (nominal)

| Input <br> impedance | Conditions |
| :--- | :--- |
| $0 \Omega$ | Other than conditions below. |
| $2 \Omega$ | Test signal voltage $\leq 0.2 \mathrm{Vrms}$, Impedance range $\geq 3 \mathrm{k} \Omega$, |
|  | DC bias current range $\leq 200 \mu \mathrm{~A}$ |
|  | Test signal voltage $\leq 2 \mathrm{Vrms}$, Impedance range $\geq 10 \mathrm{k} \Omega$, |
|  | DC bias current range $\leq 200 \mu \mathrm{~A}$ |
|  | Test signal voltage $>2 \mathrm{Vrms}$, Impedance range $=100 \mathrm{k} \Omega$, |
|  | DC bias current range $\leq 200 \mu \mathrm{~A}$ |

## DC source signal

Table 40. Test signal voltage

| Range | -10 V to 10 V |
| :--- | :--- |
| Resolution | 1 mV |
| Accuracy | $0.1 \%+3 \mathrm{mV}\left(23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}\right)$ |
|  | $(0.1 \%+3 \mathrm{mV}) \times 4$ |
|  | $\left(0\right.$ to $18{ }^{\circ} \mathrm{C}$ or 28 to $\left.55^{\circ} \mathrm{C}\right)$ |

Table 41. Test signal current
Range $\quad-45 \mathrm{~mA}$ to 45 mA (nominal)

## Output impedance

$100 \Omega$ (nominal)

## DC resistance (Rdc) accuracy

## Absolute measurement accuracy Aa

Absolute measurement accuracy $A$ a is given as
Equation 15. Aa $A e+$ Acal

Aa Absolute accuracy (\% of reading value)
Ae Relative accuracy (\% of reading value)
Acal Calibration accuracy

## Relative measurement accuracy $\mathbf{A e}$

Relative measurement accuracy Ae is given as
Equation 16. $A e=[A b+(R s /|R m|+G o \times|R m|) \times 100] \times K t$
Rm Measurement value
Ab Basic accuracy
Rs Short offset $[\Omega]$
Go Open offset [S]
Kt Temperature coefficient

## Calibration accuracy Acal

Calibration accuracy Acal is $0.03 \%$.

## Basic accuracy Ab

Table 42. Basic accuracy Ab is given below.

| Measurement <br> time mode | Test signal voltage |  |
| :--- | :---: | :---: |
|  | $\leq \mathbf{2}$ Vrms | $>\mathbf{2}$ Vrms |
| SHORT | $1.00 \%$ | $2.00 \%$ |
| MED | $0.30 \%$ | $0.60 \%$ |

## Open offset Go

Table 43. Open offset Go is given below.

| Measurement <br> time mode | Test signal voltage |  |
| :--- | :---: | :---: |
|  | $\leq \mathbf{2}$ Vrms | $>\mathbf{2}$ Vrms |
| SHORT | 50 nS | 500 nS |
| MED | 10 nS | 100 nS |

## Short offset Rs

Table 44. Short offset Rs is given below.

| Measurement <br> time mode | Test signal voltage |  |
| :--- | :---: | :---: |
|  | $\leq \mathbf{2}$ Vrms | $>\mathbf{2}$ Vrms |
| SHORT | $25 \mathrm{~m} \Omega$ | $250 \mathrm{~m} \Omega$ |
| MED | $5 \mathrm{~m} \Omega$ | $50 \mathrm{~m} \Omega$ |

## Effect of cable length (Short offset)

Table 45. The following value is added to Rs when the cable is extended.

| Cable length |  |  |
| :--- | :--- | :--- |
| $\mathbf{1 m}$ | $\mathbf{2 m}$ | $\mathbf{4 m}$ |
| $0.25 \mathrm{~m} \Omega$ | $0.5 \mathrm{~m} \Omega$ | $1 \mathrm{~m} \Omega$ |

## Temperature coefficient Kt

Table 46. Temperature coefficient Kt is given below.

| Temperature $\left[{ }^{\circ} \mathbf{C}\right]$ | $\mathbf{K t}$ |
| :--- | :--- |
| $0-18$ | 4 |
| $18-28$ | 1 |
| $28-55$ | 4 |

## Other options

Option 002 (Bias current interface): Adds a digital interface to allow the E4980A LCR meter to control the Agilent 42841A bias current source.

Option 005 (Entry model): Economy option with less measurement speed. Same measurement accuracy as the standard model.

Option 007 (Standard model): Upgrade to the standard model.
Option 201 (Handler interface): Adds handler interface.
Option 301 (Scanner interface): Adds scanner interface.

Table 47. Power source

| Voltage | $90 \mathrm{VAC}-264 \mathrm{VAC}$ |
| :--- | :--- |
| Frequency | $47 \mathrm{~Hz}-63 \mathrm{~Hz}$ |
| Power consumption | Max. 150 VA |

Table 48. Operating environment

| Temperature | $0-55^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Humidity <br> $\left(\leq 40^{\circ} \mathrm{C}\right.$, no condensation) | $15 \%-85 \% \mathrm{RH}$ |
| Altitude | $0 \mathrm{~m}-2000 \mathrm{~m}$ |

Table 49. Storage environment

| Temperature | $-20-70^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Humidity <br> $\left(\leq 60^{\circ} \mathrm{C}\right.$, no condensation $)$ | $0 \%-90 \% \mathrm{RH}$ |
| Altitude | $0 \mathrm{~m}-4572 \mathrm{~m}$ |

Outer dimensions: 375 (width) $\times 105$ (height) $\times 390$ (depth) mm (nominal)


Figure 2. Dimensions (front view, with handle and bumper, in millimeters, nominal)


Figure 3. Dimensions (front view, without handle and bumper, in millimeters, nominal)


Figure 4. Dimensions (rear view, with handle and bumper, in millimeters, nominal)


Figure 5. Dimensions (front view, without handle and bumper, in millimeters, nominal)


Figure 6. Dimensions (side view, with handle and bumper, in millimeters, nominal )


## Note

Effective pixels are more than $99.99 \%$. There may be $0.01 \%$ (approx. 7 pixels) or smaller missing pixels or constantly lit pixels, but this is not a malfunction.

Figure 7. Dimensions (side view, without handle and bumper, in millimeters, nominal)
Weight: 5.3 kg (nominal)
Display: LCD, $320 \times 240$ (pixels), RGB color

## The following items can be displayed:

- measurement value
- measurement conditions
- limit value and judgment result of comparator
- list sweep table
- self-test message

| Description | Supplemental Information |
| :---: | :---: |
| EMC |  |
|  | European Council Directive 89/336/EEC, 92/31/EEC, 93/68/EEC <br> IEC 61326-1:1997 +A1:1998 +A2:2000 <br> EN 61326-1:1997 +A1:1998 +A2:2001 <br> CISPR 11:1997 +A1:1999 +A2:2002 <br> EN 55011:1998 +A1:1999 +A2:2002 Group 1, Class A <br> IEC 61000-4-2:1995 +A1:1998 +A2:2001 <br> EN 61000-4-2:1995 +A1:1998 +A2:2001 $4 \mathrm{kV} \mathrm{CD} / 8 \mathrm{kV}$ AD <br> IEC 61000-4-3:1995 +A1:1998 +A2:2001 <br> EN 61000-4-3:1996 +A1:1998 +A2:2001 3 V/m, 80-1000 MHz, 80\% AM <br> IEC 61000-4-4:1995 +A1:2001 +A2:2001 <br> EN 61000-4-4:1995 +A1:2001 +A2:2001 1 kV power / 0.5 kV Signal <br> IEC 61000-4-5:1995 +A1:2001 <br> EN 61000-4-5:1995 +A1:2001 0.5 kV Normal/1 kV Common <br> IEC 61000-4-6:1996 +A1:2001 <br> EN 61000-4-6:1996 +A1:2001 3 V, 0.15-80 MHz, 80\% AM <br> IEC 61000-4-11:1994 +A1:2001 <br> EN 61000-4-11:1994 +A1:2001 100\% 1cycle |
| ICES/NMB-001 | This ISM device complies with Canadian ICES-001:1998. Cet appareil ISM est conforme a la norme NMB-001 du Canada. |
| ( N10149 | AS/NZS 2064.1 Group 1, Class A |

## Safety

| ISM 1-A | European Council Directive 73/23/EEC, 93/68/EEC <br> IEC 61010-1:2001/EN 61010-1:2001 <br> Measurement Category I, Pollution Degree 2, Indoor Use <br> IEC60825-1:1994 Class 1 LED |
| :--- | :--- |
| LR95111C | CAN/CSA C22.2 61010-1-04 <br> Measurement Category I, Pollution Degree 2, Indoor Use |

## Environment

This product complies with the WEEE Directive (2002/96/EC)
marking requirements. The affixed label indicates that you must
not discard this electrical/electronic product in domestic house
hold waste.
Product Category: With reference to the equipment types in the
WEEE Directive Annex I, this product is classed as a "Monitoring
and Control instrumentation" product.

## Supplemental Information

## Note

Discharge capacitors before connecting them to the UNKNOWN terminal or a test fixture to avoid damages to the instrument.

## Settling time

Table 50. Test frequency setting time

| est frequency setting time | Test frequency (Fm) |
| :--- | :--- |
| 5 ms | $\mathrm{Fm} \geq 1 \mathrm{kHz}$ |
| 12 ms | $1 \mathrm{kHz}>\mathrm{Fm} \geq 250 \mathrm{~Hz}$ |
| 22 ms | $250 \mathrm{~Hz}>\mathrm{Fm} \geq 60 \mathrm{~Hz}$ |
| 42 ms | $60 \mathrm{~Hz}>\mathrm{Fm}$ |

Table 51. Test signal voltage setting time

| Test signal voltage setting time | Test frequency (Fm) |
| :--- | :--- |
| 11 ms | $\mathrm{Fm} \geq 1 \mathrm{kHz}$ |
| 18 ms | $1 \mathrm{kHz}>\mathrm{Fm} \geq 250 \mathrm{~Hz}$ |
| 26 ms | $250 \mathrm{~Hz}>\mathrm{Fm} \geq 60 \mathrm{~Hz}$ |
| 48 ms | $60 \mathrm{~Hz}>\mathrm{Fm}$ |

Switching of the impedance range is as follows:
$\leq 5 \mathrm{~ms} /$ range switching

## Measurement circuit protection

The maximum discharge withstand voltage, where the internal circuit remains protected if a charged capacitor is connected to the UNKNOWN terminal, is given below.

Table 52. Maximum discharge withstand voltage

| Maximum discharge withstand voltage | Range of capacitance value C of DUT |
| :--- | :--- |
| 1000 V | $\mathrm{C}<2 \mu \mathrm{~F}$ |
| $\sqrt{2 / \mathrm{C}} \mathrm{V}$ | $2 \mu \mathrm{~F} \leq \mathrm{C}$ |



Figure 8. Maximum discharge withstand voltage

## Measurement time

## Definition

This is the time between the trigger and the end of measurement (EOM) output on the handler interface.

## Conditions

Table 53 shows the measurement time when the following conditions are satisfied:

- Normal impedance measurement other than Ls-Rdc, Lp-Rdc, Vdc-Idc
- Impedance range mode: hold range mode
- DC bias voltage level monitor: OFF
- DC bias current level monitor: OFF
- Trigger delay: 0 s
- Step delay: 0 s
- Calibration data: OFF
- Display mode: blank

Table 53. Measurement time [ms](DC bias:OFF)

|  | $\begin{array}{l}\text { Measurement } \\ \text { time mode }\end{array}$ | Test frequency |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |$]$



Figure 9. Measurement time (DC bias: OFF)

Table 54. Measurement time when option 005 is installed [ms] (DC bias: OFF)

|  | Measurement <br> time mode | Test frequency |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | $\mathbf{2 0 ~ H z}$ | $\mathbf{1 0 0} \mathbf{~ H z}$ | $\mathbf{1 ~ k H z}$ | $\mathbf{1 0} \mathbf{~ k H z}$ | $\mathbf{1 0 0} \mathbf{~ k H z}$ | $\mathbf{1 ~ M H z}$ | $\mathbf{2 ~ M H z}$ |
| 1 | LONG | 1190 | 650 | 590 | 580 | 570 | 570 | 570 |
| 2 | MED | 1150 | 380 | 200 | 180 | 180 | 180 | 180 |
| 3 | SHORT | 1040 | 240 | 37 | 25 | 23 | 23 | 23 |



Figure 10. Measurement time (DC bias: OFF, Option 005)
When DC bias is $O N$, the following time is added:
Table 55. Additional time when DC bias is ON [ms]
Test frequency

| $\mathbf{2 0 ~ H z}$ | $\mathbf{1 0 0 ~ H z}$ | $\mathbf{1 ~ k H z}$ | $\mathbf{1 0} \mathbf{~ k H z}$ | $\mathbf{1 0 0} \mathbf{~ k H z}$ | $\mathbf{1 ~ M H z}$ | $\mathbf{2 ~ M H z}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 30 | 30 | 10 | 13 | 2 | 0.5 | 0.5 |

When the number of averaging increases, the measurement time is given as

Equation 17. MeasTime $+($ Ave -1$) \times$ AveTime

| MeasTime | Measurement time calculated based on Table 53 and Table 54 |
| :--- | :--- |
| Ave | Number of averaging |
| AveTime | Refer to Table 56 |

Table 56. Additional time per averaging [ms]

| Measurement <br> time mode | Test frequency |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Table 57. Measurement time when Vdc-Idc is selected [ms]

|  | Test frequency |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Measurement time mode | $\mathbf{2 0 ~ H z}$ | $\mathbf{1 0 0} \mathbf{~ H z}$ | $\mathbf{1} \mathbf{~ k H z}$ | $\mathbf{1 0} \mathbf{~ H z}$ | $\mathbf{1 0 0} \mathbf{~ H z z}$ | $\mathbf{1} \mathbf{~ M H z}$ | $\mathbf{2 ~ M H z}$ |
| SHORT | 210 | 46 | 14 | 14 | 14 | 14 | 14 |
| MED | 210 | 170 | 170 | 170 | 170 | 170 | 170 |
| LONG | 410 | 410 | 410 | 410 | 410 | 410 | 410 |

Add the same measurement time per 1 additional average
Additional Measurement time when the Vdc and Idc monitor function is ON.
Add SHORT mode of Table 57. When using only Vdc or Idc, add a half of SHORT mode of Table 57.

Table 58. Measurement time when Ls-Rdc or Lp-Rdc is selected [ms]

|  | Test frequency |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: |
| Measurement time mode | $\mathbf{2 0 ~ H z}$ | $\mathbf{1 0 0} \mathbf{~ H z}$ | $\mathbf{1 ~ k H z}$ | $\mathbf{1 0} \mathbf{~ k H z}$ | $\mathbf{1 0 0} \mathbf{~ k H z}$ | $\mathbf{1 ~ M H z}$ | $\mathbf{2 ~ M H z}$ |
| SHORT | 910 | 230 | 43 | 24 | 22 | 22 | 22 |
| MED | 1100 | 450 | 300 | 280 | 270 | 270 | 270 |
| LONG | 1400 | 820 | 700 | 670 | 660 | 650 | 650 |

Add the three times of measurement time per 1 additional average number

## Display time

Except for the case of the DISPLAY BLANK page, the time required to update the display on each page (display time) is as follows. When a screen is changed, drawing time and switching time are added. The measurement display is updated about every 100 ms .

Table 59. Display time

| Item | When Vdc, Idc <br> monitor is 0FF | When Vdc, Idc <br> monitor is ON |
| :--- | :--- | :--- |
| MEAS DISPLAY page drawing time | 10 ms | 13 ms |
| MEAS DISPLAY page (large) drawing time | 10 ms | 13 ms |
| BIN No. DISPLAY page drawing time | 10 ms | 13 ms |
| BIN COUNT DISPLAY page drawing time | 10 ms | 13 ms |
| LIST SWEEP DISPLAY page drawing time | 40 ms | - |
| Measurement display switching time | 35 ms | - |

## Measurement data transfer time

This table shows the measurement data transfer time under the following conditions. The measurement data transfer time varies depending on measurement conditions and computers.

Table 60. Measurement transfer time under the following conditions:

| Host computer: | DELL OPTIPLEX GX260 Pentium 42.6 GHz |
| :--- | :--- |
| Display: | ON |
| Impedance range mode: | AUTO (The overload has not been generated.) |
| OPEN/SHORT/LOAD compensation: | OFF |
| Test signal voltage monitor: | OFF |

Table 61. Measurement data transfer time [ms]

| Interface | Data transfer format | using :FETC? command (one point measurement) |  | using data buffer memory <br> (list sweep measurement) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Comparator ON | Comparator OFF | $\begin{gathered} 10 \\ \text { points } \end{gathered}$ | $\begin{gathered} 51 \\ \text { points } \end{gathered}$ | $\begin{gathered} 128 \\ \text { points } \end{gathered}$ | $\begin{gathered} 201 \\ \text { points } \end{gathered}$ |
| GPIB | ASCII | 2 | 2 | 4 | 13 | 28 | 43 |
|  | ASCII Long | 2 | 2 | 5 | 15 | 34 | 53 |
|  | Binary | 2 | 2 | 4 | 10 | 21 | 32 |
| USB | ASCII | 2 | 2 | 3 | 8 | 16 | 23 |
|  | ASCII Long | 2 | 2 | 4 | 9 | 19 | 28 |
|  | Binary | 2 | 2 | 3 | 5 | 9 | 13 |
| LAN | ASCII | 3 | 4 | 5 | 12 | 24 | 36 |
|  | ASCII Long | 3 | 3 | 5 | 13 | 29 | 44 |
|  | Binary | 3 | 3 | 5 | 9 | 18 | 26 |

DC bias test signal current (1.5 V/2.0 V): Output current: Max. 20 mA
Option 001 (Power and DC Bias enhance):
DC bias voltage: DC bias voltage applied to DUT is given as:
Equation 18. $\quad V d u t=V b-100 \times \mathrm{lb}$
Vdut [V] DC bias voltage
Vb [V] DC bias setting voltage
lb [A] DC bias current

DC bias current: DC bias current applied to DUT is given as:
Equation 19.

$$
\text { Idut }=\text { Vb/(100 + Rdc) }
$$

Idut [A] DC bias current
Vb [V] DC bias setting current
Rdc [ $\Omega$ ] DUT's DC resistance

## Maximum DC bias current

Table 62. Maximum DC bias current when the normal measurement can be performed.

| Impedance range [ $\Omega$ ] | Bias current isolation |  |  |
| :---: | :---: | :---: | :---: |
|  | ON | OFF |  |
|  |  | Test signal voltage $\leq 2$ Vrms | Test signal voltage > $\mathbf{2}$ Vrms |
| 0.1 | Auto range | 20 mA | 100 mA |
| 1 | mode: 100 mA | 20 mA | 100 mA |
| 10 |  | 20 mA | 100 mA |
| 100 | its values for | 20 mA | 100 mA |
| 300 | the range. | 2 mA | 100 mA |
| 1k |  | 2 mA | 20 mA |
| 3 k |  | $200 \mu \mathrm{~A}$ | 20 mA |
| 10 k |  | $200 \mu \mathrm{~A}$ | 2 mA |
| 30 k |  | $20 \mu \mathrm{~A}$ | 2 mA |
| 100 k |  | $20 \mu \mathrm{~A}$ | $200 \mu \mathrm{~A}$ |

## When DC bias is applied to DUT

When DC bias is applied to the DUT, add the following value to the absolute accuracy Ab .

Table 63. Only when Fm < 10 kHz and |Vdc|>5 V

| SHORT | MED, LONG |  |
| :--- | :--- | :--- |
| $0.05 \% \times(100 \mathrm{mV} / \mathrm{Vs}) \times(1+\sqrt{(100 / \mathrm{Fm})})$ | $0.01 \% \times(100 \mathrm{mV} / \mathrm{Vs}) \times(1+\sqrt{(100 / \mathrm{Fm})})$ |  |
| Fm $[\mathrm{Hz}] \quad$ | Test frequency |  |
| Vs $[\mathrm{V}] \quad$ | Test signal voltage |  |

## Relative measurement accuracy with bias current isolation

When DC bias Isolation is set to ON , add the following value to the open offset Y .
Equation 20.

$$
\text { Yo_DCI1 } \times(1+1 /(V s)) \times(1+\sqrt{(500 / F m}))+Y o \_D C l 2
$$

$\mathrm{Zm}[\Omega] \quad$ Impedance of DUT
Fm [Hz] Test frequency
Vs [V] Test signal voltage
Yo_DCI1,2 [S] Calculate this by using Table 61 and 62
$\mathrm{Idc}[\mathrm{A}] \quad \mathrm{DC}$ bias isolation current

Table 64. Yo_DCI1 value

| DC bias current range | Measurement time mode |  |
| :--- | :--- | :--- |
|  | SHORT | MED, LONG |
| $20 \mu \mathrm{~A}$ | 0 S | 0 S |
| $200 \mu \mathrm{~A}$ | 0.25 nS | 0.05 nS |
| 2 mA | 2.5 nS | 0.5 nS |
| 20 mA | 25 nS | 5 nS |
| 100 mA | 250 nS | 50 nS |

## Table 65. Yo_DCI2 value

| DC bias current range | Measurement time mode |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\leq 100 \Omega$ | $300 \Omega, 1 \mathrm{k} \Omega$ | 3 k $\Omega$, $10 \mathrm{k} \Omega$ | $30 \mathrm{k} \Omega$, $100 \mathrm{k} \Omega$ |
| $20 \mu \mathrm{~A}$ | 0 S | 0 S | 0 S | 0 S |
| $200 \mu \mathrm{~A}$ | 0 S | 0 S | 0 S | 0 S |
| 2 mA | 0 S | 0 S | 0 S | 3 nS |
| 20 mA | 0 S | 0 S | 30 nS | 30 nS |
| 100 mA | 0 S | 300 nS | 300 nS | 300 nS |

## DC bias settling time

When DC bias is set to ON , add the following value to the settling time:
Table 66. DC bias settling time

|  | Bias | Settling time |
| :--- | :--- | :--- |
| 1 | Standard | Capacitance of DUT $\times 100 \times \log _{\mathrm{e}}(2 / 1.8 \mathrm{~m})+3 \mathrm{~m}$ |
| 2 | Option 001 | Capacitance of DUT $\times 100 \times \log _{\mathrm{e}}(40 / 1.8 \mathrm{~m})+3 \mathrm{~m}$ |



Figure 11. DC bias settling time

## Web Resources

Visit our Web sites for additional product information and literature.

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Printed in USA, October 10, 2006
5989-4435EN

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[^0]:    1. Option E4980A-001 is required.
[^1]:    1. When auto level control function is on.
    2. This is not an output value but a displayed test signal level
    3. Typ. when test frequency is $>1 \mathrm{MHz}$ with test signal voltage $>10 \mathrm{Vrms}$.
